

# RELIABILITY ANALYSIS/ASSESSMENT OF ADVANCED TECHNOLOGIES 

## Westinghouse Electric Corporation

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RADC-TR-90-72 has been reviewed and is approved for publication.

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### 1.0 INTRODUCTION

### 1.1 OBJECTIVES

The main objectives of this study have been: (1) to examine the existing failure rate prediction models in the Microcircuit Section of MIL-HDBK-217E, to determine if they are applicable to state-of-the-art devices; (2) to revise or extrapolate the existing models as necessary to reflect current and future device reliability; (3) to perform a reliability assessment of device types. being designed into state-of-the-art systems, for which no models presently exist; and (4) to develop new reliability prediction models for emerging technology devices. These objectives support the goal of developing accurate, user-friendly models for possible inclusion in a future revision to MIL-HDBK-217.

### 1.2 BACKGROUND

MIL-HDBK-217 has been used as a guide for predicting system reliability for many years. The consistent approach used by the authors of the handbook (RADC) has been to examine field and life test component failure data to identify key elements to which this data best fits. These key elements are then combined in an additive and multiplicative form to develop a component failure rate value dependent upon the type and application of the specific component. Component failure rate values can be combined, according to the specified system architecture, to obtain a predicted value of the system failure rate. Using this approach, the authors have been successful in maintaining a usable model. However, because of increasing microcircuit complexities and new component types, there is a need for an improved, updated prediction model for advanced microcircuits.

To develop a set of requirements for a reliability prediction model, it is necessary to understand the intended use of the model. Reliability prediction models, such as MIL-HDBK-217E, are used extensively to determine the reliability trade-offs between various system designs, in order to produce the
optimum reliable design. The requirement to deliver systems with higher reliability is being pursued aggressively by 000 . The seriousness with which the Air Force views system reliability is demonstrated in the goals of R\&M 2000, with similar initiatives being pursued by the Army and Navy. In order to achieve these goals, it is imperative that the major reliability risks in the system design be accurately identified and eliminated without unnecessary reliability design complications, such as over-redundancy or the use of inappropriate cooling system strategies. The reliability prediction model must be capable of realistically approximating the reliability of each component comprising the system, including the advanced microcircuits. The methods of reliability prediction modeling investigated address the requirements of accuracy of the predicted failure rate, comprehensiveness of microcircuit types, integration with microcircuit screening, and model maintainability, all with minimal impact on usability.

### 1.3 LIST OF ACRONYMS

A list of acronyms with their associated meanings as used in this report is as follows:

AC - Assignable Cause
Ag - Silver
Al - Aluminum
ALSTTL - Advanced Low-power Schottky Transistor-Transitor Logic
ASIC - Application Specific Integrated Circuit
ASTTL - Advanced Schottky Transistor-Transistor Logic
Au - Gold
B - Boron
BIMOS - Bipolar/Metal Oxide Semiconductor
BIR - Built-in Reliability
CCD - Charge Coupled Device
CERDIP - Ceramic Dual Inline Package
CGA - Configurable Gate Array
CHE - Channel Hot Electron
CI - Charge Injection

```
Cl - Chlorine
CML - Current-Mode Logic
CMOS - Complementary Metal Oxide Semiconductor
CPU - Central Processing Unit
CVD - Chemical Vapor Deposition
DIP - Dual In-line Package
DOD - Department of Defense
DRAM - Dynamic Random-Access Memory
DTL - Diode-Transistor Logic
Ea - Activation Energy
ECL - Emitter-Coupled Logic
EEPROM - Electrically Eraseable Programmable Read-Only Memory
EM - ElectroMigration
EMI - Electromagnetic Interference
EMP - Electromagnetic Pulse
EPROM - Eraseable Programmable Read-Only Memory
ESD - ElectroStatic Discharge
eV - Electron Volt
F - Fluorine
FET - Field-Effect Transistor
FGMOS - Floating Gate Metal-Oxide Semiconductor
FLOTOX - Floating Gate Tunnel-Oxide
FPMH - Failures Per Million Hours
FR - Failure Rate
FTTL - Fast Transistor-Transistor Logic
GaAs - Gallium Arsenide
Ge - Germanium
H - Hydrogen
HAL - Hard Array Logic
HBT - Heterojunction Bipolar Transistor
HEMT - High-Electron Mobility Transistor
HMOS - High-performance Metal-Oxide Semiconductor
HTRB - High Temperature Reverse Bias burn-in
IC - Integrated Circuit
IEEE - Institute of Electrical and Electronics Engineers
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```
IIL - Integrated Injection Logic
In - Indium
IRPS - International Reliability Physics Symposium
K - Boltzman's constant
K - Potassium
K - Thermal conductivity
KÅ - Kilo Angstroms
LCC - Leadless Chip Carrier
LEFM - Linear Elastic Fracture Mechanics
LSI - Large-Scale Integration (1,001 to 10,000 logic gates)
LSTTL - Low-power Schottky Transistor-Transistor Logic
LTTL - Low-power Transistor-Transistor Logic
MDR - Microcircuit Device Reliability (RAC publicatons)
MESFET - Metal Semiconductor Field-Effect Transistor
MHP - Multichip Hybrid Package
MIL-HDBK - Military Handbook
MIL-STD - Military Standard
MIMIC - Millimeter-wave Monolithic Integrated Circuit
MLA - Masked-Logic Array
MLO - Multi-level Oxide
MMIC - Monolithic Microwave Integrated Circuit
MNOS - Metal-Nitride-Oxide Semiconductor
MOS - Metal-Oxide Semiconductor
MOSFET - Metal-Oxide Semiconductor Field-Effect Transistor
MSI - Medium-Scale Integration (101 to 1,000 logic gates)
MTBF - Mean Time Between Failures
MTTF - Mean Time To Failure
N - Nitrogen
Na - Sodium
NDP - Numerical Data Processor
NMOS - N-channel Metal-Oxide Semiconductor
O-Oxygen
P - Phosphorous
P-DIP - Plastic Dual In-line Package
PAL - Programmable Array Logic
```

```
PCB - Printed Circuit Board
PGA - Pin Grid ArrayPLA - Programmable Logic Array
PMOS - P-channel Metal-Oxide Semiconductor
PPM - Parts Per Million
PROM - Programmable Read-Only Memory
PSG - Phosphosilicate Glass
RAAAT - Reliability Analysis/Assessment of Advanced Technologies
RAC - Reliability Analysis Center
RADC - Rome Air Development Center
RAM -. Random-Access Memory
RH - Relative Humidity
RMC - Representative Microcircuit Configuration
ROM - Read-Only Memory
SAW - Surface Acoustic Wave
SF - Screening Factor
Si - Silicon
SIA - Semiconductor Industry Association
PHP - Power Hybrid Package
SRAM - Static Random-Access Memory
SSI - Small-Scale Integration (i to loo logic gates)
STTL - Schottky Transistor-Transistor Logic
Tch - Channel Temperature
TODB - Time Dependent Dielectric Breakdown
Tj - Junction Temperature
TTL - Transistor-Transistor Logic
ULSI - Ultra Large-Scale Integration (greater than 100,000 logic gates)
UVEPROM - Ultra-violet Eraseabie Programmable Read Only Memory
VHSIC - Very High-Speed Integrated Circuit
VLSI - Very Large-Scale Integration (10,000 to 100,000 logic gates)
WEC - Westinghouse Electric Corporation
WSI - Wafer-Scale Integration
2.0 REPORT ORGANIZATION
```

Section 3.0 presents the approach which was taken in the conduct of this study
contract. It lists the microcircuit types which were the subject of study, and it summarizes the methodology employed, the types of models which were developed, and their intended usage.

Section 4.0 is the main body of the report. It discusses the model development for each of the primary categories of devices, as listed below:

- VLSI/ULSI Devices (including microprocessors and gate array devices) - Section 4.1
- Memory Devices (including programmable logic devices) - Section 4.2
- Monolithic GaAs Devices (including microwave and digital devices) Section 4.3
- Hybrid Microcircuits (including all styles of multi-chip hybrids) Section 4.4
- Packaging Models (including corrosion, cracking, and wire-bond failure models) generic to all packages - Section 4.5

In addition, the development of failure rate adjustment factors ( $\pi$ factors) to account for different quality levels, product maturity, device functions and operating environments, is presented in Section 4.6.

Section 5.0 discusses predictive model validation, where it was possible to validate the models. Section 6.0 presents our conclusions and recommendations for follow-on analysis and study, and section 7.0 is the combined bibliography for the report.

Appendix $A$ is a page-for-page replacement for Section 5.1.2 of MIL-HDBK-217E.

Appendices $B$ and $C$ are, respectively, mathematical derivations and fortran programs supporting the development of the VLSI/ULSI models.

Appendix $D$ contains tables of probability of sucess and hazard rate at 10,000 operating hours for the predominant wearout failure mechanisms, electromigration and time-dependent dielectric breakdown. Appendix E contains memory devices life test data.

Appendices F, G and H are detailed summaries of the work performed in the development of the deterministic package failure models, presented in the format of technical papers.

Appendix $I$ provides the derivation of $\Delta T$ default values to be used for various part usage environments.

### 3.0 APPROACH

The approach which was pursued in assessing the reliability of advanced technology microcircuits consisted of a five-step process.

1. A review of MIL-HDBK-217 identified the component styles and the device technologies which needed to be addressed. If the validity of the existing model was questionable, or if no model existed, it was added to the list. The following areas were selected for research and analysis:
```
Application Specific ICs (ASIC)
Very Large-Scale Integration (VLSI)
Ultra Large-Scale Integration (ULSI)
Very High-Speed Integrated Circuits (VHSIC)
Random-Access Memory (RAM)
Read-Only Memory (ROM)
Programmable Read-Only Memory (PROM)
Programmable Array Logic, Logic Array, Hard Array Logic (PAL, PLA, HAL)
Configurable Gate Array (CGA)
Current-Mode Logic (CML)
Pin Grid Array (PGA)
Monolithic Microwave IC, Gallium Arsenide (MMIC, GaAs)
Hybrids (MHP, PHP)
Packaging (Materials, Seals, Die Attach, Wire Bonds, Corrosion)
```

2. A literature search was conducted to determine if the reliability of these component/technology types had been documented. Emphasis was placed on device failure mechanisms and data relative to failure physics, because it was
intended to develop deterministic models to the maximum extent possible. A partial listing of the references is included in the bibliography and the appendices.
3. Data was collected from several sources, including the Reliability Analysis Center (RAC) Microcircuit database, technical journals, technical periodicals, manufacturers' device data books, and the Westinghouse Failure Analysis and field Failure databases. In addition, an industry survey was made, by mail and by telephone, of 227 suppliers and users of advanced microelectronic devices. The data was categorized for the primary model development areas, and each of these databases is discussed in the appropriate paragraphs of Section 4.0 of this report.
4. The data was analyzed for applicability to the model development effort.
5. Predictive models were developed, based on the data collected. Where possible, the models were validated by using additional sources of information and/or by comparison of the results with MIL-HDBK-217E.

### 3.1 METHODOLOGY

Initially, the attempt was made to develop only deterministic models for all of the component types identified for study. However, several pitfalls became evident in this approach. First, the resultant form of the model, a combination of all failure distributions, although inherently accurate and mathematically correct, is not user-friendly. It is not possible to improve model accuracy and comprehensiveness without adversely affecting the model development and use. Second, the resulting model form does not readily lend itself to inclusion in MIL-HDBK-217, which is an ultimate goal. And third, deterministic models cannot account for the early and middle life microcircuit failures - those which typically occur within the useful life of the components, and which appear to occur randomly. Since these failures are of significance to the user of the model, they must be included.

Therefore, the reliability prediction model which was developed for advanced
microcircuits estimates the early, middle, and end-life of these microcircuits. In general, early and middle-life microcircuit failures are "assignable cause" fallures. These failures are premature failures whose causes can be "assigned" to specific random defects or events. The early and middle-life failures typically exhibit a substantially greater failure rate than do end-life failures. The end-life failures of microcircuits are "common cause" failures. These failures are material wearout failures whose causes are "common" because of the common materials used in the fabrication of the microcircuits. MIL-HDBK-217E and its predecessors only considered assignable cause failures in the development of prediction models, since common cause failures did not typically occur within the lifetimes of military systems. However, the geometry scaling required to attain the complexity of the advanced microcircuits in question may result in common cause failures that contribute significantly to the overall failure rate of the microcircuits under standard operating conditions.

Much of the prediction modeling effort was dedicated to distinguishing between assignable cause failures and common cause failures. Since the failure models for early, middle and end life are not typically the same, a generic model was developed to combine these individual failure models. This Superposition Model is described in detail in section 4.l.l, but it is also described briefly below.

As previously mentioned, the early and middle-life failures, or "assignable cause" failures, are defect-related, and they can be accurately modeled by a constant (time-independent) failure rate, as was done in MIL-HDBK-217. If there are $n$ independent assignable cause failure mechanisms operating on a component population, then

$$
\begin{equation*}
\lambda_{A T}=\sum_{i=1}^{n} \lambda_{A i}, \tag{3.1.1}
\end{equation*}
$$

where:
$\lambda_{A T}=$ the total component failure rate due to assignable causes
$\lambda_{A i}=$ the component failure rate due to the $i^{\text {th }}$ assignable cause

Further, the reliability of the component, or the probability of its operating without failure for some time, $\tau$, may be expressed as

$$
\bar{R}=e^{-\lambda} A T^{\tau}
$$

However, this model does not account for the end of life (wearout) failure mechanisms, which are typically distributed log-normally - implying non-constant failure rates. Equation 3.1 .2 may be expanded to include these failure mechanisms, and thus becomes

$$
\bar{R}=e^{-\lambda A T^{\tau}} \times \prod_{i=1}^{m}\left(1-F_{i}(\tau)\right),
$$

where:
$F_{\mathfrak{i}}(\tau)$ is the time-dependent probability of failure for the
ith failure mechanism, and
$m \quad$ is the number of independent wearout mechanisms.

The problems presented by this model are: (1) the non-constant (time dependent) failure rate of the wearout mechanisms, implying that the time in the component's life used to evaluate the reliability will alter the result; and (2) the fact that failure rates of components can no longer be added to derive a total system failure rate. The first problem is overcome if a common time is chosen for comparative analysis of the reliability of all components. Ten thousand operating hours is a common design criteria for avionics systems (programs such as ALQ-165 and APG-68), and it has been chosen in our modeling effort. A fallure rate for each wearout mechanism can then be calculated, as described in section 4.1. The second problem is overcome by using reliability, rather than failure rate, as the figure of merit, or by ignoring the common causes (by reverting to use of equation 3.l.2). The latter may be done legitimately if the calculated value of the effective failure rate of the common cause failure mechanisms is much less than the failure rate due to
assignable causes. Even then, the common cause models are useful as design tools, both in the assessment of inherent reliability (failure free operating period) and in the verification of adequate derating margins.

### 3.2 MODELS

Models have been developed for the primary categories of advanced technology devices as shown in Table 3.2-1.

Table 3.2-1 NEW MICROCIRCUIT MODELS

| $\begin{aligned} & \text { DEVICE } \\ & \text { CATEGORY } \\ & \hline \end{aligned}$ | ASSIGNABLE CAUSE (EARLY-MIDDLE-LIFE) | COMMON CAUSE (END-LIFE/WEAROUT) | REMARKS |
| :---: | :---: | :---: | :---: |
| VLSI/ULSI | E | $N$ | $E=$ extrapolated or modified 217 model based on new data |
| Memories | E | $N$ | $N=$ new model |
| GaAs | N | - | Insufficient data for commone cause model development |
| Hybrids | $N$ | $N$ | Common causes addressed in chip, package models |
| Packages | E | $N$ |  |

1
Quality, learning, environment and hybrid function failure rate adjustment factors are modifiers of the assignable cause failure rates only.

With the exception of the hybrid model, which has been greatly simplified, the assignable cause models are similar in form to the models in MIL-HDBK-2I7E. A comparison is presented in Table 3.2-2.
Table 3.2-2 ASSIGNABLE CAUSE MODEL COMPARISON

| $\begin{aligned} & \text { DEVICE } \\ & \text { CATEGORY } \end{aligned}$ | MIL-HDBK-217E | NEW MODEL |
| :---: | :---: | :---: |
| VLSI/ULSI (LSI) | $\lambda_{P}=\pi_{Q}\left(C_{1} \pi_{T} \pi_{V}+C_{2} \pi_{E}\right) \pi_{L}$ | $\lambda_{P}=\pi_{Q}\left(C_{1} \pi_{T}+C_{2} \pi_{E}\right) \pi_{L}$ |
| memories | $\lambda_{P}=\pi_{Q}\left(C_{1} \pi_{T} \pi_{V}+C_{2} \pi_{E}\right) \pi_{L}$ | $\lambda_{P}=\pi_{Q}\left(C_{1} \pi_{T}+C_{2} \pi_{E}+\lambda_{C Y C}\right) \pi_{L}$ |
| GaAs | none | $\lambda_{P}=\pi_{Q}\left(\left(C_{1 A} \pi_{T A}+C_{1 P} \pi_{T P}\right) \pi_{A}+C_{2} \pi_{E}\right) \pi_{L}$ |
| HYBRIDS | $\begin{aligned} \lambda_{P}= & {\left[\Sigma N_{C} \lambda_{C} \pi_{G}+\left(N_{R} \lambda_{R}+\right.\right.} \\ & \left.\left.\sum N_{I} \lambda_{I}+\lambda_{S}\right) \pi_{F} \pi_{E}\right] \\ & \pi_{Q} \pi_{D} \end{aligned}$ | $\lambda_{P}=\pi_{Q}\left(E N_{C} \lambda_{C}\left(1+.2 \pi_{E}\right)\right) \pi_{L} \pi_{F}$ |
| packages | $c_{2} \pi_{E}$ | $C_{2}{ }^{\text {m }}$ |

## LEGEND TO TABLE 3.2-2

| $\lambda_{p}$ | is the device failure rate in $\mathrm{F} / 10^{6}$ hours |
| :---: | :---: |
| $\pi_{0}$ | is the quality factor |
| $\pi_{T}$ | is the temperature acceleration factor (MOS and Bipolar) |
| ${ }^{T}$ TA | is the GaAs temperature acceleration factor (active devices) |
| TTP | is the GaAs temperature acceleration factor (passive devices) |
| $C_{1}$ | is the circuit complexity factor (MOS and Bipolar) |
| $C_{1 A}$ | is the GaAs circuit complexity factor (active devices) |
| $C_{1 P}$ | is the GaAs circuit complexity factor (passive devices) |
| ${ }^{\pi} \mathrm{E}$ | is the application environment factor |
| $\pi_{L}$ | is the device learning factor |
| $C_{2}$ | is the package complexity factor |
| ${ }^{\text {cre }}$ | is the EEPROM cycling-induced failure rate |
| $\pi_{F}$ | is the circuit function factor (hybrids) |
| ${ }^{N}$ | is the number of each particular component (within hybrids) |
| $\lambda_{C}$ | is the component fallure rate (for each component within hybrids) |
| ${ }^{\prime} \mathrm{G}$ | is the die correction factor |
| $N_{R}$ | is the number of chip or substrate resistors |
| $\lambda_{R}$ | is the failure rate of the chip or substrate resistor |
| $N_{\text {I }}$ | is the sum of the hybrid interconnections |
| $\lambda_{\text {I }}$ | is the failure rate per interconnect |
| ${ }_{0}$ | is the hybrid density factor |
| $\lambda_{S}$ | is the failure rate of the hybrid package |
| $\Pi_{\text {A }}$ | GaAs MMIC application factor |

### 4.0 MODEL DEVELOPMENT

### 4.1 VLSI/ULSI MICROCIRCUITS AND MICROPROCESSORS

The device list which was considered for an updated VLSI/ULSI prediction model included bipolar and MOS digital devices (including shift registers, programmable logic arrays (PLA) and programmable array logic (PAL)), bipolar and MOS linear devices, bipolar and MOS digital microprocessor devices (including controllers), bipolar and MOS analog microprocessor devices, charge coupled devices (CCD), and wafer scale integration (WSI). For the end-life failure model, several class modifications were made (see Table 4.1-1). The first two classes of devices were renamed bipolar digital and linear devices (including gate/logic arrays) and MOS digital and linear devices (including gate/logic arrays), since the wearout mechanisms are similar within these classes. From discussions with microprocessor suppliers, ${ }^{[8]}$ bipolar VLSI/ULSI microprocessor devices do not have a moderate to high probability of being used in near future military systems; therefore, the next two classes of devices were renamed MOS digital microprocessors (including controllers) and MOS analog microprocessors (including controllers). Because of insufficient data on the manufacturing technology of MOS analog microprocessor devices and CCDs, adequate life-prediction models could not be developed. WSI was not modeled as a separate category since it comprises many different microcircuit types whose failure rates can be calculated separately and then combined using the model of section 4.1.1.

During the development of the prediction model for VLSI/ULSI microcircuits, several assumptions were made that could not be fully substantiated during the course of the contract. The assumptions are highlighted in section 6.0 with possible direction in verifying these assumptions.

The literature search for the VLSI/ULSI model development spanned the RAC database, the Proceedings of the International Reliability Physics Symposia (IRPS), the Proceedings of the Reliability and Maintainability Symposia, the Transaction of the Reliability Society of the IEEE, and numerous other technical journals. The data collected for the end-life model development was sparse.

## Table 4.1-1

## VLSI/ULSI Device Category Changes

Bipolar Digital \& Linear Devices ..... [1]
(Including Gate/Logic Arrays)
MOS Digital \& Linear Devices ..... [1]
(Including Gate/Logic Arrays)
Bipolar Digital Microprocessors ..... [1]
(Including Controllers)
MOS Digital Microprocessors ..... [1]
(Including Controllers)
Monolithic Bipolar \& MOS Analog[2]
Microprocessor Devices (Including Controllers)
MOS Analog Microprocessors ..... [3]
(Including Controllers)
Charge Coupled Devices (CCDs) ..... [3]
Wafer Scale Integration (WSI) ..... [4]
[1] Model developed
[2] Model not viable
[3] Insufficient ..... data
[4] End of life models for VLSI/ULSI can be used by extrapolation

Except for sources such as the IRPS (papers identified in the references), very little information was available to understand why system failures occur. Trend analysis of system data is not appropriate for developing values for the parameters in the wearout models developed. Therefore, sources such as the RAC database, the WEC field database, most industry contacts, and the bulk of the available literature on failures, all of which heavily depend on trend analysis, lack the detail necessary to pinpoint the failure mechanism, parametric stress conditions and the time-to-failure.

### 4.1.1 Model Overview - The Superposition Model

The approach to the updated VLSI/ULSI reliability prediction model development initially concentrated on the types and causes of system failures. By definition, a system failure is that event in which the specification of a performance parameter of the system is exceeded due to physical processes operating on the system that proceed naturally during the life of the system. Table 4.1-2 outlines the results of a recent survey ${ }^{[40]}$ of system failures with respect to percent contribution of component replacement for a particular component type. The survey shows that the microcircuit is still the leading component to which many system failures are attributed.

Table 4.1-2 Summary of Parts Replacement Distributions [40]


A survey ${ }^{[36]}$ of the causes of VLSI/VHSIC microcircuit failures specifically, outlined in Table 4.1-3, shows VLSI/VHSIC microcircuits of similar complexity
failing for totally different reasons. A VLSI/VHSIC prediction model that cannot account for this inconsistency in observed failure mode/mechanisms may result in a grossly inaccurate prediction. To address this inconsistency, microcircuit fallures were classified into two categories: common cause failures and assignable cause failures. These two categories of failures were then modeled separately.

## Table 4.1-3 Vendor Data[36]


$X=$ failure mode occurs but no percentage given in survey response.

By modeling the common cause microcircuit failure rate separately from the total microcircuit failure rate, it is possible to evaluate the system reliability improvement due to the use of mature microcircuits which have minimized the assignable causes of failure. It is noted that these assignable cause failures can be minimized or eliminated by use of built-in-reliability (BIR) techniques or screening. The "band" of potential reliability improvement is displayed graphically in Figure 4.l-1. Assuming a bathtub-like system failure rate curve, it is reasonable for the failure rate of a system that has not eliminated the assignable causes of component failures to be an order of magnitude (or more) greater than the common cause system failure rate. Therefore, the failure rate value that should be used to predict the system reliability depends on the maturity of the microcircuits and the effectiveness of the microcircuit and system screens prior to system delivery. In the early- and middle-life defect model, these effects are addressed by the learning and quality factors.

Figure 4.1-1


A general reliability prediction model, the Superposition Model, was developed to combine the early-, middle- and end-life prediction models. In addition, this model is used to combine the individual failure mechanism models developed as part of the end-life prediction model. This model can also be used to address end-life failure rates of WSI devices by making the assumption that the WSI device is composed of many different device styles competing to cause failure of the total WSI device.

The Superposition Model is a modified competing-risk model used to combine the early-, middle- and end-life failure distributions, as well as the individual failure mechanism distributions. According to the competing-risk model, [37] the probability of failure at time $t$ for a microcircuit has the form

$$
F(t)=1-\prod_{i=1}^{k}\left(1-F_{i}(t)\right),
$$

Where $F_{j}(t)$ is the probability of failure for the $i$ th failure distribution of $k$ total failure distributions identified at time $t$.

$$
\begin{equation*}
F_{i}(t)=\int_{0}^{t} f_{i}(t), \tag{4.1.2}
\end{equation*}
$$

where $f_{i}(t)$ is the $i^{\text {th }}$ failure probability density function. Rearranging terms in equation 4.1.1, and making the substitution that the probability of success at time $t, P(t)$, is the complement of the probability of failure at time $t$,

$$
\begin{equation*}
P(t)=1-F(t), \tag{4.1.3}
\end{equation*}
$$

equation 4.l.1 can be rewritten

$$
\begin{equation*}
P(t)=\prod_{i=1}^{k} P_{i}(t) . \tag{4.1.4}
\end{equation*}
$$

This model is not limited to specific types of failure distributions and does not require that the failure distributions be of the same type; however, the model does require independence of the failure distributions.

The Superposition Model can be used to estimate the lifetime of a microcircuit given the early-life, middle-life and end-life failure models. Since early-and middle-life fallures are assignable cause failures, the model used to approximate these failures is the exponential probability density function. The functional form is given by

$$
\begin{equation*}
f(t)=\lambda \exp [-\lambda t] \tag{4.1.5}
\end{equation*}
$$

where $\lambda$ can be shown to be the hazard (time-independent) rate. Given $\lambda_{\text {early }}$ and $\lambda_{\text {middle }}$, the hazard rates for early and middle-life respectively, the probability of success for the microcircuit is defined as

$$
\begin{equation*}
P(t)=\exp \left[-\lambda_{\text {early }} t\right] * \exp \left[-\lambda_{\text {middle }} t\right] * P_{\text {end }}(t), \tag{4.1.6}
\end{equation*}
$$

where:

$$
\begin{aligned}
P_{\text {end }}(t)= & \text { probability of success of the end }-1 \text { ife failure } \\
& \text { distribution. }
\end{aligned}
$$

Equation 4.1 .6 can also be written in the form of a microcircuit hazard rate at time $t_{0}$ :

$$
\begin{equation*}
\lambda\left(t_{0}\right)=\lambda_{\text {early }}+\lambda_{\text {middle }}-\ln \left(P_{\text {end }}\left(t_{0}\right)\right) / t_{0} \tag{4.1.7}
\end{equation*}
$$

It must be noted that $-\ln \left(P_{\text {end }}\left(t_{0}\right)\right) / t_{0}$ is not a true hazard rate for endlife at time $t_{0}$ since the end-life failure distribution is not necessarily an exponential distribution; however, this "effective hazard rate" transforms properly to a worst-case probability of success using the standard equation

$$
\begin{equation*}
P=\exp [-\lambda t] . \tag{4.1.8}
\end{equation*}
$$

A log-normal distribution is a wear-out distribution in which the hazard rate increases with time; therefore, the hazard rate at time $t_{0}$ will be greater than the hazard rate at time $t_{1}$ for $t_{1}<t_{0}$. The associated probability of success at time $t_{0}$ will be less than the probability of success at time $t_{1}$; therefore, for all time less than $t_{0}$, a worst-case probability is derived.

All end-life probability of successes, hazard rates, and effective hazard rates are calculated for $t_{0}=10,000$ hours, a standard avionics system lifetime requirement which is typically specified in the contract statements of work for avionic equipment.

### 4.1.2 Early- and Middle-Life Prediction Models

Early- and middle-life of VLSI/ULSI microcircuits are limited by random failures that similarly plague non-VLSI/ULSI microcircuits. Random failures can be due to pinholes or particles in dielectrics resulting in electrical shorts, ionic contamination causing shifts in transistor parameters, and many other types of random defects. MIL-HDBK-217E is based upon exponential failure distributions which describe random failures. The exponential model is appropriate for these failures because in aggregate (at the system level where failures are reported) they appear random even though they have physical causes. This is due to the overlap of many distinct defect distributions, each having its own MTTF and standard deviation. Furthermore, the temperature dependence of the failure rate is defensible because the predominant defect failure mechanisms - dielectric breakdown and metallization failure - are accelerated by temperature. This has been shown in the literature and through life testing. While it is true that perfectly made IC's would not experience these "random" defects, it is also true that periodically flawed components go undetected in environmental screening and later manifest themselves as field failures. The literature search did not discover any failure mechanisms for VLSI/ULSI devices which do not also pertain to SSI, MSI and LSI devices. A reasonable approximation of early and middle-life for VLSI/ULSI microcircuits would therefore be an extrapolation of MIL-HDBK-2l7E to the complexity of these advanced technology components. From an evaluation of available VHSIC data, the extrapolation for MOS VLSI devices seems reasonable, but the activation energy requires modification.

The IITRI/Honeywell SSED VHSIC Report ${ }^{[36]}$ endeavored to create time-dependent failure rates (hazard rates) for early- and middle-life failure mechanisms. The mechanisms addressed included oxide failures, metal failures, hot carrier effects, ESD effects, and miscellaneous defect failures. In the
present study efforts, that data was analyzed to determine the actual shape of the distributions (as opposed to assuming a decreasing exponential based upon two points). The three primary defect areas contributing to the early-life failure rate were found to be oxide, metal, and miscellaneous; all others were at least an order of magnitude smaller in contribution. The oxide data is plotted in figure 4.1-2, the metal data in figure 4.l-3, and the miscellaneous data in figure 4.1-4. The intervals were those given in the IITRI/Honeywell VHSIC report, and were so chosen because in many cases sources reported failures occurring within a time interval. The failure rates were determined by dividing the number of failures in each interval by the accelerated parthours from operating life tests, burn-in, and various environmental tests (adjusted to $25^{\circ} \mathrm{C}$ based on the Arrhenius relationship) for that interval. As can be seen, the defects are not distributed as decreasing exponentials which would be straight lines with negative slope on a logarithmic scale. Instead, since the failures are assumed to be random, an average failure rate was calculated at $25^{\circ} \mathrm{C}$ as shown in the figures. The failure rates were then adjusted for temperature by use of the appropriate activation energy for the failure mechanism, as extracted from the VHSIC report, and summed to get a total failure rate. Once this was done, a combined activation energy, ( $E_{a}$ ) was calculated by using the Arrhenius relationship (see Table 4.l-4) and weighting according to the partial contribution of each mechanism to the total failure rate. The activation energy is not constant, but increases with temperature; the range is .31 eV at $30^{\circ} \mathrm{C}$ to .325 eV at $150^{\circ} \mathrm{C}$. However, for MOS devices, a value of .35 has been selected because this value is conservative (all errors are positive), and it is equal to the value calculated in derivation of the early-life MOS microprocessor model (. 35 eV ). The failure rate using . 35 eV is presented over temperature in the column "FR using $E A=0.35 . "$ The value at $25^{\circ} \mathrm{C}$ is .029 failures per million hours, implying a Cl complexity value (in the format of the MIL-HDBK-217E model) of .29 for VLSI/ULSI microcircuits ( $C_{1}$ is equal to ten times the failure rate at $25^{\circ} \mathrm{C}$ ). MIL-HDBK-2l7E may be considered accurate if (a) the .29 value is used for VLSI/ULSI complexity levels, and (b) the activation energy for MOS devices, (HMOS, NMOS, CMOS, etc) is changed to 0.35 eV . Insufficient data was available for this contract to develop VLSI/ULSI bipolar failure rates.

FIGURE 4.1-2


OXIDE EARLY-LIFE FAILURE DATA ${ }^{[36]}, e_{A}=0.3 \mathrm{eV}$

| RANGE (HOURS) | MIDPOINT | In MIDPOINT | LAMBDA $\left(25^{\circ} \mathrm{C}\right)$ |
| :---: | :---: | :---: | :---: |
| 0-2,344 | 1,172 | 7.0665 | . 004652 |
| 2,345-8,204 | 5,275 | 8.5707 | . 008119 |
| 8,205-16,950 | 12,578 | 9.4397 | 000606 |
| 16,951-24,417 | 20,684 | 9.9371 | . 013848 |
| 24,418-48,834 | 36,626 | 10.5085 | . 053133 |
| 48,835 - 49,224 |  |  |  |
|  | 49,640 | 10.8126 | . 142502 |
| 49,225-50,446 |  |  |  |
| 50,447-138,452 | 94,450 | 11.4558 | . 003812 |
| 138,453-193,123 | 165,788 | 12.0185 | . 084240 |
| AVERAGE LAMBDA |  |  | . 0269 |

FIGURE 4.1-3


METAL EARLY-LIFE FAILURE DATA ${ }^{[36]}, e_{A}=0.55 \mathrm{eV}$

| RANGE (HOURS) |  | MIDPOINT | $\underline{\ln \text { MIDPOINT }}$ | LAMBDA ( $25^{\circ} \mathrm{C}$ ) |
| :---: | :---: | :---: | :---: | :---: |
| 0 | 59,872 | 29,936 | 10.3068 | . 000182 |
| 59,873 | - 209,553 | 134,713 | 11.8109 | . 000146 |
| 209,554 | - 623,669 | 416,612 | 12.9399 | . 000115 |
| 623,670 | - 1,247,337 | 935,504 | 13.7488 | . 000323 |
| AVERAGE | LAMBDA |  |  | . 000219 |

FIGURE 4.1-4


MISCellaneous failure data ${ }^{[36]}, e_{A}=0.423 \mathrm{eV}$

| RANGE (HOURS) |  |  | MIDPOINT | In MIDPOINT | LAMBDA $\left(25^{\circ} \mathrm{C}\right)$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 0 | - | 11,543 | 5,572 | 8.6607 | . 000630 |
| 11,544 | - | 20,183 | 15,864 | 9.6718 | . 000422 |
| 20,184 | - | 40,402 | 30,293 | 10.3187 | . 007634 |
| 40,403 | - | 66,083 | 53,243 | 10.8826 | . 000202 |
| 66,084 | - | 70,642 | 68,363 | 11.1326 | . 001151 |
| 70,643 | - | 82,514 | 76,579 | 11.2461 | . 000910 |
| 82,515 | - | 112,394 | 97,455 | 11.4871 | . 000286 |
| 112,395 | - | 120,244 | 116,320 | 11.6641 | . 004195 |
| 120,245 | - | 210,243 | 165,244 | 12.0152 | . 000984 |
| 210,244 | - | 240,488 |  |  |  |
|  |  |  | 226,328 | 12.3297 | . 001777 |
| 240,489 | - | 242,412 |  |  |  |
| 242,413 | - | 355,239 | 289,826 | 12.6076 | . 000796 |
| 355,240 | - | 393,352 | 374,296 | 12.8328 | . 002183 |
| 393,353 | - | 420,487 | 406,920 | 12.9164 | . 003678 |
| 420,488 | - | ,510,862 | 965,675 | 13.7806 | . 019915 |
| AVERAGE | LA | BDA |  |  | . 001872 |




足


MIL-HDBK-217E does not distinguish between MOS and bipolar devices in the Cl terms for SSI, MSI and LSI devices. The predominant failure mechanism for MOS devices is TDDB which, as is well documented in the literature, has an activation energy of 0.3 eV , whereas the most common bipolar mechanisms are metallization defects and electromigration which have activation energies ranging from 0.42 to 0.9 eV . This implies that bipolar devices, having higher activation energies, will have higher failure rates than will MOS devices of similar maturity and complexity. This would be plausible if the failure rates of the two technologies were similar at $25^{\circ} \mathrm{C}$; however, reliability data published by British Telecom ${ }^{[101]}$ indicates that, for each level of IC complexity, the intrinsic failure rate of MOS devices is approximately 3.6 times higher than that of bipolar devices in benign environments. Assuming that this ratio holds for ICs at $25^{\circ} \mathrm{C}$, the value of Cl for bipolar VLSI devices should be . 08 , rather than .29. Using the complexity progression of MIL-HDBK-217E yields Cl values ranging from .0025 (SSI) to .08 (VLSI) for bipolar devices. The failure rates of bipolar devices will thus be lower than those of CMOS devices up to a temperature of $109^{\circ} \mathrm{C}$ (assuming the MIL-HDBK-217E energy of 0.5 eV for LSTTL).

To develop the microprocessor failure rates, data was compiled from two sources, ${ }^{[97, ~ 104]}$ and a summary is presented in Table 4.1-5. As was done in MIL-HDBK-217E, the devices were grouped by bit complexity although some of the assignments were subjective (based upon device description). Several points need to be made concerning the data for these devices:

1. The database was very small.
2. Some manufacturers' data show no distinction in failure rate due to device complexity.
3. Very little, if any, correlation was found between device package type and die-related failure mechanisms for hermetic versus molded plastic packages. The reason for this is that microcircuit manufacturers today employ die passivation in non-hermetic applications. Corrosion will not be a problem, particularly for the short duration and controlled environment of a burn-in or life test from which this data was derived.



Table 4.1-5 Microprocessor Data

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TTL
4. The assignment of complexity factors to devices such as CPUs, controllers, coprocessors, clock-drivers, bus arbiters, and other microprocessor peripherals is difficult to do.
5. A microprocessor comprised of one or two microcircuit chips will be more reliable than one comprised of more, but lower-complexity, microcircuits.

As shown in Table 4.l-5, the data was presented in the form of fallure rates from life tests of commercial devices (D quality level) at $70^{\circ} \mathrm{C}$. These failure rates were then adjusted to $B-l e v e l$ by dividing by 3.3 , the value of $\pi_{Q}$ for the $D$ quality level (see paragraph 4.6.1 for derivation of this value). The database provided activation energies for each failure mechanism experienced by each device type listed. Failure rates were also presented for each failure mechanism. Average activation energies were obtained by weighting according to their percentage contribution to the total failure rate at $70^{\circ} \mathrm{C}$. An example calculation is given below:

```
mechanism A: . 3 eV . }04\mathrm{ fpmh
mechanism B: . }5\textrm{eV}..20 fpm
mechanism C: . 4 eV . }56\mathrm{ fpmh
average E E : ((.3 x.04) + (.5 x. 20) + (.4 x . 56)) / . 80=.42 eV
```

Using the average activation energies, the failure rates at $25^{\circ} \mathrm{C}$ were calculated by employing the Arrhenius relationship:

```
\lambda25 = \lambda70 * exp [E [ / K (1/343 - 1/298)], where
```

$\lambda 25$ is the failure rate at $25^{\circ} \mathrm{C}$
$\lambda 70$ is the failure rate at $70^{\circ} \mathrm{C}$
$E_{A}$ is the average activation energy
$K$ is Boltzman's constant (8.617E-5 eV/ ${ }^{\circ} \mathrm{Kelvin}$ )
343 is $70^{\circ} \mathrm{C}$ in Kelvin, and 298 is $25^{\circ} \mathrm{C}$ in Kelvin

The $C_{1}$ values for these devices were derived to be consistent with the MIL-HDBK-217 convention (a $\pi_{T}$ value of 0.1 at $25^{\circ} \mathrm{C}$ ) by multiplying the failure rates at $25^{\circ} \mathrm{C}$ by 10 . It should be noted that the failure rates and
$C_{1}$ values approximately double for each increase in microprocessor bit complexity. Consequently, the proposed values of $C_{1}$ to be used are presented in the last column of Table 4.l-5. The values for bipolar devices are less than half the MOS values at $25^{\circ} \mathrm{C}$. This is because the failure rates of the two technology devices at $70^{\circ} \mathrm{C}$ were similar, but the bipolar devices had higher activation energies.

Two factors which had been considered for inclusion in the models were omitted. The first is a voitage-acceleration factor for MOS devices. While it is true that the predominant MOS failure mechanism, oxide failure, is accelerated by higher voltages, most MOS devices now operate at 5 volts. To attempt to correct for higher voltages in a defect model is inconsistent with ease of use, and that level of accuracy is not supported by the database. Furthermore, devices made to operate at higher voltages should have thicker oxides; the end-life model presented in section 4.1.3.1 should be used to assess the voltage effect.

The second factor is an electrostatic-discharge factor to reflect the device susceptibility to ESD damage. While the susceptibility can be quantified, the probability of failure due to that susceptibility cannot because it is dependent upon how the device is handled. From our experience in the Westinghouse Reliability Analysis Laboratory, approximately $0.1 \%$ of all failures are attributable to ESD; therefore, if an ESD factor was desired, a value of 1.001 could be used. It has been omitted from our models in the interest of simplicity, and also because it is "in the noise" of the accuracy of the early-middle-life models. Other electrical overstress failure rates, which are purely secondary events, should not be included in any early-midlife prediction model.

### 4.1.3 End-Life Failure Mechanism Models

Figure 4.l-5 shows graphically how the Superposition Model is developed for modeling end-life failure prediction. With three failure mechanisms competing on a particular microcircuit, it is necessary to know the failure rate of the microcircuit at a particular time, $t$. If the values of the cumulative
failure distributions (probability of failure functions) for each mechanism (appropriately scaled) at time tl are small (i.e., less than $1 \%$ - a reasonable assumption at the time the microcircuit is delivered as part of a system), then the value of the total cumulative failure distribution is approximately the sum of the cumulative failure distributions of each mechanism. Although many potential failure mechanisms can be identified, their impact on the total cumulative failure distribution may not be significant. An understanding of which mechanisms must be modeled for each VLSI/ULSI technology was pursued.

From literature searches and in-house failure analyses, a list of failure mechanisms affecting VLSI/ULSI microcircuits was developed. The electrical mechanisms are outlined in Table 4.1-6. Of those failure mechanisms, it was necessary to identify those which are related to common cause failures. The list was reduced to three failure mechanisms: time dependent dielectric breakdown (TDDB), electromigration (EM), and charge injection (CI). The latter mechanism was further discounted as being a design consideration rather than an inherent physical property and therefore should not contribute to the total end-life failure distribution (see section 4.1.3.3). With the common cause failure mechanisms identified, each mechanism was quantified using available data from literature and in-house reliability analysis programs. A survey of these microcircuits was performed to make the model user-friendly. The methodology for applying the end-life failure mechanism models to specific microcircuits can be found in section 4.1.4.

### 4.1.3.1 TDDB Model

According to the literature on time-dependent dielectric breakdown (TDDB), ${ }^{[16]}$ failure occurrences are distributed normally with the logarithm of time. The general form of the failure density function is

$$
\begin{equation*}
f(t)=\frac{1}{\sigma t \sqrt{2 \pi}} \exp \left[(-1 / 2)\left(\frac{\ln t-\left(A_{A} * \ln \left(t_{50 \%} /\left(A_{T} * A_{E F}\right)\right)\right)}{\sigma}\right)^{2}\right], \tag{4.1.9}
\end{equation*}
$$

## Superposition: An Example


$F(t)=1-[(1-F a(t))(1-F b(t))(1-F c(t))]]$
$\mathrm{Fa}(\mathrm{t}) \mathrm{l})=0.0100$
$\mathrm{Fb}(\mathrm{t})=0.0020$
$F c(t)=0.0008$


Note: $\mathrm{F}(\mathrm{t}) \sim \mathrm{Fa}+\mathrm{Fb}+\mathrm{Fc}$

Figure 4.1-5

## Table 4.1-6 Potential Electrical Failure Mechanisms for Advanced Technologies

| Mechanism | Failure Mode | Accelerating Conditions |
| :---: | :---: | :---: |
| Time Dependent <br> Dielectric <br> Breakdown | Gate shorts, interlayer shorts in interconnection system | Voltage, increased temperature |
| Electromigration | Interlayer or intralayer shorts in interconnection system, and open circuits | Current, increased temperature |
| Hot Carriers | Threshold shifts, $g_{m}$ shifts | Source/drain voltage, decreased temperature |
| Mobile Ions | Threshold shifts | Gate/source voltage, decreased temperature |
| Surface State Movement | Leakage | Radiation, current |
| Latent ESD Damage | Gate shorts, protection network shorts | Voltage, current |
| Corrosion | Opens in interconnections | Humidity, increased temperature |
| Unequal Metal Diffusion Rates | Contact resistance change | Current, increased temperature |

where:

$$
\begin{aligned}
& t_{50 \%}=\text { median of the reference distribution } \\
& \sigma=\text { standard deviation of the reference distribution } \\
& A_{A}=\text { acceleration factor due to area } \\
& A_{T}=\text { acceleration factor due to temperature } \\
& A_{E F}=\text { acceleration factor due to an electric field. }
\end{aligned}
$$

## Area Acceleration Factor

Dielectrics are inherently defective because of their amorphous structure. Defects will always exist no matter how small an area is being stressed. It is assumed that dielectric defects are randomly distributed along two dimensions and are indistinguishable. Bose-Einstein statistics allow the determination of the defect density, ${ }^{[38]} D(t)$, knowing the area of the structure in question, $A$, and the probability of failure function, $F(t)$. For this uniform defect density,

$$
\begin{equation*}
D(t)=(1 / A)(F(t) /(1-F(t))) . \tag{4.1.10}
\end{equation*}
$$

From this expression, the probability of failure function can be obtained for structures of different areas, assuming the defect density and the failure mechanism are the same. That is,

$$
\begin{equation*}
\left(1 / A_{0}\right)\left(F_{0}(t) /\left(1-F_{0}(t)\right)\right)=D(t)=\left(1 / A_{S}\right)\left(F_{S}(t) /\left(1-F_{S}(t)\right)\right), \tag{4.1.11}
\end{equation*}
$$

$$
\text { where } \begin{aligned}
A_{0} & =\text { area of the reference structure } \\
A_{S} & =\text { area of the new structure }
\end{aligned}
$$

Rearranging terms gives

$$
\begin{equation*}
F_{0}(t)=\left[1+\left(A_{S} / A_{0}\right)\left(\left(1 / F_{S}(t)\right)-1\right)\right]^{-1} . \tag{4.1.12}
\end{equation*}
$$

This equation describes the relationship between the probability of failure for the new structure, $F_{S}(t)$, and the probability of failure for the reference structure, $F_{0}(t)$, at any time $t$.

The area acceleration factor, $A_{A}$, is defined by

$$
\begin{equation*}
A_{A}=\mu_{S} / \mu_{0}=\ln \left(t_{S} 50 \%\right) / \ln \left(t_{0} 50 \%\right) \tag{4.1.13}
\end{equation*}
$$

$$
\begin{aligned}
\text { where } t_{S} 50 \% & =\text { median of the distribution of the new structure } \\
t_{0} 50 \% & =\text { median of the distribution of the reference structure. }
\end{aligned}
$$

Although $\mu_{0}$ is known, $\mu_{S}$ must be determined to calculate the value of $A_{A}$ for the new structure. One method for determining the value of $\mu_{S}$ is to realize that $F_{S}\left(t=t_{S} 50 \%\right)=0.5$, by definition. Substituting this value into equation 4.1.12 gives

$$
\begin{equation*}
F_{0}\left(t_{S} 50 \%\right)=A_{0} /\left(A_{0}+A_{S}\right) . \tag{4.1.14}
\end{equation*}
$$

$F_{0}\left(t_{S} 50 \%\right)$ is the probability of failure of the reference structure at the time in which $50 \%$ of the new structures would fail. Since the $F_{0}(t)$ function is known, and the associated number of sigmas away from the reference median, $z$, can be approximated by the area under the normal (gaussian) density function provided by tables in most comprehensive statistics texts or by the software program in Appendix $C$, it is possible to determine $\mu_{S}$ directly by

$$
\begin{equation*}
\mu_{S}=\mu_{0}+(Z * \sigma) . \tag{4.1.15}
\end{equation*}
$$

The variance, $\sigma^{2}$, for a uniform defect density is 1 , and equation 4.1 .15 can be rewritten

$$
\begin{equation*}
\mu_{S}=\mu_{0}+z \tag{4.1.16}
\end{equation*}
$$

Substituting equation 4.4.16 into equation 4.1.13 gives

$$
\begin{equation*}
A_{A}=1+\left(2 / \mu_{0}\right) \tag{4.1.17}
\end{equation*}
$$

where $\mu_{0}=\ln \left(t_{0} 50 \%\right)$.
For convenience, Table 4.1-7 provides $Z$ values for some values of $F_{0}(t)$.

| Table 4.l-7 | Common Z-Values |
| :---: | :---: |
| $F_{0}(t)$ | Z-Value |
| $-\cdots-\cdots---1$ |  |
| 0.0013 | 3.00 |
| 0.0228 | 2.00 |
| 0.1587 | 1.00 |
| 0.5000 | 0.00 |
| 0.8413 | -1.00 |
| 0.9772 | -2.00 |
| 0.9987 | -3.00 |

## Temperature Acceleration Factor

The acceleration factor due to temperature, $A_{T}$, is given by the well-known Arrhenius relationship: ${ }^{[16]}$

$$
\begin{equation*}
A_{T}=\exp \left[\frac{E_{\alpha}}{k}\left(\frac{1}{T_{0}}-\frac{1}{T_{S}}\right)\right], \tag{4.1.18}
\end{equation*}
$$

where:

$$
\begin{aligned}
& \mathrm{E}_{\mathrm{a}}=\text { experimentally determined activation energy ( } 0.3 \mathrm{eV} \text { ) } \\
& \mathrm{K}=\text { Boltzmann's constant }=8.617 \mathrm{E}-5 \mathrm{eV} /{ }^{\circ} \mathrm{K} \\
& T_{\mathrm{S}}=\text { operating stress temperature, user supplied ( }{ }^{\circ} \mathrm{K} \text { ) } \\
& \mathrm{T}_{\mathrm{O}}=\text { reference temperature }\left(295^{\circ} \mathrm{K}\right)
\end{aligned}
$$

## Electric Field Acceleration Factor

The acceleration factor due to the applied electric field, $A_{E F}$, is given by ${ }^{[16]}$

$$
\begin{equation*}
A_{E F}=\exp \left[B *\left(E_{S}-E_{O}\right)\right] \tag{4.1.19}
\end{equation*}
$$

where:

```
ES = operating electric field stress (user supplied Mv/cm)
E
B = experimentally determined electric field constant (4.5 cm/Mv)
```


## Reference Distribution

A literature review identified reasonably consistent values for the acceleration coefficients, $E_{a}$ and $B$ while accelerated life data on Westinghouse test structures was used to develop the reference distribution statistics, $\mu_{0}$ and $\sigma$.

Table 4.l-8 lists the pertinent parameters and references from which the values of $E_{a}$ and $B$ were derived. The value of $E_{a}=0.3 \mathrm{eV}$ was consistent for dielectric thickness between $100 \AA$ and $1100 \AA$. The value of $B$ varied considerably between authors. Crook[16] identified a B of 16.1 for known defective oxides of 400 。 $A$ to $1100 \AA$. Abadeer $[17]$ identified a $B$ of 6.4 for oxides of 150 A to 450 A . Baglee ${ }^{[12]}$ identified a $B$ of approximately 4.5 for 100 A oxides. Hokari[13] identified a B of 4.0 for 600 A to 1000 A . The value of $B$ is apparently dependent on the type of dielectric defect; however, since the end-life failure distribution is defined as wear out of the dielectric, not random defects, the value of $B=4.5$ was most consistent for dielectric thickness between $100 \AA$ and $1000 \AA$.

The test structure used in the accelerated life test had total gate area, field oxide periphery and polycrystalline silicon gate periphery comparable to a $4 k$ SRAM. The gate area, specifically, was $1.782 E 5 \mathrm{um}^{2}\left(5.25 \mathrm{log} \mathrm{um}^{2}\right)$. The thermally grown oxide thickness was 225 angstroms. The life test was a ramped voltage-breakdown test where the voltage on the gate was ramped at $5 \mathrm{~V} / \mathrm{sec}$ ond, starting at 0 volts with the silicon substrate at 0 volts. The breakdown voltage was the voltage at which >1 UA of current was measured between the gate and substrate. Subsequent isolation tests of the structures verified catastrophic breakdown had occurred. All testing was performed at $22^{\circ} \mathrm{C}$ on a Keithley 350 tester.

Because of the linear relationship between breakdown voltage and the normal distribution of cumulative percent failure, a linear least squares fit to the data was performed to obtain the median breakdown voltage, $V_{b} 50 \%$, and the standard deviation, $\sigma_{b}$. Table 4.1-9 shows the results of the life tests of seven wafers of 15 test structures each.

Table 4.1-8 Observed Dielectric Breakdown Parameter Values

| dielec type | dielec thick (A) | dielec area (cm2) | cap | dielec <br> temp <br> (C) | stress temp | brkdun cond (Mv/cm) | stress cond. ( $\mathrm{Mv} / \mathrm{cm}$ ) | defect type | defect density | $\begin{gathered} \mathrm{E}_{\mathrm{ev}} \\ \hline \end{gathered}$ | ${ }_{(\mathrm{cm} / \mathrm{Hv})}^{\mathrm{B}}$ | (hurs) | sig | ref |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| thermal SiO2 | 32 | 0.1 | $\begin{aligned} & 4000 \mathrm{~A} \\ & \text { poly } \mathrm{si} \end{aligned}$ | 1000 | 25 | <1 | constant <br> field <br> time vary | si surface | >65\% |  |  |  |  | 1 |
|  |  |  |  |  |  | 1 to 8 |  | si $u$ defect | 0\% |  |  |  |  |  |
|  | 110 | 0.1 |  | 1000 | 25 | ¢1 |  |  | <15\% |  |  |  |  |  |
|  |  |  |  |  |  | 1 7808 |  |  | $\stackrel{0 x}{<58}$ |  |  |  |  |  |
|  | 348 | 0.1 |  | 1000 |  |  |  |  | - $5 \times$ |  |  |  |  |  |
|  |  |  |  |  |  | ${ }_{>8}^{1}$ to 8 |  |  | - |  |  |  |  |  |
|  | 621 | 0.1 |  | 1000 |  |  |  |  |  |  |  |  |  |  |
|  |  |  |  |  |  | ${ }_{>8}^{1}$ to 8 |  |  | $\begin{aligned} & <25 x \\ & <50 x \\ & < \end{aligned}$ |  |  |  |  |  |
| oxide1 oxide2 | $\begin{aligned} & 198 \\ & 198 \end{aligned}$ |  | poly si |  |  |  | 7.5 |  |  |  |  | 3.04 | 1.54 |  |
| thermal SiO2 | 100 | 0.0097 | $\begin{aligned} & 5000 \mathrm{~A} \\ & \text { LPCVO } \\ & \text { poly } \end{aligned}$ | 900 | 25 | 10-11v | stress votage short duration | electric breakdown | 45x |  |  |  |  | 12 |
|  | 100 100 | 0.0097 0.0097 |  | 900 900 | 25 25 | 11-12v |  |  | 55\% | 0.3 |  | 2.02 |  |  |
|  | 100 | 0.0097 |  | 900 | 85 |  | 8 |  |  | 0.3 |  | 1.11 |  |  |
|  | 100 | 0.0097 |  | 900 | 155 |  | 8 |  |  | 0.3 |  |  |  |  |
|  | 100 | 0.0097 |  | 900 | 150 |  | 5 |  |  |  | 4.25-4.61 |  |  |  |
|  | 100 | 0.0097 |  | 900 | 150 |  | 7 |  |  |  | 4. $25-4.61$ |  | 2.37 |  |
|  | 100 100 | 0.0097 0.0097 |  | 900 900 | 150 150 |  | 8 |  |  |  | 4.25-4.61 |  |  |  |
|  |  |  |  |  |  |  |  |  |  | 1 | 4.01 |  |  | 13 |

Table 4.1-8 Observed Dielectric Breakdown Parameter Values CONTD


Table 4.1-8 Observed Dielectric Breakdown Parameter Values CONTD

|  | \% |  |  |
| :---: | :---: | :---: | :---: |
|  |  |  |  |
| 碞 | 3ibl | \% |  |


| Lot Wafer | $V_{b 50 \%}(V)$ | $o_{b}(V)$ | $r^{2}$ |
| :---: | :---: | :---: | :---: |
| 6424-11 | 20.73 | 0.15 | 0.84 |
| 6424-12 | 20.36 | 0.17 | 0.96 |
| 6424-17 | 20.76 | 0.11 | 0.91 |
| 6424-19 | 20.74 | 0.08 | 0.83 |
| 6424-24 | 20.42 | 0.25 | 0.90 |
| 6431-10 | 20.39 | 0.26 | 0.80 |
| 6431-13 | 20.21 | 0.35 | 0.85 |
|  |  | - | ---- |
| Average | 20.52 | 0.20 |  |
| Error | 0.21 | 0.09 |  |

Worst case estimates of $V_{b} 50 \%$ and $\sigma_{b}$ were obtained using

$$
\begin{align*}
& V_{b} 50 \%=\operatorname{average}\left(V_{b} 50 \%\right)-3 * \operatorname{error}\left(V_{b} 50 \%\right)  \tag{4.1.20}\\
& \sigma_{b}=\operatorname{average}\left(\sigma_{b}\right)+3 * \operatorname{error}\left(\sigma_{b}\right) \tag{4.1.21}
\end{align*}
$$

The conservative estimates of $V_{b}$ and $\sigma_{b}$ were calculated to be 19.90 volts and 0.47 volts, respectively.

The relationship between breakdown voltage under ramped voltage stress and time at a constant voltage stress is given by ${ }^{[17]}$

$$
\begin{equation*}
t=\left(t_{O X} / B R\right) \exp \left[B\left(E_{R}-E_{0}\right)\right] \tag{4.1.22}
\end{equation*}
$$

where:

```
t = the time required to attain a probability of failure
        under a constant electric field stress, E E, that is the
        same as the probability of failure obtained by ramping
        when electric field reaches a value, E E .
t
R = ramp rate
E
E
B = experimentally determined constant.
```

Using this relationship, the values of $\mu_{0}$ and $\sigma$ were determined to be 8.4 and $0.4 \log$ hours, respectively, for a constant operating voltage of 5 volts.

With the TDDB reference distribution statistics identified, the user must determine the acceleration factors for total transistor gate area, dielectric temperature, and electric field stress to obtain the TDDB distribution statistics for the microcircuit in question. Figures 4.1-6 through 4.1-8 are plots of equations 4.1.17-4.1.19 and may be used instead of equations 4.1.17-4.1.19 to determine the area acceleration factor, $A_{A}$, the temperature acceleration factor, $A_{T}$, and the electric field acceleration factor, $A_{E F}$, respectively. From the TDDB distribution statistics for the microcircuit, the user can calculate probability of success, hazard rate, and effective hazard rate at any time $t$ for TDDB. Alternatively, the user can use the tables in Appendix $D$ to determine the probability of success at 10,000 hours and the hazard rate at 10,000 hours given total transistor gate dielectric area, junction temperature and electric field stress.

Note: Tables 4.1-10 and 4.1-11 provide one example of each of the TDDB probability of success and effective hazard rate distributions, respectively. The comprehensive associated tables for TDDB effective hazard rate may be found in Appendix A.
Electric Field Stress (MV/cm)














| 8 |
| :---: |
| 8 |
| 8 |
|  |

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Figure 4.1-6 Area Acceleration Factor for TDDB


Figure 4.1-7 Temperature Acceleration Factor for TDDB


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Figure 4．1－8 Electric Field Acceleration Factor for TODB

（10700）501）10700」 U0！70101000サ Plo！」

### 4.1.3.2 Electromigration Model

According to the literature on electromigration (EM), ${ }^{[23]}$ failure occurrences are distributed normally with the logarithm of time, similar to TDDB. The general form of the failure density function is

$$
\begin{equation*}
f(t)=\frac{1}{\sigma t \sqrt{2 \pi}} \exp \left[(-1 / 2)\left(\frac{\ln t-\left(\ln \left(t_{50 \%} /\left(A_{T} * A_{J}\right)\right)\right)}{\sigma}\right)^{2}\right], \tag{4.1.23}
\end{equation*}
$$

where:

$$
\begin{aligned}
& t_{50 \%}=\text { median of the reference distribution } \\
& \sigma=\text { standard deviation of the reference distribution } \\
& A_{T}=\text { acceleration factor due to temperature } \\
& A_{J}=\text { acceleration factor due to current density. }
\end{aligned}
$$

## Temperature Acceleration Factor

The acceleration factor due to temperature, $A_{T}$, is given by the well-known Arrhenius relationship: ${ }^{[16]}$

$$
\begin{equation*}
A_{T}=\exp \left[\frac{E_{\mathrm{a}}}{\bar{k}}\left(\frac{1}{T_{0}}-\frac{1}{T_{S}}\right)\right], \tag{4.1.24}
\end{equation*}
$$

where:

$$
\begin{aligned}
& E_{\mathrm{a}}=\text { experimentally determined activation energy (.5 eV) } \\
& \mathrm{K}=\text { Boltzmann's constant }=8.617 \mathrm{E}-5 \mathrm{eV} / \mathrm{K} \\
& \left.\mathrm{~T}_{\mathrm{S}}=\text { operating stress temperature (user supplied } \mathrm{K}\right) \\
& T_{0}=\text { reference temperature }(488 \mathrm{~K})
\end{aligned}
$$

## Current Density Acceleration Factor

The acceleration factor due to current density, $A_{J}$, is given by [18]

$$
\begin{equation*}
A_{J}=\left(J_{S}, J_{0}\right)^{n} \tag{4.1.25}
\end{equation*}
$$

where:
$J_{S}=$ effective operating current density (user supplied $M A / \mathrm{cm}^{2}$ )
$J_{0}=$ reference current density ( $1 \mathrm{MA} / \mathrm{cm}^{2}$ )
$\mathrm{n}=$ experimentally determined exponent (2)

## Reference Distribution

A literature review identified consistent values for the acceleration coefficients, $E_{a}$ and $n$, and the reference distribution statistics, $\mu_{0}$ and $\sigma$. Table 4.1-12 lists the pertinent parameters and references from which the values of $E_{a}$ and $n$ were derived. The most thorough work in understanding electromigration was done by Schafft ${ }^{[22]}$ and associates. From this work, consistent values of $E_{a}$ and $n$ were determined to be 0.5 eV and 2 , respectively. These values were determined for $\mathrm{Al}-1 \%$ Si metallization. This metallization system is expected to be the worst-case system for interconnect on VLSI/ULSI microcircuits, since pure Al is never used because of process considerations such as over-sintering of shallow junctions. Other metal systems, such as Ti-AL-TiW, do not readily electromigrate because of the heavier metal ions. (There is, however, concern that resistance changes may occur to cause performance problems which are difficult to quantify.)

In addition to the values of the acceleration coefficients, Schafft also developed the reference distribution statistics, $t_{0} 50 \%$ and $\sigma$. The values of these statistics were determined to be 32.12 and 0.33 hours with associated errors of 2.38 and 0.04 hours, respectively, for an operating temperature of $175^{\circ} \mathrm{C}$, a current density of $1 \mathrm{MA} / \mathrm{cm}^{2}$, for all interconnect lengths greater than $800 \mu \mathrm{~m}$. Worst-case estimates of $t_{0} 50 \%$ and $\sigma$ were obtained using

$$
\begin{equation*}
t_{050 \%}(\text { worst case })=t_{050 \%}-3 * \operatorname{error}\left(t_{0} 50 \%\right) \tag{4.1.26}
\end{equation*}
$$

```
\sigma (worst case) = \sigma + 3* error (\sigma).
```

Table 4.1-12
Observed Electromigration Parameter Values



The conservative estimates of $t_{0} 50 \%$ and $\sigma$ were calculated to be 24.98 hours and 0.45 hours, respectively.

Since metals do not have an intrinsic defect density, the variance in lifetime is most probably due to process variations. It is noted that the variance for $E M$ is much smaller than the variance for TDDB.

With the EM reference distribution statistics identified, the user must determine the acceleration factors for metal film temperature and current density to obtain the EM distribution statistics for the microcircuit in question. Figures 4.1-9 and 4.1-10 may be used to determine the temperature acceleration factor, $A_{T}$, and the current density acceleration, $A_{J}$, respectively. From the EM distribution statistics for the microcircuit, the user can calculate the probability of success, hazard rate, and effective hazard rate at any time $t$ for EM. Alternatively, the user can use tables 4.1-13 and 4.1-14 to determine the probability of success and effective hazard rate at 10,000 hours given junction temperature and effective current density.

Figure 4.1-9 Temperature Acceleration Factor for EM



Figure 4.1-10 Current Density Acceleration Factor for EM





### 4.1.3.3 Charge Injection/Hot Carrier Model

A literature review of articles written on charge injection/hot carrier failure modes resulted in three conclusions. First, charge injection is only a concern for MOS transistor channel lengths less than 1.5 um. Second, many authors make the distinction that charge injection is a design consideration rather than a reliability consideration. Third, the inconsistency in reported failures due to charge injection, either reported as microcircuit failures or laboratory test structure failures, reflects the inconsistency of microcircuit failures due to ionic contamination 15 years ago. At present, charge injection is not considered a wearout mechanism, but a quality/design factor.

### 4.1.3.4 Other Mechanism Models

The other mechanisms outlined in Table 4.l-3, including mobile ions, surface state shift, leakage, and latent ESD are considered assignable cause mechanisms. These mechanisms contribute to the early and middle life failure rate, outlined in section 4.1.2.

### 4.1.4 End-Life Prediction Models

With the contributing end-life failure mechanism models identified, these models must be addressed in terms familiar to the user. Figure 4.1-11 is a breakdown of the end-life failure mechanism models and the parameters which must be supplied to complete the model. The parameters highlighted by bold outlined boxes must be supplied by the user. The parameters shown in the remaining boxes have default values available if the user does not have sufficient knowledge about the microcircuit to supply actual values. Table 4.1-15 identifies the failure mechanisms that apply to the microcircuits in question. Only time-dependent dielectric breakdown (TDDB) and electromigration (EM) are considered end-life limiting failure mechanisms; therefore, the effective hazard rate for end-life predictions has the form

$$
\text { where: } \begin{align*}
\lambda_{\text {end }}\left(t_{O}\right) & =\lambda_{T O D B}\left(t_{O}\right)+\lambda_{E M}\left(t_{0}\right)  \tag{4.1.28}\\
\lambda_{T D D B}\left(t_{O}\right) & =\text { effective hazard rate for TDDB at time } t_{0} \\
\lambda_{E M}\left(t_{0}\right) & =\text { effective hazard rate for EM at time } t_{0} .
\end{align*}
$$

Figure 4.1-11



1) Time Dependent Dielectric Breakdown C
2) Electromigration
3) Charge Injection
4) Mobile Ions A
5) Surface State Shifts
6) Latent ESD
7) Contact Resistance
Change
8) Other Random Defects

A
A

C C C
$C$ C

D

A
D D

A A A
A A A
A A A

C

A
A
A

A
A
A
A A A

Key: C indicates common cause failure mechanism D indicates design consideration A indicates assignable cause mechanism

For those microcircuits whose lifetimes are limited by TDDB, the user will use representative sample Tables 4.1-10 and 4.1-11 (more comprehensive tables are available in Appendix D). To identify which tables are appropriate, the user must know the total transistor gate oxide area on the microcircuit. If the user does not know total gate area, Table 4.1-16 provides default area values dependent upon the number of transistors in the microcircuit. Alternatively, the dependence of total gate area on transistor count is shown graphically in figures 4.1-12 and 4.1-13 for MOS microprocessor devices and MOS digital and linear devices, respectively. The data in these figures is bounded by an upper (worst-case) limit defined by

$$
\begin{equation*}
A=\log \left(4 * T R * 10^{-0.744 *}(\log (T R)-5.50)\right)\left(\log \mu m^{2}\right) \tag{4.1.29}
\end{equation*}
$$

for MOS microprocessor devices, and

$$
\begin{equation*}
A=\log \left(6 * T R * 10^{-0.580 *}(\log (T R)-5.78)\right),\left(\log \mu m^{2}\right) \tag{4.1.30}
\end{equation*}
$$

Figure 4.1-12


Figure 4.1-13

for MOS digital and linear devices,
where $T R=$ number of transistors on the device in question.

Next the user must determine the electric field stress given the operating voltage. The electric field stress, $E_{S}$, is given by

$$
\begin{equation*}
E_{S}=.1\left(V_{O p} / t_{O X}\right)(M v / c m), \tag{4.1.31}
\end{equation*}
$$

where:

$$
\begin{aligned}
& V_{o p}=\text { operating voltage (user supplied } V \text { ) } \\
& \left.t_{o x}=\text { oxide thickness (user supplied } K^{*}\right)
\end{aligned}
$$

Again, if the user does not know oxide thickness, by knowing the number of transistors in the microcircuit, the user can obtain a default value for oxide thickness from Table 4.l-17. Alternatively, the dependence of oxide thickness on transistor count is shown graphically in figures 4.1-14 and 4.1-15 for MOS microprocessor devices and MOS digital and linear devices, respectively. The data in these figures is bounded by a lower (worst-case) limit defined by

$$
\begin{equation*}
T_{0 x}=10-0.406 *(\log (T R)-3.68)(K A) \tag{4.1.32}
\end{equation*}
$$

for microprocessor devices, and

$$
\begin{equation*}
T_{0 x}=10^{-0.296 *(\log (T R)-3.14),(K A), ~} \tag{4.1.33}
\end{equation*}
$$

for MOS digital and linear devices,
where $T R=$ number of transistors on the device in question.

After identifying the electric field stress, the user must determine the appropriate dielectric temperature stress. A calculated junction temperature, $T_{J}$, results in the worst-case approximation of the dielectric

Figure 4.1-14

(\# 60I) esoqa!eu0」1 to sequnn

Figure 4.1-15

temperature. The value of the junction temperature may be supplied by the manufacturer or may be developed in a standard fashion, where

$$
\begin{equation*}
T_{J}=T_{\text {case }}+\theta_{J C} * P\left({ }^{\circ} \mathrm{C}\right), \tag{4.1.34}
\end{equation*}
$$

where:

```
T
0 隹 = junction to case thermal resistance (user supplied }\mp@subsup{}{}{\circ}\textrm{C}/W\mathrm{ )
P = worst-case power (user supplied W).
```

Once the total transistor gate oxide area, oxide thickness, and junction temperature have been identified, the user can determine the associated probability of success or hazard rate for the microcircuit due to TDDB.

For those microcircuits whose lifetimes are limited by electromigration, the user will use Tables 4.1-13 and 4.1-14. If the user does not know the maximum current density through the metal on the microcircuit, a default value of $0.125 \mathrm{MA} / \mathrm{cm}^{2}$ should be used. (See Appendix $B$ for the derivation of this default value.) The appropriate metal film temperature stress is determined in a similar fashion as the temperature stress for TDDB. Once the current density and junction temperature have been identified, the user can determine the associated probability of success or hazard rate for the microcircuit due to electromigration.

It is noted here that many microprocessors utilize on-chip static RAM. The contribution of the failure rate of this SRAM to the total microprocessor failure rate is insignificant. Since the technology used to fabricate the SRAM transistors is similar to the technology used to fabricate the processor transistors, the mechanisms which result in end-life failures are similar; therefore, the SRAM, which comprises only $1 \%$ to $5 \%$ of the total active circuitry of the microprocessor, has minimal impact when predicting the total failure rate of the microprocessor.

Table 4.1-16 Total Transistor Gate Area $\left(\log \mu m^{2}\right)$

| Complexity | Digital Microprocessors | Digital and Linear |
| :--- | :--- | :--- |
| (\# of trans.) | (including Controllers) | Gate / Logic Arrays |


| $100-500$ | 5.39 | 5.24 |
| ---: | ---: | ---: |
| $500-1 k$ | 5.47 | 5.37 |
| $1 k-5 k$ | 5.64 | 5.67 |
| $5 k-10 k$ | 5.72 | 5.80 |
| $10 k-50 k$ | 5.90 | 6.10 |
| $50 k-100 k$ | 5.97 | 6.23 |
| $100 k-500 k$ | 6.15 | 6.52 |
| $500 k-1 M$ | 6.23 | 6.65 |
| $1 M-5 M$ | 6.41 | 6.95 |
| $5 M-10 M$ | 6.48 | 7.08 |


|  | Table $4.1-17$ | Dielectric Thickness $(K A)$ |
| :--- | :--- | :--- |
| Complexity | Digital Microprocessors | Digital and Linear. |
| (\# of trans.) | (including Controllers) | Gate / Logic Arrays |

$100-500 \quad 4.81 \quad 2.17$
500 - $1 k \quad 2.50 \quad 1.35$
1 k - 5k $1.89 \quad 1.10$
$5 k-10 k \quad 0.98 \quad 0.68$
10k - 50k $0.74 \quad 0.56$
50k - 100k 0.39 0.35
100k - 500k $0.29 \quad 0.28$
500k - 1 M
0.15
0.17
$1 M-5 M$
0.11
0.14
$\begin{array}{lll}5 M-10 M & 0.06 & 0.09\end{array}$

### 4.2 MEMORY DEVICES

### 4.2.1 Database

Literature Survey - This was one of the first activities conducted for the modeling task, and, although most sources were identified early in this effort, it continued throughout the program. A total of 63 articles and papers from trade journals and symposiums were identified as being relevant to memory reliability modeling. They were reviewed and filed. Most of the literature was related to non-volatile memories (e.g., EPROMs and EEPROMs), which is appropriate since these device types were recognized from the start of the modeling task as ones that required the most study. Others were specific to device types such as SRAMs and DRAMs, or were directed towards various technology areas (for example, CMOS and BiMOS). Relatively little literature on older, less complex technologies and devices such as MOS ROMs, bipolar ROMs/PROMs/PLAs/PALs was found during the search. Direct and indirect contributions by this literature to the memory model development will be noted, as appropriate, throughout this section of the report.

The primary use of the literature was to aid in determining the true failure modes and mechanisms of the device types investigated and the relative contribution of these modes and mechanisms to the overall failure rates of these devices. The literature was used to a limited degree in the evaluation of the sensitivity of device failure rates to parameters such as temperature and complexity.

Industry Contacts - A key source of information for the modeling task was the semiconductor industry. At the start of the program, questionnaires were sent to a large number of companies requesting whatever support that could be provided. For memory devices, ll companies expressed initial interest in the project, with 9 of them ultimately providing various degrees of information. These companies were exclusively semiconductor device manufacturers. The industry information was used in conjunction with the literature data to identify the applicable failure modes and mechanisms for memory devices. This information included life test data and device parameter information, and was
also helpful during development of the actual models.

The following is a list of the industry contacts that provided data and answered questions regarding memory devices:

| Raytheon | National Semiconductor |
| :--- | :--- |
| Intel | Advanced Micro Devices |
| Seeq | Signetics |
| Xicor | Atmel |
| Inmos |  |

Most of the data collected from the various manufacturers was in the form of already published data books, reliability reports and pamphlets. The life test data that was gained from the manufacturers was collected and put on a computer database for reference throughout the project. See Appendix $E$ for the life test results. It should be noted that a significant amount of requested information could not be provided by the manufacturers because of manpower and/or data confidentiality constraints. As with the literature search, the largest portion of the information gained from the manufacturers related to non-volatile memories.

### 4.2.2 Model

### 4.2.2.1 Approach/Mechanism Identification

In the development of the memory model, the various sources of information described earlier in this section (literature, manufacturer data, in-house experience) were used to identify the applicable failure mechanisms involved with the various device types. These mechanisms were then evaluated individually to determine whether they are defect-related or intrinsic to the device. This information provided guidance in the overall approach to the development of the actual model in addition to the form that the model ought to take. Table 4.2-1 presents the results of the failure mechanism investigation task that is documented in this section.

$$
\begin{aligned}
& \text { Electron Trapping In Oxide } \\
& \text { Time Dep. Dielectric Breakdown } \\
& \text { Oxide Defect - Contamination } \\
& \text { 0xide Defect - Pinholes, faults } \\
& \text { Silicon Defect } \\
& \text { Metallization Defect } \\
& \text { Electromigration } \\
& \text { Intrinsic Charge Loss } \\
& \text { Hot Carrier Injection } \\
& \text { Soft Errors }
\end{aligned}
$$

$$
\begin{aligned}
& \text { I - Intrinsic tailure mechanism } \\
& \star \text { - Not a signiticant contributor } \\
& \times * \text { - See discussion for BimOS }
\end{aligned}
$$

Table 4.2-1 Memory Failure Mechanisms

$$
\begin{aligned}
& \text { D - Defect induced failure mechanism } \\
& \text { NA - Not Applicable } \\
& \text { FG MOS - Fluating Gate Metal 0xide Semiconductor }
\end{aligned}
$$

## UVEPROMS, Flash EEPROMs

Flash EEPROMs are treated similarly to EPROMs in this analysis. Flash EEPROMs use the same CHE (Channel Hot Electron) programming mechanism as do UVEPROMs, and use the same one transistor/cell approach. The primary difference between the two is that Flash cells incorporate a thin floating gate-source or - drain gap to allow for a Fowler-Nordheim tunneling erase mechanism (UVEPROMs use a UV light photocurrent erase mechanism). [45,67]

The life test data reviewed for UVEPROMs showed the primary failure mode to be storage gate charge loss, with a secondary mode of charge gain. These modes result in the lowering or raising of the cell threshold voltage, thus narrowing the cell read margin. The literature search also supported the selection of these modes as the most prevalent. ${ }^{[47,48,49,71]}$ Either of the two modes can be caused by ionic contaminants or defects in the gate oxide. A defect in the oxide or an induced breakdown of the oxide can cause a pathway for stored charge to leak off, or it can attract unwanted electrons under read bias. Charge gain or loss are the primary causes of retention failures (a cell changing state on its own over time) in these devices. The only other failure modes found in the UVEPROM life test data collected were parametric test failures, with no hint as to the mechanism(s) involved. The small amount of Flash EEPROM life test data found also indicated charge loss as the primary failure mode. ${ }^{[45]}$ Charge gain can be caused by the trapup of electrons in the gate oxide as a consequence of movement of electrons through the gate oxide during programming and erasure. This must be considered for devices (standard EEPROMS) that experience a high number of erase/reprogram cycles. However, UVEPROMs and Flash EEPROMS are expected to experience a much lower number of cycles during their lifetime; therefore the failure rate contribution by charge trapup is considered to be negligible.

The phenomenon of intrinsic charge loss in UVEPROMS/Flash EEPROMs has been identified in literature, ${ }^{[45,47]}$ and may be due to the detrapping of electrons trapped during erase; ${ }^{[47]}$ however, evidence strongly suggests that the amount of degradation is limited in nature (the total charge lost by a storage transistor in this manner is not enough to cause a failure in an
otherwise good cell) and is a negligible contributor to UVE/Flash failure rates.

The failure modes of spurious programming and erasure have been identified in literature ${ }^{[45,49]}$ for both UVEPROMS and Flash EEPROMS. Spurious programming is a defect-induced failure mode resulting in unwanted cells being programmed. Spurious erasure is also defect-induced and results in unwanted cells being erased during the program cycle.

As mentioned, charge loss may be caused by a breakdown in the oxide. A high electric field is present across the gate dielectric during the programming step for both UVEPROMs and Flash EEPROMs. Time Dependent Dielectric Breakdown (TDDB) is greatly accelerated by increased voltage and has been identified by a number of sources as being a contributing failure mechanism for all MOS devices, particularly as geometries get smaller and smaller. This mechanism was therefore identified for further analysis during the development of the model. Electromigration, the other intrinsic failure mechanism, was also selected for further study. Both of these mechanisms influence the reliability of the peripheral circuitry, as do the defect-related mechanisms found in other IC types.

Because of the information found in the various literature sources, the reliability of Flash EEPROMs and UVEPROMs was considered to be equal during the initial stages of the model development task, at least when the total number of reprogram cycles during the life of the part is 100 cycles or fewer.

Refer to the SRAM paragraphs in this section for a more general discussion regarding HCI (Hot Carrier Injection). None of the literature researched named this as a significant failure mode for Flash and UVEPROMS. This can be compared to the charge trapup mechanism as (at least for the array storage transistors) these devices use hot injection as a programming mechanism. For this modeling effort, HCI was considered to be an insignificant contributor, provided that a limit is placed on the number of reprogram cycles (about 100 cycles).

Soft errors like HCI have become more of an issue with memories as geometries have been reduced. See the DRAM paragraphs in this section for a further discussion on this mechanism. None of the literature reviewed considered this to be a relevant failure mechanism for nonvolatile memories. An alpha particle striking the floating gate loses little of its energy there and creates fewer carriers, and few of these escape over the floating gate's high energy barrier.

MOS PLAs, PALs, and PROMs using UVEPROM style cells in place of fuses were considered equivalent to UVEPROMS with respect to reliability during the development of the model, the primary difference being that these devices are one - time programmable.

## EEPROMS

This class of device consists of all EEPROMs except for "Flash" (discussed earlier), and MNOS (Metal Nitride Oxide Semiconductor), which will be discussed later. It can further be broken down into two types: FLOTOX (Floating gate Tunnel Oxide), and Textured Polysilicon (Tex-Poly). Both types store charge on a floating gate that is isolated by oxide and use fowler-Nordheim (F-N) tunneling for both programming and erasure. FLOTOX devices use a thin turine 1 oxide (generally less than $100 \AA$ ) to achieve the F-N tunneling. Textured-Poly devices use a thicker tunnel oxide (greater than 150 A ) and achieve tunneling through enhanced localized E-fields created by a textured ("bumpy") Si-SiO2 interface. The cell structures for these two EEPROM types also differ: FLOTOX generally uses two transistors per cell (one for storage and one for a support transistor), whereas Tex-poly cells use a single, more complex storage transistor. ${ }^{[44,67,68]}$ Both of these EEPROMS may experience thousands of reprogram cycles during their lifetime. The literature search indicated a strong relationship between reprogram cycling and device failure rate. Two primary failure mechanisms are associated with this cycling: oxide breakdown and charge trapping in the tunnel oxide (trapup). Both of these mechanisms can result in memory retention failures or stuck bit failures in the memory array, depending upon the degree of degradation. The literature also indicated that the two EEPROM types have very different sensitivities to
reprogram cycling and the associated failure mechanisms. $[44,68,72]$ For this reason, part of the EEPROM modeling approach was to treat these two EEPROM types separately and incorporate a cycling relationship into the model. Other failure mechanisms such as oxide breakdown can occur with little or no cycling and can be caused by things such as oxide pinholes or contaminants, just as with other IC types. This was supported by a small amount of life test data (it does not include any reprogram cycling) that was collected. The failures that occurred during this testing (for which the cause could be determined) were caused by either contaminants or oxide breakdown. Time dependent dielectric breakdown was incorporated into the modeling approach for EEPROMs, as was electromigration. These two mechanisms are intrinsic to EEPROMs by the nature of their construction and may be significant under certain circumstances (for instance, very small geometry devices). Intrinsic charge loss was not mentioned by any of the literature researched, nor did it appear in any life test data. It is therefore being treated as it is for UVEPROMs and is not considered to be a significant contributor to the failure rate of the device.

## MNOS Metal Nitride Oxide Semiconductor EEPROMS

This device type gained early popularity at the start of EEPROM device development but has in recent years been used much less frequently by industry as compared to FLOTOX and Textured-Poly. MNOS devices store charge at a nitride layer as opposed to storage on a floating gate. This permits a simpler cell structure than that of either FLOTOX or Textured-Poly. The tunnel oxide used for MNOS is thinner than that of FLOTOX, making the device more susceptible to any defects or contaminants in that oxide layer, and it also results in loss of data retention over a period of time. The literature also indicates that MNOS EEPROM retention characteristics are degraded by repeated reprogram cycles and are more susceptible to corruption of cell contents by read operations (read disturb) ${ }^{[74]}$ than to other EEPROMS. Because the tunnel oxide is very thin, charge trapup in the oxide should not be a contributing mechanism, and none of the literature researched considered trapup in the oxide to be a significant problem; however, cycling can introduce electron migration into the nitride layer after being trapped at the $\mathrm{Si}-\mathrm{SiO}_{2}$ interface, ${ }^{\text {[75] }}$ although this effect seems to be significant only at very high levels of
cycling (in excess of lxIOE6 cycles) and is influenced by device design and process parameters. The other failure mechanisms such as silicon defects, time-dependent dielectric breakdown, and electromigration were considered to be contributing failure mechanisms during the model development program just as they were for the other device types. No MNOS life test data was found during the model development program.

Bipolar ROMs, PROMs, PALs

This group includes PALs (Programmable Array Logic), PLAs (Programmable Logic Array), and HALs/MLAs which are hard-wired versions of the first two. Together with bipolar ROMs/PROMs, these devices are very similar in that they consist of an array of fuses (if programmable) supported by conventional bipolar logic. Very little literature data was found that directly addresses the reliability of these devices. The initial approach during the memory model development program was to separately treat two aspects of the programmable versions of these devices: the fuses that make up the array, and the peripheral logic. A substantial amount of life test data was found from manufacturer sources. There were zero failures (due to either a defectinduced or intrinsic failure mechanism) attributed to fuses. Conversations with representatives from device manufacturers also supported the assertion that fuses are not significant contributors to device failure rate. For this reason, a failure rate for fuses was not considered during the development of the model. This left the supporting peripheral circuitry in addition to the simple diode structures that reside in the array. No failures due to oxide defects were found in the life test data, which is appropriate since these are bipolar devices. The failure mechanisms of electromigration, silicon defects, and metal defects were judged to be the contributors to the overall device failure rate. This was supported by the life test data, and these mechanisms were considered during the development of the model.

## MOS ROMS

Members of this class of devices are MOS-based with a hard-wired array and
are the simplest of the memory devices modeled. As with PROMs/PLAs, virtually no literature regarding the reliability of this device type was available; however, the life test data collected indicated that the failure modes of silicon, oxide, and metal defects were contributors to the failure rate of the device. Electromigration and $T O D B$ were also chosen for evaluation during the development of the model as these are intrinsic to the structures found on MOS ROMS.

## Static RAMS

These devices are implemented using bipolar, MOS, and (more recently) BiMOS (which combines the two technologies on one chip). Memory contents are stored as memory-cell transistors that are constantly biased "on" or "off". They do not incorporate exotic charge storage structures as are found in UVEPROMs or EEPROMs, and in that respect they may be compared to more conventional logic devices. MOS versions of these devices can fail because of defects in the oxide (causing threshold shifts or leaky/shorted FETs), silicon or metal defects, or contaminants. ${ }^{[76,77]}$ This is supported by the life test data collected, which identified FET leakage, oxide and metal defects among the failure causes. Time Dependent Dielectric Breakdown was considered to be a possible contributor to the MOS SRAM failure rate because it is intrinsic to the technology. For both bipolar and MOS technologies, electromigration was selected for further analysis during the model development task, as it was for all memories.

The phenomenon of Hot Carrier Injection (HCI) has been identified in literature as a potential MOS SRAM failure cause. ${ }^{[50,76]}$ HCI occurs when available carriers gain energy as they move through the E-field associated with the FET channel. A sufficiently high field may cause some of these carriers to be injected into the gate dielectric, thus influencing the threshold voltage of the FET. This mechanism is accelerated by lower temperatures and higher voltages and becomes an issue as device geometries are scaled down without any scaling of the supply voltage used to operate the device. None of the literature contained data hinting at the percent contribution of HCI failures to the overall failure rate of the device, and the life test data collected
showed no HCI failures. Although this can be considered an intrinsic mechanism, it can be minimized or eliminated by special design or processing techniques. ${ }^{\text {[50] }}$ There is also evidence that HCI has a self-limiting effect, at least for NMOS structures, ${ }^{[60]}$ which makes it difficult to accurately model any failure rate contribution by the mechanism. This mechanism was not considered for modeling during the modeling task. Also refer to the VHSIC/logic section of this report.

Although no failure rate data was found either in the literature search or in the available life test data regarding BiMOS reliability, for the purposes of the modeling effort, this technology was considered to have some failure rate contribution by the failure mechanisms identified independently for both MOS and bipolar SRAMs.

## DRAMs

These devices store data as parasitic capacitance in a specialized one-transistor memory cell. This charge-storage structure has built-in leakage, and therefore requires frequent "refreshing" or voltage pulse application, which is done automatically on the device. The simplicity of the DRAM cell allows it to be much smaller than a SRAM cell, which requires 4 or 6 transistors to implement a cell. The available literature indicated that the various defect mechanisms identified for other devices are also valid for DRAMs. ${ }^{[78,79] ~ T i m e ~ D e p e n d e n t ~ D i e l e c t r i c ~ B r e a k d o w n ~ w a s ~ a l s o ~ c o n s i d e r e d ~ t o ~ b e ~}$ a potential contributor; this is also supported by the literature.

Hot Carrier Injection is an issue with DRAMs, as it is for SRAMs. DRAMs are more susceptible than SRAMs because some internal circuitry can temporarily raise the voltage on part of the chip to relatively high levels. [58] literature indicated that hot carrier stress can potentially affect parameters such as retention time, subthreshold leakage currents, and substrate current, which may cause device failure depending upon the application and degree of degradation. ${ }^{[57,58]}$ Life test data that was collected was very limited for DRAMs but did not identify HCI as a failure cause. As with SRAMs, HCI effects can be minimized or eliminated by careful design and process techniques. Also
refer to logic/VHSIC section of this report. During the model development task, HCI was not modeled as a contributing mechanism because of its dependence on design, process, and application parameters.

Soft Errors (non-permanent failures) are also an issue with DRAMs. They are caused by electrical transients or particle radiation that upset charge levels within the device, typically affecting one bit. $\left.{ }^{80}, 81,82\right]$ This mechanism is more of a problem for DRAMS than SRAMs because of the simplicity of the memory cell and the need to constantly refresh the parasitic capacitance in each cell. It has become progressively more of a problem as DRAM geometries have been decreased to permit 2 Mbit and larger device capacities, which in turn results in decreased normal operating charges within the device. The difficulty of modeling the soft-error failure rate is due to the number and nature of influencing parameters and the lack of any empirical data. Soft errors may be caused by solar or cosmic radiation particle strikes, alpha particles emitted by the package of the device, or electrical transients. The factors that need to be accounted for when modeling this mechanism include:

- System application (Space, Airborne, Etc.)
- If airborne, system operating altitude, and possibly latitude
- Degree of external radiation shielding related to the system
- Memory cell dimensions
- Cell construction technique (specialized design to minimize susceptibility)
- Type of packaging used in the memory device
- Any error correction circuitry internal or external to the device

Because of the large amount of effort required to adequately model soft-error failures, they were not modeled during this project.

### 4.2.2.2 Model Development

Development of reliability prediction models for memory devices commenced once the applicable memory failure mechanisms were identified in the first phases
of the program. Two objectives were kept in mind during the development process:

- Make the model representative of what is physically causing failure.
- Make the model user-friendly, i.e., require only easily-found user input parameters.

A few observations regarding the memory devices to be modeled were made that helped to define the form of the model. One observation is that the basic technologies and processes used to fabricate memory devices are very similar to those of logic devices, especially when one looks at the peripheral circuitry of the memory as opposed to the array. Based on this, close coordination with the logic/VHSIC model development task was deemed to be desirable. Another observation is that the primary functions required to be performed on a memory circuit are basically the storage of data and the transfer of this data into and out of the storage. These two functions are segregated physically on the device in the form of the memory array and the interface or peripheral circuitry.

A basic approach used in the development of the model was to use the superposition approach. For the memory model, this requires analysis of the causes of failure individually, determining the contribution of each of these causes to the overall device failure rate, then adding the contributions together, which yields the device failure rate. It should be noted here that, for the purposes of the memory model discussion, the term "device" actually refers only to the "die", or chip, failure rate. This failure rate is added to the package failure rate in the final memory model. Refer to the package model section for the package failure rate determination.

This section will address the modeling of the applicable failure mechanisms individually and then present the final form of the model.

## Electromigration

This failure mechanism was identified as being a potential failure rate
contributor for all memory devices. As part of the logic/VHSIC modeling task, a deterministic model representing electromigration was developed (see section 4.1.3.2). This same model is used to represent the electromigration failure rate for memory devices.

Because of the failure distribution determined as part of the electromigration modeling task, it is used here as essentially a "go-no go" check. Given a current density (such as the default value of $.125 \mathrm{MA} / \mathrm{cm}^{2}$ ), the resultant probability of success is basically either 1.000 or zero. Therefore, it is not considered an additive contributing failure rate to the overall model. The user must only check the operating junction temperature in addition to either the known current density or the default value in order to determine the acceptability of using the device in that application.

## Time Dependent Dielectric Breakdown

Earlier in the approach/failure mechanism section, this was identified as a contributing failure mechanism for all MOS devices. To model the effect of this failure mechanism on memory device reliability, the TDDB modeling effort as part of the logic/VHSIC model development task was used as a basis (also see section 4.1.3.1). A basic assumption made here is that the oxides used for memory devices are the same as the oxides used for logic devices, which is a reasonable assumption. To determine $\lambda_{T O D B}$ (the failure rate due to TDDB), some physical parameters of the device must be known. These are: total gate oxide area, gate oxide thickness, oxide electric field, and temperature of the oxide (or $T_{j}$ ).

At the start of the $\lambda_{\text {TDDB }}$ modeling effort for memories, the approach was taken to evaluate the memory array and peripheral circuitry separately. This was done because for some memory devices the physical parameters required differ significantly between the array and periphery. So, for some device types, the total $\lambda_{T O O B}$ equals the $\lambda_{T O D B}$ (array) added to the $\lambda_{T O D B}$ (periphery). For FLOTOX and Tex-POly EEPROMs, only the $\lambda_{\text {TODB }}$ for the periphery was considered, since the array oxide failure rate due to voltage stress is assumed to be accounted for by the reprogram cycling failure rate
model (see the Trapup section). The various manufacturer sources were asked to provide data regarding oxide thickness and area. Based on the data provided by the manufacturers, tables were developed that show the parameter values to be used for each memory device. A range is given for each device capacity value. If the user does not know the value for the device, then the most conservative value in the range provided is used (thinnest oxide, or largest gate oxide area). These values are shown in Tables 4.2-2 through 4.2-3.

## TDDB Discussion

In most cases for memory devices, the resultant failure rate due to TDDB turns out to be negligibly small (for the typical 5 V operation). The exception to this is for the thinner oxide devices that experience relatively high field stress. In general, the memory TDDB failure rate is insignificant for an applied voltage of 5 V or less.

The TODB model presented here was determined to be inadequate for modeling the oxide failure rate due to programming stress. This affects the UVEPROM, Flash, MNOS, and FG PROM arrays, and the portion of EEPROM periphery circuitry that is exposed to a high programming voltage. The programming stress condition is characterized by a very high field stress for a very short period of time. Using the TDDB model to calculate the failure rate due to programming results in very high hazard rate values that are not valid when compared to the actual experience that the industry has with reprogrammable devices.

The evidence gained during the memory reliability modeling effort suggests that oxide failures due to programming on UVEPROMs, Flash EEPROMs, and MNOS EEPROMs are primarily due to either contaminants in the oxides, or microscopic physical faults in the oxide itself that precipitate failure upon repeated pulses of high electric fields. For this model, the cycling failure rate for the devices just mentioned will be considered to be zero, providing that a limit of 100 cycles is not exceeded. The great majority of UVEPROM, Flash EEPROM, and MNOS EEPROM applications do not require in excess of 100 cycles during the life of the system.

Table 4.2-2 Total Gate Oxide Area - Memories

UVEPROMs, Flash EEPROMs, MNOS EEPROMs, Floating Gate PROMs - ARRAY ONLY MOS PALs/PLAs - ARRAY ONLY*

| Capacity (\#bits) | Total Gate Oxide Lower Limit | Area (um²) Upper Limit |
| :---: | :---: | :---: |
| 2 K | 8192 | 16384 |
| 4 K | 16384 | 32768 |
| 8K | 32768 | 65536 |
| 16 K | 65536 | 131072 |
| 32K | 131072 | 262144 |
| 64K | 147456 | 327680 |
| 128K | 294912 | 655360 |
| 256K | 589,824 | 1,310,720 |
| 512K | 1,179,648 | 2,621,440 |
| 1M | 2,359,296 | 5,242,880 |
| 2 M | 4,718,592 | 10,485,760 |

*     - For MOS PAL/PLA devices, determine the number of bits in the programmable array, then use next highest bit count category listed in the above table.

UVEPROMs, Flash and MNOS EEPROMs, Float. Gate PROM/PAL/PLA - PERIPHERY ONLY MOS ROMs/HALs/MLAs - ENTIRE DEVICE

For all devices memory capacities, use range of $260,000-1,209,000 \mathrm{um}^{2}$.

Table 4.2-2 Total Gate Oxide Area - Memories (Continued)
FLOTOX and Textured-POly EEPROMs - PERIPHERY EXPOSED TO PROGRAMMING STRESS
For all devices, use $103,000-602,500 \mathrm{um}^{2}$.
FLOTOX and Textured-POly EEPROMS - PERIPHERY EXPOSED TO SUPPLY VOLTAGE STRESS
For all devices, use $260,000-1,209,000 \mathrm{um}^{2}$.
MOS SRAMS - ENTIRE DEVICE
BiMOS SRAMs - ENTIRE DEVICE*

| Capacity <br> (\# bits) | Total Gate Oxide <br> Lower Limit | Area (um <br> Upper Limit |
| :--- | :--- | :--- |
| $1 K$ | 99,176 | 497,056 |
| $2 K$ | 149,352 | 798,112 |
| $4 K$ | 45,864 | 192,888 |
| $8 K$ | 82,728 | 358,776 |
| $16 K$ | 156,456 | 690,552 |
| $32 K$ | 303,912 | $1,354,104$ |
| $64 K$ | 598,824 | $2,482,600$ |
| $128 K$ | $1,188,648$ | $2,681,208$ |
| $256 K$ | $1,052,576$ | $4,730,592$ |
| $512 K$ | $3,101,152$ | $9,449,184$ |
| $1 M$ | $4,198,304$ | $18,886,368$ |
| $2 M$ | $8,392,608$ | $37,760,736$ |

*     - For BiMOS SRAMs, multiply oxide area by .667

MOS DRAMs - ENTIRE DEVICE

| Capacity (\# bits) | Total Gate Oxide Lower Limit | Area (um²) Upper Limit |
| :---: | :---: | :---: |
| 1 K | 98,588 | 394,352 |
| 2 K | 123,676 | 494,704 |
| 4K | 31,932 | 95,796 |
| 8K | 50,364 | 151,092 |
| 16 K | 87,228 | 261,684 |
| 32K | 160,956 | 482,868 |
| 64K | 308,412 | 925,236 |
| 128K | 603,324 | 1,809,972 |
| 256K | 530,288 | 1,590,864 |
| 512K | 1,054,576 | 3,163,728 |
| 1 M | 2,103,152 | 6,309,456 |
| 2 M | 4,200,304 | 12,600,912 |

Table 4.2-3 Gate Oxide Thickness - Memories
IJVEPROMs, Float. Gate PROMs - ARRAY ONLY
MOS ROMs/PLAs/PALs/MLAs/HALs - ENTIRE DEVICE*

| Capacity | Gate Oxide Thickness (Angstroms) <br> (\# bits) |
| :--- | :--- |

$2 K$ ..... 600 ..... 700
4K ..... 600 ..... 700
8K ..... 600 ..... 700
16K ..... 600 ..... 700
32K 600 ..... 700
64K 400 ..... 600
128K 400 ..... 500
256K 400 ..... 500
512K 400 ..... 500
1M ..... 250 ..... 400
$2 M$ 250 ..... 400

*     - For MOS ROMs/PLAs/PALs/MLAs/HALs determine number of bits in array,then use above table, rounding up to the next highest bit category.
Flash EEPROMs - ARRAY ONLYCapacity Gate Oxide Thickness (Angstroms)(\# bits) Lower Limit Upper Limit
32K 250 ..... 250
64K 250 ..... 250
128K 250 ..... 250
256K ..... 105 ..... 250
512K 105 ..... 250
1M 105 ..... 250
2M 105 ..... 250
MNOS EEPROMs - ARRAY ONLY
Use Range of 15 - 30 Angstroms.
Table 4.2-3 Gate Oxide Thickness - Memories (Continued)
UVEPROMs, MNOS/Flash EEPROMs, Float. Gate PROMs - PERIPHERY ONLY
Capacity Gate Oxide Thickness (Angstroms) (\# bits) Lower Limit Upper Limit
2K 600 ..... 700
4K 600 ..... 700
8K 600 ..... 700
16K ..... 600 ..... 700
32K 600 ..... 700
64K 400 ..... 600
128K 300 ..... 400
256K ..... 300 ..... 400
512K 235 ..... 400
1 M 235 ..... 400
2M 235 ..... 400
FLOTOX and Tex-Poly EEPROMs - PERIPHERY ONLY
Capacity Gate Oxide Thickness (Angstroms)
(\# bits) Lower Limit Upper Limit
8 K 600 ..... 750
16K 600 ..... 750
32K 600 ..... 750
64K 400 ..... 600
128K 340 ..... 500
256K 340 ..... 500
512K 300 ..... 500
1 M 300 ..... 500
2M 300 ..... 500


## Table 4.2-3 Gate Oxide Thickness - Memories (Continued)

## MOS SRAMs, DRAMs - ENTIRE DEVICE

Bimos sRams - ENTIRE DEVICE


## Charge Trapping

This was identified as an intrinsic failure mechanism for fotox and Textured-Poly EEPROM devices. The literature information showed that the Tex-Poly device type is more susceptible to failures caused by trapup than FLOTOX devices (by virtue of the fact that the threshold voltage change due to trapup is related to oxide thickness). [44] On the other hand, the very thin tunnel oxide used for FLOTOX devices makes them more sensitive to defect-related oxide breakdown failures. A number of papers have been written on the subject of charge trapping. The point at which a failure actually occurs because of charge trapping is determined by a number of variables such as the trap density of the oxide (influenced by the intrinsic characteristics of the oxide), charge injected into the oxide, E-field within the oxide, threshold voltage of the memory cell, and even the time duration between reprogram cycles. Based on the nature of these variables, a decision was made not to try to model this mechanism using strictly deterministic methods. Instead, this contribution to the overall failure rate of EEPROM devices was modeled using empirical data from device manufacturer sources as well as information provided as part of the literature search.

Charge trapup is an issue only when the EEPROM is repeatedly reprogrammed. Reprogramming also accelerates certain defect-induced failure mechanisms within the tunnel/gate oxides. Indeed, high voltage stress is one method used to screen out such defects, although the voltage used in such a screen must be carefully chosen so as not to damage good oxide. EEPROM manufacturers perform "endurance" testing (read/erase/write cycling) to evaluate the failure rate of a device type due to reprogramming. Failures that occur during this testing are basically due to either oxide failures caused by defects, or failures caused by excessive charge trapping. A typical failure mode during such endurance testing is a single-bit failure in the memory array. Vendor endurance test data was used to derive a reprogram cycling portion of the overall memory device failure rate model.

The EEPROM read/erase/write failure rate, or $\lambda_{c y c}$, is the following:

$$
\lambda_{c y c}=\left[A_{1} B_{1}+\left(A_{2} B_{2} / \pi_{Q}\right)\right] \pi_{E C C}
$$

where:


Endurance test results for two EEPROM device types, each from a different manufacturer (a $16 K$ FLOTOX device and a $64 K$ Tex-Poly device), were used for the analysis. The test results were in the form of percent failures for a given number of cumulative reprogram cycles. For the FLOTOX device, the test results showed a constant failure rate of $.0225 \%$ failures per 1000 cycles. This indicates that all failures are defect-induced, which is supported by literature data. [44] Although some trapup could be occurring, the data indicates that FLOTOX failures caused by trapup are not significant until very high cycling rates (on the order of $1 \times 10^{6}$ cycles) are achieved. The Textured-poly endurance test data was more complex. Two separate test results were used. One test evaluated cycling reliability at the lower region of total cycles (up to lok cycles) by using a cycling method that enhances defect-induced failures. The second test evaluates cycling reliability at the upper region of total cycles (more than look cycles) using a method that enhances trapup related failures. The results of the two tests are presented in figures 4.2-1 and 4.2-2.

From these test results, a failure rate expression in failures per million hours was derived using the following relationships:

```
MTBF \(=(\# \text { Parts } \times \text { F.R. } \% / 1000 \text { Hrs. })^{-1} \times\left(1 \times 10^{5}\right)\)
F.R. \% / 1000 Hrs. = (F.R. \% / 1000 cycles) \(\times\) (\#Cycles/Hr.)
F.R. \%/ 1000 cycles \(=\) Cumulative \% F.R. at Total \# Cycles
(Total \#cycles) / 1000
```

Figure 4.2-1


Figure 4.2-2


Then:

$$
\text { F.R. \% / } 1000 \text { Hrs. }=\frac{\text { (Cumulative \% F.R. at Total \#Cycles) }}{\text { (Total \#cycles) } / 1000} \times(\# \text { Cycles/Hr) }
$$

$$
\left.M T B F=\frac{((\text { Cumulative \% F.R. at Total \#Cycles })}{(\text { Total \#cycles }) / 1000} \times(\# \text { Cycles/Hr. })\right)^{-1} \times\left(1 \times 10^{5}\right)
$$

The failure rate is taken to be the reciprocal of the calculated MTBF. It can be shown that for a 10,000 hour system lifetime, the failure rate equals the cumulative percent failure rate at the total number of cycles. See Tables 4.2-4 and 4.2-5 for the resulting $A_{1}$ and $A_{2}$ values. Note that "base" and "B Normalized" values are given for $A_{1}$. The test data that yields $A_{1}$ values per the above formulas are for commercial grade parts, which correspond to "D" quality. The $T_{Q}$ factor developed for all models in this project is normalized to a B-level quality. Therefore, the $A_{1}$ values must be adjusted to be consistent with "B" quality. Using the $\pi_{Q}$ values developed in this project, this adjustment is a 3.3 divisor. These adjusted values (to be used when calculating device failure rates) are the "B" normalized numbers. These values are provided for a baseline system operating lifetime of 10,000 hours. For different assumed lifetimes, the user must multiply $A_{1}$ or $A_{2}$ by $(10,000) /\left(s y s t e m\right.$ lifetime). The $A_{2}$ table addresses only the upper region of cycling for Tex-Poiy devices. It is divided by the $\pi_{Q}$ factor in the final model because it is related to an intrinsic mechanism that is not influenced by screening. This $\pi_{Q}$ divisor negates the influence of the $\pi_{Q}$ multiplier on the overall defect failure rate of the device. The next paragraph details an example of how the "A" factors were derived.

Determine the $A_{1}$ cycling factor for a FLOTOX device experiencing between 100 and 200 reprogram cycles during its lifetime.

1) Two initial assumptions are made here. One is that the worst case number of cycles (200) is used to derive an $A_{1}$ factor applicable to the $100-200$ cycle category. Also assumed is a 10,000 hour system lifetime.
2) Note the relationship that is used to derive "MTBF" due to cycling: MTBF $=((\text { Cumulative \% F.R. at Total \#Cycles }) \times(\# \text { Cycles } / \mathrm{Hr}))^{-1} \times\left(1 \times 10^{5}\right)$ (Total \# Cycles) / 1000
3) The FLOTOX endurance test data used (figure 4.2-1) gives a constant failure rate of $.0225 \%$ per 1000 cycles.

At 200 cycles, $.0225 \times 200 / 1000$ yields .0045 cumulative percent F.R. and \# cycles $/ \mathrm{hr} .=200 / 10000 \mathrm{hrs} .=.02$ cycles $/ \mathrm{hr}$. Then,

MTBF $=((.0045) \times(.02))^{-1} \times\left(1 \times 10^{5}\right)=2.222 \times 10^{8} \mathrm{hrs}$.

This equals . 0045 failures/million hrs.

The vendor endurance testing was performed on devices screened to D-level quality. To be compatible with the $\pi_{Q}$ factors developed for all microcircuit models, the $A$ factors needed to be normalized to $B$-level quality. To do this, the derived A factors need to be divided by 3.3, which is the $B$-level to D-level quality factor ratio.

This yields $.0045 / 3.3=.0014$ for the $A_{1}$ factor.

This same process was used to derive A values for Tex-Poly devices; however, the Tex-Poly endurance data does not yield a flat cumulative percent failure rate per 1000 cycles. Rather, the data consisted of a curve from which a percent failure rate could be found once the number of cycles is known.

The A factor must now be modified to account for the effects of temperature and complexity. The A-table values are normalized at $60^{\circ} \mathrm{C} \mathrm{T}_{\mathrm{J}}$ for a 16 K device for FLOTOX and $30^{\circ} \mathrm{C} T_{j}$ for a 64 K device for Tex-Poly. The temperature sensitivity was derived using a combination of vendor and literature data. The endurance test data taken from the FLOTOX manufacturer is based on the testing done at $60^{\circ} T_{j}$. The Tex-Poly endurance test data used is based on testing done at $30^{\circ} \mathrm{T}_{\mathrm{J}}$. Therefore, normalization for the A tables was done at both temperatures depending on whether the part is Tex-Poly or FLOTOX. The
available information indicated an $E_{a}$ of between .12 and .15 eV for FLOTOX. ${ }^{[43,44,67] ~ A . ~} 15$ value was chosen. The $E_{a}$ for Tex-Poly endurance failures is dependent on the total number of cycles. For high number of cycles, trapup dominates the Tex-Poly failure rate. The available data $[44,68]$ indicates -.1 eV as being appropriate (negative because of the detrapping effects of elevated temperature) for more than 300 K total cycles. For the lower region of endurance ( $<300 \mathrm{~K}$ cycles), .12 eV was selected, because it represents the lower range of the $E_{a}$ found for EEPROM defectrelated endurance failures. An $E_{a}$ lower than that of FLOTOX was deemed appropriate because any latent defects in the thicker Tex-Poly oxide should be less sensitive to increasing temperature.

No empirical data was available showing the relationship of cycling failure rate to the complexity of the EEPROM device (number of reprogram cycles). All relevant sources of data indicated that fLOTOX was more sensitive to scaling effects than Textured-Poly because the thinner oxide for FLOTOX is more difficult to scale down than Tex-Poly. The same sensitivity to complexity as the MIL-HDBK-217E MOS PROM model was chosen for FLOTOX as this is consistent with the fact that the failures are defect-driven and is supported by literature data. ${ }^{[44]}$ A complexity sensitivity of half the fLOTOX sensitivity was chosen for Tex-Poly EEPROM types. This assumption is also supported by literature data. [44] The temperature/complexity multipliers $\left(B_{1}, B_{2}\right)$ are shown in tables 4.2-6 through 4.2-8.

## Error Correction Factor

A few EEPROM manufacturers have incorporated on-chip error correction circuitry into some or all of their devices. One objective of the memory model effort was to develop a factor in the model which takes this into account. Two error correction schemes were found during the literature search and manufacturer survey activities: a Hamming code approach using 4 correct bits for 8 data bits, and a redundant cell approach which uses an extra storage transistor in every cell. The approach taken was to evaluate the failure rate improvement for a single memory cell and apply this improvement factor to the memory-array failure rate.

| Total Number Of Cycles ( $X$ ) | FLOTOX |  | Textured-Poly |  |
| :---: | :---: | :---: | :---: | :---: |
|  | Base | "B" Normalized | Base | "B" Normalized |
| up to 100 | . 0023 | . 0007 | . 0320 | . 0097 |
| $100<x \leq 200$ | . 0045 | . 0014 | . 0460 | . 0139 |
| $200<x \leq 500$ | . 0113 | . 0034 | . 0760 | . 0230 |
| $500<x \leq 1 K$ | . 0225 | . 0068 | . 110 | . 033 |
| $1 \mathrm{~K}<x \leq 3 \mathrm{~K}$ | . 0675 | . 0204 | . 200 | . 061 |
| $3 \mathrm{~K}<X \leq 5 K$ | . 1125 | . 0341 | . 300 | . 091 |
| $5 K<X \leq 7 K$ | . 1575 | . 0478 | . 450 | . 136 |
| $7 \mathrm{~K}<X \leq 9 K$ | . 2025 | . 0614 | . 700 | . 212 |
| $9 \mathrm{~K}<x \leq 10 \mathrm{~K}$ | . 2250 | . 0682 | 1.000 | . 303 |
| $10 \mathrm{~K}<\mathrm{X} \leq 15 \mathrm{~K}$ | . 3375 | . 1023 | 1.000 | . 303 |
| $15 \mathrm{~K}<\mathrm{X} \leq 20 \mathrm{~K}$ | . 4500 | . 1364 | 1.000 | . 303 |
| $20 \mathrm{~K}<\mathrm{X} \leq 30 \mathrm{~K}$ | . 6750 | . 2045 | 1.000 | . 303 |
| $30 \mathrm{~K}<\mathrm{X} \leq 50 \mathrm{~K}$ | 1.125 | . 3409 | 1.000 | . 303 |
| 50K < $x \leq 100 \mathrm{~K}$ | 2.250 | . 6818 | 1.000 | . 303 |
| $100 \mathrm{~K}<x \leq 200 \mathrm{~K}$ | 4.500 | 1.364 | 1.000 | . 303 |
| $200 \mathrm{~K}<\mathrm{X} \leq 300 \mathrm{~K}$ | 6.750 | 2.045 | 1.000 | . 303 |
| $300 \mathrm{~K}<\mathrm{X} \leq 325 \mathrm{~K}$ | 7.313 | 2.216 | 0* |  |
| $325 \mathrm{~K}<\mathrm{X} \leq 350 \mathrm{~K}$ | 7.875 | 2.386 | $0 *$ |  |
| $350 \mathrm{~K}<\mathrm{X} \leq 400 \mathrm{~K}$ | 9.000 | 2.727 | 0* |  |
| 400K < $X \leq 450 \mathrm{~K}$ | 10.13 | 3.070 | 0* |  |
| 400K < $X \leq 500 \mathrm{~K}$ | 11.25 | 3.409 | 0* |  |

If using a system life of other than 10000 hours, multiply Al by $\frac{10000}{\text { sys. Life }}$.

*     - See A2 Table 4.2-5


## Table 4.2-5 $A_{2}$ Cycling Factor

For FLOTOX, $A_{2}=0$
For Tex - Poly:
Total \# of Cycles
A2
Up to 300K 0.0
$300 K<X \leq 325 K \quad 2.50$
$325 \mathrm{~K}<\mathrm{X} \leq 350 \mathrm{~K} \quad 10.0$
$350 K<X \leq 400 K \quad 20.0$
$400 K<X \leq 450 K \quad 30.0$
$450 \mathrm{~K}<\mathrm{X} \leq 500 \mathrm{~K} \quad 40.0$
If using a system life of other than 10000 hours, multiply Al by $\frac{10000}{\text { Sys. Life }}$.
Table 4.2-6
$B_{1}$ for flotox $\quad(.15 \mathrm{eV})$
Table 4.2-6
$B_{1}$ for flotox $\quad(.15 \mathrm{eV})$
$\mathrm{T}_{\mathbf{J}}\left({ }^{\circ} \mathrm{C}\right)$

Table 4.2-7 B, for TEX-POLY
 | $128 \mathrm{k}|1.031| 1.206|1.397| 1.603|1.825| 2.061|2.312| 2.578|2.857| 3.150|3.455| 3.773|4.102| 4.442|4.793|$
 |256k $|1.246| 1.457|1.688| 1.937|2.204| 2.490|2.794| 3.115|3.452| 3.805|4.174| 4.556|4.956| 5.367|5.791|$
 | $512 \mathrm{k}|1.505| 1.761|2.039| 2.341|2.664| 3.010|3.376| 3.764|4.172| 4.599|5.045| 5.508|5.989| 6.486|6.998|$
 $\lim |1.815| 2.123|2.459| 2.822|3.212| 3.628|4.07||4.538| 5.330|5.544| 6.082|6.641| 7.221|7.820| 8.437 \mid$ $1 \ldots|1.265| 2.287|2.637| 3.014|3.417| 3.859|4.30||4.78||5.284| 5.810|6.359| 6.928|7.518| 8.127|8.753|$
Table 4.2-8
$B_{2}$ for TEX-POLY



For a redundant cell approach, the conventional $M$ out of $N$ reliability for Time $=$ infinity relation was used:

MTBF = Sum from $\mathrm{J}=0$ to $\mathrm{J}=\mathrm{K}$ the term $\frac{1}{(N-J) L}$
where:

$$
\begin{aligned}
& N=\text { Number of active assemblies }(N=2) \\
& M=\text { Min. number of assemblies required }(M=1) \\
& L=\text { Assembly Failure Rate ( } L \text { normalized to } 1) \\
& J=\text { Number of assembly failures } \\
& K=N-M
\end{aligned}
$$

This becomes MTBF $=\frac{1}{(2-0)}+\frac{1}{(2-1)}=\frac{3 / 2 \text { MTBF improvement, or } 2 / 3 \text { Fail. }}{\text { Rate reduction }}$.

This .6667 factor is multiplied by the cycling failure rate to determine the equivalent failure rate.

For the Hamming code approach, the failure rate improvement factor ( $\pi_{E C C}$ ) is derived as follows:

Ordinary 8 bit word failure rate $=\left(\lambda_{w}\right)=8 \times$ Bit failure rate $=8 \times \lambda_{b}$
"New" word reliability $=R_{w}=R^{12}+12 R^{11} Q=R^{12}+12 R^{11}(1-R)$
$=R^{12}+12 R^{11}-12 R^{12}=12 R^{11}-11 R^{12}=12 e^{-11 \lambda t}-11 e^{-12 \lambda t}$

Integrating the above expression from zero to infinity yields an effective "new" word failure rate of:
$\frac{n(n-1)}{2 n-1}=\frac{(12)(11)}{23}=5.74 \lambda_{b}$
This yields an improvement factor ( $\pi E C C$ ) of :
$\frac{\lambda w^{\prime}}{\lambda w^{\prime}}=\frac{5.74 \lambda b}{8 \lambda b}$
where

$$
\begin{aligned}
& \lambda w^{\prime}=\text { New word failure rate } \\
& \lambda w=\text { Old word failure rate } \\
& \lambda b=b i t \text { failure rate }
\end{aligned}
$$

This factor is applied to the cycling failure rate. It is a conservative approach because it affects only the cycling failure rate portion of the model. If device types other than EEPROMs incorporate on-chip error correction in the future, this factor can also be applied to the defect failure rate (although careful judgment must be made regarding the percentage of defect failures that are correctable).

## Defect Failure Rate

Earlier in this section, defects were identified as a very significant contributor to the overall device failure rate for all memory device types. This was evident from the literature search in addition to the life test data collected. The life test data provided much information regarding failure modes and mechanisms that basically were defect-related. The life test data was then used to determine the defect failure rate of the devices.

Table 4.2-9 is a summary of the life test data collected as part of this study. All of the life tests were conducted at $125^{\circ} \mathrm{C}$. The column titled "Hrs (M)" indicates the total number of millions of device hours at $125^{\circ} \mathrm{C}$ for all devices of the designated type and complexity. The column titled "Hrs (M) @ $25^{\circ} \mathrm{C}^{\prime \prime}$ indicates the equivalent part hours at $25^{\circ} \mathrm{C}$, assuming an activation energy of 0.8 eV for memories. "FPMH e $25^{\circ} \mathrm{C}$ " is the calculated failure rate in failures per million hours using the Chi-square distribution at 50\% confidence. The column "217E e $25^{\circ} \mathrm{C}$ " is the MIL-HDBK-2l7E base failure rate $\left(C, \pi_{T}\right)$ at $25^{\circ} \mathrm{C}$, and the final column is a ratio of the calculated value to the MIL-HDBK-217E value.

The 0.8 eV value was derived by analyzing the published activation energy distributions for different memory failure mechanisms provided by the memory model literature search; these were categorized as metallization, oxide, and

Table 4.2-9
Derived Failure Rates - Memories

NEW/21TE







白 兹



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Table 4.2-9 (CONTD)
Derived Failure Rates - Memories
```


## NEW/21TE

上


命 $\quad \infty, \infty, \infty, \infty, \infty \quad \infty, \infty, \infty, \infty, \infty \quad \infty, \infty, \infty, \infty, \infty, \infty, \infty, \infty \quad \infty, \infty, \infty, \infty$,





miscellaneous defect-related mechanisms. The average $E_{a} s$ were computed to be $.84, .37$, and .85 , respectively. RAC-MDR-21 was consulted to determine the weighting factors to be associated with each of these mechanisms for bipolar and MOS memories. Table 4.2-10 provides the results. Interestingly, the results for the two technologies were nearly the same, hence the value of 0.8 eV for all memory devices. This relatively high activation energy is driven by the preponderance of oxide step coverage metallization defects in the MDR-21 database. If oxide defects had been predominant, the activation energy would have been much lower.

From the life test analysis, a defect failure rate model (similar to MIL-HDBK - 217E) was derived that uses two factors: a temperature acceleration factor ( $\pi_{T}$ ) and a base failure rate/complexity modifier ( $C_{1}$ ). The $\pi_{T}$ relationship is taken from MIL-HDBK-217E and is as follows:

$$
\pi_{T}=0.1\left(e^{x}\right) \quad \text { where: } \quad x=-A\left(\frac{1}{\left(T_{J}+273\right)}-\frac{1}{298}\right)
$$

In most instances, insufficient test data was available to make a detailed evaluation of the impact of device complexity on failure rate. The complexity factors of MIL-HDBK-217E were therefore used as guidance in the $C_{1}$ factor development. The following paragraphs describe the defect failure rate model for each memory device category. Refer to Appendix $E$ for the life test data, and Table 4.2-9 for the derived failure rates.

MOS PROMs (Including UVEPROMS, EEPROMs, Floating gate MOS PALs/PLAs)

The data collected did show some correlation between device complexity (capacity in bits) and failure rate. The average failure rate of the 64 K , 128K, and 256K UVEPROM test data was used as a baseline failure rate. This value is . 00112 FPMH (Failures Per Million Hours) at $25^{\circ} \mathrm{C}$ for D-level quality. This equals .000339 FPMH after normalizing to B-level quality. The .8 eV activation energy is used to determine the failure rates at temperatures other than $25^{\circ} \mathrm{C}$. This activation energy yields an $A$ value of 9270 . The FLOTOX and Tex-Poly derived failure rate data is consistent with the UVEPROM
calculations, and the 16 K EEPROM resultant failure rate (together with the UVEPROM calculated values) supports the 217 E complexity relationship. A complexity relationship equal to that of MIL-HDBK-2l7E is used, which results in the following $C_{1}$ values (these are multiplied by $\pi_{E}$ to determine the overall defect failure rate):


Up to 16 K bits .00085
16K < X $\leq 64 K \quad .00169$
64K < X $\leq 256 \mathrm{~K} .00339$
256 K < X < 1M . 00678
(Note: the $25^{\circ} \mathrm{C}$ normalized failure rates have been multiplied by 10 to get $C_{1}$ values - this is to compensate for the 0.1 multiplier in the $\pi_{T}$ expression.)

## Bipolar PALs/PLAs

The 0.8 eV activation energy ( 9270 "A" value) is used for $\pi_{T}$. Very little correlation between programmable array bit count and defect failure rate was found for these device types; however, the devices for which life test data was available all contained 200 gates or less. The average failure rate for these devices was determined to be .003456 FPMH at $25^{\circ} \mathrm{C}$ for D-level quality. This is . 001047 after normalizing to B-level quality. A complexity relationship similar to MIL-HDBK-217E is assumed for higher gate count devices, which yields the following complexity factors:

## $C_{1}$

```
Up to 200 gates .01047
200<X\leq 1000 gates . .02094
1000< X < 2000 gates . 04188
```


## Bipolar PROMS

Most of the life test data available was for low complexity (less than 16 K bit) devices. The derived failure rates for $\leq 16 \mathrm{~K}$ devices are roughly equal; the 32 K part failure rate was about triple this. The average failure rate for the $\leq 16 \mathrm{~K}$ group was .003104 at $25^{\circ} \mathrm{C}$ for D-level quality or .000941 when normalizing to $B$ quality. The $32 k$ bit device test data was deemed insufficient to warrant departure from the $217 E$ complexity relationship. Using the $217 E$ relationship yields the following $C_{1}$ values:

## $c_{1}$

Up to 16 K bits .0094
$16 \mathrm{~K}<\mathrm{X} \leq 64 \mathrm{~K} \quad .0188$
$64 K<x \leq 256 K \quad .0376$
256K < X $<1$. 0753

## MOS ROMS

A weak correlation of complexity to failure rate was found. The 128 K and 256 K device failure rate data was used to develop an average failure rate of .0008605 FPMH for that device category at $25^{\circ} \mathrm{C}$ and D-level reliability. This yields .000261 FPMH when normalizing for B-level quality. Using the $217 E$ complexity relationship results in the following:

## $C_{1}$

Up to 16 K bits .00065
$16 K<x \leq 64 K \quad .0013$
$64 K<X \leq 256 K \quad .0026$
$256 \mathrm{~K}<\mathrm{X}<1 \mathrm{M} .0052$

## Bipolar SRAMs

Test data for low complexity SRAMs of this type were available (under

16 K bits). The average failure rate was calculated to be .001734 FPMH at $25^{\circ} \mathrm{C}$ for D-level quality, or .000525 for B-level quality. The $C_{1}$ values are:

## $C_{1}$

Up to 16 K bits . 0052
$16 K<x \leq 64 K \quad .0105$
$64 K<X \leq 256 K .0210$
256K < X < 1 M . 0420

## MOS SRAMS

Life test data for 16 K MOS SRAMs was used and is . 002575 FPMH for that complexity at $25^{\circ} \mathrm{C}$ and D-level quality. Normalizing for B-level quality gives .000780 FPMH. The same $C_{1}$ values as are used for bipolar SRAMs are then applied.

Up to 16 K bits .0078
$16 \mathrm{~K}<\mathrm{X} \leq 64 \mathrm{~K} \quad .0156$
$64 K<X \leq 256 K \quad .0312$
$256 \mathrm{~K}<\mathrm{X}<\mathrm{M}$. 0624

DRAMS

Data for 64K DRAMs was available. The average failure rate is .000842 FPMH for this device at $25^{\circ} \mathrm{C}$ and D-level quality. This equals . 000255 for B-level quality. The 217E complexity relationship yields:

## $C_{1}$

Up to $16 K$ bits . 0013
$16 K<x \leq 64 K \quad .0025$
$64 K<x \leq 256 K$. 0051
256K < X < 1M . 0100

Table 4.2-10


### 4.2.2.3 Memory Model Form

Based on the information and data just presented, the memory device model form that has been developed for this project is as follows:
$\lambda_{P}=\lambda_{E M}+\lambda_{T D D B}+\left[\left(C_{1}\right)\left(\pi_{T}\right)+\lambda_{C y C}+\left(C_{2}\right)\left(\pi_{E}\right)\right]\left(\pi_{Q}\right)\left(\pi_{L}\right)$
where:
$\lambda_{p} \quad$ is the device predicted failure rate in failures per million hours.
$\lambda_{E M}$ is the "go - no go" failure rate due to electromigration.
Also refer to section 4.1.3.2.
$\lambda_{\text {TDDB }}$ is the failure rate due to Time dependent dielectric breakdown.
Also refer to section 4.1.3.1.
$C_{1}$ is the base failure rate for defect-related failures.
$\pi_{T} \quad$ is the temperature multiplier for the defect-related failure rate.
$\lambda_{c y c}$ is the EEPROM* read/write cycling induced failure rate and is:

$$
\lambda_{C y c}=\left[A_{1} B_{1}+A_{2} B_{2} / \pi_{Q}\right] \pi_{E C C}
$$

where:
$A_{1}$ and $A_{2}$ are the base cycling failure rates.
$B_{1}$ and $B_{2}$ are the temperature/complexity multipliers.
$\pi_{E C C} \quad$ is the on-chip error correction factor:
$=.7174$ for Hamming Code with 8 data bits and 4 correct bits.
$=.6667$ for a two-needs-one redundant cell approach.
$=1.0$ for any device not using on-chip error correction.

* $\lambda_{c y c}=0$ for all devices other than Flotox or Textured Poly EEPROMS.
$C_{2}$ is the package base failure rate.
$\pi_{E}$ is the environmental factor. Refer to sect. 4.6.4.
$\pi_{Q}$ is the quality factor. Refer to sect. 4.6.1.
$\pi_{L}$ is the learning factor. Refer to sect. 4.6.2.


### 4.3 MONOLITHIC GaAs DEVICES

### 4.3.1 GaAs Database - Summary of Sources and Data

The GaAs model database relied on information from an industry survey, telephone contacts with additional companies, and published literature. The published literature includes papers, articles, books, company data books, and company application notes. The GaAs industry survey by mail was largely unsuccessful since only one useful set of data was obtained from the thirteen companies that responded (see Table 4.3-1). General Electric supplied accelerated life test data on a power MMIC amplifier through the survey format. Litton and Harris formally withdrew from the survey after receiving specific instructions for the type of data that would be required. Seven additional companies (see Table 4.3-1) were contacted independently of the industry survey and NEC Corp. supplied useful accelerated life test data from an application note. Other data in the form of accelerated life test reports on discrete GaAs field effect transistors and diodes was obtained from Alpha, Sanders, Avantek, Fujitsu, Harris, NEC Corp., and Texas Instruments although the data was not useful for this study. There appears to be a tendency among the GaAs integrated circuit manufacturers to carefully guard specific process details and reliability test results especially in this area where emerging technology is being built. This tendency is understandable since much of the technology is considered proprietary and many of the company contacts from the industry survey expressed this view. The most useful data was obtained from published papers and data books which discussed the results of accelerated life tests on GaAs integrated circuits and other circuit elements.

Approximately ninety six papers, articles, and books were reviewed during the literature search for failure mechanism information and this source also provided most of the data for the development of models. The results of accelerated life test studies from the six most useful papers or articles and three company data books are summarized in Tables 4.3-2, 4.3-3 and 4.3-4. The integrated circuit element summary data (see Table 4.3-4) was developed from a paper by Roesch and Stunkard ${ }^{[92]}$. The other papers are referenced in Tables 4.3-2 and 4.3-3.

Table 4.3-1

GaAs Data Collection and Industry Contacts

| COMPANIES RESPONDING TO SURVEY | BUILDS MMIC GaAs | BUILDS OIGITAL GaAs | WITH- <br> DREW <br> FROM <br> SURVEY | DOES NOT BUILD GaAs | $\begin{aligned} & \text { SENT } \\ & \text { DATA } \\ & \hline \end{aligned}$ | DATA USEFUL |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Litton Electron Devices Microwave Solid State |  |  | X |  |  |  |
| Harris Microwave Semiconductor | X | X | X |  |  |  |
| Mostek |  |  |  | X |  |  |
| Pacific Monolithics | X |  |  |  |  |  |
| Tachonics Corp. | $x$ |  |  |  |  |  |
| TriQuint Semiconductor | X | X |  |  |  |  |
| Watkins Johnson Co. | X |  |  |  |  |  |
| Vitesse Semiconductor |  | X |  |  |  |  |
| Gain Electronics |  | X |  |  |  |  |
| Anadigics | $x$ | $x$ |  |  |  |  |
| M/A-COM AAD | X |  |  |  |  |  |
| Microwave Semiconductor Corp. | X |  |  |  |  |  |
| Alpha | X | X |  |  | $x$ |  |
| G.E. | $x$ |  |  |  | X | X |
| Avantek | X |  |  |  |  |  |
| Sanders Microelectronic Center | X |  |  |  | X |  |
| ADDITIONAL TELEPHONE CONTACTS |  |  |  |  |  |  |
| NEC Corp. | $x$ | $\chi$ |  |  | X | X |
| David Sarnoff Research Center |  |  |  | X |  |  |
| Raytheon Special Microwave Devices Operation | $x$ |  |  |  |  |  |
| Adams Russell Electronics | X | X |  |  |  |  |
| Eaton-AIL-Division | X |  |  |  |  |  |

Table 4.3-2
GaAs MMIC Data Summary

|  |  | I | TEST\| |  | ACTIVATION\| | failure rate\| |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  |  | TEMP\| | SAMPLE\| | energy | REFERENCED | Reference |
| MANUFACTURER | IEST TYPE | DEVICE TYPE | $\left.\underline{(0}{ }^{\circ} \mathrm{C}\right) \mid$ | SIZE 1 | (ev) | TO $150^{\circ} \mathrm{C}$ | NO. |
|  |  | 1 |  |  |  |  |  |
| TriQuint | Accelerated | TW91110 | 225 \| | 131 | 1.6 | $4.26 \times 10^{-7}$ | $83 \& 84$ |
| Semiconductor | Life Test | LAmplifier |  |  |  |  |  |
|  |  | I |  |  |  |  |  |
| Harris Microwave | Accelerated | HMM-11810 | 200 | 31 | 1.6 | $4.36 \times 10^{-7}$ | 83 \& 85 |
| Semiconductor | Life Test | Amplifier |  |  |  |  |  |
|  |  |  |  |  |  |  |  |
| General | Accelerated | MMIC Power | 200 | 17 | 1.5 | $1.29 \times 10^{-6}$ | 89 |
| Electric Co. | Life Test | LAmplifier |  |  |  |  |  |
|  |  | I |  | \| |  |  |  |
| NEC Corporation | Accelerated | Amplifiers | 220 | 30 | 1.17 | $7.85 \times 10^{-7}$ | 90 |
|  | Life Test | \& Interface |  | 1 |  |  |  |
|  |  | LICs |  |  |  |  |  |
| M/A-COM Inc. |  |  |  |  |  |  |  |
|  | Accelerated | \| matgmzol | 250 | 20 | 1.35 | $2.06 \times 10^{-7}$ | 91 |
|  | Life Test | \| MA4GM211 |  | 1 |  |  |  |
|  |  | 1 SPST Switches |  |  |  |  |  |
| WEIGHTED AVERAGES |  | I |  |  |  |  |  |
|  |  | \| | 1 | 1 | 1.5 | $4.51 \times 10^{-7}$ |  |
|  |  |  |  |  |  |  |  |

Table 4.3-3

GaAs Digital Data Summary


Table 4.3-4

GaAs Integrated Circuit Element Data Summary

| INTEGRATED CIRCUIT ELEMENT | TEST TYPE | TEST TEMP <br> ( ${ }^{\circ} \mathrm{C}$ ) | $\begin{gathered} \text { SAMPLE } \\ \text { SIZE } \end{gathered}$ | ACTIVATION ENERGY (ev) | FAILURE RATE REFERENCED TO $150^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Implanted Resistors \& Ohmic Contacts | Accelerated Life Test | 203 | $\sim 90$ | -- | $1.57 \times 10^{-7}$ |
| Thin Film Resistors | Accelerated Life Test | $\begin{aligned} & 125 \\ & 150 \\ & 175 \\ & 100 \\ & \hline \end{aligned}$ | 70 | 1.0 | $3.05 \times 10^{-7}$ |
| First Level Metallization | Accelerated Life Test | $\begin{array}{r} 250 \\ 275 \\ 300 \\ \hline \end{array}$ | 80 | 1.8 | $0.059 \times 10^{-7}$ |
| Air Bridge Metallization | Accelerated Life Test | 170 | $\sim 70$ | 0.43 | $0.68 \times 10^{-7}$ |

### 4.3.2 GaAs Failure Rate Models

No GaAs integrated circuit models currently exist in MIL-HDBK-217E. The only reference to GaAs in MIL-HDBK-217E is in the discrete semiconductor FET section where an application factor and a quality factor are applied to GaAs FETs. The 2l7E model is basically a silicon model. Significant material and processing differences ${ }^{[88,93,94]}$ exist between silicon and GaAs (see Table 4.3-5) and these differences result in different failure mechanisms for the two materials and require different failure rate models.

The literature search revealed that the primary failure mechanism affecting GaAs integrated circuits centers around metallization and GaAs interdiffusion ${ }^{[83,93,95]}$. In particular Au-GaAs interdiffusion involves a slow degradation in the GaAs contact regions and in the Schottky gate regions of the MESFET components. The MESFET channel regions become reduced and hot spots can develop. Ohmic contact resistance will increase in the drain and source contacts on the MESFETs and in the other contacts in the integrated circuit. Failures will initially involve parametric changes in performance but will eventually involve catastrophic damage. Other failure mechanisms including electromigration, corrosion, backgating, and capacitor dielectric defects have been reported to occur rarely in comparison to the Au-GaAs interdiffusion failure mechanism ${ }^{[83]}$.

The circuits selected for failure rate modeling were the GaAs MMIC (Monolithic Microwave Integrated Circuit) and the GaAs digital circuits. Significant processing differences exist between the two circuit types and the differences resulted in two different models. GaAs MMICs use depletion mode MESFETs with fewer transistors dissipating more power than on digital circuits which use larger numbers of smaller size depletion or enhancement mode MESFETs that dissipate less power ${ }^{[83]}$. MMICs use many capacitors (metal insulator metal, interdigited, stub, Schottky barrier), inductors (lumped or distributed), resistors (implanted or thin film), and Au based air bridge interconnects ${ }^{[93]}$. Digital GaAs circuits make limited use of implanted resistors and Schottky diodes. No air bridge interconnects are used on
digital GaAs circuits. Higher frequency GaAs MMIC devices require more control of interconnect and substrate dimensions to maintain good quality transmission line interconnections. MMIC devices use more extensive backside processing steps because of the low inductance ground connections that are required ${ }^{[93]}$. This step can also serve to increase the thermal conductivity through the MMIC substrate and this is not applicable on digital GaAs circuits.

Accelerated life test studies in industry indicate that the MESFETs (active devices) used in MMIC and digital GaAs devices fail at higher rates than the other components on the integrated circuits. This requires that the failure rate models must be dominated by the MESFET failure mechanism (Au-GaAs interdiffusion). Since the failure mechanism of the MESFET is based on a diffusion process, temperature was determined to be the driving factor in the active device failure rate model ( $\lambda_{A}$ in figures 4.3-1 and 4.3-2) which was then based on the modified Arrhenius equation ${ }^{[96]}$ as follows:

$$
\lambda_{2}=\lambda_{1} e^{\frac{E_{A}}{K}\left\{\frac{1}{T 1}-\frac{1}{T 2}\right\}}
$$

where:

$$
\begin{aligned}
E a & =\text { Activation energy (ev) } \\
T 1 \& T 2 & =\text { Temperatures (Kelvin) } \\
\lambda_{1} \& \lambda_{2} & =\text { failure rates at } T 1 \& T 2 \\
K & =\text { Boltzmann's constant }
\end{aligned}
$$

The complete GaAs MMIC and digital failure rate models are presented in figures 4.3-1 and 4.3-2 with all of the symbols and equations defined except for $C_{2} \pi_{E}, \pi_{L}$, and $\pi_{Q}$ which are found in other sections of this report. The active device base failure rate $\left(\lambda_{A}\right)$ for both MMICs and digital GaAs devices were developed from equation 4.3.1 by calculating weighted averages (based on sample size) of the MMIC and digital GaAs accelerated life test failure rates and activation energies that were listed in Tables 4.3-2 and 4.3-3. The reference temperature is $150^{\circ} \mathrm{C}\left(423^{\circ} \mathrm{K}\right)$ and the only remaining unknown is the channel temperature ${ }^{T}{ }_{C H}$ (see figures 4.3-1 and
4.3-2). The application factor for MMICs ( $\pi_{A}$ ) was developed by comparing the ratio of the $150^{\circ} \mathrm{C}$ failure rates (see Table 4.3-2) for a known low noise MMIC ( $\pi_{A}=1$ ) made by Harris Semiconductor and a power amplifier MMIC made by General Electric ( $\pi_{A}=3.0$ for power devices). The General Electric MMIC was also used to establish the maximum power range ( 3000 mw ) for the application factor. The MMIC active device complexity factor ( $\pi_{C A}$ ) was derived from a set of MMIC failure rate data from NEC Corporation ${ }^{[90]}$ (see Table 4.3-6). A ratio of failure rate data was found by dividing the data with greater than one hundred transistors at three given quality levels by data with less than one hundred transistors. This ratio was then averaged and used as the MMIC active device complexity factor ( ${ }^{(C A}$ ). The digital GaAs active device complexity factor ( $\pi_{C A}$ ) was derived from failure rate data in a paper by Venkataraman, Kotz, and Welch ${ }^{[87]}$ (see Table 4.3-7). Small scale and medium scale integration failure rates were averaged together as a group and compared to large scale integration failure rates to develop the digital complexity factor ( $\pi_{C A}=2.0$ ). The passive device failure rates ( $\lambda_{p}$ in figures 4.3-1 and 4.3-2) for MMICs and digital GaAs devices were derived from a paper by Roesch and Stunkard ${ }^{[92]}$ (see Table 4.3-8) where accelerated life tests were performed on GaAs integrated circuit elements. Composite digital passive failure rates were developed by summing the failure rates for the implanted resistors, ohmic contacts, and first level metallization used in digital GaAs circuits. The failure rates of thin film resistors and air bridge metallization (used in MMICs) was added to the digital composite failure rate to establish a passive MMIC failure rate since all of the passive circuit elements are used on MMIC devices. The failure rate data for integrated circuit elements in Table 4.3-8 ( $75 \%$ current level) were derated from the maximum current levels ( $100 \%$ ) given in the referenced paper to represent a more typical operating level for the circuit elements. A composite activation energy (. 43 eV ) was used for both MMIC and digital GaAs passive failure rate models. The complexity factor ( $\pi_{C P}$ ) appearing in the MMIC failure rate model was derived from an engineering estimate based on the much wider use of passive components in MMIC devices when compared to digital GaAs devices. The digital passive device GaAs model does not have a complexity factor because of the more limited use of passive devices on
digital circuits and because this information is more difficult to determine on digital circuits. When information for the model factors is unknown, the default values revert to the maximum numbers listed for each factor. The temperature term ( $T$ ) required for the passive failure rate models (see figures 4.3-1 and 4.3-2) is meant to apply to the maximum passive device temperature on each circuit. If this temperature is unknown, the default value becomes the active device channel temperature ( ${ }^{( }{ }_{C H}$ ) which must be known. Also, the weighted averages of the failure rates listed in Tables 4.3-2 and 4.3-3 which determine $\lambda_{A}$ for both models and the failure rates developed from Table 4.3-4 for $\lambda_{p}$ were based on B-level quality devices to correspond to a quality factor $\pi_{Q}$ of "one". Table 4.3-9 contains calculated values for active and passive base failure rates from $25^{\circ} \mathrm{C}$ to $175^{\circ} \mathrm{C}$ for both MMIC and digital GaAs devices. The failure rates are carried to four places (failures $/ 10^{6}$ hours) which results in zero values for the active device failure rates at the lower temperatures. The maximum channel temperature listed in Table $4.3-9$ is $175^{\circ} \mathrm{C}$ which was the highest maximum operating temperature reported by any of the manufacturers.

The original proposed form for MMIC devices is shown in equation 4.3.2.

$$
\begin{equation*}
\lambda_{p}(M M I C)=\sum_{i=1}^{n}\left(\lambda_{m i} \pi A i \pi C L i\right)+\left(\lambda_{R} \pi C R+\lambda_{L} \pi C L+\lambda_{C} \pi C C\right) \pi Q \tag{4.3.2}
\end{equation*}
$$

The base failure rate ( $\lambda_{m i}$ ) was designed to account for different size active device operating at different channel temperatures on the same chip. This would require a careful thermal survey of the device and this information was not available for this study. Individual integrated circuit element failure rate terms for resistors ( $\lambda_{R}$ ), inductors ( $\lambda_{L}$ ), and capacitors ( $\lambda_{C}$ ) were also proposed but the minimal amount of data on circuit elements made this concept difficult to implement and the resulting composite or lumped passive failure rates were developed in this study.

The final model equations and symbols were modified in order to make them compatible with MIL-HDBK-217E.

A temperature factor ( $\pi_{T}$ ) was defined by including only the exponential terms from $\lambda_{A}$ and $\lambda_{p}$.

The modified equations are shown in equations 4.3-3 and 4.3-4 below.

$$
\begin{align*}
& \lambda_{M}=\left[\left(C_{1 A} \pi_{T A}+C_{1 P} \pi_{T P}\right) \pi_{A}+C_{2} \pi_{E}\right] \pi_{L} \pi_{Q}  \tag{4.3.3}\\
& \lambda_{D}=\left[C_{1 A} \pi_{T A}+C_{1 P} \pi_{T P}+C_{2} \pi_{E}\right] \pi_{L} \pi_{Q} \tag{4.3.4}
\end{align*}
$$

where:

```
\(\lambda_{M}=\) MMIC GaAs Part Failure Rate
\(\lambda_{D}=\) Digital GaAs Part Failure Rate
\(C_{1 A}=\) GaAs Active Device Complexity Factor (For
        transistors and diodes)
\(C_{1 P}=\) GaAs Passive Device Complexity Factor (For
        resistors, capacitors, inductors)
    \(\pi_{T A}=\) GaAs Active Device Temperature Factor
    \(\pi_{T P}=\) GaAs Passive Device Temperature Factor
    \(\pi_{A}=\) MMIC Application Factor
\(C_{2} \pi_{E}=\) Package Failure Rate
    \(\pi_{L}=\) Experience or Learning Factor
    \(\pi_{Q}=\) Quality Factor
```

FIGURE 4.3-1
GaAs MMIC FAILURE RATE MODEL
$\lambda_{M}=\left[\left(\lambda_{A} \pi C A+\lambda_{P} \pi C P\right) \pi_{A}+C_{2 \pi E}\right] \pi L \pi_{Q} \frac{\text { failures }}{10^{6} \text { hours }}$

```
\lambdaM = MMIC PART FAILURE RATE
\lambdaA}= MMIC ACTIVE DEVICE BASE FAILURE RATE
#
\lambdap}=\mathrm{ MMIC PASSIVE DEVICE BASE FAILURE RATE
#
\pi
C}\mp@subsup{\mp@code{2}}{}{\pi}\mp@subsup{\pi}{E}{}= PACKAGE FAILURE RATE
\mp@subsup{\pi}{L}{}}=\mathrm{ = EXPERIENCE OR LEARNING FACTOR
\pi
```

```
    -17380 (}\frac{1}{\mp@subsup{}{}{T}CH+273}-\frac{1}{423})\frac{failures}{106 hours}; E EA = 1.5 ev
\lambdaA}=0.4506 
\piA = 1.0 FOR LOW NOISE AND LOW POWER LESS. THAN OR EQUAL TO 100 mw
    3.0 FOR DRIVER AND HIGH POWER GREATER THAN 100 mw TO 3000 mw
\piCA = 1.0 FOR LESS THAN 100 ACTIVE DEVICES
    1.6 FOR 100 TO 1000 ACTIVE DEVICES
\pi
    1.2 FOR 11 TO 100 PASSIVE DEVICES
    1.3 FOR 101 TO 1000 PASSIVE DEVICES
```

$\lambda p=0.2263 \mathrm{e}^{-4980}\left(\frac{1}{T+273}-\frac{1}{423}\right) \frac{\text { failures }}{10^{6} \text { hours }} ; E_{A}=0.43 \mathrm{ev}$

FIGURE 4.3-2

## GaAs DIGITAL FAILURE RATE MODEL

```
\lambdaD}=[(\mp@subsup{\lambda}{A}{}\piCA+\lambdap)+C2\piE]\piL\piQ \frac{failures}{1\mp@subsup{0}{}{6}\mathrm{ hours}
\lambda
\lambdaA}=\mathrm{ DIGITAL GaAs ACTIVE DEVICE BASE FAILURE RATE
#
\lambda
C}\mp@subsup{C}{}{\prime}\mp@subsup{\pi}{E}{}=\mathrm{ PACKAGE FAILURE RATE
\pi
#
```

$$
\begin{aligned}
\lambda_{A}= & \left.2.5303 \mathrm{e}^{-16220}{ }^{\left(\frac{1}{{ }^{T} C H}+273\right.}-\frac{1}{423}\right) \frac{\text { failures }}{10^{6} \text { hours }} ; E_{A}=1.4 \mathrm{ev} \\
\pi_{C A}= & 1.0 \text { FOR LESS THAN } 1000 \text { ACTIVE DEVICES (1) } \\
& 2.0 \text { FOR } 1000 \text { TO } 10,000 \text { ACTIVE DEVICES (2) }
\end{aligned}
$$

$$
\lambda_{p}=0.0687 \mathrm{e}^{-4980} \frac{\left(\frac{1}{T+273}-\frac{1}{423}\right) \frac{\text { failures }}{10^{6} \text { hours }} ; E_{A}=0.43 \mathrm{ev} . \mathrm{ev}}{}
$$

(1) THIS FACTOR INCLUDES SMALL SCALE AND MEDIUM SCALE INTEGRATION PARTS.
(2) THIS FACTOR INCLUDES LARGE SCALE INTEGRATION PARTS.

Table 4.3-5
GaAs Material and Process Comparison With Si

| MATERIAL PROPERTIES (300 K) | GaAs | Si | COMMENTS |
| :---: | :---: | :---: | :---: |
| $\begin{aligned} & \text { Electron } \\ & \text { Mobility } \\ & \left(\mathrm{cm}^{2} / \mathrm{v} . \mathrm{s}\right) \end{aligned}$ | 8500 | 1500 | GaAs has higher mobility (5.7 times) which translates to at least twice the speed of Si |
| Carrier Drift Velocity (cm/s) | $2.2 \times 10^{7}$ | $6.5 \times 10^{6}$ | GaAs has a faster switching speed. |
| Electric Field at Peak Electron Velocity (v/cm) | $7 \times 10^{3}$ | $3 \times 10^{4}$ | GaAs has potential for lower power dissipation. |
| Intrinsic Resistivity (ohm-cm) | $2.3 \times 10^{5}$ | $1 \times 10^{8}$ | A semi-insulating substrate for GaAs means no problems with oxide or junction isolation. |
| Energy Bandgap (ev) | 1.42 | 1.12 | GaAs has special optical properties and a better radiation tolerance. |
| ```Intrinsic Temp ( }\mp@subsup{}{}{\circ}\textrm{C}\mathrm{ at }1\mp@subsup{0}{}{13}\mp@subsup{\textrm{cm}}{}{-3 background concentration)``` | 300 | 130 | At more than twice the intrinsic temperature of Si, GaAs has potential to operate at higher temperatures. |
| Linear Coefficient of Thermal Expansion ( ${ }^{\circ} \mathrm{C}^{-1}$ ) | $6.86 \times 10^{-6}$ | $2.6 \times 10^{-6}$ | Thermal mismatches between materials will be a more difficult problem on GaAs. |
| Thermal Conductivity ( $\mathrm{W} / \mathrm{cm}^{\circ} \mathrm{C}$ ) | 0.46 | 1.5 | The higher thermal resistance (more than 3 times greater) of GaAs means that heat sinks are usually required and other thermal management issues are a serious concern. |
| Melting Point $\left({ }^{\circ} \mathrm{C}\right)$ | 1238 | 1415 | -- |


| Gable 4.3-5 (cont) |  |  |  |
| :---: | :---: | :---: | :---: |
| PROCESSING STEPS | GaAs | Si | COMMENTS |
| Transistor Structures | Schottky <br> Barrier | Bipolar \& MOS | GaAs MESFETs are free from the surface effects, ionic contamination, charge trapping, and time dependent dielectric breakdown problems seen in Si. |
| Metallization | $\begin{aligned} & \text { Au, Ti, Pt } \\ & \text { Based } \end{aligned}$ | $\begin{aligned} & \text { Al and } \\ & \text { Polysilicon } \\ & \text { Based } \end{aligned}$ | GaAs is less susceptible to the electromigration and corrosion mechanisms on Si products. |
| Native Oxide | None Stable | $\mathrm{SiO}_{2}$ | Construction of MOS devices and use of traditional processing techniques is not possible on GaAs. |
| Backside Processing | Required | Minimal | Thinner wafers and backside processing creates more handiling problems (breakage and damage) on GaAs. |


| NEC GaAs MMIC Failure Rates at $125^{\circ} \mathrm{C}$ (90) |
| :--- |
| QUALITY <br> LEVEL |
| JAN-S <br> Equivalent |
| 50 |



Table 4.3-8 GaAs Passive IC Element Failure Rates ${ }^{\text {(92) }}$

|  | failure rate at |  |  |
| :---: | :---: | :---: | :---: |
| PASSIVE INTEGRATED | $150^{\circ} \mathrm{C}$ derated to | COMPONENT | COMPONENT |
| CIRCUIT ELEMENT | 75\% CURRENT LEVEL | USE ON MMIC | USE ON DIGITAL |
|  |  |  |  |
| Implanted Resistors |  |  |  |
| and Ohmic Contacts | $6.62 \times 10^{-8}$ | $x$ | X |
|  |  |  |  |
|  |  |  |  |
| Thin Film Resistors |  |  |  |
|  | $1.29 \times 10^{-7}$ | $x$ |  |
|  |  |  |  |
|  |  |  |  |
| First Level |  |  |  |
| Metallization | $2.48 \times 10^{-9}$ | $x$ | $x$ |
|  |  |  |  |
|  |  |  |  |
| Air Bridge |  |  |  |
| Metallization | $2.86 \times 10^{-8}$ | $x$ |  |
|  |  |  |  |
|  |  |  |  |
| Composite Passive |  |  |  |
| Failure Rates | - -- | $2.26 \times 10^{-7}$ | $6.87 \times 10^{-8}$ |
|  |  |  |  |

Table 4.3-9
GaAs MMIC \& Digital Base Failure Rate Table
(Failures/Million Hours)

|  | GaAs MMIC | GaAs DIGITAL IC |  |  |
| ---: | :---: | :---: | :---: | :---: |
| $T_{\text {CHANNEL }}$ | $\lambda_{A}$ | $\lambda_{P}$ | $\lambda_{A}$ | $\lambda_{P}$ |
| $\left.{ }^{\circ} \mathrm{C}\right)$ |  |  |  |  |
| 25 | $0.0000^{*}$ | 0.0016 | $0.0000^{*}$ | 0.0005 |
| 35 | $0.0000^{*}$ | 0.0028 | $0.0000^{*}$ | 0.0008 |
| 45 | $0.0000^{*}$ | 0.0046 | $0.0000^{*}$ | 0.0014 |
| 55 | $0.0000^{*}$ | 0.0075 | $0.0000^{*}$ | 0.0023 |
| 65 | $0.0000^{*}$ | 0.0117 | 0.0002 | 0.0036 |
| 75 | $0.0000^{*}$ | 0.0179 | 0.0007 | 0.0054 |
| 85 | 0.0003 | 0.0267 | 0.0024 | 0.0081 |
| 95 | 0.0010 | 0.0389 | 0.0082 | 0.0118 |
| 105 | 0.0034 | 0.0557 | 0.0263 | 0.0169 |
| 115 | 0.0111 | 0.0782 | 0.0796 | 0.0237 |
| 125 | 0.0341 | 0.1080 | 0.2275 | 0.0328 |
| 135 | 0.0995 | 0.1468 | 0.6178 | 0.0445 |
| 145 | 0.2757 | 0.1966 | 1.5993 | 0.0596 |
| 155 | 0.7283 | 0.2597 | 3.9605 | 0.0788 |
| 165 | 1.8406 | 0.3387 | 9.4095 | 0.1028 |
| 175 | 4.4633 | 0.4367 | 21.5088 | 0.1325 |

* Value carried to four places only

GaAs MMIC

$$
\begin{aligned}
& \text { MMIC } \\
& \left.\lambda_{A}=0.4506 \mathrm{e}^{-17380}{ }^{\left(\frac{1}{T C H}+273\right.}-\frac{1}{423}\right) \\
& \lambda_{P}=0.2263 \mathrm{e}^{-4980} \frac{\left(\frac{1}{\mathrm{~T}+273}-\frac{1}{423}\right)}{}
\end{aligned}
$$

GaAs Digital IC

$$
\lambda_{A}=2.5303 \mathrm{e}
$$

$$
\lambda_{p}=0.0687 \mathrm{e}
$$

$$
e^{-16220} \begin{aligned}
& \left(\frac{1}{T^{T} C H+273}-\frac{1}{423}\right) \\
& -4980\left(-\frac{1}{T+273}-\frac{1}{423}\right)
\end{aligned}
$$

### 4.4 HYBRIDS

### 4.4.1 Database

The data collected came from two sources: field data on the APG-68 radar system, and data from life testing conducted both in-house and in the industry. Table 4.4-1 lists the hybrid part types used on the APG-68 radar and the cumulative removal rate based on 263,990 hours of system operation over the period studied.

Table 4.4-2 lists the data collected from the life tests. Part of this data was collected as the result of the survey conducted. Both 1000 hour life (extended burn-in) and extended temperature cycling tests are included.

Table 4.4-1 APG-68 Hybrid Cumulative Removal Rate
(Nov 1984 - June 1988)

| PART NUMBER | NAME | CLASS | $\begin{aligned} & \text { QTY } \\ & \text { USED } \\ & \text { ISYS } \\ & \hline \end{aligned}$ | QTY REMOVED | $\begin{gathered} \text { CUMULATIVE } \\ \text { FIELD } \\ \text { REMOVAL RATE } \\ \text { (/MILLION HRS) } \\ \hline \end{gathered}$ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 583R379A01 | Digibus | Digital | 3 | 49 | 61.87 |
| 585R927A02 | Dumped Intg. | Digital | 2 | 14 | 26.52 |
| 585R928A02 | RAM | Digital | 2 | 9 | 17.05 |
| 586R291A01 | $\mu \mathrm{P} / \mathrm{RAM}$ | Digital | 1 | 1 | 3.79 |
| 586R517AO1 | Mux | Digital | 1 | 8 | 30.30 |
| 12604356 | 10 Bit D/A | Linear | 2 | 5 | 9.47 |
| 583R352HOI | A/D | Linear | 1 | 15 | 56.82 |
| 583R505HOI | D/A | Linear | 1 | 117 | 443.18 |
| 583R979HOI | D/A | Linear | 2 | 4 | 7.58 |
| 585R056HOI | S/D Conv | Linear | 1 | 20 | 75.76 |
| 585R150A03 | SW Driver | Linear | 1 | 32 | 121.21 |
| 585R209A01 | BORAM I/O | Linear | 20 | 61 | 11.55 |
| 585R587A0 1 | Timing | Linear | 1 | 95 | 359.85 |
| 585R588HO1 | A/D | Linear | 1 | 116 | 439.39 |
| 585R972HOI | D/A | Linear | 2 | 12 | 22.73 |
| 585R974H02 | S/D | Linear | 2 | 7 | 13.26 |
| 586R290A01 | RAM I/O | Linear | 1 | 60 | 227.27 |
| 586R292A01 | Monitor | Linear | 1 | 10 | 37.88 |
| 635A870H01 | A/D | Linear | 1 | 0 |  |
| 583R407H01 | Buffer | Linear | 2 | 31 | 58.71 |

Table 4.4-1 APG-68 Hybrid Cumulative Removal Rate (contd.)
(Nov 1984 - June 1988)

| PART <br> NUMBER | NAME | CLASS | QTY USED ISYS | QTY REMOVED | ```CUMULATIVE FIELD REMOVAL RATE (/MILLION HRS)``` |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 583R412HO1 | Amp | Linear | 2 | 9 | 17.05 |
| $583 \mathrm{R} 495 \mathrm{HO2}$ | Volt. Ref. | Linear | 1 | 0 |  |
| 584RO32H03 | Driver | Linear | 1 | 0 |  |
| 584 R 353 HO 3 | Amp | Linear | 1 | 2 | 7.58 |
| 584R353H04 | Amp | Linear | 1 | 12 | 45.45 |
| 584 R 548 HO 3 | Sample/Hold | Linear | 2 | 41 | 77.65 |
| 585R149A02 | Control | Linear | 1 | 19 | 71.97 |
| 583R504H04 | Reg-5V, 3. 5A | PHP | 2 | 19 | 35.98 |
| 583R504H23 | Reg-5V,2V, 19A | PHP | 1 | 13 | 49.24 |
| 583R504H24 | Reg-15V, 9.5A | PHP | 1 | 14 | 53.03 |
| 583R511H12 | Reg--5.3V, 29A | PHP | 1 | 32 | 121.21 |
| 583R511H13 | Reg--15V,4.4A | PHP | 1 | 5 | 18.94 |
| 583 R 512 HO | Reg-+15V, -15V,2A | PHP | 3 | 26 | 32.83 |
| 583R512H10 | Reg-28V, 3A | PHP | 1 | 15 | 56.82 |
| 583R520H03 | Reg-15V,0.5A | PHP | 5 | 23 | 17.42 |
| 584R550A04 | INV, PreReg | PHP | 2 | 138 | 261.36 |
| 584R551A04 | INV, Bridge | PHP | 2 | 124 | 234.85 |
| 585R151A03 | Reg-20V, 1.5A | PHP | 1 | 9 | 34.09 |
| 586R508A01 | Reg- | PHP | 1 | 8 | 30.30 |
| 586R509A02 | Reg-2.75V | PHP | 1 | 6 | 22.73 |
| 586R509A03 | Reg-5.45V, 21A | PHP | 1 | 13 | 49.24 |
| 12604360-6 | Switch | uwave | 1 | 7 | 26.52 |
| 583R405H01 | Switch | uwave | 2 | 19 | 35.98 |
| 583R405H02 | Switeh | uwave | 1 | 2 | 7.58 |
| 584 R 422 HO 1 | Switch | uwave | 1 | 4 | 15.15 |
| 585R736H04 | Amp | uwave | 2 | 11 | 20.83 |
| 585R736H05 | Amp | uwave | 1 | 8 | 30.30 |
| 585R736H09 | Amp | uwave | 1 | 4 | 15.15 |
| 12604361-1 | Switch | Video | 1 | 0 |  |
| 12604427 | Amp | Video | 2 | 16 | 30.30 |
| 583R154HI6 | Amp | Video | 5 | 16 | 12.12 |
| 583R154H30 | Amp | Video | 1 | 2 | 7.58 |
| 583R154H31 | Amp | Video | 3 | 5 | 6.31 |
| 583R154H53 | Amp | Video | 2 | 7 | 13.26 |
| 583R154H56 | Amp | Video | 4 | 9 | 8.52 |
| 583R154H61 | Amp | Video | 5 | 6 | 4.55 |
| 583R161H21 | Amp | Video | 1 | 11 | 41.67 |
| 584R213HO1 | Switch | Video | 2 | 2 | 3.79 |





$$
\begin{gathered}
\text { Table 4. } \\
\text { Life Test }
\end{gathered}
$$

| COMMENTS |
| :--- |
| Teledyne |
| Teledyne |
| Teledyne |
| Teledyne |
| Teledyne |
| Teledyne; improper |
| test, TC $=200^{\circ} \mathrm{C}$ |
| Teledyne |
| Teledyne |
| Teledyne; PR 1216; |
| improper test, |
| TC $=200^{\circ} \mathrm{C}$ |
| Teledyne |
| Teledyne |
| Teledyne |
| Teledyne |
| WEC |
| Solitron |
| WEC |
| WEC, FA M30487 |
| Solitron |
| WEC |
| WEC, FA M24087 |
| Leads damaged due |
| to mishandling |
| WEC, FA M20287 |
| WEC, Test terminated |
| e 675 |
| WEC, FA M00 188 |
| WEC |
| WEC |
| WEC, FA M18387 |





| $\because$ |  |  |
| :---: | :---: | :---: |
| $\cdots$ | $\pm$ |  |
| $\stackrel{\sim}{\square}$ | \% |  |
| $\stackrel{E}{\stackrel{E}{\oplus}}$ | $\begin{aligned} & \text { O} \\ & 0 \end{aligned}$ |  |
| $\frac{3}{4}$ | $\underset{\Xi}{\stackrel{\text { ® }}{ \pm}}$ | - |

光 $N$ ๓

$\stackrel{n}{\square}$
0
1 @ 15 shock



| TYPE |
| :--- |
| Digital |
| Linear |
| Video Anp |
| Linear |
| Linear |
| Digital |
| Digital |
| Digital |
| Digital |
| Digital |
| Linear |
| Digital |
| Digital |
| Power Inv |
| Power Inv |
| Power Inv |
| Power Inv |
| Power Inv |
| Power Inv |
| Linear |
| Linear |
| Linear |
| Linear |
| Linear |
| Linear |

COMMENTS
WEC, FA M26187
WEC, FA M29287
WEC, FA M14687
WEC
WEC
WEC
WEC
WEC
WEC, FA M26787
Anaren
WEC
Q-Bit, No failures atter
Insulation change
Q-Bit
Q-Bit
Anaren
Anaren
Anen
Table $4.4-2($ contd $)$

| FAILURE MECHANISM |  | TEST CONDITIONS |
| :--- | :--- | :--- |
| Cracked solder |  | Temp Cycle/Thermal Shock |
| lidseal |  | 115 Cycles |
| Substrate attach |  | 3000 Hr. Life, T $=125^{\circ} \mathrm{C}$ |
| Overstressed in test | Temp Cycle/Thermal Shock |  |
|  |  | 1120 Cycles |

Iemp Cycle/Thermal Shock
115 Cycles
Temp Cycle/Thermal Shock
115 Cycles
Temp Cycle/Thermal Shock
115 Cycles
Temp Cycle/Thermal Shock 115 Cycles 1000 Hr. Lite, $\mathrm{T}=125^{\circ} \mathrm{C}$

1000 Hr. Life, $T=125^{\circ} \mathrm{C}$
1000 Hr. Life, $T=125^{\circ} \mathrm{C}$

Life Test, $I=125^{\circ} \mathrm{C}$
Life Test, $1=125^{\circ} \mathrm{C}$
Life Test, $T=125^{\circ} \mathrm{C}$
Life Test, $T=125^{\circ} \mathrm{C}$



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yoous si el

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Power Reg
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Power Reg 586R509A03
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### 4.4.2 Model Development

The present version of the hybrid model as it appears in MIL-HDBK-217E is unnecessarily complex. It invokes failure rate dependency on the number of interconnects within the hybrid, the failure rates of the chips and film resistors, the substrate density, the seal perimeter and several multipliers. Some of the equations - such as the one indicating a temperature-dependence of the seal failure rate - have no physical basis. Therefore, the current effort has focused on simplifying the model while retaining reasonable accuracy. The new model presents the early life failure rate as being equal to the sum of the chip failure rates multiplied by $\pi$ factors. The contributions due to wearout mechanisms are computed separately. The preliminary form of the model is therefore:

$$
\begin{equation*}
\lambda=\left[\lambda_{C}+\lambda_{S}\right] \pi_{i} \cdots \pi_{n} \tag{4.4.1}
\end{equation*}
$$

See Sections 4.1-4.3 for VLSI chip failure rate calculations and 4.5 for packaging models. For all other semiconductor devices, the models in MIL-HDBK-217E are to be used. The chip capacitor model in MIL-HDBK-217E is to be used also.

No contributions to the hybrid failure rate from resistors, either chip or substrate, are considered. These failure rates are considered insignificant based on failure analysis experience and the life test data available. Published data on field reliability for hybrids (a paper published in the 1984 ISHM Proceedings, "Demonstrated Field Failure Rate for Custom Hybrids" by Murphy and Sainer, page 95) showed the failure rates for chip and substrate resistors to be 0.0008 and 0.000053 failures per million hours at $99 \%$ C.L.

The $\pi_{G}$ factor has been eliminated from the model. The additional process steps and handling that the die are exposed to during the construction of a hybrid compensate for any reduction in failure rate due to the absence of the discrete package.

The package failure rate, as explained in section 4.5 , is comprised of a base failure rate and failure rates which represent several wearout mechanisms. The
base package failure rate for hybrids. $\lambda_{S}$, is represented as being equal to a percentage of the total failure rate. The basis for this is that several studies have shown that packaged related failures represent approximately $40 \%$ of the total hybrid failures. MDR 14, "Hybrid Circuit Data, Winter 79/80" 1 ists $40.6 \%$ of the field failures and $45.2 \%$ of the equipment test failures as being caused by package related defects. The previously referenced paper, "Demonstrated Field Failure Rate for Custom Hybrids" lists $39 \%$ of the verified hybrid failures to be package related. Furthermore, $40 \%$ is consistent with the percentage of hybrid failures attributable to package failures at Westinghouse. If the percentage of package failures is represented as $K$, then

$$
\begin{align*}
\lambda & =\left[\lambda_{C}+\frac{K}{1-K} \lambda_{C}\right] \pi_{i} \ldots \pi_{n}  \tag{4.4.2}\\
& =\left[\lambda_{C}\left(1+\frac{K}{1-K}\right)\right] \pi_{i} \ldots \pi_{n}
\end{align*}
$$

Since the system environment will accelerate the failure of devices with point defects, an environmental factor is necessary to modify the base package failure rate.

To determine the relationship between the portion of failures due to package defects and the application environment, the data in MDR-14 was grouped by the application environment. The results are shown in Table 4.4-3 below.

Table 4.4-3: MDR-14 Data Summary

A relationship of $K=0.2 \pi_{E}$ was established by plotting the data. The general form of the model now becomes

$$
\begin{equation*}
\lambda=\left[\lambda_{C}\left(1+.2 \pi_{E}\right)\right] \pi_{i} \cdots \pi_{n} \tag{4.4.3}
\end{equation*}
$$

It is our experience that, excluding secondary failures and erroneous removals,
the majority of hybrid failures experienced during life testing and field usage are caused by process related defects such as die attach and wire bonding. Therefore, the sum of the chip and package failure rates are multiplied by factors which are related to the difficulty of the process $\left(\pi_{F}\right)$, the experience with the process ( $\pi_{L}$ ), and the degree of screening employed to remove process related defects ( $\pi_{Q}$ ).

The final form of the model is

$$
\begin{equation*}
\lambda_{P}=\left[\sum \lambda_{C} N_{C}\left(1+.2 \pi_{E}\right)\right] \pi_{Q} L^{\pi}{ }^{\pi} F \tag{4.4.4}
\end{equation*}
$$

where:
$\lambda_{C}$ is the chip failure rate
$N_{C}$ is the number of each chip
$\pi_{Q}$ is the quality factor
$\pi_{F}$ is the circuit function factor
$\pi_{L}$ is the learning factor

The quality factor will be determined as detailed in section 4.6.l, the learning factor will be determined as detailed in section 4.6.2, and the function factor will be determined as detailed in section 4.6.3.

Additionally, the end of life package models of section 4.5 should be used to assess the mean time to failure (or cycles to failure) for the hybrid package, including the wirebonds, substrate and die attach, and hermeticity.

### 4.4.3 Chip Junction Temperature Calculation

Since the hybrid model is so heavily dependent upon the failure rates of the chips, it is imperative that the operating junction temperatures be calculated accurately. The best way to do this is through actual measurement (thermal survey) or finite element analysis, but this may not be practical for the reliability analyst. The following is a reasonable alternative for estimating the operating junction temperatures of the chips in a hybrid device.

A hybrid is normally made up of one or more substrate assemblies mounted within a sealed package. Each substrate assembly consists of active and passive chips with thick or thin film metallization mounted on the substrate, which in turn may have multiple layers of metallization and dielectric on the surface. Figure 4.4-1 is a cross-sectional view of a hybrid with a single multi-layered substrate. The layers within the hybrid are made up of various materials with different thermal characteristics. Table $4.4-4$ provides a list of commonly used hybrid materials with typical thicknesses and corresponding thermal conductivities (K). The thermal resistance of each layer is determined by the expression.
$\theta=(1 / K)(L / A)$, where:
$\theta$ is the thermal resistance of a layer in ${ }^{\circ} \mathrm{C} /$ Watt $\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right)$.
$K$ is the material thermal conductivity from Table 4.4-4 (or user provided).
$L$ is the material thickness in inches from Table 4.4-4 (or user provided).
$A$ is the top surface area of the chip (user provided).

An estimated thermal resistance value for junction to case ( $\theta_{J C}$ ) can be developed for each chip in the hybrid by summing the resistances of all- the material layers of the hybrid structure from the chip down to the case:
$\theta_{J C}=\frac{\sum_{i=1}^{n}\left(1 / K_{i}\right) L_{i}}{A}$,
where $n$ is the number of material layers. Then,
$T_{J}=T_{C}+0.9\left(\theta_{J C}\right)\left(P_{D}\right)$, where
$T_{J}$ is the junction temperature of the chip $\left({ }^{\circ} \mathrm{C}\right)$
${ }^{T} C$ is the case temperature of the hybrid $\left({ }^{\circ} \mathrm{C}\right)$
$\theta_{J C}$ is defined as above ( ${ }^{\circ} \mathrm{C} / \mathrm{W}$ ), and
$P_{D}$ is the power dissipated by the chip (W)

The factor of 0.9 in equation 4.4 .7 represents the cosine of $26^{\circ}$. This angle accounts for the fact that the heat is not all conducted vertically from the chip to the case, but rather "spreads" radially as well as downward.

Figure 4.4-1


Table 4.4-4 Hybrid Materials

| MATERIAL |  | TYPICAL | FEATURE FROM | K |
| :---: | :---: | :---: | :---: | :---: |
|  | TYPICAL USAGE | THICKNESS (") | FIGURE 4.4-1 | $\left(\mathrm{W} /{ }^{\circ} \mathrm{C}-\mathrm{in}\right)$ |
|  |  |  |  |  |
| Silicon | chip device | 0.01 | A | 2.20 |
| GaAs | chip device | 0.007 | A | 0.76 |
| Au Eutectic | chip attach | 0.0001 | B | 6.91 |
| Solder | chip/substrate attach | 0.003 | B/E | 1.27 |
| Epoxy (diel) | chip/substrate attach | 0.0035 | $B / E$ | 0.006 |
| Epoxy | chip attach | 0.0035 | B | 0.15 |
| (conductive) |  |  |  |  |
| Thick film dielectric | glass insulating | 0.003 | c | 0.66 |
|  | layer |  |  |  |
| Alumina | Substrate, MHP | 0.025 | D | 0.64 |
| BeO | Substrate, PHP | 0.025 | D | 6.58 |
| Kovar | Case, MHP | 0.02 | F | 0.425 |
| Aluminum | Case, MHP | 0.02 | F | 4.58 |
| Copper | Case, PHP | 0.02 | F | 9.96 |

### 4.5 FAILURE MECHANISMS OF MICROELECTRONIC PACKAGES

### 4.5.1 Introduction

The non-electrical failure mechanisms of microelectronic device can be classified into package related failures, die failures and failures due to interconnects. Based on data from MDR-21, die failures constitute about $25-30 \%$ of the total failures, the package accounts for $40-50 \%$ of the failures, and interconnects involve $20-30 \%$ of the non-electrical failures in microelectronic packages.

In this section of this report we are concerned with package, interconnect and thermo-mechanical die, die attach and substrate attach failures. The package related failure sites include the package seal, package lid, package body, the lead frame, external leads and the package encapsulant. The die failure sites include the die, the die attach and the substrate attach. The interconnect failure sites include the wire, the wire bond and the conductor paths in the die and the substrate.

For simplicity we define all these failures as package failures. Package failures can be divided into two categories. The first includes failures that result from poorly controlled or poorly designed manufacturing processes. The second category consists of the failures caused during the normal operation of the device. This approach is justified when failures in the first category are removed during quality control inspection and screening processes. The package modeling effort has concentrated on the latter category, and the derived models are deterministic in nature.

In general, early and middle life failures are premature failures where causes can be "assigned" to specific defects or events. The early life failures typically exhibit a greater failure rate than do middle life failures. End of life failures are considered "common cause" failures. These failures are attributable to wire bond failure mechanisms, corrosion related failure mechanisms, and die attach related failure mechanisms.

MIL-HDBK-217E and its predecessors only consider assignable cause failures in the development of prediction models, since common cause failures do not typically occur within the life-times of military systems. The $C_{2} \pi_{E}$ term as presented in Table 5.1.2.7-6 of MIL-HDBK-217E will continue to be used for the early and middle life failure predictions for the different package types. In addition, the pin grid array (PGA) package has been added to this table under the column "Hermetic Dual-In Line Package (DIP) with Solder weld Seal."

For the most part, the DIP pin counts are in the 14 to 18 leads range ( 80 percent of devices produced annually) with the balance going up to 64 leads. However, when more than 40 external pins are needed, the conventional DIP becomes impractical because of increased internal density, pin spacing, increased weight and thermal limitations. At this point, the PGA becomes more practical, typically having pin counts of 14 or more, with 128,224 and 525 being common variants, reference [98].

The justification for including the PGA packages with the DIP and LCC packages may be reviewed in references [99 and 100]. Briefly, it has been observed that the PGA packages are on a par with the industry standard DIP as to reject rate and failure modes during equivalent environmental screening. Many thousands of these packages have been tested by several different vendors. The recorded data indicate that the same controls and assembly techniques used for DIP's have been successfully transferred to PGA's with similar reliable results. Furthermore, no new failure modes characteristic to these packages have emerged. The thermal performance (junction to case thermal resistance) of a PGA package is equal to or less than that for a DIP, when selected package material, chip attach material, and heatsink attach epoxy and heatsink configurations are employed. The use of "fin" heatsinks configurations and aluminum-filled heatsink-attach epoxy with a lower bulk thermal resistance have produced thermal resistances less than $6^{\circ} \mathrm{C} /$ watt in PGA applications.

Therefore, based on these facts it would appear that the logical choice is to include the PGA packages under the DIP column in the $C_{2}$ table.

In the following paragraphs we discuss the end of life, or wearout, failure mechanisms and failure life models for the package, the interconnects and the die due to mechanical, thermo-mechanical and other environmental stresses.

Mathematical models developed used material properties which were in some cases estimated due to lack of experimental data. The accuracy of the models can be improved by using properties obtained from more extensive experiments on the material properties.

The failure prediction models recommended in this report can be described in generic terms as power law relationships between the mean cycles to failure and the local state of stress/strain in the specimen. This approach can be implemented either for crack initiation, as in Basquin's or Coffin-Manson equations, or for fatigue crack propagation, as in Paris's power law. The latter method is preferred when the material is likely to experience brittle crack propagation. In either situation the stress amplitude in the specimen has to be monitored and expressed in terms of the fatigue life of the material. Estimating the stress amplitude in the specimen can be a non-trivial task and needs a numerical scheme such as the finite element method. However, since the aim of the failure models cited below is to identify simple closed-form expressions for quick, on-line stress/strain analysis and for fatigue failure predictions, only approximate models are presented, with appropriate simplifications. For more accurate stress analysis, the user will need to employ the finite element or other appropriate numerical methods.

It is reiterated at this point that the accuracy of all the models depends on the simplifying assumptions about the material properties and associated constitutive equations. Due to the lack of appropriate data on electronic materials, simplified linear elastic behavior has been assumed in many cases, and the temperature dependence of all the material properties is ignored. It is clearly understood that material property data is essential for accurate life predictions and it is recommended that an extensive experimental program be undertaken to determine all the required data.

### 4.5.1.1 Wire-Wire Bond Related Failure Mechanisms

Fatigue is the dominant phenomenon causing the failure of the wire bond during normal life of microelectronic devices. Temperature and electrical power cycling can induce failure of the bond due to flexure and shear fatigue.

Repeated flexure of the wire due to temperature cycling can cause cracking of the wire at the heel due to bending fatigue. The differential thermal expansion of the bond pad and the substrate can result in a detachment of the bond pad from the substrate or the cracking of the substrate as a result of stresses generated. The differential thermal expansion between the bond pad and the wire can cause shear fatigue of the bond pad resulting in detachment of the wire from the substrate or cratering of the substrate. In plastic encapsulated packages, differential thermal expansion between the encapsulant and the wire can cause axial fatigue of the wire, resulting in tensile fatigue failure of the wire.

### 4.5.1.2 Corrosion Related Failure Mechanisms

Moisture and other contaminants can ingress into a package through flaws in the construction material or permeation through the wall of the package. Moisture can also be inherently trapped in the cavity of the package before being sealed. An extreme drop in temperature will cause the sealed cavity to attain its dew point and the moisture can condense on the surface of the chip and the wire bond. The condensed vapor together with other ionic contaminants will form an electrolyte for the transfer of ions essential for the wet corrosion process to occur.

The use of a passivation layer on integrated circuits has greatly reduced the corrosion problem although an imperfect passivation layer would promote pitting and eventually lead to corrosion of the metallization. In addition, due to the necessity of wire bonding, bond pads remain unpassivated and consequently are exposed to the package environment. Bond wires and bonds between dissimilar metal bond wires and bond pads or lead frames are
especially susceptible to corrosive attack. In practice, the die and die attach are not significantly affected by corrosion.

### 4.5.1.3 Die Related Failure Mechanisms

Another failure site in the microelectronic packages is the die assembly consisting of the die, die attach and the substrate attach. The major concern here is the mechanical failure, fracture and fatigue of the die die attach and substrate attach. Thermal stresses are induced in the die, the substrate and the case as a result of temperature fluctuations. Typically, microcracks present on the top surface or edges of the die or the edges of the die attach or the substrate attach can propagate under the influence of thermal stresses produced due to temperature cycling. This can cause the failure of the die due to horizontal or vertical cracking. A vertical crack is the result of large tensile stresses in the central portion of the top surface of the die. A horizontal crack of the die is the result of high shear stresses at the edges of the die. A failure of the die attach or the substrate attach is often the result of the presence of voids or microcracks near the edges, which propagate towards the center resulting in failure of the attach.

The die attach and substrate attach models delineated herein assume that the attach failure occurs in the bulk of the attach material. Each attach material forms an adhesive bond to the adjacent layer, i.e., an adhesive bond is formed between the die and the die attach and between the substrate and the die attach. Similarly, adhesive bonds are formed between the substrate attach and the adjacent substrate and package base surfaces. Failure of these adhesive bonds is not addressed in this report because it is felt that such failures are fabrication process related and will be detected during screen testing.

### 4.5.2 Fatigue Failure Models of Wire and Wire Bonds

### 4.5.2.1 Description of the Models

Failure of the wire bond occurs predominantly as a result of fatigue caused by
repeated flexure of the wire, shear stresses generated between the bond pad and the wire and shear stresses generated between the bond pad and the substrate, all resulting from temperature or power cycling.

Flexure of the wire will produce stresses at the heel of the bond in the case of wedge bonds and stitch bonds. Reversals in the bending stresses cause the eventual fatigue (breakage) of the wire at the heel. Due to the absence of any reduced section on the ball bond, failure due to flexure is uncommon for the ball bonds.

Shear stresses between the bond pad and the substrate result from the differences in the coefficients of thermal expansion between the substrate and the bond pad. This in turn results in the eventual detachment of the bond pad from the substrate, an increase in the thermal resistance between the die and the substrate, or the cratering of the substrate.

Shear stresses between the wire and the bond pad result from the differential thermal expansion between the wire and the substrate.

In encapsulated packages, if the encapsulant is in contact with the wire, the differential thermal expansion between the encapsulant and the wire can cause axial fatigue of the wire. This failure mechanism will not occur in encapsulated packages with a low modulus buffer coating between the wire and the encapsulant.

The number of cycles to failure of the wires and wire bonds in a microelectronic package depends on the environmental conditions, the geometry of the wire bond and the materials of the substrate, wire and bond pad. The fatigue failure prediction models take into account the environmental conditions and the geometry of the bond, which is consistent with the fact that the number of failures vary with the environmental conditions to which the wire bond is subjected. The stresses generated are a function of the geometry of the wire bond, the temperature fluctuation and the material properties.

The development of the models for wire and wire bond failure mechanisms are more fully discussed in Appendix $F$.

### 4.5.2.2 Wire and Wire Bond Failure Models

As discussed in 4.5.2.1, models have been developed for one bond wire and two bond pad failure mechanisms, as follows:

## (1) Bond Wire Flexure Fatigue

The model for the number of cycles to flexure fatigue failure is defined by equation F5.8 as follows:

$$
\begin{equation*}
N_{f(f l e x)}=A_{1}\left(\varepsilon_{f}\right)^{n_{1}} \tag{F5.8}
\end{equation*}
$$

where:
$N_{f(f l e x)}$ is the number of cycles to failure for the wire in flexure.
$A_{1}$ is a material property dependent coefficient for the wire material obtained from Table 4.5-4.
$N_{1}$ is a material property dependent exponent for the wire material obtained from Table 4.5-4.
$\varepsilon_{f}$ is the wire strain magnitude and is defined by equation F5.7a as follows:

$$
\begin{equation*}
\varepsilon_{f}=\frac{r}{35.1}\left|\frac{\operatorname{Cos}^{-1}\left(0.966\left(1-\left(\alpha_{w}-\alpha_{s}\right) \Delta T\right)\right)}{15}-1\right| \tag{F5.7a}
\end{equation*}
$$

where:
$r$ is the radius of the wire, mm .
$\alpha_{w}$ is the coefficient of thermal expansion of the wire obtained from Table 4.5-1.
$\alpha_{s}$ is the coefficient of thermal expansion of the substrate obtained from Table 4.5-2.
$\Delta T$ is the temperature difference obtained from Table 4.5-17.

## (2) Shear Fatigue at Bond Pad/Substrate Interface

The model for the number of cycles to shear fatigue fallure is defined by equation F 5.10 as follows:

$$
\begin{equation*}
N_{f(\text { shear }) s}=A_{2}\left(\varepsilon_{f s}\right)^{n_{2}} \tag{F5.10}
\end{equation*}
$$

where:
$N_{f(s h e a r) s}$ is the number of cycles to failure in shear at the bond
pad/substrate interface.
$A_{2}$ is a material property dependent coefficient for the bond pad material obtained from Table 4.5-5.
$n_{2}$ is a material property dependent exponent for the bond pad material obtained from Table 4.5-5.
$\varepsilon_{f}$ is the bond pad shear strain magnitude and is defined by equation 55.9 as follows:

$$
\begin{equation*}
\varepsilon_{f s}=K \Delta T \tag{75.9}
\end{equation*}
$$

where:
$K$ is a constant for a particular pad/substrate combination obtained from Table 4.5-6.
$\Delta T$ is the temperature difference encountered, obtained from Table 4.5-17.
(3) Shear Fatigue at Bond Pad/Wire Interface

The model for the number of cycles to shear fatigue failure at the bond pad/wire interface is identical to the model for shear fatigue failure at the bond pad/substrate interface and is defined by equation 55.10 as follows:

$$
\begin{equation*}
N_{f(\text { shear }) w}=A_{2}\left(\varepsilon_{f s}\right)^{n_{2}} \tag{F5.10}
\end{equation*}
$$

where:
$N_{f(s h e a r) w}$ is the number of cycles to failure for the wire in shear at the bond pad/wire interface.
$A_{2}$ is a material property dependent coefficient for the wire material obtained from Table 4.5-5.
$n_{2}$ is a material property dependent exponent for the wire material obtained from Table 4.5-5.
$\varepsilon_{f}$ is the wire shear strain magnitude and is defined by equation F5.14 as follows:

$$
\begin{equation*}
\varepsilon_{f s}=(1 / 2)\left|\alpha_{w}-\alpha_{s}\right| \Delta T \tag{F5.14}
\end{equation*}
$$

where:
$\alpha_{w}$ is the coefficient of thermal expansion of the wire obtained from Table 4.5-1.
$\alpha_{s}$ is the coefficient of thermal expansion of the substrate obtained from Table 4.5-2.
$\Delta T$ is the temperature difference encountered by the component obtained from Table 4.5-17.
4.5.2.3 Application Examples for Wire/Wire Bond Failure Models
(1) Bond Wire Flexure Fatigue
(A) Assume a microcircuit with a Represetative Microcircuit Configuration (RMC) as defined in paragraph 4.5.6 and used in a MIL-HDBK-217 ground-fixed ( $G_{F}$ ) application environment. Then the mean number of cycles to failure due to bond wire flexure fatigue is found from equations F5.7a and F5.8, which are combined following:

$$
N_{f(f l e x)}=A_{1}\left\{\frac { r } { 3 5 . 1 } \left[\frac{\left.\left.\cos ^{-1} \frac{\left(0.966\left(1-\left(\alpha_{W}-\alpha_{S}\right) \Delta T\right)\right)}{15}-1\right]\right\}^{n_{1}} \quad(F 5.7 \mathrm{a}}{\&}\right.\right.
$$

The variables in this equation are defined in paragraph 4.5.2.2(1) and data are obtained from the following sources:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $A_{1}$ | $3.9323 \times 10^{-10}$ | N/A | Table 4.5-4 |
| $n$ | -5.134 | N/A | Table 4.5-4 |
| r | $1.6 \times 10^{-2}$ | mm | RMC-Para 4.5.6 |
| $\alpha_{w}$ | $23.2 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-1 |
| $\alpha_{s}$ | $4.67 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-2 |
| $\Delta T$ | 55 | ${ }^{\circ} \mathrm{C}$ | Table 4.5-17 |

Substituting in equations F5.7a and F5.8:
$\left.N_{f(f l e x)}=3.9323 \times 10^{-2}\left\{\frac{1.6 \times 10^{-2}}{35.1} \frac{\left[\operatorname{Cos}^{-1}\left(0.966\left(1-\left(23.2 \times 10^{-6}-4.67 \times 10^{-6}\right) 55\right)\right)\right.}{15}-1\right]\right\}^{5.134}$
$=5.6 \times 10^{7}\left[\frac{\operatorname{Cos}^{-1}(0.9650155011)-1}{15}\right]^{-5.134}$ $=2.357 \times 10^{17}$ cycles
(B) Assume the same conditions as paragraph 4.5.2.3(1)(A) except bond wire diameter is $0.127 \mathrm{~mm}(5 \mathrm{mils})$. Then $r=0.127 / 2=6.35 \times 10^{-2} \mathrm{~mm}$ and all other variables remain the same. Substituting in equations $F 5.7 a$ and F5.8:

$$
\begin{aligned}
N_{f(f l e x)} & \left.=3.9323 \times 10^{-10} \frac{\left\{6.35 \times 10^{-2}\right.}{35.1}\left[\frac{\cos ^{-1}\left(0.966\left(1-\left(23.2 \times 10^{-6}-4.67 \times 10^{-6}\right) 55\right)\right)}{15}-1\right]\right\}^{-5.134} \\
& =1.987 \times 10^{14} \text { cycles }
\end{aligned}
$$

(C) Assume the same conditions as 4.5.2.3(1)(B) except bond wire material is gold. Then $A_{1}=3.5844 \times 10^{-11}$ and $n_{1}=-4.9828$ from Table 4.5-4, and all other variables remain the same. Substituting in equations F 5.7 a and F5.8:

$$
\begin{aligned}
N_{f(f l e x)} & \left.=3.5844 \times 10^{-11}\left\{\frac{6.35 \times 10^{-2}}{35.1} \frac{\left[\cos ^{-1}\left(0.966\left(1-\left(23.2 \times 10^{-6}-4.67 \times 10^{-6}\right) 55\right)\right)\right.}{15}-1\right]\right\} \\
& =3.636 \times 10^{-12} \text { cycles }
\end{aligned}
$$

## (2) Bond Pad/Die Interface Shear Fatigue

(A) Assume a microcircuit with a Representative Microcircuit Configuration (RMC) as defined in paragraph 4.5 .6 and used in a MIL-HDBK-217 ground-fixed $\left(G_{F}\right)$ application environment. Then the mean number of cycles to failure due to bond pad/die interface shear fatigue is found from equations F5.9 and F5.10, which are combined following:
$N_{f(\text { shear }) s}=A_{2}(K \Delta T)^{n_{2}}$

The variables in this equation are defined in paragraph 4.5.2.2(2) and data are obtained from the following sources:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $\mathrm{A}_{2}$ | $4.3386 \times 10^{-11}$ | N/A | Table 4.5-5 |
| $\mathrm{n}_{2}$ | -5.134 | N/A | Table 4.5-5 |
| $k$ | $1.46 \times 10^{-5}$ | N/A | Table 4.5-6 |
| $\Delta T$ | 55 | ${ }^{\circ} \mathrm{C}$ | Table 4.5-17 |

Substituting in equations F5.9 and F5.10:

$$
\begin{aligned}
N_{f(\text { shear }) s} & \left.=4.3386 \times 10^{-11}\left(1.46 \times 10^{-5}\right)(55)\right)^{-5.134} \\
& =3.377 \times 10^{5} \text { cycles }
\end{aligned}
$$

(B) Assume the same conditions as paragraph 4.5.2.3(2)(A) except bond pad material is gold. then from Table $4.5-5, A_{2}=4.2948 \times 10^{-12}$ and $n_{1}$ $=-4.9828$, and from Table $4.5-6, K=0.90 \times 10^{-5}$. All other variables remain the same. Substituting in equations F5.9 and F5.10:

$$
\begin{aligned}
N_{f(\text { shear }) s} & =4.2948 \times 10^{-12}\left(0.90 \times 10^{-5}(55)\right)^{-4.9828} \\
& =1.268 \times 10^{5} \text { cycles }
\end{aligned}
$$

(3) Bond Pad/Wire Interface Shear Fatigue
(A) Assume a microcircuit with a Representative Microcircuit Configuration (RMC) as defined in paragraph 4.5.6 except wire material is gold. The device is used in a MIL-HDBK-217 ground-fixed ( $G_{F}$ ) application environment. Then the mean number of cycles to failure is found from equations F5.10 and F5.14, which are combined following:
$\left.\left.N_{f(\text { shear }) w} \equiv A_{2}\right|_{-} ^{-} \frac{\alpha_{w}-\alpha_{s} L \Delta T}{2}\right|^{n_{2}}$
The variables in this equation are defined in paragraph 4.5.2.2(3) and data are obtained from the following sources:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $\mathrm{A}_{2}$ | $4.2948 \times 10^{-12}$ | N/A | Table 4.5-5 |
| $\mathrm{n}_{2}$ | -4.9828 | N/A | Table 4.5-5 |
| $\alpha_{w}$ | $14.2 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-1 |
| $\alpha_{s}$ | $4.67 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-2 |
| $\Delta T$ | 55 | ${ }^{\circ} \mathrm{C}$ | Table 4.5-17 |

Substituting in equations $\mathrm{F5} .10$ and $\mathrm{F5} .14$ :

$$
\begin{aligned}
N_{f(\text { shear }) w} & =4.2948 \times 10^{12}\left[\frac{14.2 \times 10^{-6}-4.67 \times 10^{-6} \mid(55)}{2}\right]^{-4.9828} \\
& =3.014 \times 10^{6} \text { cycles }
\end{aligned}
$$

(8) Assume the same conditions as paragraph 4.5.2.3 except pad material is gold and wire material is aluminum. Then the following data is obtained:

| VARIABLE |
| :---: |
| $A_{2}$ |
| $n_{2}$ |
| $\alpha_{w}$ |
| $\alpha_{s}$ |

$\frac{\text { VALUE }}{4.3386 \times 10^{-11}}$
$\frac{\text { UNITS }}{\text { N/A }}$

SOURCE
Table 4.5-5
$n_{2}$
$-5.134$
N/A
Table 4.5-5
$\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ Table $4.5-1$
$\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C} \quad$ Table $4.5-2$

Substituting in equations F 5.10 and F 5.14 :

$$
\begin{aligned}
N_{f(\text { shear }) w} & =4.3386 \times 10^{-11}\left[\frac{\left|23.2 \times 10^{-6}-4.67 \times 10^{-6}\right|(55)}{2}\right]^{-5.134} \\
& =3.488 \times 10^{6} \text { cycles }
\end{aligned}
$$

### 4.5.2.4 Evaluation

The results from the application examples given in paragraph 4.5.2.3 are summarized following:

| FAILURE MECHANISM | MICROCIRCUIT CONFIGURATION* | $\mathrm{Nf}_{\text {( }}$ cycles) |
| :---: | :---: | :---: |
| Bond Wire | RMC | $2.4 \times 10^{17}$ |
| Flexure | RMC except: 5 mil bond wire | $2.0 \times 10^{14}$ |
| Fatigue | RMC exceot: 5 mil bond wire <br> : gold bond wire | $3.6 \times 10^{12}$ |
| Bond Pad/Die |  |  |
|  | RMC | $3.4 \times 10^{5}$ |
| Interface | RMC except: gold bond pad | $1.3 \times 10^{5}$ |
| Shear Fatigue |  |  |
| Bond Pad/Wire PMC except: gold bond wire $3.0 \times 106$ |  |  |
|  | RMC except: gold bond wire | $3.0 \times 10^{6}$ |
| Interface | RMC except: gold bond pad | $3.5 \times 10^{6}$ |
| Shear Fatigue |  |  |

These failure predictions are consistent with the fact that flexure failures are less often seen as compared to the failures do to shear fatigue. Nevertheless, this does not rule out the possibility of failure due to flexure. Given a different set of environmental conditions, flexure could be the dominant mechanism, since the stress due to flexure depends not only on the temperature conditions and the materials in consideration but also on the geometry of the bond wire e.g. wire diameter, radius of curvature at the bond, the angle of the bond wire with the substrate, etc. Therefore, a change in wire diameter for the same environmental conditions may cause an increase in the flexure stresses without significantly changing the shear fatigue stresses. The relative importance of each of these failure mechanisms is subject to the various factors on which each of the mechanisms depend.

From the summary table it is seen that the bond pad material has negligible effect on the bond pad/die interface shear fatigue mechanism. This supports existing knowledge gained from failure analysis that the failure usually occurs in the bulk die material immediately below the pad due to bulk defects in the die acting as failure initiation sites.

The bond pad/wire interface shear fatigue mechanism can occur only when the pad and the wire are of dissimilar materials. The summary table shows that the choice of material for either member has little effect on life when the same two materials are paired.

### 4.5.3 Failure Models for the Die, Die Attach and Substrate Attach, Fracture and Fatique

### 4.5.3.1 Description of the Models

The die attach unit of microelectronic component packages consists of the die or chip and the substrate and the case, which are usually made of different materials and therefore have different thermal expansion coefficients. During environmental thermal and power cycling, as the temperature fluctuates, longitudinal and shear stresses are introduced in the package.

Microcracks are typically introduced in the die during manufacturing operations and are present at the edges of the die. If a microcrack is large enough, i.e. if it is equal to or greater than a critical crack size, the die may fail in the first power cycle. If the microcrack is less than the critical crack size, then during temperature cycling, it may propagate and eventually the die would fail when this crack reaches the critical size.

Different thermal expansion coefficients of the die, substrate and case and the presence of edge voids in the attach materials introduce high stresses and are responsible for the failure of the die attach and the substrate attach. The voids in the attach materials may act as microcracks, which may propagate during temperature cycling and eventually cause delamination of the die or the substrate.

A fracture mechanics approach is taken to calculate the critical crack size in the die. If the initial crack size is smaller than the critical crack size then Paris's power law of fatigue crack propagation is used to calculate the number of cycles for the crack to grow to critical size. The die attach and substrate attach materials fail by ductile mechanisms and hence the linear elastic fracture mechanics (LEFM) approach is not appropriate in this situation. The Manson-Coffin relationship is used therefore, to calculate the number of cycles to failure in die attach and substrate attach.

The development of the models for die, die attach and substrate attach fracture and fatigue are more fully discussed in appendix $G$.

### 4.5.3.2. Die, Die Attach and Substrate Attach Failure Models

As discussed in 4.5.3.1, models have been developed for die brittle cracking, die fatigue cracking, die attach fatigue and substrate attach fatigue and fatigue failure mechanisms, as follows:

## (1) Die Brittle Cracking

Brittle failure of a die with a vertical edge crack can occur upon first application of thermomechanical stress when the criterion defined in equation G. 4 is satisfied:

$$
\begin{equation*}
a_{i} \geq a_{c} \tag{G.4}
\end{equation*}
$$

where

$$
\begin{aligned}
& a_{i} \text { is the initial crack length, meters } \\
& a_{c} \text { is the critical crack length, meters, required to cause rapid } \\
& \text { propagation of the crack through the die, and is defined by equation } \\
& \text { G. } 5 \text { as follows: }
\end{aligned}
$$

$$
\begin{equation*}
a_{c}=\frac{K_{I C}^{2}}{\pi \sigma_{a p p}^{2}} \tag{G.5}
\end{equation*}
$$

where

$$
K_{\text {IC }} \text { is the fracture toughness of the die material obtained from }
$$ Table 4.5-7.

$\sigma_{\text {app }}$ is the maximum applied tensile stress in the die and is defined
by equation $G .6$ as follows:

$$
\begin{equation*}
\sigma_{a p p}=2 \times 10^{-7}\left|\alpha_{s}-\alpha_{d}\right| \Delta T \sqrt{E_{s} E_{a} L / x} \tag{G.6}
\end{equation*}
$$

where
$\alpha_{s}$ is the coefficient of thermal expansion of the substrate to which the die is mounted, obtained from Table 4.5-9.
$\alpha_{d}$ is the coefficient of thermal expansion of the die obtained from Table 4.5-7.
$\Delta T$ is the temperature difference encountered, obtained from Table 4.5-17.
$E_{s}$ is the tensile (Young's) modulus of the substrate obtained from Table 4.5-9.
$E_{a}$ is the tensile (Young's) modulus of the die attach obtained from Table 4.5-8.
$x$ is the die attach thickness, meters obtained from Table 4.5-18.
$L$ is the diagonal length of the die, meters, and may be approximated by equation G. 7 as follows:

$$
\begin{equation*}
L=1.5 \times 10^{-3}+1.0 \times 10^{-4} p \tag{G.7}
\end{equation*}
$$

where $P$ is the number of active pin terminals in the microcircuit.

## (2) Die Fatigue Cracking

The model for the number of cycles to die fatigue cracking failure is defined by equation G.l0e as follows:

$$
\begin{equation*}
\left.N_{f}=\left.\frac{2}{(n-2) A \sigma_{a p p}^{n} \pi^{n / 2}}\right|_{-\frac{1}{a_{i}} \frac{1}{((n-2) / 2)}} ^{-\frac{1}{((n-2) / 2)}}{ }_{a_{f}} \right\rvert\, \tag{G.10e}
\end{equation*}
$$

for $n$ <> 2
where
$N_{f}$ is the number of cycles to die fatigue cracking failure.
$n$ is a material property dependent exponent for the die material obtained from Table 4.5-7.

A is a material property dependent coefficient for the die material obtained from Table 4.5-7.
$a_{i}$ is the initial crack length, meters
$a_{f}$ is the final crack length at failure, meters

MIL-STD-883, Method 2010 visual criteria for die cracks prohibits any surface cracks in an active circuit area of the die and prohibits any edge cracks with a total length greater than tabulated below, or edge cracks with a total length greater than tabulated below, or edge cracks of lesser length that extend more than 1 mil past the scribe grid line along the die edge:

| Quality Level |  |
| :---: | :---: |
| B | $\frac{\text { Maximum Crack Length }}{5 \mathrm{mils}}$ |
| S | 3 mils |

It can be expected than any population of microcircuit dice will contain a
proportion of cracks up to the limit of acceptability. It can be further expected that these cracks will propagate during operational use of the completed microcircuits due to thermomechanically induced stress. The increase in crack length required for an allowable crack to enter active areas of the die and cause failure will vary depending upon the inital directional orientation of the crack and its proximity to the die active area pattern geometry. It is believed that it is conservative to assume that crack propagation to a total length of 15 mils is the maximum that can be permitted before penetration of an active area is imminent. From the visual acceptance criteria and this assumption, appropriate values for $a_{i}$ and $a_{f}$ are proposed as follows:


## (3) Die Attach Fatigue

The model for the number of cycles to die attach fatigue failure is defined by equations G. 11 and G. 12 which are combined as follows:

$$
\begin{equation*}
N_{f}=0.5\left|\frac{L \alpha_{s}-\alpha_{d} \mid \Delta T_{-}^{-}}{y_{f}^{\prime}}\right|^{1 / c} \tag{G.11}
\end{equation*}
$$

where:
$N_{f}$ is the number of cycles to die attach fatigue failure.
$\alpha_{s}$ is the coefficient of thermal expansion of the substrate obtained from Table 4.5-9.
$\alpha_{d}$ is the coefficient of thermal expansion of the die obtained from Table 4.5-7.
$\Delta T$ is the temperature difference encountered, obtained from Table 4.5-17.
$x_{\text {, }}$ is the height of die attach, meters, obtained from Table 4.5-18.
$\gamma_{f}$ is the fatigue ductility coefficient (defined as the shear strain required to cause failure in one load reversal) obtained from Table 4.5-8.
$c$ is the Manson-Coffin fatigue exponent (slope of low cycle fatigue curve of $\log$ shear strain vs. $\log$ cycles to failure) obtained from Table 4.5-8.
$L$ is the diagonal length of the die, meters, and may be approximated by equation G. 7 as follows:
$L=1.5 \times 10^{-3}+1.0 \times 10^{-4} \mathrm{P}$
where $P$ is the number of active pin terminals in the microcircuit.

## (4) Substrate Attach Fatigue

The model for the number of cycles substrate attach fatigue failure is similar to the die attach fatigue failure model and is defined by equation (G.13) as follows:

$$
\begin{equation*}
N_{f}=0.5\left|\frac{L_{s}\left|\alpha_{c}-\alpha_{s}\right| \Delta T}{x_{s a}^{\prime}} \gamma_{f}^{-}\right| 1 / c \tag{G.13}
\end{equation*}
$$

where:
$L_{S}$ is the diagonal length of substrate, meters.
$\alpha_{c}$ is the coefficient of thermal expansion of the case obtained from Table 4.5-10.
$\alpha_{s}$ is the coefficient of thermal expansion of the substrate obtained from Table 4.5-9.
$\Delta T$ is the temperature difference encountered obtained from Table 4.5-17.
$x_{\text {sa }}$ is the thickness of the substrate attach, meters obtained from Table 4.5-18.
$\gamma_{f}^{\prime}$ is the fatigue ductility coefficient of substrate attach (defined as the shear strain required to cause failure in one load reversal) obtained from Table 4.5-8
c is the Manson-Coffin fatigue exponent (slope of low cycle fatigue curve of $\log$ shear strain vs. $\log$ cycles to failure) obtained from Table 4.5-8
4.5.3.3 Application Examples for the Die, Die Attach and Substrate Attach Failure Models.
(1) Die Brittle Cracking
(A) Assume a micrccircuit with a Representative Microcircuit Configuration (RMC) as defined in paragraph 4.5.6 and use in a MIL-HDBK-217 ground-fixed ( $G_{F}$ ) application environment. Brittle failure of a die will occur upon first application of thermomechanical stress if criterion equation $G .4$ is satisfied. Evaluation of this criterion requires solution of equations $G .5$ and G.6, which are combined following:

$$
a_{c}=\frac{K_{I C}^{2}}{\Pi\left(2 \times 10^{-7}\left|\alpha_{s}-\alpha_{d}\right| \Delta T \sqrt{E_{s} E_{a} L / x}\right)^{2}}
$$

The variables in this equation are defined in paragraph 4.5.3.2(1) and data are obtained from the following sources:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| K IC | 0.82 | M Pa $\sqrt{\mathrm{m}}$ | Table 4.5-7 |
| $\alpha_{s}$ | $7.3 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-9 |
| $\alpha_{\text {d }}$ | $4.67 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-7 |
| $E_{s}$ | $255 \times 10^{9}$ | Pa | Table 4.5-9 |
| $E_{a}$ | $2.8 \times 10^{9}$ | m | RMC |
| $\times$ | $5.1 \times 10^{-5}$ | m | RMC |
| $\Delta T$ | 55 | ${ }^{\circ} \mathrm{C}$ | Table 4.5-17 |
| L | $3.22 \times 10^{-3}$ | m | RMC |

Substituting in equations G. 5 and G.6:


From the specified MIL-STD-883 quality level for the RMC it is found from paragraph 4.5.3.1(2) in the discussion following equation G.10e that $\mathrm{a}_{\mathrm{i}}=$ $1.3 \times 10^{-4} \mathrm{~m}(5 \mathrm{mils})$. Applying the criterion equation G .4 :

$$
\begin{equation*}
a_{i} \geq a_{c} \tag{G.4}
\end{equation*}
$$

Substituting in equation G.4:

$$
1.3 \times 10^{-4}<5.673 \times 10^{-3}
$$

Hence, die brittle cracking will not occur.
(B) Assume the same conditions as 4.5.3.3(1)(A) ewxcept the die attach material is Au-Si eutectic and the die diagonal length is 0.01 m (400 $\dot{m i l s}$ ) and all other variables remain the same. Then from Table 4.5-18, $x$ $=2.5 \times 10^{-6} \mathrm{~m}(0.1 \mathrm{mil})$ and from Table $4.5-8, E_{a}=59.2 \times 10^{9} \mathrm{~Pa}$. Substituting in equations G. 5 and G.6:
${ }^{a_{c}}=$ $\qquad$

$$
=\frac{0.6724}{\Pi(50538)}=4.235 \times 10^{-6 m}(0.17 \mathrm{mi} 1 \mathrm{~s})
$$

Substituting in criterion equation G.4:

$$
1.3 \times 10^{-4}>4.2 \times 10^{-6}
$$

Hence, die brittle cracking will occur upon first application of thermomechanical stress (provided a maximum acceptable size crack from MIL-STD-883 visual criteria is present).

## (2) Die Fatigue Cracking

(A) Assume a microcircuit with a Representative Microcircuit Configuration (RMC) as defined in paragraph 4.5.6 and use in a MIL-HDBK-217
ground-fixed $\left(G_{F}\right)$ application environment. Then the mean number of cycles to failure due to die fatigue cracking is found from equation G.10e:

$$
\begin{equation*}
N_{f}=\frac{2}{(n-2) A \sigma_{a p p} n^{n / 2}}\left[\frac{1}{a_{i}}-\frac{1}{((n-2) / 2)}-\frac{1}{a_{f}^{((n-2) / 2)}}\right], n \neq 2 \tag{G.10e}
\end{equation*}
$$

where $\sigma_{a p p}$ is found from equation G.6:

$$
\begin{equation*}
\sigma_{a p p}=2 \times 10^{-7}\left|\alpha_{s}-\alpha_{d}\right| \Delta T \sqrt{E_{s} E_{a} L / x} \tag{G.6}
\end{equation*}
$$

The variables in these equations are defined in paragraphs 4.5.3.2(1) and 4.5.3.2(2) and data are obtained from the following sources:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| n | 4 | N/A | Table 4.5-7 |
| A | $1 \times 10^{-12}$ | N/A | Table 4.5-7 |
| $\mathrm{a}_{i}$ | $1.3 \times 10^{-4}$ | m | RMC |
| ${ }^{\text {a }}$ f | $3.8 \times 10^{-4}$ | m | Para 4.5.3.2(2) |
| $\mathrm{K}_{\text {IC }}$ | 0.82 | M Pa $\sqrt{\mathrm{m}}$ | Table 4.5-7 |
| $\alpha_{s}$ | $7.3 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-9 |
| $\alpha_{\text {d }}$ | $4.67 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-7 |
| $E_{s}$ | $255 \times 10^{9}$ | Pa | Table 4.5-9 |
| $E_{\text {a }}$ | $2.8 \times 10^{9}$ | Pa | Table 4.5-8 |
| , | $5.1 \times 10^{-5}$ | m | RMC |
| L | $3.22 \times 10^{-3}$ | m | RMC |
| $\Delta T$ | 55 | ${ }^{\circ} \mathrm{C}$ | Table 4.5-17 |

Substituting in equation G.6:

$$
\begin{aligned}
\sigma_{a p p} & =2 \times 10^{-7}\left|7.3 \times 10^{-6}-4.67 \times 10^{-6}\right|(55) \sqrt{\left(255 \times 10^{9}\right)\left(2.8 \times 10^{9}\right)\left(3.22 \times 10^{-3}\right) /\left(5.1 \times 10^{-5}\right)} \\
& =6.142 \mathrm{MPa}
\end{aligned}
$$

Applying this result to equation G.l0e:

$$
\begin{aligned}
N_{f} & =\frac{2}{(2)\left(1 \times 10^{-12}\right)(6.142)^{4} \pi^{2}}\left[\frac{1}{1.3 \times 10^{-4}}-\frac{1}{3.8 \times 10^{-4}}\right] \\
& =3.603 \times 10^{11} \text { cycles }
\end{aligned}
$$

(B) Assume the same conditions as paragraph 4.5.3.3(2)(A) except the die attach material is Au-Si eutectic and the die diagonal length is $1 x$ $10^{-2} \mathrm{~m}(400 \mathrm{mils})$ and all other variables remain the same. Then from Table 4.5-18, $x=2.5 \times 10^{-6} \mathrm{~m}(0.1 \mathrm{mil})$ and from Table 4.5-8, $E_{a}=$ $59.2 \times 10^{9} \mathrm{MPa}$. Substituting in equation G.6:

$$
\begin{aligned}
\sigma_{\mathrm{app}} & =2 \times 10^{-7}\left|7.3 \times 10^{-6}-4.67 \times 10^{-6}\right|(55) \sqrt{\left(255 \times 10^{9}\right)\left(59.2 \times 10^{9}\right)\left(1 \times 10^{-2}\right) /\left(2.5 \times 10^{-6}\right)} \\
& =212.5 \mathrm{MPa}
\end{aligned}
$$

Applying this result to equation G.l0e:

$$
\begin{aligned}
N_{f} & =\frac{2}{(2)\left(1 \times 10^{-12}\right)(212.5)^{4} \pi^{2}}\left[\frac{1}{1.3 \times 10^{-4}}-\frac{1}{3.8 \times 10^{-4}}\right] \\
& =2.515 \times 10^{5} \text { cycles }
\end{aligned}
$$

(C) Assume the same conditions as paragraph 4.5.3.3(2)(B) except the MIL-STD-883 quality level is Class $S$. This implies that $a_{i}=7.6 \times$ $10^{-5} \mathrm{~m}(3 \mathrm{mils})$ and all other variables remain the same. Applying the previous result for equation G. 6 and substituting in equation G.10e:

$$
\begin{aligned}
N_{f} & =\frac{2}{(2)\left(1 \times 10^{-12}\right)(212.5)^{4} \pi^{2}}\left[\frac{1}{7.6 \times 10^{-5}}-\frac{1}{3.8 \times 10^{-4}}\right] \\
& =5.230 \times 10^{5} \text { cycles }
\end{aligned}
$$

(3) Die Attach Fatigue
(A) Assume a microcircuit with a Representative Microcircuit Configuration (RMC) as defined in paragraph 4.5.6 and used in a MIL-HDBK-217 ground-fixed ( $G_{F}$ ) application environment. Then the mean number of cycles to failure due to die attach fatigue is found from equations G.ll
and G.12, which are combined following:

$$
\left.N_{f}=\frac{1}{2} \frac{\left[L L_{s}^{a_{s}}-a_{d} L \Delta T\right]^{1}}{x y_{f}}\right]^{1 / c}
$$

The variables in this equation are defined in paragraph 4.5.3.2(3) and data are obtained from the following sources:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| L | $3.22 \times 10^{-3}$ | m | RMC |
| $\alpha_{s}$ | $7.3 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-9 |
| $\alpha_{d}$ | $4.67 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-7 |
| $\Delta T$ | 55 | ${ }^{\circ} \mathrm{C}$ | Table 4.5-17 |
| $x$ | $5.1 \times 10^{-5}$ | m | RMC |
| $\gamma_{f}$ | 1.1 | N/A | Table 4.5-8 |
| $c$ | -0.49 | $N / A$ | Table 4.5-8 |

Substituting in equations G. 11 and G.12:

$$
\begin{aligned}
N_{f} & =\frac{1}{2}\left[\frac{\left(3.22 \times 10^{-3}\right) 17.3 \times 10^{-6}-4.67 \times 10^{-6} \downharpoonright(55)}{\left(5.1 \times 10^{-5}\right)(1.1)}\right]^{1 /-0.49} \\
& =8.820 \times 10^{3} \text { cycles }
\end{aligned}
$$

(B) Assume the same conditions as paragraph 4.5.3.3(3)(A) except the die attach material is Au-Si eutectic, and all other variables remain the same. Then from Table $4.5-18, x=2.5 \times 10^{-6} \mathrm{~m}(0.1 \mathrm{mil})$. Substituting in equations G. 11 and G.12:

$$
\begin{aligned}
N_{f} & =\frac{1}{2}\left[\frac{\left(3.22 \times 10^{-3}\right)\left\lfloor 7.3 \times 10^{-6}-4.67 \times 10^{-6}[(55)\right.}{\left(2.5 \times 10^{-6}\right)(1.1)}\right]^{1 /-0.49} \\
& =19 \text { cycles }
\end{aligned}
$$

(4) Substrate Attach Fatigue
(A) Assume a hybrid microcircuit used in a MIL-HDBK-217 ground-fixed ( $G_{F}$ ) application environment with the following configuration:

Package Material - Copper
Substrate Material - Alumina Ceramic
Substrate Attach - Au-Si eutectic
Substrate Size $-1.91 \times 10^{-2} \mathrm{~m}$ square (. 75 in square)

Then the mean number of cycles to failure due to substrate attach fatigue is found from equation G.l3:

$$
\begin{equation*}
N_{f}=\frac{1}{2}\left[\frac{L_{S} \alpha_{C}-\alpha_{S} \mid \Delta T}{X_{s \alpha} Y_{f}^{\prime}}\right]^{1 / c} \tag{G.13}
\end{equation*}
$$

The variables in this equation are defined in paragraph 4.5.3.2(4) and data are obtained from the following sources:

VARIABLE
VALUE UNITS
SOURCE

| $L_{s}$ | $2.7 \times 10^{-2}$ | m | configuration: | $\left(\sqrt{2}\left(1.91 \times 10^{-2}\right)\right)$ |
| :---: | :---: | :---: | :---: | :---: |
| $\alpha_{c}$ | $16.9 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-10 |  |
| $\alpha_{s}$ | $7.3 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-9 |  |
| $\Delta T$ | 55 | ${ }^{\circ} \mathrm{C}$ | Table 4.5-17 |  |
| ${ }_{\text {x }}{ }_{\text {a }}$ | $2.5 \times 10^{-6}$ | m | Table 4.5-18 |  |
| $Y_{f}$ | 1.1 | N/A | Table 4.5-8 |  |
| $c$ | -0.49 | $N / A$ | Table 4.5-8 |  |

Substituting in equation G.13:

$$
\begin{aligned}
N_{f} & =\frac{1}{2}\left[\frac{\left(2.7 \times 10^{-2}\right) 16.9 \times 10^{-6}-7.3 \times 10^{-6} \perp(55)}{\left(2.5 \times 10^{-6}\right)(1.1)}\right]^{1 /-0.49} \\
& =1.7 \times 10^{-2} \text { cycles i.e. will not survive the first thermal cycle. }
\end{aligned}
$$

(B) Assume the same conditions as paragraph 4.5.3.3(4)(A) except the die attach material is 70-30 In-Pb solder, and all other variables remain the
same. Then from Table $4.5-18, x_{s a}=1.5 \times 10^{-4} \mathrm{~m}(6 \mathrm{mils})$. Substituting in equation G.13:

$$
\begin{aligned}
N_{f} & =\frac{1}{2}\left[\frac{\left(2.7 \times 10^{-2}\right)\left[16.9 \times 10^{-6}-7.3 \times 10^{-6} \mid(55)\right.}{\left(1.5 \times 10^{-4}\right)(1.1)}\right]^{1 /-0.49} \\
& =74 \text { cycles }
\end{aligned}
$$

(C) Assume the same conditions as paragraph 4.5.3.3(4)(A) except the package material is Kovar, and all other variables remain the same. Then from Table 4.5-10, $\alpha_{c}=5.2 \times 10^{-6} \mathrm{~m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$. Substituting in equation G.13:

$$
N_{f}=\frac{1}{2}\left[\frac{\left(2.7 \times 10^{-2}\right) \mid 5.2 \times 10^{-6}-7.3 \times 10^{-6}\lfloor(35)}{\left(2.5 \times 10^{-6}\right)(1.1)}\right]^{1 /-0.49}
$$

$=3.9 \times 10^{-1}$ cycles i.e. will not survive the first thermal cycle.
(D) Assume the same conditions as paragraph 4.5.3.3(4)(A) except the package material is Kovar and the die attach material is $70-30 \mathrm{In}-\mathrm{Pb}$ solder, and all other variables remain the same. Then from Table 4.5-10, $\alpha_{c}=$ $5.2 \times 10^{-6} \mathrm{~m} / \mathrm{m} /{ }^{\circ} \mathrm{c}$ and from Table $4.5-18, x_{\text {sa }}=1.5 \times 10^{-4} \mathrm{~m}(6$ mils). Substituting in equation G.l3:

$$
\begin{aligned}
N_{f} & =\frac{1}{2}\left[\frac{\left(2.7 \times 10^{-2}\right)\left[5.2 \times 10^{-6}-7.3 \times 10^{-6} \downharpoonright(55)\right.}{\left(1.5 \times 10^{-6}\right)(1.1)}\right]^{1 /-0.49} \\
& =1646 \text { cycles }
\end{aligned}
$$

(E) Assume the same conditions as paragraph 4.5.3.3(4)(D) except the substrate size is $1.27 \times 10^{-2} \mathrm{~m}$ square ( 0.5 in square). Then $L_{s}$ $=\overline{\sqrt{2}} 2\left(!.27 \times 10^{-2}\right)=1.8 \times 10^{-2} \mathrm{~m}$. Substituting in equation G .13 :
$N_{f}=\frac{1}{2}\left[\frac{\left(1.8 \times 10^{-2}\right) \int 5.2 \times 10^{-6}-7.3 \times 10^{-6}(55)}{\left(1.5 \times 10^{-4}\right)(1.1)}\right]^{1 /-0.49}$
$=3765$ cycles
4.5.3.4 Evaluation
The results from the application examples given in paragraph 4.5.3.3 are summarized following:

| FAILURE MECHANISM | MICROCIRCUIT CONFIGIJRATION* | $\mathrm{Nf}_{\text {( }}$ (cycles) |
| :---: | :---: | :---: |
| Die Brittle | RMC | Note 1 |
| Cracking | RMC except: Au-Si eutectic <br> : die attach <br> $: L=1 \times 10^{-2}(400 \mathrm{mils})$ | Note 2 |
|  | RMC | $3.6 \times 10^{11}$ |
| Cracking | $\begin{aligned} \text { RMC except: } & \text { Au-Si eutectic } \\ & \text { die attach } \\ : & L=1 \times 10^{-2} \mathrm{~m}(400 \mathrm{mi} 1 \mathrm{~s}) \end{aligned}$ | $2.5 \times 10^{5}$ |RMC except: Au-Si eutecticdie attach$5.2 \times 10^{5}$

$: L=1 \times 10^{-2} \mathrm{~m}(400 \mathrm{mils})$: MIL-STD-883, Class S

| Die Attach | RMC |  |
| :--- | :--- | :--- |
| Fatigue | RMC except: Au-Si eutectic | $8.8 \times 10^{3}$ |
|  |  | die attach |

SubstrateSame except 70-30 In-Pb74Attachsolder attach
Fatigue Same except Kovar case will not surivefirst cycle
Same except Kovar case, 70-30 In-Pb ..... 1646solder attach
Same except Kovar case, 70-30 In-Pbsolder attach, substrate $1.3 \times 10^{-2 m}$square substrate (0.5 in square)3765
*RMC is defined in paragraph 4.5.6
Note 1. Die brittle cracking will not occur.
2. Die brittle cracking during first thermal cycle will occur.

From the summary table it is clear that the microcircuit designer's choice of materials, fabrication processes and geometry strongly influence the presence and severity of the failure mechanisms considered in this section.

Die brittle cracking is not normally seen in typical microcircuits. However, it could become a frequently occurring problem if the trend to larger die sizes is accompanied by the use of thin layer eutectic attach materials. Thick layer attach materials are preferable for larger die sizes.

Die fatigue cracking is rarely experienced in most current production microcircuits. However, mean cycle life can be reduced by 6 or more orders of magnitude if the trend to larger die sizes is accompanied by the use of thin layer eutectic atach materials. It is noted that upgrading the quality level from MIL-STD-883, Class B to Class S has negligible effect on life cycle improvement.

Die attach fatigue is frequently seen in power microcircuits and hybrids, and will become of greater prevalence if thin layer eutectic attach materials are employed. This failure mechanism frequency can be reduced by using thick layer low modulus of elasticity attach materials.

Substrate attach fatigue is found only in hybrid or multi-chip microcircuits where microcircuit components are mounted on substrates. The summary table deomonstrates the extreme importance of evaluation of package materials and substrate attach materials to optimize mean cycles to failure. Additionally, this mechanism can be further reduced by the strategy of using several smaller substrates in lieu of a single large substrate.

### 4.5.4 Failure Models of Metallization and Wire Bond Corrosion

### 4.5.4.1 Description of Models

The time to failure of a microelectronic package due to corrosion is dependent upon the package type, corroding material, and environmental conditions. The
package type is defined in terms of package geometry, encapsulating materials and lid and lead seals. These attributes together with the environmental conditions (relative humidity and temperature) determine the rate of moisture ingress, hermeticity and the moisture induction time for the package. The properties of the corroding material, contaminant and condensed moisture will control the rate of the corrosion process. For example, corrosion is less likely to occur in a cool, dry environment while a hot and humid environment will shorten the induction time and promote the galvanic transfer of ions for the corrosion process.

As the temperature increases, the rate of moisture ingress increases which leads to a shorter induction time. However, if the microelectronic device is electrically activated such that the temperature surrounding a potential corroding material is high enough to prevent moisture condensation, then corrosion will not occur. Thus the non-operating environment of the package is more severe than the operating environment for the corrosion failure mechanism.

The induction time between hermetic and non-hermetic packages can differ by four orders of magnitude. However, with new encapsulating package materials, such differences are being minimized and permeation is playing a smaller role on moisture ingression as compared to moisture flow.

Corrosion of metallization and bonding materials occurs predominantly on aluminum subjected to a chlorine or other halogen ionic contaminant. However, as the component dimensions are miniaturized and the current densities are increased, even gold will corrode provided there is an electrolyte for galvanic transfer. Furthermore a high quality and contaminant-free passivation layer can extend the time to failure by as much as 4 orders of magnitude compared to an unprotected counterpart.

The deveyopment of the model for corrosion induced failure is more fully discussed in Appendix $H$.

### 4.5.4.2 Metallization and Wire Bond Corrosion Failure Models

As discussed in 4.5.4.1, models have been developed for conductor metallization and bond pad corrosion failure. The total time to corrosion failure is the sum of two terms as defined by equation (H2.1):

$$
\begin{equation*}
\tau=\tau_{1}+\tau_{2} \tag{H2.1}
\end{equation*}
$$

where
$\tau$ is the time to corrosion failure.
$\tau_{1}$ is the induction time necessary for the internal package volume to reach the threshold moisture content to support the corrosion process.
$\tau_{2}$ is the time required for the corrosion process to terminate in failure.

In Appendix $H$ it is shown that $\tau_{2} \gg t_{1}$. Therefore, the total time to corrosion failure can be effectively approximated by equation (H2.la), as follows:

$$
\begin{equation*}
\tau=\tau_{2} \tag{H2.la}
\end{equation*}
$$

It is useful to evaluate $t_{1}$ to compare the effect of varying package leak rates for hermetically sealed packages, or to compare the effectiveness of alternate encapsulation materials for a non-hermetic package. Figure 4.5-2 delineates $\tau_{1}$ for hermetic packages as a function of the package volume and the allowable leak rate of the package from MIL-STD-883. The induction time for a non-hermetic package is defined by equation (H2.2) as follows:

$$
\begin{equation*}
\tau_{1}(\text { non-hermetic })=\frac{12 L^{2}}{\pi^{2} D} \tag{H2.2}
\end{equation*}
$$

where:
i is the effective thickness of the package barrier between the microcircuit and the external ambient, cm, which may be approximated by one-half of the overall package thickness.
$D$ is the permeability of the encapsulant material, $\mathrm{cm}^{3}-\mathrm{cm} / \mathrm{cm}^{2}-\mathrm{sec}-\mathrm{bar}$ (i.e. cubic centimeter volume of permeant at standard temperature and pressure per square centimeter of barrier area per second bar differential pressure across the barrier per centimeter of barrier thickness).

The two principal sites for corrosion failure are discussed below.
(1) Conductor Metallization Corrosion Failure

The model for the time required for conductor metallization failure is defined by equation (H3.8).

$$
\begin{equation*}
\tau_{2 m}=8 \times 10^{11} \frac{k_{1} k_{2} k_{3}}{k_{4}} \frac{w^{2} h n d \rho}{M V} \quad(\mathrm{sec}) \tag{H3.8}
\end{equation*}
$$

where:
$\tau_{2 m}$ is the time to failure for conductor metallization, seconds.
$k_{1}$ is the physical properties index of the conductor material
obtained from Table $4.5-12$.
$k_{2}$ is the coating integrity factor obtained from Table $4.5-13$.
$k_{3}$ is the equipment operating time factor obtained from Table $4.5-14$.
$k_{4}$ is the temperature-humidity environment acceleration factor
obtained from figure $4.5-1$.
$w \quad$ is the width of the conductor metallization, cm.
$h \quad$ is the height of the conductor metallization, cm.
$n \quad$ is the chemical valence of the conductor material obtained from

$d \quad$| is the density of the conductor material obtained from Table $4.5-12$. |
| :--- |

$M \quad$ is the atomic weight of the conductor material obtained from Table
$V \quad 4.5-12$
is the applied or galvanic electrical bias, volts, chosen as

The model for the time required for bond pad metallization failure is defined by equation (H3.10) as follows:

$$
\begin{equation*}
\tau_{2 w}=8 \times 10^{11} \frac{k_{1} k_{2} k_{3}}{k_{4}} \frac{V_{C} n d \rho}{M V} \tag{H3.10}
\end{equation*}
$$

where:
${ }^{\tau} 2 w$ is the time to failure for conductor metallization, seconds.
$k_{1}$ is the physical properties index of the bond pad material obtained from Table 4.5-12.
$k_{2}$ is the coating integrity factor obtained from Table 4.5-13, which for an uncoated bond pad is equal to unity.
$k_{3}$ is the equipment operating time factor obtained from Table 4.5-14.
$k_{4}$ is the temperature-humidity environment acceleration factor obtained from Figure 4.5-1.
$V_{C}$ is the bond pad volume, $\mathrm{cm}^{3}$, obtained from Table 4.5-11.
$n$ is the chemical valence of the anodic member of the bond pad/bond wire combination, obtained from Table 4.5-16 and 4.5-12.
$d$ is the density of the anodic member of the bond pad/bond wire combination, obtained from Tables 4.5-16 and 4.5-12.
$M$ is the atomic weight of the anodic member of the bond pad/bond wire combination, obtained from Tables 4.5-16 and 4.5-12.
$\checkmark$ is the applied or galvanic electrical bias, volts, chosen as described in Table 4.5-16.
$\rho \quad$ is the resistivity of the electrolyte, ohm-cm, obtained from Table 4.5-15.

### 4.5.4.3 Application Examples for Conductor and Bond Pad Metalizaticn Corrosion Failure Models

(1) Conductor Metallization Corrosion
(A) Assume a microcircuit with a Representative Microcircuit Configuration
(RMC) as defined in 4.5 .6 and used in a MIL-HDBK-217 ground-fixed ( $G_{F}$ ) application environment in which the equipment is operated an average of three hours per day. Then the mean time to failure due to conductor metallization corrosion is found from equation H3.8:

$$
\begin{equation*}
\tau_{2 m}=8 \times 10^{11} \frac{k_{1} k_{2} k_{3}}{k_{4}} \frac{w^{2} n n d \rho}{M V} \tag{H3.8}
\end{equation*}
$$

The variables in this equation are defined in paragraph 4.5.4.2(1) and data are obtained from the following sources:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| k1 | 0.1 | N/A | Table 4.5-12 |
| k2 | 10 | N/A | Table 4.5-13 |
| k3 | 1.14 | N/A | Table 4.5-14 |
| k4 | 0.34 | N/A | Figure 4.5-1 |
| w | $1.5 \times 10^{-4}$ | cm | RMC |
| h | $7.5 \times 10^{-5}$ | cm | RMC |
| n | 3 | N/A | Table 4.5-12 |
| d | 2.7 | gm/cc | Table 4.5-12 |
| $\rho$ | $7.3 \times 10^{6}$ | ohm-cm | Table 4.5-15 |
| M | 27 | amu | Table 4.5-12 |
| V | 5 | volts | RMC |

Substituting equation H3.8:

$$
\begin{aligned}
\tau_{2 \mathrm{~m}} & =\left(8 \times 10^{11}\right) \frac{(0.1)(10)(1.14)}{(0.34)} \frac{\left(1.5 \times 10^{-4}\right)^{2}\left(7.5 \times 10^{-5}\right)(3)(2.7)\left(7.3 \times 10^{6}\right)}{(27)(5)} \\
& =1.983 \times 10^{6} \text { seconds }=551 \text { hours }
\end{aligned}
$$

(B) Assume the same conditions as paragraph 4.5.4.3(1)(A) except the conductor metallization is gold. Then from Table $4.5-12, \mathrm{~K}_{1}=1.0, \mathrm{M}=$ 197, $d=19.32, n=3$ and all other variables remain the same. Substituting in equation H3.8:

$$
\begin{aligned}
{ }^{\tau} 2 \mathrm{~m} & =\left(8 \times 10^{11}, \frac{(1.0)(10)(1.14)}{(0.34)}\left(1.5 \times 10^{-4}\right)^{2}\left(7.5 \times \frac{\left.10^{-5}\right)(3)(19.32)\left(7.3 \times 10^{6}\right)}{(197)(5)}\right.\right. \\
& =1.944 \times 10^{7} \text { seconds }=5400 \text { hours }
\end{aligned}
$$

(C) Assume the same conditions as in paragraph 4.5.4.3(1)(A) except the conductor metallization line width is $5 \times 10^{-5} \mathrm{~m}$ ( 0.5 microns). The $w=5 \times 10^{-5} \mathrm{~m}$ and all other variables remain the same. Substituting in equation H 3.8 :

$$
\begin{aligned}
\tau_{2 m} & =\left(8 \times 10^{11}\right) \frac{(0.1)(10)(1.14)}{(0.34)}\left(5 \times 10^{-5}\right)^{2}\left(7.5 \times 10^{-5}\right)(3)(2.7)\left(7.3 \times 10^{6}\right) \\
& =2.203 \times 10^{5} \text { seconds }=61 \text { hours }
\end{aligned}
$$

(D) Assume the same conditions as in paragraph 4.5.4.3(1)(A) except the microcircuit will be used in an environment with a significantly higher chlorine content than normal. Then from Table 4.5-15, $\rho=$ $2.3 \times 10^{6}$ ohm-cm and all other variables remain the same. substituting in equation H3.8:

$$
\begin{aligned}
\tau_{2 m} & =\left(8 \times 10^{11}\right) \frac{(0.1)(10)(1.14)}{(0.34)}\left(5 \times 10^{-4}\right)^{2}\left(7.5 \times 10^{-5}\right)(3)(2.7)\left(2.3 \times 10^{6}\right) \\
& =6.246 \times 10^{5} \text { seconds }=174 \text { hours }
\end{aligned}
$$

(E) Assume the same conditions as in paragraph 4.5.4.3(1)(A) except the signal power supply voltage is 1.5 volts and all other variables remain the same. Substituting in equation H3.8:

$$
\begin{aligned}
\tau_{2 \mathrm{~m}} & =\left(8 \times 10^{11}\right) \frac{(0.1)(10)(1.14)}{(0.34)} \frac{\left(1.5 \times 10^{-4}\right)^{2}\left(7.5 \times 10^{-5}\right)(3)(2.7)\left(7.3 \times 10^{6}\right)}{(27)(1.5)} \\
& =6.609 \times 10^{6} \text { seconds }=1836 \text { hours }
\end{aligned}
$$

(F) Assume the same conditions as paragraph 4.5.4.3(1)(A) except the microcircuit metallization has been covered by a protective coating that has been demonstrated to provide a strong chemcical bond to the metallization that is inherently free from cohesive or bulk defects and is not detrimentally affected by a $G_{F}$ environment e.g. silicon gel or equivalent. Then from Table 4.5-13, $K_{2}=100$ and all other variables remain the same. Substituting in equation H3.8:

$$
\begin{aligned}
\tau_{2 m} & =\left(8 \times 10^{11}\right) \frac{(0.1)(100)(1.14)}{(0.34)} \frac{\left(1.5 \times 10^{-4}\right)^{2}\left(7.5 \times 10^{-5}\right)(3)(2.7)\left(7.3 \times 10^{6}\right)}{(27)(5)} \\
& =1.983 \times 10^{7} \text { seconds }=5507 \text { hours }
\end{aligned}
$$

(G) Assume the same conditions as paragraph 4.5.4.3(1)(A) except the equipment is operated an average of 16 hours per day. Then from Table $4.5-14, K_{3}=3$ and all other variables remain the same. Substituting in equation H3.8:

$$
\begin{aligned}
\tau_{2 m} & =\left(8 \times 10^{11}\right) \frac{(0.1)(10)(3)}{(0.34)} \frac{\left(1.5 \times 10^{-4}\right)^{2}\left(7.5 \times 10^{-5}\right)(3)(2.7)\left(7.3 \times 10^{6}\right)}{(27)(5)} \\
& =5.217 \times 10^{6} \text { seconds }=1449 \text { hours }
\end{aligned}
$$

(2) Bond Pad Corrosion
(A) Assume the same conditions as paragraph 4.5.4.3(1)(A). Then the mean time to failure due to bond pad corrosion is found from equation H3.10:

$$
\begin{equation*}
\tau_{2 w}=8 \times 10^{11} \frac{k_{1} k_{2} k_{3}}{k_{4}} \frac{C^{V} n d \rho}{M V} \tag{H3.10}
\end{equation*}
$$

The variables in this equation are defined in paragraph 4.5.4.2(2) and the data values and data sources for this equation are the same as tabulated in paragraph 4.5.4.3(1)(A), except $V_{C}$ is obtained from Table 4.5-11. For the assumed conditions $V_{C}$ is defined as the least value of equations $H .8 a$ and $H .8 b$ :

$$
\begin{align*}
& v_{c}=0.3 \mathrm{~s}^{2} t_{b}  \tag{H.8a}\\
& v_{c}=0.236 \mathrm{D}_{3} \tag{H.8b}
\end{align*}
$$

The variables in these equations are defined in Table 4.5-11. From the RMC definition in paragraph 4.5 .6 the following values are obtained:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| D | $3.2 \times 10^{-3}$ | cm | RMC |
| S | $1 \times 10^{-2}$ | cm | RMC |
| $t_{b}$ | $7.5 \times 10^{-5}$ | cm | RMC |

Substituting in equations H.8a and H.8b and choosing the least value:

$$
V_{C}=2.25 \times 10^{-9} \mathrm{~cm}^{3}
$$

Substituting in equation H3.10:

$$
\begin{aligned}
\tau_{2 w} & =\left(8 \times 10^{11}, \frac{(0.1)(10)(1.14)}{(0.34)}\left(\frac{\left(2.25 \times 10^{-9}\right)(3)(2.7)\left(7.3 \times 10^{6}\right)}{(27)(5)}\right.\right. \\
& =2.643 \times 10^{9} \text { seconds }=7.343 \times 10^{5} \text { hours }
\end{aligned}
$$

(B) Assume the same conditions as paragraph 4.5.4.3(1)(A) except the bond wire material is gold. Since the bond wire and bond pad are dissimilar metals, from Table 4.5-16, it is determined that the bond pad material (aluminum) is anodic to gold and that

$$
\begin{aligned}
V_{\text {galvanic }} & =1+\left(V_{\text {cathode }}-V_{\text {anode }}\right)=1+(1.5-(-1.66)) \\
& =4.16 \text { volts }
\end{aligned}
$$

Since $V_{\text {galvanic }}<V=5$ volts, the latter value is used in equation H3.10. From Table 4.5-11 it is determined that the corrosively attacked member is the bond pad and that equation H.8a defines the corrosion volume:

$$
\begin{equation*}
v_{C}=0.3 \mathrm{~s}^{2} t_{b} \tag{H.8a}
\end{equation*}
$$

The variables for this equation are defined in Table 4.5-11 and the variable values are determined from the RMC definition in paragraph 4.5.6. The values tabulated in paragraph 4.5.4.3(2)(A) apply. Substituting these values in equation H.8a:

$$
v_{C}=(0.3)\left(1 \times 10^{-2}\right)^{2}\left(7.5 \times 10^{-5}\right)=2.25 \times 10^{-9} \mathrm{~cm}^{3}
$$

Since the corrosively attacked member is the bond pad all the applicable variable values tabulated in paragraph 4.5.4.3(1)(A) apply to this condition. Substituting these values in equation H3.10:

$$
\begin{aligned}
\tau_{2 w} & =\left(8 \times 10^{11}\right) \frac{(0.1)(10)(1.14)}{(0.34)} \frac{\left(2.25 \times 10^{-9}\right)(3)(2.7)\left(7.3 \times 10^{6}\right)}{(27)(5)} \\
& =2.643 \times 10^{9} \text { seconds }=7.343 \times 10^{5} \text { hours }
\end{aligned}
$$

(C) Assume the same conditions as paragraph 4.5.4.3(1)(A) except the bond pad is gold and the bond wires are attached with wedge bonds. Since the bond wire and bond pad are dissimilar metals, from Table 4.5-16, it is determined that the bond pad material is cathodic to the bond wire material (aluminum) and that

$$
\begin{aligned}
V_{\text {galvanic }} & =1+V_{\text {cathode }}-V_{\text {anode }}=1+1.5-(-1.66) \\
& =4.16 \text { volts }
\end{aligned}
$$

Since $V_{\text {galvanic }}<V=5$ volts, the latter value is used in equation H3.10. From Table $4.5-11$ it is determined that the corrosively attacked member is the bond wire and for wedge bonds equation H. 8 b defines the corrosion volume:

$$
\begin{equation*}
V_{C}=0.236 D^{3} \tag{H.8b}
\end{equation*}
$$

The variable for this equation is defined in Table 4.5-11. From the RMC definition in paragraph 4.5 .6 the value $D=3.2 \times 10^{-3} \mathrm{~cm}$ is obtained.
Substituting in equation H.8b:

$$
V_{C}=(0.236)\left(3.2 \times 10^{-3}\right)^{3}=7.733 \times 10^{-9} \mathrm{~cm}^{3}
$$

Since the corrosively attacked member is the bond wire, all the applicable variable values tabulated in paragraph 4.5.4.3(1)(A) apply to this condition. Substituting these values in equation H3.10:

$$
\begin{aligned}
\tau_{2 w} & =\left(8 \times 10^{11}\right) \frac{(0.1)(10)(1.14)}{(0.34)} \frac{\left(7.733 \times 10^{-9}\right)(3)(2.7)\left(7.3 \times 10^{6}\right)}{(27)(5)} \\
\ddots & =9.085 \times 10^{9} \text { seconds }=2.524 \times 10^{6} \text { hours }
\end{aligned}
$$

### 4.5.4.4 Evaluation

The results from che application examples givell in paragraph 4.5.4.3 are summarized following:

| FAILIJRE MECHANISM |  | MICROCIRCIJIT CONFIGURATION* |
| :--- | :--- | :--- |

* RMC is defined in paragraph 4.5.6

Comparison of the mean time to failure for the two corrosion sites described in the summary table clearly demonstrates that conductor metallization corrosion is predicted to be much more prevalent than bond pad corrosion.

The conductor metallization corrosion mechanism can cause three or more orders of magnitude variation in mean time to failure, dependent on design, materials, fabrication processes and operating conditions. Significant improvement in microcircuit resistance to this failure mechanism can be achieved by two steps, either separately or in combination viz3.

- develop improved conductor protective coatings (passivation)(order magnitude increase)
- use of more corrosion resistant conductor metals (order of magnitude increase)

The trend to higher density microcircuits has contradictory effects on conductor metallization corrowion. On one hand narrower conductor widths can reduce mean time to failure by an order of magnitude. On the other hand the lower signal voltage levels can increase mean time to failure by a factor up to three. This suggests that the overall effect of higher density microcircuits will be an increasing susceptability to the corrosion mechanism. Thus it is emphasized that it will become increasingly important to implement the reliability improvement steps highlighted above.

Finally, it is observed that increasing equipment operating time per day will incroase the mean time to failure from corrosion mechanisms. Continuously operating equipment will not experience corrosion failure. Not only do the models predict this result, but it is in agreement with experience. Corrosion is an electrochemical process and liquid phase moisture is a necessary condition for the process to occur. Under the thermal conditions of equipment operation only vapor phase moisture is present within microcircuit enclosures.

### 4.5.5 Differential Temperature for Use in Failure Models

Transient differential temperature at the failure site is the principal source of stress that drives the failure mechanisms discussed in paragraphs 4.5.2 and 4.5.3. The models developed for these mechanisms utilize the differential temperature raised to a power. Hence, the model predictions are sensitive to the differential temperature value employed. Development of realistic delta temperature values for use in the models is discussed in Appendix I.

### 4.5.6 Representative Microcircuit Configuration (RMC)

The objective for the failure mechanism models developed in this report was to obtain "easy to use" models with variables that are reasonable and accessible for use by reliability analysts and that accurately predict the time or number of cycles to failure. This dual objective is self-contradictory in that accuracy requires inclusion of all variables with significant effect on the failure mechanisms and simplicity requires minimization of variables. Our solution to this dilemma is two-fold:
(1) Develop models in accordance with the applicable laws of physics, chemistry and engineering that fully and accurately relate all significant variables to their effect on component life.
(2) Simplify the models for use by reliability analysts using the concept of a Representative Microcircuit Configuration (RMC), as further described.

When mature technology microcircuits are produced to established performance and package standards by numerous manufacturers, competitive pressures ensure that.a high degree of similarity will exist between parts of equivalent performance housed in interchangeable packages. Hence, many of the failure mechanism variables will be approximately equal for all MIL-M-38510 microcircuits. Production efficiency requirements will ensure repetitive usage of materials and certain geometric features throughout a complete technology product line. The RMC concept exploits this similarity.

Westinghouse experience in application, reliability characterization and
failure analysis of microcircuits and design and manufacturing of multichip hybrids, combined with discussions with the microcircuit suppliers ${ }^{[102,103]}$ has resulted in the following definition of an RMC:

- PACKAGE : Hermetically sealed
: $\mathrm{Al}_{2} \mathrm{O}_{3}$ Alumina ceramic base and lid
- DIE
: Silicon
: Diagonal length $=3.23 \times 10^{-3} \mathrm{~m}(127 \mathrm{mils})$
: Thickness $=3.7 \times 10^{-4} \mathrm{~m}(14.5 \mathrm{mils})$
- DIE ATtACH : Mounted to package base
: Ag-glass epoxy
: After cure thickness $=5.1 \times 10^{-5} \mathrm{~m}(2 \mathrm{mils})$
- CONDUCTORS : Aluminum
: Passivation coated
: Width $\left.=1.5 \times 10^{-4} \mathrm{~cm}(1.5 \mathrm{microns})(0.06 \mathrm{mils})\right)$
$:$ Thickness $=7.5 \times 10^{-5} \mathrm{~cm}(7500 \mathrm{~A})(0.03 \mathrm{mils})$.
- BOND PADS : Aluminum
: Not passivation coated
$:$ Size $=1 \times 10^{-2} \mathrm{~cm} \times 1 \times 10^{-2} \mathrm{~cm}(4 \mathrm{mils} \times 4 \mathrm{mils})$
$:$ Thickness $=7.5 \times 10^{-5} \mathrm{~cm}(7500 \mathrm{~A})(0.03 \mathrm{mils})$
- BOND WIRE : Aluminum
$:$ Diameter $=3.2 \times 10^{-2} \mathrm{~mm}\left({ }^{*} 1.25 \mathrm{mils}\right)=3.2 \times 10^{-3} \mathrm{~cm}$
- APPLIED VOLTAGE : 5 Volts
- QUALITY LEVEL : MIL-STD-883, Level B
: Allowable vertical edge crack length $=1.3 \times$ $10^{-4} \mathrm{~m}$ ( 5 mils )
- AMBIENT: Temperature $=70^{\circ} \mathrm{C}$
: Humidity $=90 \% \mathrm{RH}$


### 4.5.7 Model Simplification

## 4.5.\%.1 Fallure Mechanism Models

The following non-electrical (package related) failure mechanism models have been developed in Section 4.5 of this report.
(1) Bond Wire Flexure Fàtigue (Equations F5.7a and F5.8, Paragraph 4.5.2.2(1)).
(2) Shear Fatigue at Bond Pad/Substrate Interface (Equations F5.9 and F5.10, Paragraph 4.5.2.2(2)).
(3) Shear Fatigue at Bond Pad/Bond Wire Interface (Equations F5. 10 and F5.14, Paragraph 4.5.2.2(3)).
(4) Die Brittle Cracking (Equations G.4, G.5 and G.6, Paragraph 4.5.3.2(1)).
(5) Die Fatigue Cracking (Equations G.5, G.6 and G.10e, Paragraph 4.5.3.2(2)).
(6) Die Attach Fatigue (Equations G.11 and G.12, Paragraph 4.5.3.2(3)).
(7) Substrate Attach Fatigue (Equation G.13, Paragraph 4.5.3.2(4)).
(8) Conductor Metallization Corrosion (Equations H2.la and H3.8, Paragraph 4.5.4.2(1)).
(9) Bond Pad Corrosion (Equations H2.1a and H3.10, Paragraph 4.5.4.2(2)).

### 4.5.7.2 Failure Mechanisms Present in an RMC

Using the parenthetical numbers assigned to the failure mechanisms in paragraph 4.5.7.l, only the following mechanisms are potentially present in an RMC:
(1) Bond Wire Flexure Fatigue
(2) Shear Fatigue at Bond Pad/Substrate Interface
(4) Die Brittle Cracking
(5) Die Fatigue Cracking
(6) Die Attach Fatigue
(8) Conductor Metallization Corrosion
(9) Bond Pad Corrosion

The mechanisms which are not included in an RMC, and the reasons for their
omission, are discussed below.
(3) Shear Fatigue at Bond Pad/Bond Wire Interface

This mechanism is not present because the bond pad and bond wire are made from the same material, thus eliminating the cause of the mechanism (differential thermal expansion). Single-metal bonds have greater industry usage than do bi-metallic bonds, so the former is used in the RMC.

## (7) Substrate Attach Fatigue

This mechanism is not present because the predominant practice in microcircuit construction is to directly attach the die to the package base. This mechanism can be of significance in hybrids, however.

### 4.5.7.3 Simplified Failure Mechanism Models for an RMC

The applicable fully delineated failure mechanism models defined in paragraphs $4.5 .2,4.5 .3$ and 4.5 .4 have been simplified by the Representative Microcircuit Configuration (RMC) concept described in paragraph 4.5.6 and are presented below. The simplification applies only to the seven applicable models discussed in paragraph 4.5.7.2.

### 4.5.7.3.1 Bond Wire Flexure Fatigue

The fully delineated model for this mechanism is defined by equations F5.7a and . 5 5. 8 given in paragraph 4.5.2.2(1). Following is a list of the variables in this model for which numerical values are obtained from the sources noted, using the RMC concept:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $A_{1}$ | $3.9232 \times 10^{-10}$ | N/A | Table 4.5-4 |
| ${ }^{1}$ | -5.134 | N/A | Table 4.5-4 |
| $r$ | $1.6 \times 10^{-2}$ | mm | RMC |
| $\alpha_{w}$ | $23.2 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-1 |
| $\alpha_{s}$ | $4.67 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-2 |

Incorporating these values provided the following simplified model:

$$
\begin{equation*}
N_{f}(f l e x)=5.6 \times\left. 10^{7}\right|_{-} ^{-} \frac{\cos ^{-1}\left(9.66-1.79 \times 10^{-5} \Delta T\right)}{15}-\left.1\right|_{-} ^{-5.134} \tag{4.5.1}
\end{equation*}
$$

where
$\Delta T$ is the temperature difference encountered in the application, obtained from Table 4.5-17, or user supplied.

### 4.5.7.3.2 Shear Fatigue at Bond Pad/Substrate Interface

The fully delineated model for this mechanism is defined by equations 55.9 and F5. 10 given in paragraph 4.5.2.2(2). Following is a list of the variables in this model for which numerical values are obtained from the sources noted, using the RMC concept:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $A_{2}$ | $4.3386 \times 10^{-11}$ | $N / A$ | Table 4.5-5 |
| $\mathrm{n}_{2}$ | -5.134 | N/A | Table 4.5-5 |
| $k^{2}$ | $1.46 \times 10^{-5}$ | $N / A$ | Table 4.5-6 |

Incorporating these values provides the following simplified model:

$$
\begin{equation*}
N_{f(\text { shear }) s}=2.9078 \times 10^{14} \Delta T-5.134 \tag{4.5.2}
\end{equation*}
$$

## where

$\Delta T$ is the temperature difference encountered in the application, obtained from Table 4.5-17, or user supplied.

### 4.5.7.3.3 Die Brittle Cracking

The fully delineated model for this mechanism is defined by equations G.4, G. 5 and G. 6 given in paragraph 4.5.3.2(1). Following is a list of the variables in this model for which numerical values are obtained from the sources noted, using the RMC concept:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| K Ic | 0.82 | $\mathrm{MPa} \sqrt{\mathrm{m}}$ | Table 4.5-7 |
| $\alpha_{s}$ | $7.3 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-9 |
| $\alpha_{\text {d }}$ | $4.67 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-7 |
| $\mathrm{E}_{\mathrm{s}}$ | $255 \times 10^{9}$ | Pa | Table 4.5-9 |
| $E_{\text {a }}$ | $2.8 \times 10^{9}$ | Pa | Table 4.5-8 |
| X | $5.1 \times 10^{-5}$ | m | RMC |
| L | $3.22 \times 10^{-3}$ | m | RMC |
| $a_{i}$ | $1.3 \times 10^{-4}$ | m | RMC |

Incorporating these values provides the following simplified criterion for the presence of this failure mechanism:

$$
\begin{equation*}
a_{c}=\frac{17.2}{\Delta T^{2}} \leq a_{i}=1.3 \times 10^{-4} \tag{4.5.3}
\end{equation*}
$$

where
$\Delta T$ is the temperature difference encountered in the application, obtained from Table 4.5-17, or user supplied.

The maximum value of $\Delta T$ obtainable from Table $4.5-17$ is $\Delta T=55^{\circ} \mathrm{C}$.
Substituting this value in equation 4.5 .3 yields the following:

$$
a_{c}=\frac{17.2}{(55)^{2}}=5.67 \times 10^{-5 m}>a_{i}=1.3 \times 10^{-4 m}
$$

Since $a_{c}$ is two orders of magnitude greater than $a_{j}$, this failure mechanism will not occur in any MIL-HDBK-217 application environment defined in Table 4.5-17 for the Representative Microcircuit Configuration presented in paragraph 4.5.6.

### 4.5.7.3.4 Die Fatigue Cracking

The fully delineated model for this mechanism is defined by equations G.5, G. 6 and G.10e given in paragraph 4.5.3.2(2). Following is a list of the variables in this model for which numerical values are obtained from the sources noted, using the RMC concept:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $n$ | 4 | N/A | Table 4.5-7 |
| A | $1 \times 10^{-12}$ | N/A | Table 4.5-7 |
| $a_{i}$ | $1.3 \times 10^{-4}$ | m | RMC |
| $a_{f}$ | $3.8 \times 10^{-4}$ | m | Para. 4.5.3.2(2) |
| $\mathrm{K}_{\text {I }}$ | 0.82 | $\mathrm{MPa} \sqrt{\mathrm{m}}$ | Table 4.5-7 |
| $\alpha_{s}$ | $7.3 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-9 |
| $\alpha_{d}$ | $4.57 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-7 |
| $E_{s}$ | $255 \times 10^{9}$ | Pa | Table 4.5-9 |
| $E_{a}$ | $2.8 \times 10^{9}$ | Pa | Table 4.5-8 |
| X | $5.1 \times 10^{-5}$ | m | RMC |
| L | $3.22 \times 10^{-3}$ | m | RMC |

Incorporating these values provides the following simplified model:

$$
\begin{equation*}
N_{f}=3.3 \times 10^{18} / \Delta T^{4} \tag{4.5.4}
\end{equation*}
$$

where
$\Delta T$ is the temperature difference encountered in the application, obtained from Table 4.5-17, or user supplied.

### 4.5.7.3.5 Die Attach Fatigue

The fully delineated model for this mechanism is defined by equations G.ll and G. 12 given in paragraph 4.5.3.2(3). Following is a list of the variables in this model for which numerical values are obtained from the sources noted, using the RMC concept:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $\alpha_{s}$ | $7.3 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-9 |
| $\alpha_{\text {d }}$ | $4.67 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-7 |
| $x$ | $5.1 \times 10^{-5}$ | m | RMC |
| $\gamma^{\prime} \mathrm{f}$ | 1.1 | N/A | Table 4.5-8 |
| c | -0.49 | $N / A$ | Table 4.5-8 |
| L | $3.22 \times 10^{-3}$ | m | RMC |

Incorporating these values provides the following simplified model:

$$
\begin{equation*}
N_{f}=3.217 \times 10^{7} \Delta T^{-2.041} \tag{4.5.5}
\end{equation*}
$$

where
$\Delta T$ is the temperature difference encountered in the application, obtained from Table 4.5-17, or user supplied.

### 4.5.7.3.6 Conductor Metallization Corrosion

The fully delineated model for this mechanism is defined by equations H2.la and H3.8'given in paragraph 4.5.4.2(1). Following is a list of the variables in this model for which numerical values are obtained from the sources noted, using the RMC concept:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $\mathrm{k}_{1}$ | 0.1 | N/A | Table 4.5-12 |
| $k_{2}$ | 10 | N/A | Table 4.5-13 |
| $\mathrm{k}_{4}$ | 0.34 | N/A | Figure 4.5-1 |
| w | $1.5 \times 10^{-4}$ | cm | RMC |
| h | $7.5 \times 10^{-5}$ | Cm | RMC |
| n | 3 | N/A | Table 4.5-12 |
| d | 2.7 | gm/cc | Table 4.5-12 |
| M | 27 | amu | Table 4.5-12 |
| V | 5 | Volts | RMC |
| $\rho$ | $7.3 \times 10^{6}$ | ohm-cm | Table 4.5-15 |

Incorporating these values provides the following simplified model:

$$
\begin{align*}
\tau_{2 \mathrm{~m}} & =1.7 \times 10^{6} \mathrm{~K}_{3} \text { seconds }  \tag{4.5.6}\\
\text { or } \quad \tau_{2 \mathrm{~m}} & =483 \mathrm{~K}_{3} \text { hours } \tag{4.5.6a}
\end{align*}
$$

where
$K_{3}$ is the equipment operating time factor obtained from Table 4.5-14.

### 4.5.7.3.7 Bond Pad Corrosion

The fully delineated model for this mechanism is defined by equations H 2.1 a and H3.lO given in paragraph 4.5.4.2(2). Following is a list of the variables in this model for which numerical values are obtained from the sources noted, using the RMC concept:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $\mathrm{k}_{1}$ | 0.1 | N/A | Table 4.5-12 |
| $\mathrm{k}_{2}$ | 10 | N/A | Table 4.5-13 |
| $\mathrm{k}_{4}$ | 0.34 | N/A | Figure 4.5-1 |
| $V_{c}$ | $2.2 \times 10^{-9}$ | $\mathrm{cm}^{3}$ | Table 4.5-11 |
| n | 3 | N/A | Table 4.5-12 |
| d | 2.7 | gm/cc | Table 4.5-12 |
| M | 27 | amu | Table 4.5-12 |
| V | 5 | Volts | RMC |
| $\rho$ | $7.3 \times 10^{6}$ | ohm-cm | Table 4.5-15 |

Incorporating these values provides the following simplified model:

$$
\begin{align*}
\tau_{2 W} & =2.3 \times 10^{9} \mathrm{~K}_{3} \text { seconds }  \tag{4.5.7}\\
\text { or } \quad \tau_{2 W} & =6.3 \times 10^{5} \mathrm{~K}_{3} \text { hours } \tag{4.5.7a}
\end{align*}
$$

where

$$
K_{3} \text { is the equipment operating time factor obtained from Table 4.5-14. }
$$

### 4.5.7.4 Other Simplified Failure Mechanism Models

Two failure mechanisms are identified in paragraph 4.5.7.2 that are not present in an RMC, and hence would be expected to form a minor part of the total package-related failures experienced in military electronic equipment. These mechanisms can be simplified for evaluation purposes by assuming probable material combinations and construction practices that would cause the mechanisms to be activated. The two remaining mechanisms are discussed below.

### 4.5.7.4.1 Shear Fatigue at Bond Pad/Bond Wire Interface

The fully delineated model for this mechanism is defined by equations 55.10 and F5.14 given in paragraph 4.5.2.2(3). This mechanism can be activated in a microcircuit only when the bond pad and bond wire are made from dissimilar
materials. If these two elements are made from dissimilar materials, the most probable combination would be gold wire bonded to aluminum pads. Assuming the bond pad is on a silicon die and that this combination is chosen, following is a list of the variables in this model for which numerical values are obtained from the sources noted:

VARIABLE $\qquad$
VALUE
UNITS
SOURCE

| $\mathrm{A}_{2}$ | $4.2948 \times 10^{-12}$ | $\mathrm{~N} / \mathrm{A}$ | Table 4.5-5 |
| :--- | :--- | :--- | :--- |
| $\mathrm{n}_{2}$ | -4.9828 | $\mathrm{~N} / \mathrm{A}$ | Table 4.5-5 |
| $\alpha_{\mathrm{w}}$ | $14.2 \times 10^{-6}$ | $\mathrm{~m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-1 |
| $\alpha_{\mathrm{s}}$ | $4.67 \times 10^{-6}$ | $\mathrm{~m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-2 |

Incorporating these values provides the following simplified model:

$$
\begin{equation*}
N_{f(\text { shear }) w}=1.4 \times 10^{15} \Delta T^{-4.983} \tag{4.5.8}
\end{equation*}
$$

where
$\Delta T$ is the temperature difference encountered in the application, obtained from Table 4.5-17, or user supplied.

### 4.5.7.4.2 Substrate Attach Fatigue

The fully delineated model for this mechanism is defined by equations G. 13 given in paragraph 4.5.3.2(4). This mechanism can be activated only when a substrate is inserted between a microcircuit die and the package base. Normally, this type of construction is employed in hybrid/multichip microcircuits. The substrate will usually be a base for conductor metallization to provide interconnections between passive and active leadless (chip) components. Hybrid circuits dissipating several watts of power are typicalty housed in hermetically sealed copper alloy packages with aluminum nitride substrates, employing $70-30$ In - Pb solder for efficient heat transfer. Assuming this type of construction, following is a list of the
variables in this model for which numerical values are obtained from the sources noted:

| VARIABLE | VALUE | UNITS | SOURCE |
| :---: | :---: | :---: | :---: |
| $\alpha_{s}$ | $4.5 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-9 |
| $\alpha_{c}$ | $16.9 \times 10^{-6}$ | $\mathrm{m} / \mathrm{m} /{ }^{\circ} \mathrm{C}$ | Table 4.5-10 |
| ${ }_{\text {c }}^{\text {sa }}$ | $1.5 \times 10^{-4}$ | m | Assumed |
| $\gamma_{f}$ | 1.1 | N/A | Table 4.5-8 |
| c | -0.49 | N/A | Table 4.5-8 |

Incorporating these values provides the following simplified model:

$$
\begin{equation*}
N_{f}=98.4\left(L_{s} \Delta T\right)^{-2.041} \tag{4.5.9}
\end{equation*}
$$

where
$L_{S}$ is the diagonal length of the substrate, meters.
$\Delta T$ is the temperature difference encountered in the application, obtained from Table 4.5-17, or user supplied.

### 4.5.8 Relationship Between Cycles and Time

The reliability analyst requires knowledge of the time to failure for the various failure mechanisms that may be present in an electronic component being analyzed. However, seven of the nine models developed in this report for package related failure mechanisms are a function of temperature change magnitude and can only predict the number of stress/strain cycles to fatigue or cracking failure. The duration of the temperature change cycles has negligible effect on these mechanisms, as discussed in Appendix I.

Temperature change cycles are caused by the following conditions:
(1) Air transportation in non-temperature controlled cargo compartments while the equipment is not operating.
(2) Climatic diurnal temperature variations when the equipment is not operating.
(3) Temperature increase above ambient due to internal heat dissipation during equipment operation.

The first condition is infrequently encountered and the second is of negligible temperature magnitude, as discussed in Appendix I and delineated in Table I-5. Hence, the third condition is the principal source of temperature variation.

In the context of this report an equipment operating cycle is defined to be the time elapsed between equipment turn-on and turn-off. Some types of equipment have varying power levels during an operating cycle while other types have a constant power level. The operating power level directly affects the temperature change magnitude at each component.

Equipment operating cycles vary from nearly continuous for certain types of equipment to short intermittent periods for other types. Hence, accurate determination of mean time to failure for these mechanisms depends upon accurate determination of operating cycle duration for the type of equipment being analyzed.

Little published data exists on the relationship between operating cycle duration and equipment type. Accumulation and analysis of such data are beyond the scope of this report. Time and temperature analysis of specified equipment mission profiles are the best source of data for operating temperature cycle magnitude and duration.

Appendix $I$, Table $I-1$, records the results of measured temperature variation during a flight mission for an unidentified airborne electronic equipment. This data suggests that the major temperature variations recorded had an average duration of 1.1 hours per cycle. When more accurate information is not available, it is conservative to assume a short thermal cycle duration. Based on this data the following relationship between temperature cycles and
time is tentatively offered:

$$
\begin{equation*}
T_{f}=1.25 \mathrm{~N}_{f} \tag{4.5.10}
\end{equation*}
$$

where
$T_{f}$ is the mean time to failure, hours
$N_{f}$ is the mean number of cycles to failure obtained from equations
$4.5 .1,4.5 .2,4.5 .4,4.5 .5$ and 4.5 .8 through 4.5 .9 (or the fully
delineated equations from which these are derived).

### 4.5.9 Failure Mechanism Model Assessment

Operational use of electronic equipment subjects the microcircuits employed therein to various levels of electrical, mechanical, thermal, chemical and environmental stresses. These stresses activate latent failure mechanisms that have not been removed by microcircuit quality control inspections, tests and screens. Many of these mechanisms are wearout type which cause the microcircuit probability to increase with time. In general the probability increase rate is different for each mechanism. Hence, meany mechanisms are simultaneously competing to cause device failure. Evaluation of the mean time to failure for each competing mechanism permits ranking to identify the most probable mechanisms.

The nine package related failure mechanisms modeled in this report are ranked following, based on the following assumptions:
(1) The microcircuits conform to the Representative Microcircuit Configuration (RMC) defined in paragraph 4.5.6.
(2) The relationship between the mean number of cycles to failure and the mean time to failure conforms to equation 4.5.11.
(3) The two mechanisms not present in an RMC conform to the probable configuration discussed in paragraph 4.5.7.4.
(4) The microcircuits are used in an equipment used in an application environment, as delineated in Table 4.5-17, for which a maximum $\Delta T$
is expected, i.e. either $A_{U}, G_{B}$ or $N_{U}$, for which $\Delta T=55^{\circ} \mathrm{C}$
is expected.
(5) While substrates are not utilized in an RMC, for ranking purposes, a substrate size of $2.5 \times 10^{-2} \mathrm{~m}$ square ( 1 inch square) attached with 70 - 30 In - Pb solder with an attach thickness of $1.5 \times 10^{-4} \mathrm{~m}$ ( 6 mils) is assumed.

Tabulated following are these nine mechanisms listed in order of increasing mean time to failure:

| FAILURE MECHANISM | $T_{f}$ <br> MEAN TIME TO HOURS | FAILURE YEARS |
| :---: | :---: | :---: |
| (1) Substrate Attach Fatigue | 30 | - |
| (2) Conductor Metallization Corrosion | 724 | - |
| (3) Die Attach Fatigue | $1.1 \times 10^{4}$ | 1.25 |
| (4) Bond Pad/Die Interface Shear Fatigue | $4.2 \times 10^{5}$ | 48 |
| (5) Bond Pad/Wire Corrosion | $9.4 \times 10^{5}$ | 107 |
| (6) Bond Pad/Bond Wire Interface Shear Fatigue | $3.0 \times 10^{6}$ | 433 |
| (7) Die Fatigue Cracking | $4.5 \times 10^{11}$ | $5.1 \times 10^{7}$ |
| (8) Bond Wire Flexure Fatigue | $2.9 \times 10^{17}$ | $3.4 \times 10^{13}$ |
| (9) Die Brittle Cracking | $\infty$ | - |
| 4.5.9.1 Discussion |  |  |
| The package related failure mechanism models con coefficients and exponents. The values utilized upon available data for materials similar to thos construction, due to the unavailability of data Hence, it is emphasized that the mean time to fa are useful only for ranking the mechanisms relat on the actual materials of construction are avai capable of estimating the mean time to failure for various application environments. | n material dep these models used in microc the actual ma re values pred to each other. le, the models microcircuits | ndent <br> re based rcuit erials. cted above When data will be used in |

## Table 4.5-1

## Wire Properties

| Wire Material | $\begin{gathered} \alpha_{w} \\ m / m / c \end{gathered}$ | $\mathrm{P}_{\mathrm{a}}$ |
| :---: | :---: | :---: |
| Alumi num | $23.2 \times 10^{-6}$ | $69 \times 10^{9}$ |
| Copper | $17.6 \times 10^{-6}$ | $118 \times 10^{9}$ |
| Gold | $14.2 \times 10^{-6}$ | Up to $82 \times 10^{9}$ |
| Palladium | $11.7 \times 10^{-6}$ | $124 \times 10^{9}$ |

Table 4.5-2

Bond Pad Substrate Properties

Bond Pad
Substrate
Material
$\alpha_{s}$
Gallium Arsenide $5.73 \times 10^{-6}$
Silicon $4.67 \times 10^{-6}$

# Table 4.5-3 <br> Encapsulant Properties 

| ENCAPSULANT | $\begin{array}{r} \alpha e \\ \mathrm{~m} / \mathrm{m} / \mathrm{c} \end{array}$ |
| :---: | :---: |
| Epoxy |  |
| Rigid, Unfilled | $55 \times 10^{-6}$ |
| Rigid, Filled | $30 \times 10^{-6}$ |
| Flexible, Unfilled | $100 \times 10^{-6}$ |
| Flexible, Filled | $70 \times 10^{-6}$ |
| Polyester |  |
| Rigid, Unfilled | $75 \times 10^{-6}$ |
| Flexible, Unfilled | $130 \times 10^{-6}$ |
| Silicone |  |
| Flexible, Unfilled | $400 \times 10^{-6}$ |
| Urethane |  |
| Flexible, Unfilled | $150 \times 10^{-6}$ |

Table 4.5-4
Constants for Fatigue Stress in Bending and Axial Loading

| MATERIAL | $\mathrm{A}^{*}$ | $\mathrm{n}_{1}^{*}$ |
| :---: | :---: | :---: |
| Aluminum | $3.9323 \times 10^{-10}$ | -5.134 |
| Copper | $1.0133 \times 10^{-21}$ | -9.1169 |
| Gold | $3.5844 \times 10^{-11}$ | -4.9828 |

* Values are engineering estimates

Table 4.5-5
Constants for Fatigue Stress in Shear

| MATERIAL | $A_{2}^{*}$ | $n_{2}^{*}$ |
| :--- | :--- | :--- |
| Aluminum | $4.3386 \times 10^{-11}$ | -5.134 |
| Copper | $1.9897 \times 10^{-23}$ | -9.1169 |
| Gold | $4.2948 \times 10^{-12}$ | -4.9828 |

* Values are engineering estimates

Table 4.5-6
Bond Pad-Substrate Shear Constant

| BONDPAD <br> MATERIAL | K |  |
| :--- | :---: | :---: |
|  | SUBSTRATE MATERIAL |  |
| Aluminum | $1.46 \times 10^{-5^{*}}$ | $1.56 \times 10^{-5^{*}}$ |
| Gold | $0.90 \times 10^{-5^{*}}$ | $1.02 \times 10^{-5^{*}}$ |

* Values are engineering estimates

Table 4.5-7

## Die properties

| die material | $\begin{array}{r} E \\ \mathrm{~Pa} \end{array}$ | $\begin{gathered} \alpha \\ m / m / c \end{gathered}$ | $\begin{aligned} & K_{I C} \\ & M P \sqrt{m} \end{aligned}$ | A | n |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Silicon | $128 \times 10^{9}$ | $4.67 \times 10^{-6}$ | 0.82 | * $10^{-12}$ | * 4 |
| Gallium |  |  |  |  |  |
| Arsenide | $89 \times 10^{9}$ | $5.73 \times 10^{-6}$ | 0.31 | * $10^{-12}$ | * 4 |

* Values are engineering estimates

Table 4.5-8

Die attach properties

| Die Attach Material | Percentage of different constituents | ```Tg or melting temperature *``` | $\begin{aligned} & \mathrm{E}_{\mathrm{a}} \\ & \mathrm{~Pa} \end{aligned}$ | $\gamma^{\prime} f$ | c |
| :---: | :---: | :---: | :---: | :---: | :---: |
| Eutectic | Au-3\% Si | 280 | $59.2 \times 10^{9}$ | *1.1 | *-. 49 |
|  | Au -12\% Ge | 363 | $83.0 \times 10^{9}$ | *1.1 | *-. 49 |
|  | $\mathrm{Au}-40 \% \mathrm{Ge}$ | 356 | $69.3 \times 10^{9}$ | *1.1 | *-. 49 |
| Solder | In-70\% Pb -30\% | 175 | *11.7 $\times 10^{9}$ | *1.1 | *-. 49 |
|  | Sn-40\% Pb -60\% | * 100 | *3.8 $\times 10^{9}$ | *1.1 | *-. 49 |
|  | Sn-5\% Pb -95\% | *170 | $3.8 \times 10^{9}$ | *0.18 | *. 13 |
|  | $\mathrm{Sn}-10 \% \mathrm{~Pb}-90 \%$ | 200 | $3.8 \times 10^{9}$ | *1.1 | *-. 49 |
| Epoxy - 155 |  |  |  |  |  |
| Conductive | --- | 155 | $4.1 \times 10^{9}$ | *1.1 | *-. 49 |
| Non Conductive | ve | 155 | $2.8 \times 10^{9}$ | *1.1 | *-. 49 |
| Polyimide | --- | 275 | $4.5 \times 10^{-9}$ | *1.1 | *-. 49 |

* Values are engineering estimates

Table 4.5-9
Substrate properties

| Type of substrate <br> Material | $\alpha_{S}$ <br> $\mathrm{~m} / \mathrm{m} / \mathrm{c}$ | $\mathrm{E}_{\mathrm{S}}$ |
| :--- | :--- | :--- |
| Silicon | $4.67 \times 10^{-6}$ | $164 \times 10^{9}$ |
| Alumina | $7.3 \times 10^{-6}$ | $255 \times 10^{9}$ |
| Copper | $16.9 \times 10^{-6}$ | $118 \times 10^{9}$ |
| Beryllium Oxide | $8.3 \times 10^{-6}$ | $265 \times 10^{9}$ |
| Aluminum Nitride | $4.5 \times 10^{-6}$ | $2.75 \times 10^{9}$ |
| Silicon Carbide | $3.7 \times 10^{-6}$ | $>331 \times 10^{9}$ |



Table 4.5-11
BOND PAD CORROSION VOLUME

| GALVANIC RELATIONSHIP OF BOND PAD MATERIAL TO BOND WIRE MATERIAL (FROM TABLE 4.5-16) | $\begin{aligned} & \text { BOND } \\ & \text { TYPE } \end{aligned}$ | $\begin{gathered} \text { CORROSION VOLUME } \\ V_{c} \\ \mathrm{~cm}^{3} \end{gathered}$ | Equation Number | CORROSIVELY ATTACKED MEMBER |
| :---: | :---: | :---: | :---: | :---: |
| ANODIC | ALL | $V_{C}=0.3 \mathrm{~s}^{2} \mathrm{t}_{\mathrm{b}}$ | H.8a | BOND |
| CATHODIC | WEDGE OR CRESCENT | $V_{C}=0.236 \mathrm{D}^{3}$ | H.8b | $\begin{aligned} & \text { BOND } \\ & \text { WIRE } \end{aligned}$ |
|  | BALL | $V_{C}=3.77 \mathrm{D}^{3}$ | H. 8 C |  |
|  | UNKNOWN | $V_{C}=0.236 \mathrm{D}^{3}$ | H.8b |  |
| NONE <br> (ie. same material <br> for pad and wire) | ALL | LEAST VALUE OF $\begin{aligned} & V_{c}=0.3 \mathrm{~s}^{2} \mathrm{t}_{\mathrm{b}} \\ & \mathrm{~V}_{\mathrm{c}}=0.236 \mathrm{D}^{3} \end{aligned}$ | $\begin{aligned} & \mathrm{H} .8 \mathrm{a} \\ & \mathrm{H} .8 \mathrm{~b} \end{aligned}$ | MEMBER <br> WITH <br> LEAST <br> $V_{C}$ |

NOTE: $D=$ Bond wire diameter, cm
$s=$ Bond pad size, cm (for a square pad)
$\mathrm{t}_{\mathrm{b}}=$ Bond pad thickness, cm

Table 4.5-12
Corrosion Properties of Metals

| Material | Physical <br> Property <br> Index ( $\mathrm{K}_{1}$ ) | Atomic Weight (M) | Density <br> (d) gm/cc | Chemical Valence ( $n$ ) |
| :---: | :---: | :---: | :---: | :---: |
| Aluminum | 0.1 | 27 | 2.7 | 3 |
| Copper | 0.5 | 64 | 8.93 | 2 |
| Gold | 1.0 | 197 | 19.32 | 3 |


| Table 4.5-13 |  |
| :---: | :---: |
| Coating Integrity Index |  |
| COATING TYPE | COATING INTEGRITY INDEX ( $k_{2}$ ) |
| No Coating | 1 |
| Partially Bonded | 10-50 (NOTE 1) |
| Completely Bonded | 100 |

NOTE 1: When a metallization passivation layer is present and the defect level is unknown, use $k_{2}=10$.

| Table 4.5-14 |  |
| :---: | :---: |
| Equipment Operating Time Factor |  |
| Number of Operating |  |
| Hours Per Day | $K_{3}$ |
| 1 |  |
| 2 | 1.04 |
| 3 | 1.09 |
| 4 | 1.20 |
| 5 | 1.26 |
| 6 | 1.33 |
| 7 | 1.41 |
| 8 | 1.50 |
| 9 | 1.60 |
| 10 | 1.71 |
| 11 | 1.85 |
| 12 | 2.00 |
| 13 | 2.18 |
| 14 | 2.40 |
| 15 | 2.67 |
| 16 | 3.00 |
| 17 | 3.43 |
| 18 | 4.00 |
| 19 | 4.80 |
| 20 | 6.00 |
| 21 | 8.00 |
| 22 | 12.00 |
| 23 | 24.00 |
| 24 | $I n f i n i t y$ |


| Table 4.5-15 |
| :--- |
| Electrolyte Resistivity |
| ENVIRONMENT |
| Normal $\quad \rho(0 \mathrm{hm} / \mathrm{cm})$ |
| Corrosive |

NOTE: Assume a normal environment unless there is compelling reason to assume a corrosive environment.

Table 4.5-16
Galvanic Electrochemical Potential

| Material | Standard Electrode Potential, Volts |
| :---: | :---: |
| Gold | 1.5 More Cathodic |
| Palladium | 0.95 |
| Silver | 0.8 |
| Copper | 0.34 |
| Chromium | -0.74 |
| Aluminum | -1.66 More Anodic |

NOTE: The electrical bias voltage shall be chosen as follows:
(1) For dissimilar bond wire/bond pad metals use the larger of the applied signal or power supply voltage or the galvanic potential determined from the Table as follows:

$$
v_{\text {galvanic }}=1+\left(v_{\text {cathode }}-V_{\text {anode }}\right)
$$

(2) For similar metals use the applied signal or power supply voltage.

Table 4.5-17

Recommended Value for Component Operating $\Delta T$ (See Note 1)

| USAGE ENVIRONMENT CLASSIFICATION |  | $\begin{array}{r} \hline \Delta T \\ { }^{\circ} \mathrm{C} \end{array}$ |
| :---: | :---: | :---: |
| MIL-HDBK-217E | PROPOSED |  |
| ${ }^{A_{I A}}{ }^{\text {A }}$ IB ${ }^{\text {A }}$ IC ${ }^{\text {A }}{ }_{\text {IF }}{ }^{A_{I T}}{ }^{\text {A }}$ RW | ${ }^{\text {I }}$ | 30 |
| $A_{U A} A_{U B} A_{U C}{ }^{A_{U F}} A_{U T}$ | $\mathrm{A}_{\mathrm{U}}$ | 55 |
| $\mathrm{C}_{\mathrm{L}}$ | $\mathrm{C}_{\mathrm{L}}$ | NOTE 2 |
| $\mathrm{G}_{\mathrm{B}} \mathrm{G}_{\text {MS }}$ | $\mathrm{G}_{\mathrm{B}}$ | 30 |
| $\mathrm{G}_{\mathrm{F}}$ | $\mathrm{G}_{\mathrm{F}}$ | 55 |
| $G_{M} M_{P}$ | $\mathrm{G}_{\mathrm{M}}$ | NOTE 3 |
| $M_{F A} M_{F F} M_{L}$ | M | NOTE 2 |
| $\mathrm{N}_{\mathrm{H}} \mathrm{N}_{\mathrm{S}} \mathrm{N}_{\text {SB }}$ | $\mathrm{N}_{\mathrm{I}}$ | 50 |
| $\mathrm{N}_{\mathrm{U}}$ | $\mathrm{N}_{\mathrm{U}}$ | 55 |
| ${ }^{U_{S L}}$ | $\mathrm{N}_{\mathrm{UL}}$ | NOTE 2 |
| $\mathrm{N}_{\mathrm{UU}}$ | $\mathrm{N}_{\mathrm{UU}}$ | 35 |
| $\mathrm{S}_{\mathrm{F}}$ | $\mathrm{S}_{\mathrm{F}}$ | 35 |

NOTE 1. Table 4.5-17 $\Delta T$ values are for use when thermal analysis or test data are not available.
2. Application environments referring to this note are of short duration and have negligible effects on the package (non-electrical) related failure mechanisms, for which the pre-launch storage conditions will have the dominant effect. Use $\Delta T=5^{\circ} \mathrm{C}$ for storage under controlled storage conditions and $\Delta T=20^{\circ} \mathrm{C}$ for uncontrolled storage conditions.
3. Use $G_{B}$ application environment for equipment mounted in temperature controlled compartments and $G_{F}$ for uncontrolled compartments.
Table 4.5-18
Typical Values for Die/Substrate Attach Thickness
ATtACH MATERIAL TYPICAL THICKNESS
METERS ..... MILS
Au - Si Eutectic $2.5 \times 10^{-6}$ ..... 0.1Au - Ge Eutectic$2.5 \times 10^{-6}$0.1
Au - Ge Solder$7.6 \times 10^{-5}$3
Sn 62 Solder
80 - 20 Au - Sn Solder$7.6 \times 10^{-5}$3
Dielectric Epoxy (Die)$7.6 \times 10^{-5}$3
3.5Conductive Epoxy (Die)$8.9 \times 10^{-5}$
Dielectric Epoxy (Substrate) $1.3 \times 10^{-4}$ ..... 5$8.9 \times 10^{-5}$3.5
70 - 30 In - Pb Solder $1.5 \times 10^{-4}$ ..... 6


Figure 4.5-1 TEMPERATURE-HUMIDITY ENVIRONMENT ACCELERATIIN FACTOR

Figure 4.5-2
Time to Reach 3 Monolayers of $\mathrm{H}^{2} \mathrm{O}$ as a Function of Package Internal Volume and Air Leak Rate


TIME (hours)

### 4.6 ADJUSTMENT (Pi) FACTORS

### 4.6.1 Quality Factor ( $\pi_{0}$ )

The quality factors for microcircuits found in MIL-HDBK-217E are multipliers of the base failure rate, and they are intended to reflect the differences in quality to be found in parts made to differing process controls. However, the factor descriptions reflect part qualification, screening performed, procurement practices, and package material. In reality, the quality of an IC is dependent upon the manufacturer's process controls alone, and that information cannot be quantified in a reliability model. However, there is good correlation between the amount of screening performed and the ultimate field reliability of the parts: the more screening, the less probability of infant mortality failures in the field. Consequently, the approach taken in developing the quality factors has been to concentrate on the effects of screening and to quantify the effectiveness of MIL-STD-883 screens. The quality factors are modifiers of the early-mid life failure rate only and do not affect the failure rates associated with common cause (wearout) failure mechanisms.

At a meeting held in Monterey, California as part of this contract, several IC manufacturers* stated that there is no difference between their commercial lines and their military lines, but the military product is screened more. Others stated that their screening of commercial product in some cases exceeds the military requirements, and they should be given credit in a model for more rigorous screening. The $\pi_{Q}$ model developed in the following paragraphs is flexjble in allowing for variations in the amount of screening performed.

[^0]Adjusted fallure mechanism quantities for all technology types listed in MDR-21 (1985) were itemized and totaled; the percentage contribution of each fallure mechanism was computed. See Table 4.6-1. The MIL-STD-883 screens which are effective at precipitating the various failure mechanisms were identified by analysis of MDR-22 (1987) and are presented in Table 4.6-2. Table 4.6-3 lists the failure mechanisms, their distributions, and the associated screens. The percentages of each failure mechanism which are precipitated by the screens were summed, then normalized to form a total of 100; each screen's percentage of the total was then calculated, as in Table 4.6-4, and these percentages are referred to as "weighting factors" for their respective screens. The screening methods which are associated with the $S, B$, $D$ and $D-1$ quality levels were also identified, and the weighting factors for each were summed to provide the "screening factor" for that quality level. The weighting factor for burn-in was adjusted to differentiate between S- and B- level burn-in. This was accomplished by calculating the expected fallout using the two time - temperature combinations and an average activation energy of 0.37 ev , which was derived from the MIL-STD-883 burn-in curves, as in Table 4.6-5 (high temperature reverse bias (HTRB) is an optional replacement for S-level burn-in). The screening factors for S, B, D and D-1 are 100.0, 71.3, 21.8 and 10.9 , respectively. To develop $\pi_{Q}$, the value for $B$-level was chosen as unity because (1) it is consistent with the current value, and (2) most of the data collected in the model development activity was on B-level product. Two points on the curve were thus known: $\pi_{Q}=1.0$ for B-level (screening factor $=71.3$ ), and $\pi_{Q}=.7$ for maximum screening, S-level. The relationship $\pi_{Q}=71.3 /$ screening factor (S.F.) was easily established. This relationship is depicted graphically in figure 4.6-1. It is intuitive that the most benefit is achieved with the first screens applied, and that the marginal improvement with succeeding screens is lower; the shape of the $\pi_{Q}$ curve reflects that fact.

In order to calculate $\pi_{Q}$, the user must identify which of the Table 4.6-4 screens apply to the product, sum the weighting factors associated with those screens to compute the screening factor, and then use the expression $\pi_{Q}=$ 71.3/5.F. to determine the value of the quality factor.

Table 4.6-1: Failure Totals vs Failure Mechanisms By Device Types*

| FAIL - MECH | DEVICE TYPES |  |  |  |  | $\begin{gathered} \text { SUM } \\ \text { TOTAL } \end{gathered}$ | $\begin{aligned} & \text { PERCENT } \\ & \text { OF } \\ & \text { TOTAL } \\ & \hline \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | DIGITAL | LINEAR | INTERFACE | MEMORY | VLSI |  |  |
| METALLIZATION | 89 | 27 | 16 | 236 | 10 | 378 | 10.7 |
| DIFFUSION | 23 | 7 | 3 | 0 | 2 | 35 | $<1$ |
| OXIDE FAULT | 386 | 38 | 6 | 40 | 4 | 474 | 13.5 |
| BULK | 48 | 56 | 0 | 3 | 2 | 109 | 3.2 |
| SUIRFACE | 405 | 313 | 16 | 8 | 17 | 759 | 21.5 |
| INTERCONNECTS | 260 | 19 | 10 | 7 | 2 | 298 | 8.5 |
| WIREBOND | 3 | 21 | 6 | 0 | 6 | 36 | 1.1 |
| PACKAGE | 1341 | 42 | 10 | 35 | 8 | 1436 | 40.5 |
| FAILURE TOTALS: | 2555 | 523 | 67 | 329 | 51 | 3525 | 100 |

*Source: RAC MDR-21

Table 4.6-2
Recommended Screens/Tests for Various Failure Mechanisms*

## SURFACE DEFECTS

- Contamination/Leakage - 1008, 1015/5005
- Foreign Material/Particles - 2001, 2012, 2020, 2010

口 Inversion/Channelin - 1008, 1015/5005, HTRB

## BULK DEFECTS

- Crystal Imperfections
- Cracked Die

OXIDE DEFECTS
DIFFUSION DEFECTS

- 1008, 1010, 1015/5005, 5007
- 1010, 1015/5005
- 1010, 1015/5005, HTRB
- 1015/5005
- 1015/5005
metallization defects
[ Open At Oxide Step/ Contact Window
- 1010, 1015/5005
$\square$ Short In Interlayer
- Pitted/Corroded
- Smeared/Scratched
- Electromigration
- 1010, 1015/5005
- 2010/2017
- 2010/2017
- 1015/5005

BOND DEFECTS

- Die Attach Defect
- 1010, 2001, 1015/5005, 2012, 2020, 2023
- Intermetallic Formation
- 1015/5005

INTERCONNECT DEFECTS

- Broken Wire
- 1010, 1015/5005
- Shorted Wire
- 1015/5005

Poor Lead Dress

- 1010, 2001

Corroded Wire

- 1010, 1015/5005

PACKAGE DEFECTS

- Non Hermetic Seal
- 1010, 2001, 1014
- Solder Balls (Excessive Seal Material
- 2009, 2020, 2012
- External Lead Defect
- 2009

[^1]Table 4.6-3: IC Failure Mechanisms/Screening Methods

| FAILURE MECHANISM | DISTRIBUTION | ASSOCIATED SCREENS |
| :---: | :---: | :---: |
| Metallization | 11\% | 1015/5005, 2010/2017, 1010 |
| Diffusion | 1\% | 1015/5005 |
| Oxide Faults | 14\% | 1015/5005, HTRB |
| Bulk | 3\% | 5007, 1008, 1010, 1015/5005 |
| Surface | 21\% | $\begin{aligned} & \text { 2010, 2012, 2020, 2001, 1008, } \\ & \text { 1015/5005, HTRB } \end{aligned}$ |
| Interconnect | 9\% | 1010, 1015/5005, 2001 |
| Wirebond | 1\% | $\begin{aligned} & 2023,1008,1010,2001,2010, \\ & 1015 / 5005,2012,2020 \end{aligned}$ |
| Package | 40\% | 2020, 2012, 1014, 2009, 1010, 2001 |

Table 4.6-4: Weighting Factor Determination

| SCREEN | 883 |  |  |  | B | D | D-1 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | METHOD | $5 \%$ | W.F. \% | S |  |  |  |
| Wafer Lot Accept | 5007 | 3 | 0.05 | $x$ |  |  |  |
| N.D. Bond Pull | 2023 | 1 | 0.2 | $x$ |  |  |  |
| Internal Visual | 2010/17 | 33 | 6.0 | $x$ | $x$ |  |  |
| Stabilization Bake | 1008 | 25 | 4.5 | $x$ | $x$ |  |  |
| Temp Cycling | 1010 | 64 | 11.6 | $x$ | $x$ |  |  |
| Constant Acceleration | 2001 | 71 | 12.8 | $x$ | X |  |  |
| Pind | 2020 | 62 | 11.3 | $x$ |  |  |  |
| Burn-In (S/B) | 1015 | 90/60 | 16.3/10.9 | $x$ | $x$ | $x$ |  |
| Final Electrical | 5005 | 60 | 10.9 | $x$ | X | $x$ | $x$ |
| Seal Test | 1014 | 40 | 7.3 | $x$ | $x$ |  |  |
| Radiography | 2012 | 62 | 11.3 | $x$ |  |  |  |
| External Visual | 2009 | 40 | 7.3 | x | X |  |  |
| SUM $\quad$ - |  | 551 | 100.0 | 100.0 | 71.3 | 21.8 | 10.9 |

[^2]Table 4.6-5: Calculating Burn-In Effectiveness (Fallout) With $E_{A}=0.37 \mathrm{eV}$

| Burn-In <br> Leve) | Time/Temp <br> $($ Hrs $) /\left({ }^{\circ} \mathrm{C}\right)$ | F(FPMH) | Expected Fallout <br> (Failures $\times 10^{-6)}$ | Ratio To <br> B-Level |
| :--- | :--- | :--- | :--- | :--- |
| B | $160 / 125$ | 20.84 | 3334.4 | 1.0 |
| HTRB | $240 / 125$ | 20.84 | 5001.6 | 1.5 |
|  | $72 / 150$ | 39.41 | 2837.5 | 0.85 |

Figure 4.6-1 $\pi \mathrm{Q}$ vs. Screening Factor (S.F.)


### 4.6.2 Learning Factor ( $\pi_{L}$ )

U.S. military integrated circuit manufacturers, through the Semiconductor Industry Association's Government Procurement Committee (GPC), established an ongoing quality statistics program to monitor and report industry data on various quality control indices and parameters. The data indicates that there has been a steady improvement in the level of American quality such that today, for every 10,000 parts shipped, there averages only one part with electrical defects (approximately 100 parts per million or PPM).

Military quality reporting procedures are strictly defined. Companies supplying data utilize the JEDEC Standard No. 16 (Assessment of Microcircuit Outgoing Quality Levels in Parts Per Million) guidelines for reporting outgoing quality levels. The procedures for accumulating and summarizing the data are carefully defined and follow accepted statistical quality control methods. Data reported represents Joint Army-Navy (JAN), Standard Military Drawing (SMD), 883C complaint and military source control drawing (SCD) products. Defect levels are calculated on first submission data only, covering room, hot and cold temperature extremes. The final PPM calculations use a weighted average technique. The PPM and sampling techniques are stated on conservative, statistically sound methods and are described in the JEDEC standard.

Currently there are nine SIA member companies reporting into the system, and these companies supply approximately $90 \%$ of all military microcircuits, providing a significant sample of total product consumed by the military.

These companies are:

| Advanced Micro Devices | National Semiconductor |
| :--- | :--- |
| General Electric/RCA | Rockwell |
| Harris | Signetics |
| Intel | Texas Instruments |
| Motorola |  |

Data is reported on the following technology groups:

| Linear: | Op Amp Based <br> A/D, D/A Converters <br> Other Linear |
| :--- | :--- |
| Bipolar Digital: | Memory <br> Logic <br> Processor/Peripheral |
| MOS Digital: | Memory <br> Logic <br> Processor/Peripheral |

For each product category, reported data includes (a) number of firms responding, (b) total samples tested, and (c) mean defect density levels. Summaries are provided for the three principal product sectors, as well as a total across all products. Hermeticity and visual/mechanical results are reported as aggregate measures. See Table 4.6-6.

In order to develop the learning factor ( $\pi_{L}$ ) from this data, the following assumptions were made:
I. The data presented in Table 4.6-6 represents a mix of mature and immature product for each of the technology lines specified. 2.Mature product may be defined as reaching the 100 PPM level.
3. The definition of mature product will change as the PPM defect density continues to drop, which provides flexibility in the learning factor. 4. The data can be used to represent the "learning curve" experienced by IC manufacturers in general.
5. Although a quality index, PPM defect densities can be used validly to scale failure rates since any defect represents a potential screening escape and future field failure.

Table 4.6-6
SEMICONDUCTOR INDUSTRY ASSOCIATION QUARTERLY REPORT FOR MILITARY PRODUCTS MEAN DEFECT DENSITIES

| ELECTRICAL <br> QUALITY LEVELS | 1 Q86 | $2 Q 86$ | 3086 | $4 Q 86$ | 1087 | 2087 | 3087 | 4087 | 1088 | 2088 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Total Linear | 431 | 486 | 180 | 192 | 191 | 104 | 165 | 106 | 172 | 86 |
| Total Digital <br> Bipolar | 73 | 65 | 65 | 159 | 43 | 35 | 111 | 27 | 87 | 44 |
| Total MOS <br> Digital | 338 | 259 | 469 | 332 | 223 | 237 | 179 | 294 | 211 | 152 |
| Grand Total: <br> All ICs | 191 | 168 | 169 | 203 | 111 | 93 | 136 | 81 | 133 | 76 |
| Product Type: <br> All ICs |  |  |  |  |  |  |  |  |  |  |
| Electrical <br> Defects | 191 | 168 | 169 | 203 | 111 | 93 | 136 | 81 | 133 | 76 |
| Mean Defect <br> Density |  |  |  |  |  |  |  |  |  |  |
| Hermeticity <br> Density |  |  |  |  |  |  |  |  |  |  |

The data in Table 4.6-6 was linearly regressed both as PPM vs. time and as in (PPM) vs. time. The latter yielded better correlation coefficients ( 0.6 for the composite "all integrated circuits" case). See figure 4.6-2. The composite data was used instead of the individual technology data for two reasons. First, not all technology areas are addressed, e.g., there is no GaAs data. Second, the PPM levels for digital bipolar are already below the value assumed for mature product, presumably because the technology is mature and testing requirements are well defined. However, a new IC manufacturer or one introducing a new line of components would still have to develop his processes in order to realize 100 PPM , and two years is a reasonable amount of time in which to do so.

Invoking assumption 2 above, mature product is achieved after 2.129 years, or during the first quarter of 1988 ( $\ln 100=4.605$ ). Since this time-frame is coincident with the data being collected on the RAAAT program, failure rates can be normalized to the 100 PPM point on the learning curve. When this is done, the value of $\pi_{L}$ is unity at time $=2.129$ yrs. Then, $\pi_{L}$ can be defined as the ratio of the PPM defect density at any time $Y$ to 100 PPM. The equation for $\pi_{L}$ becomes:

$$
\pi_{L}=\operatorname{EXP}(-0.35 Y+5.35) / 100=0.01 * \operatorname{EXP}(5.35-0.35 Y)
$$

where $Y$ is in years. A plot of $\pi-L$ vs. time is shown in figure 4.6-3.

The curve indicates that the failure rates of ICs will drop by an order of magnitude over a seven year interval, which seems reasonable. The learning curve factor ( $\pi_{L}$ ), as with the quality and environmental factors, is a modifier of the early life (defect-related) IC failure rate; it does not affect the wearout mechanisms.

Figure 4.6-2 SIA Data Plot


Figure 4.6-3 $\pi_{L}$ vs. Product Line Years
$P I-L_{2}=.01 \times \operatorname{EP}(5.35-0.35 Y)$


### 4.6.3 Hybrid Function Factor ( $\pi_{f}$ )

The concept of an application function factor was retained in the hybrid model. The basis for this factor is the variations in the processes used in different types of hybrids and the relative difficulty of these processes. Listed below are the hybrid technology groups and some examples of their unique features.

```
Digital - Standard packaging techniques. Base line for factor.
Linear - More custom package styles.
Video - Higher frequency packaging techniques, use of discrete
    inductors.
Microwave - Packaging techniques, use of transmission line
        structures, greater variety of materials, small-
        geometry.
Power - Die attach critical, layout based on voltage
        considerations.
```

Data collected from field experience on the APG-68 radar and from 1000 hour 1 ife tests of various hybrid types were used to determine the function factors. A summary of the field data which was presented in Table $4.4-1$ is shown in Table 4.6-7 below. The averages have been computed by adding the total number of failures within a family and dividing by the total number of device hours for the time in which the data was accumulated ( 263,990 system hours). This data along with the life test data is plotted in figure 4.6-4.

The life test data was taken from the data in Table 4.4-2 of section 4.4.1. Only the $125^{\circ} \mathrm{C}$ life test data was used. The only data omitted from the calculation of failure rates was improper test temperatures or devices which were overstressed in test. The data used is shown in Table 4.6-8. The point estimates of failure rates for each family were calculated at $50 \%$ confidence using the Chi-square distribution. The results are shown in Table 4.6-7.

It should be noted that the number of secondary failures and erroneous removals cannot be separated from the field data. The relative family ranking within the two sets of data seems to verify differences between most of the classes defined. Since the life test is the more accurate of the two, the $\pi_{F}$ factor is based on these failure rates. The $\pi_{F}$ factors chosen are shown in Table 4.6-7. They have been normalized to the digital family since this is the more standardized technology and is also the reference point in the present model. The number for the microwave family was obtained by interpolating the relative ranking in the field data and applying the same percentage to the life test ranking.

Table 4.6-7
Failure Rates By Hybrid Types

| FIELD DATA | LIFE TEST DATA |
| :---: | :---: |
| (REMOVAL RATE/MILLION HR.) | (FAILURE RATE/MILLION HR). |
|  |  |
|  | 50\% CONFIDENCE |
| Digital | 34.1 |

${ }^{\pi} F$
NORMALIZED TO DIGITAL

| Digital | 1.0 |
| :--- | :--- |
| Video | 1.2 |
| uWave | 2.6 (interpolated using field data) |
| Linear | 5.8 |
| Power | 21 |


|  |  | Table 4.6-8 Life Test Data |  |  |  |  | VENDOR |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | SAMPLE | TEST | DEVICE |  |  |  |
| QTY TYPE | P/N | QTY | HOURS | HOURS | FAIL | FAILURE |  |
| Digital | 586R291 | 22 | 1000 | 22,000 | 0 |  | WEC |
|  | 585R927 | 16 | 1000 | 16,000 | 0 |  | WEC |
|  | 586 R 517 | 5 | 1000 | 5,000 | 0 |  | WEC |
|  | 585R928 | 22 | 1000 | 22,000 | 0 |  | WEC |
|  | 583R379 | 5 | 1000 | 5,000 | 0 |  | WEC |
|  |  |  | TOTALS | 70,000 | 0 |  |  |
| Linear | 586R292 | 5 | 1000 | 5,000 | 0 |  | Teledyne |
|  | 586R587 | 22 | 1000 | 22,000 | 0 |  | Teledyne |
|  | 586 R 290 | 22 | 1000 | 22,000 | 0 |  | Teledyne |
|  | $581 R 772$ | 2 | 1500 | 3,000 | 2 | Al/Au intermetallic | WEC |
|  | 587 R 322 | 5 | 1000 | 5,000 | 0 |  | Teledyne |
|  | 584R555 | 1 | 750 | 750 | 1 | Lifted wire bond | WEC |
|  | 584 R 555 | 1 | 1500 | 1,500 | 0 |  | WEC |
|  | 585R149 | 2 | 1000 | 2,000 | 0 |  | WEC |
|  | 585R150 | 2 | 1000 | 2,000 | 0 |  | WEC |
|  |  |  | TOTALS | 64,250 | 3 |  |  |
| Video | 24552 | 1 | 2880 | 2,880 | 0 |  | Anaren |
|  | 24552 | 1 | 5760 | 5,760 | 0 |  | Anaren |
|  | 24552 | 1 | 720 | 720 | 1 | Seal | Anaren |
|  | 24552 | 1 | 1440 | 1,440 | 1 | Electrical | Anaren |
|  | 24552 | 1 | 2943 | 2,943 | 1 | Electrical | Anaren |
|  | 24552 | 1 | 5281 | 5,281 | 1 | Electrical | Anaren |
|  | 22306 | 3 | 1440 | 4,320 | 0 |  | Anaren |
|  | 22306 | 1 | 720 | 720 | 1 | Seal | Anaren |
|  | 22306 | 2 | 1440 | 2,880 | 2 | Electrical | Anaren |
|  | 22078 | 1 | 5760 | 5,760 | 0 |  | Anaren |
|  | 22078 | 2 | 6323 | 12,646 | 2 | Electrical | Anaren |
|  | 20858 | 3 | 5760 | 17,280 | 0 |  | Anaren |
|  | 20864 | 1 | 2880 | 2,880 | 0 |  | Anaren |
|  | 20864 | 1 | 5760 | 5,760 | 0 |  | Anaren |
|  | 20864 | 1 | 2160 | 2,160 | 0 |  | Anaren |
|  | 20864 | 1 | 1440 | 1,440 | 1 | Seal | Anaren |
|  | 20864 | 1 | 3600 | 3,600 | 1 | Seal | Anaren |
|  | 12604427 | 37 | 1000 | 37,000 | 0 |  | Teledyne |
|  | 12604427 | 1 | 504 | 504 | 1 | Unknown | WEC |
|  | Various | 9 | 1000 | 9,000 | 0 |  | Q-Bit |
|  | , Various | 76 | 1000 | 76,000 | 0 |  | Q-Bit |
|  | Various | 939 | 1000 | 939,000 | 0 |  | Q-Bit |
|  | Various | 2 | 1000 | 2,000 | 2 | Wire-wire shorts | Q-Bit |
|  |  |  | totals | ,185,884 | 14 |  |  |


| TYPE | P/N | SAMPLE QTY | TEST HOURS | DEVICE HOURS | $\begin{array}{r} \text { QTY } \\ \text { FAIL } \\ \hline \end{array}$ | FAILURE | VENDOR |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Power | 584 R 550 | 2 | 1000 | 2,000 | 0 |  | WEC |
|  | 584 R 550 | 1 | 504 | 504 | 1 | Cracked die | WEC |
|  | 584 R 550 | 5 | 1000 | 5,000 | 0 |  | Solitron |
|  | 584R551 | 5 | 1000 | 5,000 | 0 |  | Solitron |
|  | 581 R082 | 1 | 3000 | 3,000 | 0 |  | WEC |
|  | $581 \mathrm{R082}$ | 1 | 2500 | 2,500 | 1 | Substrate attach | WEC |
|  | 585R151 | 2 | 1000 | 2,000 | 0 |  | WEC |
|  | 586 R 509 | 1 | 1000 | 1,000 | 0 |  | WEC |
|  | 586 R 509 | 1 | 168 | 168 | 1 | Unknown | WEC |
|  | 586 R 508 | I | 1000 | 1,000 | 0 |  | WEC |
|  | 586R508 | 1 | 504 | 504 | 1 | Die Attach | WEC |
|  |  |  | TOTALS | 22,676 | 4 |  |  |

Figure 4.6-4
Hybrid Failure Rates
failures/removals per million hours


### 4.6.4 Environmental Factor ( $\pi_{F}$ )

The environment influences the failure rate of integrated circuit dice by accelerating the precipitation of package related defects in the early life model. In the long term, the magnitude and frequency of temperature cycling has a pronounced effect upon the package related mean time to failure, as discussed in section 4.5.

The development of environmental factors for advanced technology devices was hampered by the fact that there are not many of these devices in the field. In addition, part of the tasking was to develop a new set of factors such as would be compatible with the current MIL-HDBK-2l7E models for SSI, MSI and LSI packaged devices. These constraints dictated the use of the $C_{2}{ }^{\pi} E$ term to model the contribution of package related defects to the early life failure rate.

In order to satisfy the requirement for fewer environmental factors, the environments were grouped by usage environment based on equipment classifications. The environmental temperature ranges and the military specifications from which they were derived are presented in Table 4.6-9. These groupings accounted for 25 of the 27 environments listed in MIL-HDBK-2l7E. Default values for the average component case temperature and the worst case temperature excursion for each of the grouped environments were calculated, and these values are used in the package wearout models of section 4.5

The early life environmental factors were derived by calculating the geometric mean of the MIL-HDBK-217E values given for the grouped environments. These values are presented in Table 4.6-10.

Table 4.6-9 Environmental Temperature Ranges


Table 4.6-10
Integrated Circuit Environmental Factors

| MIL-HDBK-217 E <br> ENVIRONMENT | PROPOSED ENVIRONMENT | GEOMETRIC <br> MEAN VALUE |
| :---: | :---: | :---: |
| $A_{U A}=6.0$ |  |  |
| $A_{U B}=7.5$ |  |  |
| $A_{U C}=3.0$ | $A_{U}$ (AIRBORNE | 5.5 |
| $A_{U F}=9.5$ |  |  |
| $A_{U T}=4.0$ |  |  |
| $\bar{A}_{\text {IA }}=4.0$ |  |  |
| $A_{\text {IB }}=5.0$ |  |  |
| $A_{\text {IC }}=2.5$ | A (AIRBORNE | 4.4 |
| $A_{\text {IF }}=6.0$ |  |  |
| $A_{\text {IT }}=3.0$ |  |  |
| $A_{\text {RW }}=8.5$ |  |  |
| $\bar{N}_{U}=5.7$ | $\mathrm{N}_{\mathrm{J}}$ (NAVAL UNSHELTERED) | 5.7 |
| $N_{U U}=6.3$ | $\mathrm{N}_{\text {UU }} \begin{gathered}\text { (NAVAL UNDERSEA } \\ \text { UNSHELTERED) }\end{gathered}$ | 6.3 |
| $\overline{U_{S L}}=11.0$ | $N_{U L} \quad$ (NAVAL UNDERSEA LAUNCH) | 11.0 |
| $\overline{N_{H}}=5.9$ |  |  |
| $N_{S}=4.0$ | $N_{\text {I }}$ (NAVAL INHABI TED) | 4.6 |
| $N_{S B}=4.0$ |  |  |
| $M_{\text {FA }}=5.4$ |  |  |
| $M_{F F}=3.9$ | $M_{F}$ (MISSILE FLIGHT) | 6.5 |
| $M_{L}=13$ |  |  |
| $\overline{S_{F}}=0.9$ | $\mathrm{S}_{\mathrm{F}}$ (SPACE FLIGHT) | 0.9 |
| $\mathrm{G}_{\mathrm{B}}=0.38$ | $\mathrm{G}_{\mathrm{B}}$ (GROUND BENIGN) | 0.5 |
| $G_{\text {MS }}=0.65$ |  |  |
| $\overline{G_{M}}=4.2$ | $\mathrm{G}_{\mathrm{M}}$ (GROUND MOBILE) | 4.0 |
| $M_{p}=3.8$ |  |  |
| $\overline{G_{F}}=2.5$ | $\mathrm{G}_{\mathrm{F}}$ (GROUND FIXED) | 2.5 |
| $\overline{C_{L}}=220$ | $C_{L}$ (CANNON LAUNCH) | 220 |

### 5.0 MODEL VALIDATION

Data to model the failure rates of new technology devices was sparse since most of these devices have only recently become available commercially. The collection of data was further hampered by the proprietary nature of much of the data. Consequently, all of the data which was collected was used in the development of the models and could not be used for validation. The alternative validation methodology was to compare the predicted early life failure rates of representative microcircuits with the observed range of values from the database. The resulting values of the predicted to observed ratio were then evaluated for model accuracy. When only one data point was found, the high, low, and average values are the same. In addition, a comparison to the extrapolated MIL-HDBK-217 model has been made where appropriate. Table 5-1 presents the results of this effort. Some of the models are optimistic, some conservative; some yield higher failure rates than MIL-HDBK-217, some lower. All average failure rates are within the realm of acceptability, and most are conservative. No models for GaAs microcircuits exist in the current version of the MIL-HDBK. However, figure 5-1 compares the integrated circuit digital and MMIC GaAs models to the silicon based $217 E$ GaAs driver FET model, the $217 E$ Notice-1 GaAs low noise FET model, and the 217E Silicon ALS digital integrated circuit model. The higher activation energies for the GaAs integrated circuit models are apparent and indicate a higher temperature dependence of the failure rate at higher temperatures where the active device failure rates dominate the models. The effect of the passive failure rate term of the model is observed at the lower temperature. The comparison also indicates that the integrated circuit GaAs model failure rates lie between the discrete GaAs models and the silicon ALS digital integrated circuit model.

The hybrid model was validated by calculating several hybrid examples and comparing results with MIL-HDBK-217E. The calculations and results are shown below. For these calculations, it was assumed that the effects of the wearout failure mechanisms for the die and package were negligible.
Table 5-1

| DEVICE <br> TYPE | $\begin{gathered} \lambda_{0} \\ \text { (HIGH) } \end{gathered}$ | $\begin{gathered} \lambda_{0} \\ (\text { AVG.) } \end{gathered}$ | $\begin{gathered} \lambda_{0} \\ (\mathrm{LOW}) \end{gathered}$ | $\begin{gathered} \mathrm{T}_{0} \\ \left({ }^{\circ} \mathrm{C}\right) \end{gathered}$ | $\begin{aligned} & \lambda_{2} 17 E^{*} \\ & \left(\text { at } I_{0}\right) \end{aligned}$ | $\begin{gathered} \lambda_{p} \\ \left(\text { at } T_{0}\right) \end{gathered}$ | $\begin{aligned} & \lambda_{p} / \lambda_{0} \\ & (H I G H) \end{aligned}$ | $\begin{aligned} & \lambda_{p} / \lambda_{0} \\ & (A V G) \end{aligned}$ | $\begin{aligned} & \lambda_{p} / \lambda_{0} \\ & (\mathrm{LOW}) \end{aligned}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CMOS VLSI <br> (30K-60K Gates) | . 1627 | . 0290 | . 0009 | 25 | . 0320 | . 0290 | . 18 | 1.00 | 32.2 |
| CMOS VLSI <br> (30K-60K Gates) | . 6677 | . 6677 | . 6677 | 125 | . 6942 | . 06942 | 1.03 | 1.03 | 1.03 |
| 16 bit $\mu \mathrm{p}$ (MOS) | . 2294 | . 1827 | . 1545 | 70 | . 0768 | . 1456 | 63 | 80 | . 94 |
| 16 bit mp (TTL) | . 1803 | . 1803 | . 1803 | 70 | . 0768 | . 1188 | 66 | 66 | 66 |
| GaAs MMIC | 1.29 | . 515 | . 206 | 150 | -- | 451 | 35 | 88 | 2.19 |
| GaAs Digital | 4.58 | . 391 | . 033 | 150 | -- | 2.53 | 55 | 6.47 | 76.0 |
| GaAs Passive | . 305 | . 0424 | . 0059 | 150 | -- | . 125 | 41 | 2.94 | 21.1 |
| DRAM, NMOS, 64 K bit D level | 2.09 | 2.09 | 2.09 | 125 | 6.5 | 2.05 | . 98 | . 98 | . 98 |
| SRAM, NMOS, 16k bit D level | 6.39 | 6.39 | 6.39 | 125 | 13.0 | 6.38 | . 998 | . 998 | . 998 |
| SRAM, TTL, $2 K$ bit $D$ Level | 5.55 | 5.55 | 5.55 | 125 | 5.0 | 4.25 | . 766 | . 766 | 766 |
| EEPROM, Tex-Poly NMOS 16K bit, D level | 2.12 | 2.12 | 2.12 | 125 | 7.8 | . 717 | . 338 | . 338 | . 338 |
| EEPROM, FLOTOX NMOS 16K bit. D level | 1.83 | 1.83 | 1.83 | 125 | 7.8 | . 697 | . 38 | . 38 | . 38 |

[^3]Table 5－1（cont）

| MODEL VALIDATION |  |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| DEVICE TYPE | $\begin{gathered} \lambda_{0} \\ (H I G H) \end{gathered}$ | $\begin{gathered} \lambda_{0} \\ (A \vee G .) \end{gathered}$ | $\begin{gathered} \lambda_{0} \\ (\mathrm{LOW}) \end{gathered}$ | $\begin{gathered} \mathrm{T}_{0} \\ \left({ }^{\circ} \mathrm{C}\right) \end{gathered}$ | $\begin{aligned} & \lambda 217 E^{*} \\ & \left(\operatorname{at} T_{0}\right) \end{aligned}$ | $\begin{gathered} \lambda_{p} \\ \left(\operatorname{at~} T_{0}\right) \end{gathered}$ | $\begin{aligned} & \lambda_{p} / \lambda_{0} \\ & (H I G H) \end{aligned}$ | $\begin{aligned} & \lambda_{p} / \lambda_{0} \\ & (A \vee G) \end{aligned}$ | $\begin{aligned} & \lambda_{p} / \lambda_{0} \\ & (L O W) \end{aligned}$ |
| EEPROM，Tex－Poly NMOS 64K bit． <br> D level | 1.72 | 1.72 | 1.72 | 125 | 15.6 | 1.41 | ． 82 | ． 82 | ． 82 |
| EEPROM，FLOTOX 64K bit，D Level | 2.55 | 2.55 | 2.55 | 125 | 15.6 | 1.39 | ． 54 | 54 | ． 54 |
| UVEPROM，CMOS 64K，D Level | 8.16 | 4.53 | ． 91 | 125 | 26.4 | 1.38 | ． 17 | 30 | 1.51 |
| UVEPROM，NMOS 256K，D Level | 6.04 | 6.04 | 6.04 | 125 | 52.8 | 2.77 | ． 46 | ． 46 | ． 46 |
| UVEPROM，NMOS 512K，D Level | 3.14 | 3.14 | 3.14 | 125 | 105.6 | 5.55 | 1.76 | 1.76 | 1.76 |
| $\begin{aligned} & \text { FPLA, TTL } \\ & \text { く } 100 \text { gates } \\ & \text { D Level } \end{aligned}$ | 13.86 | 7.62 | 1.39 | 125 | 3.0 | 8.57 | ． 62 | 1.12 | 6.16 |
| ROM，NMOS 32K，D Level | ． 34 | ． 34 | ． 34 | 125 | 9.1 | 1.06 | 3.12 | 12 | 3.12 |
| ROM，NMOS <br> 64K，D Level | 1.67 | 1.67 | 1.67 | 125 | 9.1 | 1.06 | .63 | ． 63 | ． 63 |
| $\begin{aligned} & \text { ROM, NMOS } \\ & 256 \mathrm{~K} \\ & \hline \end{aligned}$ | 1.80 | 1.80 | 1.80 | 125 | 18.2 | 2.13 | 1.18 | 1.18 | 1.18 |
| $\begin{aligned} & \text { PROM, TTL } \\ & 8 K, \text { Level } \end{aligned}$ | 4.00 | 4.00 | 4.00 | 125 | 3.0 | 7.69 | 1.92 | 1.92 | 1.92 |
| $\begin{aligned} & \text { PROM, TTL } \\ & 16 K, \text { L Level } \end{aligned}$ | 4.01 | 4.01 | 4.01 | 125 | 3.0 | 7.69 | 1.92 | 1.92 | 1.92 |
| $\begin{aligned} & \text { PROM, TTL } \\ & 32 \mathrm{~K}, \text { D Level } \end{aligned}$ | 7.70 | 7.70 | 7.70 | 125 | 6.0 | 15.4 | 2.0 | 2.0 | 2.0 |
| LS TTL <br> Linear Hybrid | 2200.0 | 57.2 | 31.5 | 125 | 12.3 | 36.2 | ． 016 | ． 63 | 1.15 |

[^4]NOIIVOI7甘ム 7300W

## Figure 5-1

GaAs Model Comparison with 217E Models


## Example 1

Hybrid Microcircuit Description: RAM I/O, Digilog
Part Number: 586R290
Package: Hermetic, Butterfly; $1.0 \times 2.0$ in seal; $1.75 \times 0.8 \mathrm{in}$.
substrate
Interconnections: Bimetal 165; single metal 74
Active Components: 4-54LS374; 1-54LS154; 1-54LS175; 1-54LS74;
1-54LS04; 1-54LSO8; 1-7820
Passive Components: 2-Ceramic chip capacitors, $15 \%$ stress ratio, $0.1 \mu \mathrm{f}$
1-Ceramic chip capacitor, $15 \%$ stress ratio, $.001 \mu \mathrm{f}$
4-Thick film resistors
Environment: AUF; $45^{\circ} \mathrm{C}$ package temperature screened to MIL-STD-883, Method 5008, $\pi_{Q}=1.0$

Calculation per MIL-HDBK-217E:

> Failure rate of $I C s\left(\lambda_{C} \pi_{G}\right)=0.0584$ Failure rate of chip capacitors (includes $\left.\pi_{G}\right)=0.0594$ Failure rate of resistors $=0.0004$ Failure rate of interconnects $=0.1141$ Failure rate of package $=0.1016$ Density factor $\left(\pi_{D}\right)=2.10$ Function factor $\left(\pi_{F}\right)=1.25$ Environmental faCtor $\left(\pi_{E}\right)=4.0$ Quality factor $\left(\pi_{Q}\right)=1.0$ $\begin{aligned} & \lambda=\left\{\left(\left[N_{C} \lambda_{C} \pi_{G}\right)+\left[N_{R} \lambda_{R}+\left[N_{I} \lambda_{I}+\lambda_{S}\right] \pi_{F} \pi_{E}\right\} \pi_{Q} \pi_{D}\right.\right. \\ & =\{[(0.0584)+(0.0594)]+[0.0004+0.1141+0.1016](1.25)(4.0)\}(1.0)(2.10) \\ & =\{0.1178+1.0805\}(1.0)(2.10) \\ & \therefore 2.52 \text { failures } / 10^{6} \text { hours }\end{aligned}$

Calculation - per equation 4.4.4:

$$
\lambda=\left\{\Sigma N_{C} \lambda_{C}\left(1+.2 \pi_{E}\right)\right\} \pi_{Q} \pi^{\prime} \pi_{F}
$$

$=\{[.0584+(.0594 / 0.8)](1+(.2)(4.0)\}(1.0)(1.0)(5.8)$
$=\{(.13265)(1.8)\} 5.8$
$=1.38$ failures $/ 10^{6}$ hours

## Example 2

Hybrid Microcircuit Description: Inverter Bridge, Power
Part Number: 584R551
Package: Hermetic, PHP, $1.3 \times 1.7$ in seal; $1.5 \times 1.0$ in. substrate
Interconnections: Bimetal 14 ; single metal 36
Active Components: 4-Si NPN Darlington transistors (MJ10009)
$27 \%$ stress ratio for voltage,
12.7\% stress ratio for power;

Switching application, 175 W rating
4-Si General purpose diodes (Solitron ZLX-C-101);
54\% stress ratio, switching application 10 A rating
Passive Components: 4-Tantalum chip capacitors, $10 \%$ stress ratio, $0.27 \mu f$
8-Thick film substrate resistors
Environment: AUF; $100^{\circ} \mathrm{C}$ package temperature screened to MIL-STD-883, Method 5008, $\pi_{Q}=1.0$

Calculation per MIL-HDBK-217E:

```
Failure rate of transistors (includes }\mp@subsup{\pi}{G}{}\mathrm{ ) = 0.0196
Failure rate of diodes (includes }\mp@subsup{\pi}{G}{}\mathrm{ ) = 0.0029
Failure rate of capacitors (includes }\mp@subsup{\pi}{G}{}\mathrm{ ) = 0.4307
Failure rate of resistors = 0.0016
Failure rate of package = 1.1336
Failure rate of interconnects = 0.1712
Density factor ( }\mp@subsup{\pi}{D}{}\mathrm{ ) = 1.02
Function factor ( }\mp@subsup{\pi}{F}{}\mathrm{ ) = 1.25
Environmental factor ( }\mp@subsup{\pi}{E}{}\mathrm{ ) = 4.0
Quality factor ( ( }\mp@subsup{|}{Q}{})=1.
\lambda={(\sumN
    ={0.4532 + [0.0016 + 0.1712 + 1.1336] (1.25)(4.0)} (1.0)(1.02)
    = (0.4532 + 6.532) (1.02)
```

$=7.125$ failures $/ 10^{6}$ hours

Calculation per equation 4.4.4:

```
\(\lambda=\left\{\Sigma N_{C} \lambda_{C}\left(1+.2 \pi_{E}\right)\right\} \pi_{Q} \pi_{L} \pi_{F}\)
    \(=\{[(.0196 / .4)+(.0029 / .2)+(.4307 / .8)][1+.2(4.0)]\}(1.0)(1.0)(21)\)
    \(=(.6019)(1.8)(21)\)
    \(=(1.083)(21)\)
    \(=22.75\) failures \(/ 10^{6}\) hours
```


## Example 3

Hybrid Microcircuit Description: Dumped Integrator, Digital
Part Number: 585R927
Package: Hermetic, Butterfly, $1.0 \times 2.0$ in seal; $1.75 \times 0.8$ in. substrate Interconnections: Bimetal 212; single metal 58
Active Components: 4-10581; 1-10579; 3-10576
Passive Components: 4-Ceramic chip capacitors, $10 \%$ stress ratio, 1000 pf 8-Chip resistors
Environment: AUF; $80^{\circ} \mathrm{C}$ package temperature screened to MIL-STD-883, Method 5008, $\pi_{Q}=1.0$

Calculation per MIL-HDBK-2l7E:

Failure rate of $\operatorname{ICs}\left(\lambda_{C} \pi_{G}\right)=0.176$
Failure rate of chip capacitors (includes $\pi_{G}$ ) $=0.0365$
Failure rate of resistors $=0.0012$
Failure rate of interconnects $=0.6077$
Failure rate of package $=0.5143$
Density factor $\left(\pi_{D}\right)=2.24$
Function factor $\left(\pi_{F}\right)=1.0$
Eriwironmental factor $\left(\pi_{E}\right)=4.0$
Quality factor $\left(\pi_{Q}\right)=1.0$
$\begin{aligned} \lambda & =\left\{\left(\sum N_{C} \lambda_{C} \pi_{G}\right)+\left[N_{R} \lambda_{R}+\sum N_{I} \lambda_{I}+\lambda_{S}\right] \pi_{F} \pi_{E}\right\} \pi_{Q} \pi_{D} \\ & =\{0.2125+[0.0012+0.6077+0.5143](1.0)(4.0)\}(1.0)(2.24)\end{aligned}$
$=(0.2125+4.4928)(2.24)$
$=10.540$ failures $/ 10^{6}$ hours

Calculation per equation 4.4.4:

$$
\begin{aligned}
\lambda & =\left\{\sum N_{C} \lambda_{C}\left(1+.2 \pi_{E}\right)\right\} \pi_{Q} \pi_{L} \pi_{F} \\
& =\{[0.176+(0.0365 / .8)][1+(.2)(4.0)]\}(1.0)(1.0)(1.0) \\
& =\{(.2216)(1.8)\} 1.0 \\
& =0.39 \text { failures } / 10^{6} \text { hours }
\end{aligned}
$$

### 6.0 CONCLUSIONS AND RECOMMENDATIONS

The base failure rate of a VLSI/ULSI microcircuit is due to common cause failures. The final failure rate is adjusted for the lack of ability to eliminate assignable causes of failure from the device population.
Development of the failure distributions, early in the life cycle of the microcircuit, by use of test structures designed explicitly for reliability stress testing should be evaluated. It is realized that the test structure stress tests initially only consider the intrinsic reliability of the microcircuit. However, available life test data indicates that many microcircuit failures are due to random point defects. The ability to model this defect density is imperative in the development of an accurate, comprehensive early and middle life VLSI/ULSI reliability prediction model. Therefore, the development of a succinct set of test structures to evaluate the failure rates due to random defects is needed. These structures may have a form similar to those structures used in the generic MIL-M-38510/605 qualifications of product lines.

For the end life prediction models developed, two follow-on efforts were identified: determining the current density dependence on microcircuit complexity, and determining the cause of variability in the TDDB electric field constant $B$.

If the user does not know the maximum current density in the microcircuit, he must use a default value of $0.125 \mathrm{MA} / \mathrm{cm}^{2}$, regardless of technology. It is realized that VLSI/ULSI microcircuits approach the MIL-M- 38510 current density
limit of $0.5 \mathrm{MA} / \mathrm{cm}^{2}$ more than the earlier technologies because of the greater circuit densities. A review of metal interconnect widths and thicknesses should be performed to determine the relationship between current density and microcircuit complexity.

From a review of papers which develop the TDDB electric field acceleration constant, $B$, it is observed (with one exception ${ }^{[13]}$ ) that different oxide thicknesses have different values for $\beta$. The cause of the "variability" in this "constant" should be identified.

The scope of the memory reliability modeling project necessitated limitations on certain aspects of the model development. In addition, information gained regarding some areas of memory suggest the desirability of continuing analysis in specific areas.

Perhaps the most important area that requires further evaluation in UVEPROM, and Flash/NMOS EEPROM is endurance (the failure rate contributed by erase/ write cycling). The Time Dependent Dielectric Breakdown model was found to be inadequate for representing the effect of reprogramming. The available data suggest that the combination of high electrical stress and thin oxides precipitate failure in "non-perfect" oxides, and does not lend itself to modeling using deterministic methods. A recommendation in this area is to gather endurance test data for these devices, or generate such data in the event that sufficient test results are not available. An approach similar to that taken for Flotox/Textured-Poly EEPROMs (see section 4.2.2.2) may then be used.

Soft Errors (see section 4.2.2.1) were found to be a significant failure mechanism, at least for certain MOS RAMs under certain circumstances. Further investigation should be devoted to this area. A suggested approach is to use deterministic methods, evaluating the influencing factors outlined in 4.2.2.1 in conjunction with data regarding the sensitivities of different devices. No field data was found during this modeling task that could be used to derive soft error failure rates, and it is likely that such data is not available in sufficient quantity to derive failure rates using probabilistic methods.

Other recommendations relative to memories are as follows:
(1) Refine gate oxide thickness and area charts for all memories. This will permit a more accurate representation of the contribution of time dependent dielectric breakdown.
(2) Collect more life test data to develop a refined model of the defect related failure rate.

MDR-21 was used in the development of several models for this contract. However, MDR-21 needs to be updated to reflect the latest data in the RAC database. This will allow for more accurate determination of screening effectiveness ( $\pi_{Q}$ values) and activation energies for assignable cause failure mechanisms. The RAC database itself needs to be evaluated for its format and content: it is difficult to read and it contains fields with little or no data of use.

Recommendations for follow-on activities in the packaging area are contained in appendices $F, G$ and $H$ of this report.

The MMIC and digital GaAs failure rate models are believed to be reasonably representative of failure rates for GaAs integrated circuits using MESFET technology and gold based metallization because the models are based on current GaAs integrated circuit failure data. Although the data was limited in quantity, a consensus appeared in the data with regard to the dominant failure mechanism, failure rates, and activation energies especially in the case of the MMIC model. The failure rate data came from published accelerated life test reports and could therefore be relatively optimistic although the data should be representative of good processes under control.

The GaAs models developed in this contract should be continually refined and updated based on new data sources as new data becomes available. The application and complexity factors can be updated as new and more varied applications and higher complexity GaAs devices appear. As field data becomes available on devices with a high number of operating hours, new failure
mechanisms may appear and will have to be added to the models. Careful observation of the passive element failures may improve the passive device factors in the models. More digital GaAs failure rate data should be monitored and compared to the failure rates appearing in the digital model since the model is strongly influenced by a large sample of devices from one manufacturer (GigaBit).

Additional failure rate model efforts should also include new technology GaAs devices which are beginning to emerge. Microwave/Millimeter-wave Integrated Circuits (MIMICs) are higher frequency ( $30-300 \mathrm{GHz}$ ) GaAs devices and will be using high electron mobility transistors (HEMT) or heterojunction bipolar transistors (HBT) as the active devices on these integrated circuits. Linear GaAs integrated circuits (op amps, comparators, ...) are also emerging and their failure rates should be monitored for possible model development or the inclusion of an application term.

Due to the experiences encountered on this contract with regard to proprietary information, limited reliability testing and data, and limited or questionable reliability analysis (for failure mechanisms) on advanced emerging technologies, it is highly recommended that independent accelerated life tests be performed by a single contractor to address these concerns. For companies building and selling emerging devices, reliability issues are often a secondary concern. The single contractor would have to have excellent failure analysis capabilities (for determination of failure mechanisms), adequate environmental facilities (for accelerated temperature exposure), adequate electrical testing (for proper biasing, protection, and parametric measurements), and extensive experience in reliability data analysis (for correct interpretation of results and modeling). The major advantage of this recommendation is complete control of part section (all applicable devices can be purchased and covered), conditions (all applicable electrical and environmental conditions can be explored), and analysis (failure mechanism, data, and model analysis). The effort would be expensive but would be the best way to get complete, accurate, and timely failure rate models for emerging technologies.

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# MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES 

## APPENDIX A

5.1.2 MIL-HDBK-217 (REV) Microelectronic Devices
5.1.2.1 Monolithic Bipolar Digital and Linear Gate/Logic Array Devices
5.1.2.2 Monolithic MOS Digital and Gate/Logic Array Linear Devices
5.l.2.3 Monolithic Bipolar and MOS Digital Microprocessor Devices
5.I.2.4 Monolithic Bipolar and MOS Memory Devices
5.1.2.5 Monolithic GaAs Digital Devices
5.1.2.6 Monolithic GaAs MMIC Devices
5.1.2.7 Tables for Monolithic Model Parameters
5.1.2.8 Example Failure Rate Calculations (Monolithic)
5.1.2.9 Multi-chip Hybrid Microcircuits
5.1.2.10 Magnetic Bubble Memory Devices
5.1.2.11 Surface Acoustic Wave (SAW) Devices

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

| 5.1.2 Microelectronic Devices. This section pres failure rate prediction models for nine major devices, which are denoted by an asterisk ( | MIL-HDBK-217 microelectronic |
| :---: | :---: |
| Monolithic Bipolar Digital and |  |
| Linear Gate/Logic Array Devices (*) | Section 5.1.2.1 |
| Monolithic MOS Digital and |  |
| Linear Gate/Logic Array Devices (*) | Section 5.1.2.2 |
| Monolithic Bipolar and MOS Digital |  |
| Microprocessor Device (Including Controllers) (*) | Section 5.1.2.3 |
| Monolithic Bipolar and MOS Memory Devices (*) | Section 5.1.2.4 |
| Monolithic GaAs Digital Devices (*) | Section 5.1.2.5 |
| Monolithic GaAs MMIC Devices (*) | Section 5.1.2.6 |
| Tables for Monolithic Models Parameters | Section 5.1.2.7 |
| Example Failure Rate Calculations | Section 5.1.2.8 |
| Hybrid Microcircuits (*) | Section 5.1.2.9 |
| Magnetic Bubble Memories (*) | Section 5.1.2.10 |
| Surface Acoustic Wave Devices (*) | Section 5.1.2.11 |

This revision of MIL-HDBK-217 addresses these technologies and provides new prediction models for bipolar and MOS VLSI microcircuits with gate counts up to 60,000 , linear microcircuits with up to 3000 transistors, bipolar and MOS digital microprocessors and co-processors up to 32 bits, memory devices with up to 2 million bits, GaAs monolithic microwave integrated circuits (MMICs) with up to 1,000 active elements, and GaAs digital ICs with up to 10,000 transistors. A major departure from previous versions of the handbook is made in the monolithic bipolar and MOS models by the inclusion of effective hazard rates for the two predominant wearout failure mechanisms, electromigration and time-dependent dielectric breakdown. The early life, or assignable cause, failure rate continues to be represented by $C_{1}$ and $C_{2}$ factors which account for the contributions of the die and package, respectively, as functions of complexity. The $\mathrm{C}_{1}$ factors have been extensively revised to reflect new technology devices with improved reliability, and the activation energies representing the temperature sensitivity of the dice ( $\pi \mathrm{T}$ ) have been changed for MOS devices and for memories. The $C_{2}$ factor remains unchanged from the previous version, but includes pin grid arrays using the same model as hermetic, solder-sealed dual in-line packages. New values have been included for the quality factor ( $\pi_{\mathrm{Q}}$ ), the learning factor ( $\pi_{L}$ ), and the environmental factor ( $\pi E$ ). The model for hybrid microcircuits has been revised to be simpler to use, to delete the temperature dependence of the seal and interconnect failure rate contributions, and to provide a method of calculating chip junction temperatures.

In the title description of each monolithic device type, Bipolar represents all TTL, ASTTL, DTL, ECL, CML, ALSTTL, HTTL, FTTL, LTTL, STTL, LSTTL, IIL, I ${ }^{3}$ L and ISL devices. MOS represents all metal-oxide microcircuits, which includes MNOS, PMOS, CMOS and MNMOS fabricated on various substrates such as sapphire, poly crystalline or single crystal silicon. The hybrid model is structured to accommodate all of the monolithic chip device types and various complexity levels.

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Monolithic memory complexity factors are expressed in the number of bits in accordance with JEDEC STO 21A. This standard, which is used by all government and industry agencies that deal with microcircuit memories, states that memories of 1024 bits and greater shall be expressed as K bits, where 1 K $=1024$ bits. For example, a 16 K memory has 16,384 bits, a 64 K memory has 65,536 bits and a $1 M$ memory has $1,048,576$ bits. Exact numbers of bits are not used for memories of 1024 bits and greater.

The monolithic device models, along with parameter descriptions and instructions for quantifying the parameters are presented in Sections 5.1.2.1 through 5.1.2.6. The tables used for quantifying the model parameters are presented in Section 5.1.2.7.

Models for magnetic bubble memories and model for Surface Acoustic Wave (SAW) devices are listed after the hybrid section.

For devices having both linear and digital functions not covered by MIL-M-38510, use the linear model. Line drivers and line receivers are considered linear devices. For linear devices not covered by MIL-M-38510, use the transistor count from the schematic diagram of the device to determine circuit complexity.

Microprocessors (including controllers) are classified by the number of bits in the data word. This notation is used in data sheets and application notes. For example, the 8080 is an 8 bit microprocessor, the 8086 is a 16 bit microprocessor, etc.

For digital devices not covered by MIL-M-38510, use the gate count as determined from the logic diagram. A J-K to R-S flip flop is equivalent to 6 gates when used as part of an LSI circuit. For the purpose of this Handbook. a gate is considered to be any one of the following functions; AND, OR, exclusive OR, NAND, NOR and inverter. When a logic diagram is unavailable, use device transistor count to determine gate count using the following expressions:

Bipolar: No. Gates $=$ No. Transistors $\div 3.0$
CMOS: No. Gates $=$ No. Transistors $\div 4.0$
Other MOS: No. Gates $=$ No. Transistors $\div 3.0$

The prediction models for monolithic VLSI/ULSI microcircuits have the form

$$
\lambda_{P}\left(t_{0}\right)=\lambda_{A C}+\lambda_{T D D B}\left(t_{0}\right)+\lambda_{E M}\left(t_{0}\right)
$$

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

where

$$
\begin{aligned}
\lambda_{p}\left(t_{0}\right)= & \text { the total part failure rate (at time } \left.=t_{0}\right) \text { in } \\
& \text { failures per } 10^{6} \text { hours } \\
\lambda_{A C}= & \text { the probabilistic (constant failure rate) model for } \\
& \text { assignable cause (defect-related) failures } \\
\lambda_{T D D B}\left(t_{0}\right)= & \text { the end of life model for time-dependent dielectric } \\
& \text { breakdown } \\
\lambda_{E M}\left(t_{0}\right)= & \text { the end of life model for electromigration } \\
t_{0}= & 10,000 \text { operating hours }
\end{aligned}
$$

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5.1.2.1 Monolithic Bipolar Digital and Linear Devices
(Including Gate / Logic Arrays)
$\lambda_{P}\left(t_{0}\right)=\lambda_{A C}+\lambda_{E M}\left(t_{0}\right)+\lambda_{T D D B}\left(t_{0}\right)$
$\lambda_{A C}=\pi_{Q}\left(C_{1} \pi_{T}+C_{2} \pi_{E}\right) \pi_{L} \quad$ (in Failures $/ 10^{6}$ hours)
where:
$\pi_{Q}$ is the quality factor, Table 5.1.2.7-1
$\pi_{\top}$ is the temperature acceleration factor, Table 5.1.2.7-4
$\pi_{E}$ is the application environmental factor, Table 5.1.2.7-3
$\pi_{L}$ is the device learning factor, Table 5.1.2.7-2
$C_{1}$ is the circuit complexity failure rate based on gate or transistor count as follows:

$C_{2}$ is the package complexity failure rate, Table 5.1.2.7-15.
$\lambda_{E M}\left(t_{0}\right)$ is taken from Table 5.1.2.7-17 (in Failures $/ 10^{6}$ hours)
$\lambda_{T D D B}\left(t_{0}\right)=0$ for bipolar devices due to the thick oxides used in the bipolar fabrication process.

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5.1.2.2 Monolithic MOS Digital and Linear Devices
(Including Gate / Logic Arrays)

$$
\begin{aligned}
& \lambda_{P}\left(t_{0}\right)=\lambda_{A C}+\lambda_{E M}\left(t_{0}\right)+\lambda_{T D D B}\left(t_{0}\right) \\
& \lambda_{A C}=\pi_{Q}\left(C_{1} \pi_{T}+C_{2} \pi_{E}\right) \pi_{L} \quad \text { (in Failures / } 10^{6} \text { hours) }
\end{aligned}
$$

where:
$\pi_{Q}$ is the quality factor, Table 5.1.2.7-1
$\pi_{T}$ is the temperature acceleration factor, Table 5.1.2.7-4
$\pi_{E}$ is the application environmental factor, Table 5.1.2.7-3
$\pi_{L}$ is the device learning factor, Table 5.1.2.7-2
$C_{1}$ is the circuit complexity failure rate based on gate or transistor count as follows:

$C_{2}$ is the package complexity failure rate, Table 5.1.2.7-15.
$\lambda_{E M}\left(t_{0}\right)$ is taken from Table 5.1.2.7-17 (in Failures / $10^{6}$ hours)
$\lambda_{T O D B}\left(t_{0}\right)$ is taken from Table 5.1.2.7-16 (in Failures $/ 10^{6}$ hours)

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

5.1.2.3 Monolithic Bipolar and MOS Digital Microprocessors (Including Controllers)

$$
\begin{aligned}
& \lambda_{P}\left(t_{0}\right)=\lambda_{A C}+\lambda_{E M}\left(t_{0}\right)+\lambda_{T D D B}\left(t_{0}\right) \\
& \lambda_{A C}=\pi_{Q}\left(C_{1} \pi_{T}+C_{2} \pi_{E}\right) \pi_{L} \quad \text { (in Failures / } 10^{6} \text { hours) }
\end{aligned}
$$

where:
$\pi_{Q}$ is the quality factor, Table 5.1.2.7-1
$\pi_{T}$ is the temperature acceleration factor, Table 5.1.2.7-4
$\pi_{E}$ is the application environmental factor, Table 5.1.2.7-3
$\pi_{L}$ is the device learning factor, Table 5.1.2.7-2
$C_{1}$ is the circuit complexity failure rate based on bit count as follows:

| \# BITS | BIPOLAR | MOS |  |
| :--- | :--- | :--- | :--- |
|  |  |  |  |
| Up to 8 Bits | 0.06 | 0.14 |  |
| $\mid$ Up to 16 Bits | 0.12 | 0.28 | $\mid$ |
| $\mid$ Up to 32 Bits | 0.24 | 0.56 |  |

$C_{2}$ is the package complexity failure rate, Table 5.1.2.7-15.

| $\lambda_{E M}\left(t_{0}\right)$ is taken from Table 5.1.2.7-17 | (in Failures $/ 10^{6}$ hours) |
| :--- | :--- |
| $\lambda_{T D D B}\left(t_{0}\right)$ is taken from Table 5.1.2.7-16 | (in Failures $/ 10^{6}$ hours) |

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5.1.2.4 Monolithic Bipolar and MOS Memory Devices
Read Only Memories (ROMs) - MOS and Bipolar
Programmable ROMS (PROMs) - MOS and Bipolar including:
    Ultraviolet Eraseable
    "Flash", MNOS, and Floating gate Electrically Eraseable
    (UVE, Flash, MNOS models valid up to }100\mathrm{ reprogram cycles)
RAMs - including:
    MOS, Bipolar, and BiMOS Static RAMs (SRAMs)
    Dynamic RAMs (DRAMs)
Programmable Array Logic (PALs) - MOS and Bipolar including:
    Programmable Logic Arrays (PLAs)
    Masked Logic Arrays (MLAs), and Hard Array Logic (HALs)
```

The Model Form is:

$$
\begin{aligned}
\lambda_{P}\left(t_{0}\right) & =\lambda_{A C}+\lambda_{E M}\left(t_{0}\right)+\lambda_{T D D B}\left(t_{0}\right) \\
& =\pi_{Q}\left[C_{1} \pi_{T}+\lambda_{C y C}+C_{2} \pi_{E}\right] \pi_{L}+\lambda_{E M}\left(t_{0}\right)+\lambda_{T D D B}\left(t_{0}\right)
\end{aligned}
$$

where:
$\lambda_{p}\left(t_{0}\right)$ is the predicted failure rate in failures per million hours.
$\lambda_{E M}\left(t_{0}\right)$ is the failure rate due to electromigration, taken from Table 5.1.2.7-17.
$\lambda_{\text {TDDB }}\left(t_{0}\right)$ is the failure rate due to Time Dependent Dielectric
Breakdown, from Table 5.1.2.7-16. Refer to section 5.1.2.4.1.
$C_{1} \quad$ is the base failure rate for assignable cause failures.
Refer to Table 5.1.2.4-1.
$\pi_{T} \quad$ is the temperature multiplier for the assignable cause
failure rate. Refer to Table 5.1.2.7-10.

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$\lambda_{c y c}$ is the EEPROM* read/write cycling induced failure rate, and is:

$$
\lambda_{c y c}=\left[A_{1} B_{1}+A_{2} B_{2} / \pi_{Q}\right] \pi_{E C C}
$$

where:
$A_{1}$ and $A_{2}$ are the base cycling failure rates. Refer to Tables 5.1.2.4-2 and 5.1.2.4-3.
$B_{1}$ and $B_{2}$ are the temperature/complexity multipliers.
Refer to Tables 5.1.2.4-4 through 5.1.2.4-6.
$\pi_{E C C}$ is the on-chip error correction factor:
$=.7174$ for Hamming Code with 8 data bits and 4 correct. bits
$=.6667$ for a two-needs-one redundant cell approach
$=1.0$ for any device not using on-chip error correction

* $\lambda_{c y c}=0$ for all devices other than Flotow or Textured Poly EEPROMS.
$C_{2}$ is the package base failure rate. Refer to Table 5.1.2.7-15
$\pi_{E}$ is the environmental factor. Refer to Table 5.1.2.7-3
$\pi_{Q}$ is the quality factor. Refer to Table 5.1.2.7-1
$\pi_{L}$ is the learning factor. Refer to Table 5.1.2.7-2


## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

### 5.1.2.4.2 $C_{1}$ Factor (Memories)

Table 5.1.2.4-1 $C_{1}$ Factors
MOS PROMs (Including UVEPROMs, EEPROMs, Floating gate MOS PALs/PLAs)

| MOS PROMS |  | Bipolar SRAMs |  |
| :---: | :---: | :---: | :---: |
|  | C1 |  | Cl |
| Up to 16K bits | . 00085 | Up to 16K bits | . 0052 |
| $16 \mathrm{~K}<\mathrm{X} \leq 64 \mathrm{~K}$ | . 00169 | $16 \mathrm{~K}<\mathrm{X} \leq 64 \mathrm{~K}$ | . 0105 |
| 64K< X ¢ 256 K | . 00339 | 64K< X $\leq 256 \mathrm{~K}$ | . 0210 |
| $256 \mathrm{~K}<\mathrm{X}^{-}<1 \mathrm{M}$ | . 00678 | $256 \mathrm{~K}<\mathrm{X}^{-}<1 \mathrm{M}$ | . 0420 |
| Bipolar PALs/PLAs |  | MOS, BIMOS SRAMS |  |
|  | Cl |  | Cl |
| Up to 200 gates | . 01047 | Up to 16K bits | . 0078 |
| $200<x \leq 1000$ gates | . 02094 | $16 \mathrm{~K}<\mathrm{X} \leq 64 \mathrm{~K}$ | . 0156 |
| $1000<x^{-} \leq 2000$ gates | . 04188 | 64Kく X ¢ 256 K | . 0312 |
|  |  | $256 \mathrm{~K}<\mathrm{X}^{-}<1 \mathrm{M}$ | . 0624 |
| Bipolar PROMS |  | DRAMS |  |
|  | Cl |  | Cl |
| Up to 16 K bits | . 0094 | Up to 16K bits | . 0013. |
| 16 K < $\mathrm{X} \leq 64 \mathrm{~K}$ | . 0188 | $16 \mathrm{~K}<\mathrm{X} \leq 64 \mathrm{~K}$ | . 0025 |
| $64 \mathrm{~K}<\mathrm{X} \leq 256 \mathrm{~K}$ | . 0376 | 64K < X | . 0050 |
| $256 \mathrm{~K}<X^{-}<1 M$ | . 0753 | $256 \mathrm{~K}<X^{-}<1 M$ | .0100 |
| MOS ROMS |  |  |  |
|  | C1 |  |  |
| Up to 16K bits | . 000065 |  |  |
| $16 \mathrm{~K}<\mathrm{X} \leq 64 \mathrm{~K}$ | . 0013 |  |  |
| 64 K < X ¢ 256 K | . 0026 | - |  |
| $256 \mathrm{~K}<\mathrm{X}^{-}<1 M$ | . 0052 |  |  |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.4-2 A, Factor

| Total Number of Cycles (X) | FLOTOX | Textured-Poly |
| :---: | :---: | :---: |
| up to 100 | . 0007 | . 0097 |
| $100<x<200$ | . 0014 | . 0139 |
| $200<x<500$ | . 0034 | . 0230 |
| $500<x \leq 1 K$ | . 0068 | . 033 |
| $1 \mathrm{~K}<\mathrm{X} \leq 3 \mathrm{~K}$ | . 0204 | . 061 |
| $3 \mathrm{~K}<x<5 \mathrm{~K}$ | . 0341 | . 091 |
| $5 \mathrm{~K}<\mathrm{X} \leq 7 \mathrm{~K}$ | . 0478 | 136 |
| $7 \mathrm{~K}<\mathrm{X} \leq 9 \mathrm{~K}$ | . 0614 | 212 |
| $9 \mathrm{~K}<\mathrm{x} \leq 10 \mathrm{~K}$ | . 0682 | 303 |
| $10 \mathrm{~K}<\mathrm{X}^{-1} \leq 15 \mathrm{~K}$ | . 1023 | 303 |
| $15 \mathrm{~K}<\mathrm{X} \leq 20 \mathrm{~K}$ | . 1364 | 303 |
| 20 K < X | . 2045 | 303 |
| $30 \mathrm{~K}<\mathrm{X} \leq 50 \mathrm{~K}$ | . 3409 | 303 |
| 50 K < X ¢ 100 K | . 6818 | 303 |
| 100 K < $\mathrm{X}^{-} \leq 200 \mathrm{~K}$ | 1.364 | 303 |
| 200K < X < 300K | 2.045 | 303 |
| 300 K < X < 325K | 2.216 | * |
| $325 \mathrm{~K}<\mathrm{X} \leq 350 \mathrm{~K}$ | 2.386 | * |
| 350 K < X | 2.727 | * |
| 400 K < X<450K | 3.070 | * |
| 400 K < X $\leq 500 \mathrm{~K}$ | 3.409 | * |

## MIL-HDBK-217(REV) MICROELECTRONIC DEVICES

Table 5.1.2.4-3 $A_{2}$ Factor

```
For FLOTOX, A2 = 0
For Tex - Poly:
\begin{tabular}{ll} 
Total \# of Cycles & \(A_{2}{ }^{\text {* }}\) \\
\hline & \\
Up to 300 K & 0.0 \\
\(300 \mathrm{~K}<X \leq 325 \mathrm{~K}\) & 2.50 \\
\(325 \mathrm{~K}<X \leq 350 \mathrm{~K}\) & 10.0 \\
\(350 \mathrm{~K}<X \leq 400 \mathrm{~K}\) & 20.0 \\
\(400 \mathrm{~K}<X \leq 450 \mathrm{~K}\) & 30.0 \\
\(450 \mathrm{~K}<X \leq 500 \mathrm{~K}\) & 40.0
\end{tabular}
```

* If using a system life of other than 10000 hours, multiply $A_{2}$ by $\frac{10000}{\text { Sys. Life }}$.

If the EEPROM type is not known, assume FLOTOX
Table 5.1.2.4-4
8 for flotox
 $164 \mathrm{k}|\quad| .980|1.192| 1.432|1.701| 2.000|2.329| 2.688|3.081| 3.504|3.958| 4.443|4.959| 5.506|6.083| 6.689 \mid$
 | $128 \mathrm{k}|1.384| 1.683|2.022| 2.402|2.824| 3.289|3.798| 4.350|4.947| 5.588|6.273| 7.002|7.774| 8.589|9.445|$
 |256k $|1.960| 2.384|2.864| 3.402|4.000| 4.659|5.379| 6.162|7.007| 7.915|8.886| 9.918|11.011| 12.165|13.378|$
 $1512 \mathrm{k}|2.777| 3.378|4.059| 4.821|5.608| 6.602|7.622| 8.731|9.929| 11.216|12.591| 14.054|15.603| 17.238|18.956|$
 |1M $|3.919| 4.768|5.729| 6.804|8.000| 7.318|10.758| 12.323|14.014| 15.830|17.771| 19.836|22.022| 24.330|26.755|$


$$
\text { Table } 5.1 .2 .4-5
$$

$$
B_{1} \text { for TEX-POLY }
$$

$$
\begin{aligned}
& T_{j}\left({ }^{\circ} \mathrm{C}\right)
\end{aligned}
$$

Table 5.1.2.4-0
$8_{2}$ tor IEX-P0Ly ( $B_{2}=0$ for flotox )
$\mathrm{T}_{\mathrm{j}}\left({ }^{\circ} \mathrm{C}\right)$


## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

5.1.2.4.1 $\lambda_{T D D B}\left(t_{0}\right)$

For Bipolar memory devices, $\lambda_{T D D B}=0$

For MOS/BiMOS memories:

1) Determine the following parameters of the device:

Total gate oxide area in square microns (DRAMs, SRAMs, ROM/HAL/MLAs only)
Total periphery circuitry gate oxide area in square microns (PROM/PAL/PLAs, EEPROMs, UVEPROMs only)
Gate oxide electric field stress due to normal operating voltage (in MV/cm)

Operating junction temperature of the device in degrees celsius

If these values cannot be derived, refer to the following tables in selecting values:

Table 5.1.2.7-20 for gate oxide area
Table 5.1.2.7-21 for gate oxide thickness
2) Once the parameters have been determined, find $\lambda_{T D D B}$ by referring to Table 5.1.2.7-16.

Note that the $\lambda_{T D D B}$ values are valid only for a 10000 hour assumed system lifetime.

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

5.1.2.5 Monolithic GaAs Digital Devices.

Includes small scale, medium scale, and large scale integrated circuits using MESFET transistors and gold based metallization.

Digital GaAs part failure rate model:

$$
\left.\lambda_{D}=\pi_{Q}\left[C_{1 A} \pi_{T A}+C_{1 P} \pi_{T P}+C_{2} \pi_{E}\right] \pi_{L} \text { (failures } / 10^{6} \mathrm{hrs}\right)
$$

where the $C_{1}$ factors are shown in Table 5.1.2.5-1.

```
\mp@subsup{\lambda}{D}{}}=\mathrm{ Digital GaAs Part Failure Rate in failures/10
C}1A=Active Device Complexity Factor (For transistors and diodes
C
        and inductors)
#TA = Active Device Temperature Acceleration Factor, Table 5.1.2.7-13
\piTP}=\mathrm{ Passive Device Temperature Acceleration Factor, Table 5.1.2.7-14
\mp@subsup{\pi}{L}{}}=\mathrm{ Learning Factor, Table 5.1.2.7-2
#Q = Quality Factor, Table 5.1.2.7-1
C
\pi}\mp@subsup{E}{}{\prime}=\mathrm{ Environmental Factor, Table 5.1.2.7-3
```

Table 5.1.2.5-1: $C_{1 A}$ and $C_{1 P}$ FOR MONOLITHIC GaAs DIGITAL DEVICES

| COMPLEXITY | $C_{1 A}$ | $C_{1 P}$ |
| :---: | :---: | :---: |
| (NO. OF IC ELEMENTS) |  |  |
| $1-1000$ (SSI \& MSI) | 25.3 | .687 |
| $1001-10,000$ (LSI) | 50.6 | .687 |
| UnKROWn | 50.6 | .687 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

### 5.1.2.6 Monolithic GaAs MMIC Devices.

Includes GaAs MMIC devices using MESFET transistors and gold based metallization.

GaAs MMIC part failure rate model:

$$
\lambda_{M}=\pi_{Q}\left[\left(C_{1 A} \pi_{T A}+C_{1 P} \pi_{T P}\right) \pi_{A}+C_{2} \pi_{E}\right] \pi_{L}\left(\text { failures } / 10^{6} \text { hours }\right)
$$

where the $C_{1}$ factors are shown in Table 5.1.2.6-1, the $\pi_{T}$ factors are shown in Table 5.1.2.7-12 and 5.1.2.7-14, and the $\pi_{A}$ factor is shown in Table 5.1.2.6-2. The $\pi_{Q}, \pi_{L}$ and $\pi_{E}$ factors are shown in Tables 5.1.2.7-1, 5.1.2.7-2 and 5.1.2.7-3. $C_{2}$ is shown in Table 5.1.2.7-15.
$\lambda_{M}=$ MMIC GaAs Part Failure Rate
$C_{1 A}=$ GaAs Active Device Complexity Factor (For transistors and diodes)
$C_{1 p}=$ GaAs Passive Device Complexity Factor (For resistors, capacitors, inductors)
$\pi_{T A}=$ GaAs Active Device Temperature Factor
$\pi_{T P}=$ GaAs Passive Device Temperature Factor
$\pi_{A}=$ MMIC Application Factor
$\pi_{L}=$ Experience or Learning Factor
$\pi_{0}=$ Quality Factor
$C_{2}=$ Package Complexity Factor
$\pi_{E}=$ Environmental Factor

$$
\begin{gathered}
\text { MIL-HDBK-217(REV) } \\
\text { MICROELECTRONIC DEVICES }
\end{gathered}
$$

Table 5.1.2.6-1: $\quad C_{1 A}$ and $C_{1 P}$ FOR MONOLITHIC gats MMIC DEVICES

| COMPLEXITY <br> (NO. OF IC ELEMENTS) | $C_{1 A}$ | $C_{1 P}$ |
| :---: | :---: | :---: |
| $1-10$ | 4.51 | 2.26 |
| $11-100$ | 4.51 | 2.71 |
| $101-1000$ | 7.22 | 2.94 |
| Unknown | 7.22 | 2.94 |

Table 5.1.2.6-2
$\pi_{A}$ FOR MONOLITHIC GaAs MMIC DEVICES

| APPLICATION | $\pi A$ |
| :---: | :---: |
| Low noise \& low power <br> less than or equal <br> to 100 mw | 1.0 |
| Driver \& high power <br> greater than 100 mw <br> to 3000 mw | 3.0 |
| Unknown | 3.0 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

### 5.1.2.7 Tables for Monolithic Model Parameters

Table 5.1.2.7-1
$\pi_{Q}$ Quality Factors

| QUALITY <br> LEVEL | DESCRIPTION | $\pi \mathrm{Q}$ |
| :---: | :---: | :---: |
| 5 | Procured in full accordance with MIL-M-38510, Class $S$ requirements. Class S listing on QPL- 38510. | 0.7 |
| B | Procured in full accordance with MIL-M-38510 Class B requirements. Class B listing on QPL- 38510 . | 1.0 |
| D | Parts with normal reliability screening and manufacturer's quality assurance practices. Burn-in per MIL-STD-883 Method 1015 (Series), Class B, and final electrical test required. | 3.3 |
| D-1 | Commercial (or non-MIL standard) parts with no screening other than final electrical test at temperature extremes* | 6:5 |
| OTHER | Parts screened to intermediate quality levels per screening methods of MIL-STD-883. Screening factor and $\pi_{Q}$ as determined below. | - |

* Non-hermetic parts should be used only in controlled environments( $G_{B}$ )

| MIL-STD | SCREEN | POINT |
| :--- | :--- | :--- |
| -883 |  | VALUATION |
| METHOD |  | 0.5 |
| 5007 | Wafer lot acceptance testing | 0.2 |
| 2023 | Non-destructive bond pull | 6.0 |
| $2010 / 17$ | Internal visual examination | 4.5 |
| 1008 | Stabilization bare, condition B minimum | 11.6 |
| 1010 | Temperature cycling, condition B minimum | 12.8 |
| 2001 | Constant acceleration, condition B minimum | 11.3 |
| 2020 | PIND (particle impact noise detection) | $16.3 / 10.9$ |
| 1015 | Burn-in (S-level/B-level) | 10.9 |
| 5005 | Final Electrical | 7.3 |
| 1014 | Seal Test (test conditions A, B or C) | 11.3 |
| 2012 | Radiography | 7.3 |
| 2009 | External visual inspection |  |

Note 1: The screening factor is the sum of the point valuations of all MIL-STD-883 screens conducted on the parts in question.

Note 2: $\pi Q=71.3 \div$ screening factor.

$$
\begin{aligned}
& \text { MIL-HOBK-217(REV) } \\
& \text { MICROELECTRONIC OEVICES } \\
& \text { Table 5.1.2.7-2 Experience Factor } \pi L \\
& \pi_{L}=[0.01 \exp (5.35-0.35 Y)] \\
& \text { where } Y=\text { no. years in production }
\end{aligned}
$$

Table 5.1.2.7-3 Application Environment Factor $\pi E$

| ENVIRONMENT | $\pi E$ |
| :---: | ---: |
| $G_{B}$ | 0.5 |
| $G_{F}$ | 2.5 |
| $G_{M}$ | 4.0 |
| $N_{I}$ | 4.6 |
| $N_{U}$ | 5.7 |
| $N_{U U}$ | 6.3 |
| $N_{U L}$ | 11.0 |
| $A_{I}$ | 4.4 |
| $A_{U}$ | 5.5 |
| $M_{F}$ | 6.5 |
| $S_{F}$ | 0.9 |
| $C_{L}$ | 220 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-4 Technology Temperature Factor Tables

| TECHNOLOGY | EFFECTIVE <br> ACTIVATION <br> ENERGY | $\pi T$ TABLE <br> NUMBER | A |
| :--- | :---: | :---: | :---: |
| ASTTL, CML, TTL, HTTL, <br> FTTL, DTL, ECL \& ASTTL | .4 ev | $5.1 .2 .7-5$ | 4635 |
| LTTL \& STTL | .45 ev | $5.1 .2 .7-6$ | 5214 |
| LSTTL | .5 ev | $5.1 .2 .7-7$ | 5794 |
| IIL, I3L, ISL \& MNOS | .6 ev | $5.1 .2 .7-8$ | 6952 |
| DIGITAL MOS | .35 ev | $5.1 .2 .7-9$ | 4060 |
| MEMORIES (BIPOLAR \& MOS) | .8 ev | $5.1 .2 .7-10$ | 9270 |
| LINEAR (BIPOLAR \& MOS) | .65 ev | $5.1 .2 .7-11$ | 7532 |
| GaAS MMIC ACTIVE DEVICES | 1.5 ev | $5.1 .2 .7-12$ | 17380 |
| GaAS DIGITAL <br> ACTIVE DEVICES | 1.4 ev | $5.1 .2 .7-13$ | 16220 |
| GaAS PASSIVE DEVICES | .43 ev | $5.1 .2 .7-14$ | 4980 |

$$
\begin{equation*}
\text { NOTE 1. } \quad \pi T=0.1\left(e^{x}\right) \tag{5.1.2.7.3}
\end{equation*}
$$

where

$$
\begin{aligned}
& x=-A\left(\frac{1}{T_{j}+273}-\frac{1}{298}\right) \text { For Silicon Devices } \\
& x=-A\left(\frac{1}{T_{C H}+273}-\frac{1}{423}\right) \text { For GaAs Devices } \\
& A=\text { value from above Table } \\
& T_{J}=\text { device worst case junction temperature }\left({ }^{\circ} \mathrm{C}\right) \\
& T_{C H}=\text { average active device channel temperature }\left({ }^{\circ} \mathrm{C}\right) \\
& e=\text { natural logarithm base, } 2.718
\end{aligned}
$$

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

(Notes continued for Table 5.1.2.7-4)

NOTE 2. $T_{j}$, the worst case junction temperature, shall be measured or estimated using the following expression:

$$
\begin{equation*}
T_{j}=T_{C}+\theta_{J C}{ }^{p} \tag{5.1.2.7.4}
\end{equation*}
$$

where:
${ }^{\top} C$ is case temperature $\left({ }^{\circ} \mathrm{C}\right)$.
$\theta_{J C}$ is junction to case thermal resistance $\left({ }^{\circ} \mathrm{C} /\right.$ watt $)$ for a device soldered into a printed circuit board. If $\theta_{J C}$ is not available, use a value contained in a specification for the closest equivalent device or use the Tables on pages 5.1.2.7-5 through 5.1.2.7-7.
$P$ is the worst case power realized in a system application. If the applied power is not available, use the maximum power dissipation from the specification for the closest equivalent device.

If $T_{C}$ cannot be determined, use the following:

| ENVIRONMENT | $A_{U}$ | $A_{I}$ | $N_{U}$ | $N_{I}$ | $N_{U U}$ | $N_{U L}$ |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
| $T_{C}\left({ }^{\circ} \mathrm{C}\right)$ | 76 | 60 | 80 | 45 | 25 | 40 |
| ENVIRONMENT | $M_{F}$ | $S_{F}$ | $G_{B}$ | $G_{M}$ | $G_{F}$ | $C_{L}$ |
| $T_{C}\left({ }^{\circ} \mathrm{C}\right)$ | 50 | 35 | 35 | 50 | 45 | 45 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-4a
$\theta_{J C}$ Values for MIL-M-38510 Devices (from MIL-M-38510G, Appendix C)

| $\begin{aligned} & \text { JAN P/N } \\ & \text { LETTER } \\ & \underline{1} / \end{aligned}$ | SPECIFICATION DESIGNATION OUTLINE NO. 1/ | $\begin{aligned} & \operatorname{MAX} \theta \mathrm{JC} \\ & \left({ }^{\circ} \mathrm{C} / \mathrm{W}\right) \end{aligned}$ $\underline{3} /, 4 /$ | DESCRIPTION ${ }^{\text {s/ }}$ |
| :---: | :---: | :---: | :---: |
| A | F-1 | 22 | 14-1ead FP |
| B | F-3 | 22 | 14-lead FP |
| C | D-1 | 28 | 14-lead DIP |
| D | F-2 | 22 | 14-lead FP |
|  | F-2A | 22 | 14-lead FP |
| E | D-2 | 28 | 16-lead DIP |
| F | F-5 | 22 | 16-lead FP |
|  | F-5A | 22 | 16-lead FL |
| G | A-1 | 70 | 8-lead can |
| H | F-4 | 22 | 10-lead FP |
| I | A-2 | 65 | 10-lead can |
| J | D-3 | 28 | 24-lead DIP |
| K | F-6 | 22 | 24-1ead FP |
|  | F-6A | 22 | 24-lead FP |
| L | D-9 | 28 | 24-lead DIP |
| M | A-3 | 65 | 12-lead can |
| P | D-4 | 28 | 8-lead DIP |
| Q | D-5 | 28 | 40-lead DIP |
| R | D-8 | 28 | 20-lead DIP |
| S | F-9 | 22 | 20-1ead FP |
|  | F-9A | 22 | 20-1ead FP |
| v | D-6 | 28 | 18-lead DIP |
| W | D-7 | 28 | 22-lead DIP |
|  | F-8 | 22 | 24-lead FP |
|  | F-10 | 22 | 18-lead FP |
|  | F-11 | 22 | 28-1ead FP |
|  | F-11A | 22 | 28-lead FP |
|  | D-10 | 28 | 28-lead DIP |
|  | D-11 | 28 | 24-lead DIP |
|  | D-12 | 28 | 50-lead DIP |
|  | D-13 | 28 | 64-lead DIP |

See footnotes at end of table.

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-4a (continued)


See footnotes at end of table.

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-4a (continued)


The letters in this column may be alphabetic or numeric and are used in paragraph 1.2.3 of detail specifications and are dedicated to specific case outlines. Where there are no letters, the letters S, Y, Z, U, T and $N$ are used (in the order shown) but are not dedicated until they appear in the detail specification. Thus a letter $x$, for example, can be used to label more than one type of case outline provided each application is in a different detail specification.

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Notes to Table 5.1.2.7-4a

2/ The chip carrier case outline drawing describes features which are optional. These options enhance the utility of the chip carrier, not only for end use but also for manufacturing and testing. Specific case outline configurations are designated by a single letter which is used in the JAN part no. The following excerpt from a typical detail specification shows how the option is added.

3/ Values shown are worst case (MEAN $+2 \sigma$ ) for $60 \times 60 \mathrm{mil}$ die and applicable for devices with die sizes up to 14400 sq. mil.

4/ For devices die sizes greater than 14400 sq. mil. Use the following values:

| Dual-in-line | $11^{\circ} \mathrm{C} / \mathrm{W}$ |
| :--- | ---: |
| Flat pack | $10^{\circ} \mathrm{C} / \mathrm{W}$ |
| Chip carrier | $10^{\circ} \mathrm{C} / \mathrm{W}$ |
| Pingrid array | $3^{\circ} \mathrm{C} / \mathrm{W}$ |

5/ LCC = Leadless chip carrier, ceramic; GCC = Gullwing leaded chip carrier, ceramic; JCC $=J$ bend leaded chip carrier, ceramic; $P G A=P i n g r i d$ array, ceramic; $F P=$ Flat pack; DIP $=$ Dual-in-line package.

6/ Caution: Some outline configurations listed in this column are prohibited for new equipment design or redesign on and after 29 November 1986 (see 3.5.1 and case outline drawings and notes).

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-5 $\pi$ T vs Junction Temperature for ASTTL, CML, TTL, HTTL, FTTL, DTL, ECL \& ALSTTL

| $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ |
| :--- | :--- | ---: | :--- | :--- | :--- | :--- | :--- |
| 25 | .10 | 65 | .63 | 105 | 2.69 | 145 | 8.69 |
| 30 | .13 | 70 | .77 | 110 | 3.16 | 150 | 9.91 |
| 35 | .17 | 75 | .93 | 115 | 3.69 | 155 | 11.26 |
| 40 | .21 | 80 | 1.13 | 120 | 4.29 | 160 | 12.77 |
| 45 | .27 | 85 | 1.36 | 125 | 4.98 | 165 | 14.42 |
| 50 | .33 | 90 | 1.62 | 130 | 5.75 | 170 | 16.25 |
| 55 | .41 | 95 | 1.93 | 135 | 6.62 | 175 | 18.27 |
| 60 | .51 | 100 | 2.28 | 140 | 7.60 |  |  |

Table 5.1.2.7-6 $\pi T$ vs Junction Temperature for LTTL \& STTL

| $\mathrm{T}_{\mathrm{J}}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $\left.\mathrm{Tj}^{( }{ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $\mathrm{T}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $\mathrm{T}_{\mathrm{J}}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 25 | . 10 | 65 | . 79 | 105 | 4.06 | 145 | 15.19 |
| 30 | . 13 | 70 | . 99 | 110 | 4.86 | 150 | 17.60 |
| 35 | . 18 | 75 | 1.24 | 115 | 5.79 | 155 | 20.32 |
| 40 | . 23 | 80 | 1.53 | 120 | 6.87 | 160 | 23.39 |
| 45 | . 30 | 85 | 1.88 | 125 | 8.11 | 165 | 26.84 |
| 50 | 39 | 90 | 2.29 | 130 | 9.55 | 170 | 30.70 |
| 55 | . 50 | 95 | 2.79 | 135 | 11.19 | 175 | 35.01 |
| 60 | . 63 | 100 | 3.37 | 140 | 13.06 |  |  |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-7 $\pi T$ vs Junction Temperature for LSTTL

| $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ |
| :--- | :--- | ---: | ---: | ---: | ---: | ---: | :--- |
|  |  |  |  |  |  |  |  |
| 25 | .10 | 65 | 1.00 | 105 | 6.12 | 145 | 26.55 |
| 30 | .14 | 70 | 1.28 | 110 | 7.48 | 150 | 31.28 |
| 35 | .19 | 75 | 1.63 | 115 | 9.09 | 155 | 36.71 |
| 40 | .25 | 80 | 2.07 | 120 | 10.99 | 160 | 42.92 |
| 45 | .34 | 85 | 2.60 | 125 | 13.23 | 165 | 50.00 |
| 50 | .45 | 90 | 3.25 | 130 | 15.85 | 170 | 58.05 |
| 55 | .59 | 95 | 4.04 | 135 | 18.90 | 175 | 67.18 |
| 60 | .77 | 100 | 4.99 | 140 | 22.45 |  |  |

Table 5.1.2.7-8 $\pi T$ vs Junction Temperature for IIL, ${ }^{3}$ L, ISL \& MNOS

| $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| 25 |  |  |  |  |  |  |  |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.l.2.7-9 $\pi T$ vs Junction Temperature for MOS Digital Gate/Logic Array and MOS Digital Microprocessor Devices

| $\mathrm{T}_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi \mathrm{T}$ | $\mathrm{T}_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $\mathrm{~T}_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $\mathrm{~T}_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ |
| :--- | :--- | :---: | :---: | :---: | :---: | :---: | :---: |
| 25 | .10 | 65 | .50 | 105 | 1.79 | 145 | 5.00 |
| 30 | .13 | 70 | .60 | 110 | 2.06 | 150 | 5.60 |
| 35 | .16 | 75 | .71 | 115 | 2.36 | 155 | 6.27 |
| 40 | .19 | 80 | .84 | 120 | 2.69 | 160 | 6.99 |
| 45 | .24 | 85 | .98 | 125 | 3.07 | 165 | 7.78 |
| 50 | .29 | 90 | 1.15 | 130 | 3.48 | 170 | 8.64 |
| 55 | .35 | 95 | 1.34 | 135 | 3.94 | 175 | 9.57 |
| 60 | .42 | 100 | 1.55 | 140 | 4.44 |  |  |

Table 5.1.2.7-10 $\pi T$ vs Junction Temperature for Memories, Bipolar, MOS \& BIMOS

| T $\left.{ }^{( }{ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{j}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi$ | $\mathrm{T}_{\mathrm{j}}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $\mathrm{Tj}_{\mathrm{J}}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 25 | . 10 | 65 | 3.97 | 105 | 72.31 | 145 | 755.8 |
| 30 | . 17 | 70 | 5.92 | 110 | 99.6 | 150 | 982 |
| 35 | . 27 | 75 | 8.73 | 115 | 136.1 | 155 | 1269 |
| 40 | . 44 | 80 | 12.73 | 120 | 184.4 | 160 | 1629 |
| 45 | . 71 | 85 | 18.37 | 125 | 248.0 | 165 | 2081 |
| 50 | 1.11 | 90 | 26.25 | 130 | 331.1 | 170 | 2642 |
| 55 | 1.72 | 95 | 37.14 | 135 | 438.9 | 175 | 3337 |
| 60 | 2.63 | 100 | 52.05 | 140 | 577.8 |  |  |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-11 $\pi T$ vs Junction Temperature for Linear

| $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ | $T_{J}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ |
| :--- | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| 25 | .10 | 65 | 1.99 | 105 | 21.04 | 145 | 141.7 |
| 30 | .15 | 70 | 2.75 | 110 | 27.30 | 150 | 175.3 |
| 35 | .23 | 75 | 3.78 | 115 | 35.17 | 155 | 215.8 |
| 40 | .34 | 80 | 5.13 | 120 | 45.02 | 160 | 264.5 |
| 45 | .49 | 85 | 6.91 | 125 | 57.28 | 165 | 322.5 |
| 50 | .71 | 90 | 9.24 | 130 | 72.44 | 170 | 391.6 |
| 55 | 1.01 | 95 | 12.25 | 135 | 91.09 | 175 | 473.5 |
| 60 | 1.42 | 100 | 16.11 | 140 | 113.9 |  |  |

Table 5.1.2.7-12 $\pi T$ vs Channel Temperature for GaAs MMIC Active Devices

| ${ }^{T} \mathrm{CH}^{( }{ }^{\circ} \mathrm{C}$ | $\pi T$ | $\mathrm{T}_{\mathrm{CH}}\left({ }^{\circ} \mathrm{C}\right)$ |  | $\mathrm{T}_{\mathrm{CH}}\left({ }^{\circ} \mathrm{C}\right)$ |  | ${ }^{T} \mathrm{CH}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi T$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 25 | 3.274E-9 | 65 | 3.255E-6 | 105 | 7.511E-4 | 145 | $6.117 \mathrm{E}-2$ |
| 30 | 8.571E-9 | 70 | 6.888E-6 | 110 | 1.369E-3 | 150 | $1.000 \mathrm{E}-1$ |
| 35 | $2.175 \mathrm{E}-8$ | 75 | 1.427E-5 | 115 | $2.457 E-3$ | 155 | 1.616E-1 |
| 40 | $5.357 \mathrm{E}-8$ | 80 | 2.894E-5 | 120 | 4.344E-3 | 160 | $2.583 \mathrm{E}-1$ |
| 45 | $1.283 \mathrm{E}-7$ | 85 | $5.756 \mathrm{E}-5$ | 125 | $7.571 \mathrm{E}-3$ | 165 | $4.084 \mathrm{E}-1$ |
| 50 | $2.989 \mathrm{E}-7$ | 90 | 1.123E-4 | 130 | 1.301E-2 | 170 | $6.391 \mathrm{E}-1$ |
| 55 | $6.788 \mathrm{E}-7$ | 95 | $2.153 \mathrm{E}-4$ | 135 | $2.208 \mathrm{E}-2$ | 175 | 9.903E-1 |
| 60 | $1.504 \mathrm{E}-6$ | 100 | 4.055E-4 | 140 | $3.698 \mathrm{E}-2$ |  |  |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-13 $\pi T$ vs Channel Temperature for GaAs Digital Active Devices

| $\mathrm{T}_{\mathrm{CH}}{ }^{\circ} \mathrm{C}$ | $\pi T$ | ${ }^{T} \mathrm{CH}\left({ }^{\circ} \mathrm{C}\right)$ |  | ${ }^{T} \mathrm{CH}\left({ }^{\circ} \mathrm{C}\right)$ |  | ${ }^{T} \mathrm{CH}\left({ }^{\circ} \mathrm{C}\right) \quad \pi \mathrm{T}$ |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 25 | 1.034E-8 | 65 | 6.488E-6 | 105 | $1.041 \mathrm{E}-3$ | 145 | $6.321 \mathrm{E}-2$ |
| 30 | 2.539E-8 | 70 | 1.306E-5 | 110 | $1.823 \mathrm{E}-3$ | 150 | $1.000 \mathrm{E}-1$ |
| 35 | 6.055E-8 | 75 | 2. $576 \mathrm{E}-5$ | 115 | 3.146E-3 | 155 | 1.565E-1 |
| 40 | $1.404 \mathrm{E}-7$ | 80 | 4.985E-5 | 120 | 5.355E-3 | 160 | $2.424 \mathrm{E}-1$ |
| 45 | 3.172E-7 | 85 | 9.471E-5 | 125 | 8.994E-3 | 165 | $3.718 \mathrm{E}-1$ |
| 50 | $6.986 \mathrm{E}-7$ | 90 | 1.768E-4 | 130 | $1.491 \mathrm{E}-2$ | 170 | $5.647 \mathrm{E}-1$ |
| 55 | 1.502E-6 | 95 | $3.244 \mathrm{E}-4$ | 135 | $2.442 \mathrm{E}-2$ | 175 | $8.498 \mathrm{E}-1$ |
| 60 | 3.156E-6 | 100 | $5.857 \mathrm{E}-4$ | 140 | $3.952 \mathrm{E}-2$ |  |  |

Table 5.1.2.7-14 $\pi T$ vs Junction Temperature for GaAs Passive Devices

| $\mathrm{T}_{\mathrm{J}}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi$ | $\left.\mathrm{TJ}_{\mathrm{J}}{ }^{\circ} \mathrm{C}\right)$ |  | $\mathrm{T}_{\mathrm{j}}\left({ }^{\circ} \mathrm{C}\right)$ |  | $\mathrm{T}_{\mathrm{J}}\left({ }^{\circ} \mathrm{C}\right)$ | $\pi$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 25 | 7.166E-4 | 65 | 5.178E-3 | 105 | $2.462 \mathrm{E}-2$ | 145 | $8.686 \mathrm{E}-2$ |
| 30 | 9.442E-4 | 70 | 6.419E-3 | 110 | $2.924 \mathrm{E}-2$ | 150 | 1.000E-1 |
| 35 | $1.233 \mathrm{E}-3$ | 75 | $7.908 \mathrm{E}-3$ | 115 | $3.458 \mathrm{E}-2$ | 155 | $1.147 \mathrm{E}-1$ |
| 40 | $1.596 \mathrm{E}-3$ | 80 | 9.685E-3 | 120 | $4.071 \mathrm{E}-2$ | 160 | $1.312 \mathrm{E}-1$ |
| 45 | $2.050 \mathrm{E}-3$ | 85 | 1.179E-2 | 125 | $4.773 \mathrm{E}-2$ | 165 | $1.497 \mathrm{E}-1$ |
| 50 | $2.612 \mathrm{E}-3$ | 90 | $1.429 \mathrm{E}-2$ | 130 | 5.575E-2 | 170 | $1.702 \mathrm{E}-1$ |
| 55 | $3.305 \mathrm{E}-3$ | 95 | $1.721 \mathrm{E}-2$ | 135 | $6.487 E-2$ | 175 | $1.929 \mathrm{E}-1$ |
| 60 | $4.151 \mathrm{E}-3$ | 100 | $2.064 \mathrm{E}-2$ | 140 | 7.520E-2 |  |  |

## MIL-HDBK-217(REV) MICROELECTRONIC DEVICES

Table 5.1.2.7-15 $\mathrm{C}_{2}$, Package Complexity Failure Rates in Failures Per $10^{6}$ Hours

| \| Number of <br> \| Functiona <br> \| Pins | PACKAGE TYPE* |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | \| Hermetic DIPs |  |  |  |  |
|  | \|w/Solder or Wel |  |  | Hermetic |  |
|  | \|Seal Leadless |  |  | Flatpacks |  |
|  | \| Chip Carriers | Hermetic OIPs |  | with Axial |  |
|  | \|(LCC) Pin Grid | with Glass | Nonhermetic | Leads on 50 | Hermetic |
|  | Array (PGA) | Seal | DIPs | Mil Centers | Cans |
| 3 | --- | --- | - | --- | 0.0003 |
| 4 | 1 --- | --- | --- | 0.0004 | 0.0005 |
| 16 | 10.0019 | 0.0013 | 0.0018 | 0.0008 | 0.0011 |
| 8 | 10.0026 | 0.0021 | 0.0026 | 0.0013 | 0.0020 |
| 10 | \| 0.0034 | 0.0029 | 0.0034 | 0.0020 | 0.0031 |
| 12 | 10.0041 | 0.0038 | 0.0043 | 0.0028 | 0.0044 |
| 14 | 10.0048 | 0.0048 | 0.0051 | 0.0037 | 0.0060 |
| 16 | 10.0056 | 0.0059 | 0.0061 | 0.0047 | 0.0079 |
| 18 | 10.0064 | 0.0071 | 0.0070 | 0.0058 | -- |
| 22 | 10.008 | 0.010 | 0.009 | 0.008 | -- |
| 24 | 10.009 | 0.011 | 0.010 | 0.010 | --- |
| 28 | 10.010 | 0.014 | 0.012 | --- | --- |
| 36 | 10.013 | 0.020 | 0.016 | --- | --- |
| 40 | 10.015 | 0.024 | 0.019 | --- | - |
| 64 | \| 0.025 | 0.048 | 0.033 | --- | --- |
| 80 | 10.032 | - | - | --- | -- |
| 128 | 10.053 | --- | - | -- | -- |
| 180 | \| 0.076 | --- | - | --- | -- |
| 224 | \| 0.097 | - | --- | --- | --- |
| 525 | 0.243 | --- | --- | --- | --- |

*If seal type for hermetic DIP is unknown, assume glass seal.
The tabulated values are determined by the following equations:
Hermetic DIPs with solder or weld seals,
Leadless Chip Carrier (LCC) \& PGAs. $\quad C_{2}=2.8 \times 10^{-4}\left(N_{P}\right)^{1.08}$
(5.1.2.7.5)

Hermetic DIPs with glass seals
$C_{2}=9.0 \times 10^{-5}\left(N_{p}\right)^{1.51}$
$C_{2}=2.0 \times 10^{-4}\left(N_{p}\right)^{1.23}$
Hermetic Flatpacks
$C_{2}=3.0 \times 10^{-5}\left(N_{p}\right)^{1.82}$
Hermetic Cans

$$
\begin{equation*}
c_{2}=3.0 \times 10^{-5}\left(N_{p}\right)^{2.01} \tag{5.1.2.7.7}
\end{equation*}
$$

where: $N_{p}$ is the number of pins on a device package which are connected to some substrate location.







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| .031 | .518 | 4.488 | 22.021 | 69.887 | 164.147 | 315.649 | 530.680 |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| .068 | .953 | 7.071 | 30.629 | 88.977 | 197.008 | 364.242 | 596.104 |
| .138 | 1.651 | 10.604 | 41.088 | 110.476 | 232.371 | 415.106 | 663.388 |
| .265 | 2.705 | 15.230 | 53.433 | 134.262 | 270.008 | 467.969 | 732.251 |
| .477 | 4.222 | 21.064 | 67.657 | 160.193 | 309.700 | 522.581 | 802.438 |
| .817 | 6.306 | 28.189 | 83.719 | 188.116 | 351.234 | 578.709873 .720 |  |
| 1.333 | 9.061 | 36.659 | 101.553 | 217.872 | 394.408 | 636.140945 .889 |  |
| 2.082 | 12.575 | 46.496 | 121.072 | 249.305 | 439.035 | 694.68299 .000 |  |
| 3.127 | 16.927 | 57.698 | 142.180 | 282.259 | 484.939 | 754.156 | 999.000 |
| 4.531 | 22.174 | 70.242 | 164.772 | 316.589 | 531.957 | 814.403 | 999.000 |


| .826 | 6.359 | 28.358 | 84.087 | 188.742 | 352.152 | 579.940 | 875.275 | 999.000 |
| ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: | ---: |
| 1.255 | 8.669 | 35.503 | 99.183 | 213.981 | 388.817 | 628.750 | 936.642 | 999.000 |
| 1.846 | 11.514 | 43.616 | 115.467 | 240.383 | 426.459 | 678.261 | 998.382999 .000 |  |
| 2.635 | 14.940 | 52.692 | 132.873 | 267.845 | 464.961 | 728.359 | 999.000 | 999.000 |
| 3.659 | 18.981 | 62.714 | 151.331 | 296.270 | 504.218 | 778.937 | 999.000 | 999.000 |
| 4.955 | 23.664 | 73.657 | 170.769 | 325.562 | 544.129 | 829.900 | 999.000 | 999.000 |
| 6.559 | 29.003 | 85.486 | 191.117 | 355.634 | 584.602 | 881.160 | 999.00099 .000 |  |
| 8.503 | 35.008 | 98.164 | 212.303 | 386.401 | 625.553 | 932.638 | 999.000 | 999.000 |
| 10.815 | 41.678 | 111.648 | 234.259 | 417.786 | 666.904 | 984.262 | 999.00099 .000 |  |
| 13.521 | 49.007 | 125.894 | 256.919 | 449.716 | 708.584 | 999.000 | 999.000 | 999.000 |


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## MIL-HDBK-217(REV) MICROELECTRONIC DEVICES

(Notes for Table 5.1.2.7-16)

NOTE 1: Temperature axis refers to $T_{j}$ as detailed in note of Table 5.1.2.7-4.

NOTE 2: Electric Field Stress axis refers to worst case voltage applied to the thinnest transistor gate oxide using the following expression:

$$
\begin{aligned}
& E_{S}=. l\left(V_{O P} / t_{O X}\right) \quad(\text { in MV / } \mathrm{cm}) \\
& \text { where: }
\end{aligned} \quad \begin{aligned}
& V_{O P}=\text { operating voltage (in volts) } \\
& \left.t_{O X}=\text { oxide thickness (in } K A\right)
\end{aligned}
$$

If oxide thickness is not known, Table 5.1.2.7-19 gives default values based on the number of transistors on the device in question.

NOTE 3: The correct page for use is determined by the total amount of active transistor gate oxide area. If total amount of active transistor gate oxide area is not known, Table 5.1.2.7-18 gives default values based on the number of transistors on the device in question.


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## MIL-HDBK-217(REV) MICROELECTRONIC DEVICES

(Notes for Table 5.1.2.7-17)

NOTE 1: Temperature axis refers to $T_{j}$ as detailed in note of Table 5.1.2.7-4 $\left(T_{J}=T_{C}+\theta_{J C} \times P\right)$.

NOTE 2: Current Density axis refers to worst case current density on device. The default value is $.13 \mathrm{MA} / \mathrm{cm}^{2}$.

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-18 Total Transistor Gate Area $\left(\log \mu \mathrm{m}^{2}\right)$

| Complexity <br> (\# of trans.) | Digital Microprocessors <br> (including Controllers) | Digital and Linear <br> Gate / Logic Arrays |
| :---: | :---: | :---: |
| $100-500$ | 5.39 | 5.24 |
| $500-1 K$ | 5.47 | 5.37 |
| $1 \mathrm{~K}-5 \mathrm{~K}$ | 5.64 | 5.67 |
| $5 \mathrm{~K}-10 \mathrm{~K}$ | 5.72 | 5.80 |
| $10 \mathrm{~K}-50 \mathrm{~K}$ | 5.90 | 6.10 |
| $50 \mathrm{~K}-100 \mathrm{~K}$ | 5.97 | 6.23 |
| $100 \mathrm{~K}-50 \mathrm{~K}$ | 6.15 | 6.52 |
| $500 \mathrm{~K}-1 \mathrm{M}$ | 6.23 | 6.65 |
| $1 \mathrm{M}-5 \mathrm{M}$ | 6.41 | 6.95 |
| $5 M-10 \mathrm{M}$ | 6.48 | 7.08 |

NOTE Total Transistor Gate Area refers to the total amount of active transistor gate oxide area on the device based on the number of transistors on the device using the following expression:

$$
A=\log \left(4^{*} T R * 10^{-0.744^{*}(\log (T R)-5.50)}\right) \quad\left(\text { in } \log \mu m^{2}\right)
$$

for MOS Digital Microprocessors (Including Controllers), and

$$
A=\log \left(6^{*} T R^{*} 10^{-0.580 *}(\log (T R)-5.78), \quad\left(\text { in } \log \mu m^{2}\right)\right.
$$

for MOS digital and Linear Devices (Including Gate / Logic Arrays)

TR is the number of transistors on the device in question

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-19 Dielectric Thickness (KA)

| Complexity <br> (\# of trans.) | Digital Microprocessors <br> (including Controllers) | Digital and Linear <br> Gate/ Logic Arrays |
| :---: | :---: | :---: |
| $100-500$ | 4.81 | 2.17 |
| $500-1 K$ | 2.50 | 1.35 |
| $1 K-5 K$ | 1.89 | 1.10 |
| $5 K-10 K$ | 0.98 | 0.68 |
| $10 K-50 K$ | 0.74 | 0.56 |
| $50 K-100 K$ | 0.39 | 0.35 |
| $100 K-500 K$ | 0.29 | 0.28 |
| $500 K-1 M$ | 0.15 | 0.17 |
| $1 M-5 M$ | 0.11 | 0.14 |
| $5 M-10 M$ | 0.06 |  |

NOTE 1: Dielectric Thickness refers to the thinnest transistor gate oxide on the device based on the number of transistors on the device using the following expression:

$$
t_{0 x}=10^{\left.-0.406^{*}(\log (T R)-3.68)\right) \quad(\text { in } K A), ~}
$$

for MOS Digital Microprocessors (Including Controllers), and

$$
\left.t_{0 x}=10-0.296^{*}(\log (T R)-3.14)\right) \quad(i n k A)
$$

for MOS Digital and Linear Devices (Including Gate / Logic Arrays)
$T R$ is the number of transistors on the device in question

NOTE 2: The electric field stress, $E_{S}$, is given by

$$
\begin{equation*}
E_{S}=.11 v_{O p} / t_{O x} \quad(M v / c m) \tag{5.1.2.7.14}
\end{equation*}
$$

where:

$$
\begin{aligned}
& V_{\text {op }}=\text { operating voltage (user supplied } V \text { ) } \\
& t_{\text {ox }}=\text { oxide thickness (user supplied } K \AA \text { ) }
\end{aligned}
$$

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-20 Gate Oxide Area, Memories

*For BiMOS SRAMs, multiply oxide area by . 667


UVEPROMS, EEPROMS, FLOATING GATE PROMS, PALS, PLAS, MOS ROMS, HALS, MLAS For all device capacities: $260,000-1,209,000 \mu \mathrm{~m}^{2}$

NOTE: If gate oxide area is unknown, assume upper limit.

## MIL-HDBK-217(REV) MICROELECTRONIC DEVICES

Table 5.1.2.7-21 Gate Oxide Thickness, Memories

| MOS ROMs/PLAs/PALs/MLAs/HALs* |  |  |
| :---: | :---: | :---: |
| $\begin{aligned} & \text { Capacity } \\ & \text { (\#bits) } \end{aligned}$ | Gate Oxi Lower Li | (Angstroms) Upper Limit |
| 2 K | 600 | 700 |
| 4 K | 600 | 700 |
| 8K | 600 | 700 |
| 16 K | 600 | 700 |
| 32K | 600 | 700 |
| 64K | 400 | 600 |
| 128K | 400 | 500 |
| 256K | 400 | 500 |
| 512K | 400 | 500 |
| 1 M | 250 | 400 |
| 2 M | 250 | 400 |
| *For MOS ROMs/PLAs/PALs/MLAs/HALs determine number of bits in the array, then use above table, rounding up to the next highest bit category. |  |  |
| UVEPROMS, MNOS/Flash EEPROMs, Float. Gate PROMs |  |  |
| $\begin{aligned} & \text { Capacity } \\ & \text { (\# bits) } \end{aligned}$ | Gate Oxide Thickness (Angstroms) Lower Limit Upper Limit |  |
| 2 K | 600 | 700 |
| 4K | 600 | 700 |
| 8K | 600 | 700 |
| 16 K | 600 | 700 |
| 32K | 600 | 700 |
| 64K | 400 | 600 |
| 128K | 300 | 400 |
| 256K | 300 | 400 |
| 512K | 235 | 400 |
| 1 M | 235 | 400 |
| 2 M | 235 | 400 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-21 Gate Oxide Thickness, Memories (continued)


NOTE: If gate oxide thickness is unknown, assume lower limit.

## MIL-HDBK-217(REV)

MICROELECTRONIC DEVICES

Table 5.1.2.7-22: Cross Reference for Commercial Type to MIL-M-38510 Type

| COMMERCIAL | M38510/ | COMMERCIAL | M38510/ | COMMERCIAL | M38510/ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| REFIO | 12403 | LM139 | 11201 | PAL 16R6A-2 | 50409 |
| LM101A | 10103 | LM140H-05 | 10702 | PALIGL8A | 50401 |
| LM102 | 10601 | [M1 40H-12 | 10703 | PaLl6R8A | 50402 |
| 10501 | 06001 | LM1 40H-15 | 10704 | PAL 16L8A-2 | 50407 |
| 10502 | 06002 | LM140H-24 | 10705 | PAL16R8A-2 | 50408 |
| 10504 | 06201 | LM1 40K-05 | 10706 | 18020 | 47001 |
| 10505 | 06003 | (M140K-12 | 10707 | OG181A | 11101 |
| 10506 | 06004 | LM140K-15 | 10708 | DG182A | 11102 |
| 10507 | 06005 | LM140K-24 | 10709 | 1832 | 47201 |
| 10509 | 06006 | 14013B | 05151 | DG184A | 1103 |
| 10524 | 06301 | 140238 | 05053 | OG185A | 11104 |
| 10525 | 06302 | 140938 | 17701 | 1853 | 47401 |
| 10531 | 06101 | PAL 14H4 | 50303 | DG187-A | 11105 |
| 10535 | 06104 | PAL 1414 | 50308 | OG188A | 11106 |
| 10576 | 06103 | LM141H-05 | 10702 | DG190A | 11107 |
| 10597 | 06202 | LM141H-12 | 10703 | OGI91A | 1108 |
| LM106 | 10303 | LM14 $1 \mathrm{H}-15$ | 10704 | LM193 | 11202 |
| 10631 | 06102 | LM14 1H-24 | 10705 | LF198 | 12501 |
| LMIO8A | 10104 | 14502 | 17403 | LMI99a | 12401 |
| PALIOH8 | 50301 | MC 14069 | 17401 | LM199 | 12404 |
| PALIOL3 | 50306 | LF147 | 11906 | OG200 | 12301 |
| LM109 | 10701 | LM148 | 11001 | HI 200 | 12301 |
| LM110 | 10602 | LM149 | 11002 | 2003 | 14103 |
| LM111 | 10304 | LM150K | 11705 | OG201 | 12302 |
| LMI 17H | 11703 | LF151 | 11904 | H1201 | 12302 |
| LM117K | 11704 | 1524 | 12501 | pal 20R4A | 50504 |
| LM118 | 10107 | LM1524 | 12601 | pal 20R6a | 50503 |
| LM120H-05 | 11501 | LF153 | 11905 | PAL20L8A | 50501 |
| LM120H-12 | 11502 | 15482 | 00601 | PAL20R8A | 50502 |
| LM1 20H-15 | 11503 | LF155 | 11401 | LH2101A | 10105 |
| LM120H-24 | 11504 | LF155A | 11404 | LH2108A | 10106 |
| LM120K-05 | 11505 | 1558 | 10108 | LH2110 | 10603 |
| LM1 20K-12 | 11506 | LF156 | 11402 | LH2111 | 10305 |
| LM120K-15 | 11507 | LF156A | 11405 | 2114 | 23892 |
| LMI20K-24 | 11508 | LF157 | 11403 | 2114 A | 23804 |
| DAC 122110 | 12707 | LFI57A | 11406 | 2117 | 24001 |
| LM124 | 11005 | PAL 16C1 | 50305 | 2117 | 24002 |
| PAL $12 \mathrm{H6}$ | 50302 | PAL 16 H 2 | 50304 | 2117 | 24003 |
| PAL 12 L 6 | 50307 | PAL 16L2 | 50309 | 2147 | 23801 |
| LMI 29A | 12402 | PAL 16R4A | 50404 | 2147H | 23803 |
| LM1298 | 12406 | PAL $16 \times 4$ | 50405 | $2147 \mathrm{H}-3$ | 23805 |
| LM137H | 11803 | PAL 16A4 | 50406 | $2147 \mathrm{H}-2$ | 23807 |
| LM1 37K | 11804 | PAL 16R4A-2 | 50410 | 2148 H | 23806 |
| LMI 38K | 11706 | PAL 16R6A | 50403 | 2164 | 24401 |

## MIL-HDBK-217(REV) MICROELECTRONIC DEVICES

Table 5.1.2.7-22: Cross Reference for Commercial Type to MIL-M-38510 Type (continued)

| COMMERCIAL | M385 10/ | COMMERCIAL | M38510/ | COMMERCIAL | M38510/ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 2164 | 24402 | OG300 | 11601 | 4014B | 05752 |
| 2164 | 24403 | DG301A | 11602 | 4015A | 05703 |
| 2316 E | 40301 | 3018A | 10801 | 40158 | 05753 |
| 24401 | 24401 | DG302A | 11603 | 4016A | 05801 |
| 2500 | 12204 | dG303A | 11604 | 4016 B | 05851 |
| 2510 | 12205 | DG304A | 11605 | 4017A | 05601 |
| 2516 | 22101 | 3045 | 10802 | 4017 B | 05651 |
| 25LS174 | 33106 | DG305A | 11606 | 401748 | 17505 |
| 25LS175 | 33107 | OG306A | 11607 | 4018A | 05602 |
| 2520 | 12206 | OG307A | 11608 | 40188 | 05652 |
| 2532 | 22201 | MC3101 | 15501 | 4019A | 05302 |
| 0026 | 03501 | MC3106 | 15502 | 40198 | 05352 |
| 050026 | 03501 | MC3111 | 15503 | 4020A | 05603 |
| MH0026 | 03501 | MK34000 | 40301 | 4020B | 05653 |
| 2600 | 12202 | 34069 | 17401 | 4021A | 05704 |
| 2616 | 40301 | 3516 E | 40301 | 40218 | 05754 |
| 2620 | 12203 | 3636 | 21002 | 4022A | 05604 |
| OP27A | 13503 | 4000A | 05201 | 40228 | 05654 |
| 2700 | 12201 | 40008 | 05251 | 4023A | 05003 |
| 2708 | 22001 | 4001A | 05202 | 4023B | 05053 |
| 2716 | 22101 | 40018 | 05252 | 4024A | 05605 |
| 275180 | 20903 | 4002A | 05203 | 40248 | 05655 |
| 275181 | 20904 | 4002B | 05253 | 4025A | 05204 |
| 275191 | 21002 | 4006A | 05701 | 40258 | 05254 |
| 2732 | 22202 | 4006B | 05751 | 4027A | 05102 |
| NMC2816 | 22601 | 4007A | 05301 | 40278 | 05152 |
| 28S 166A | 21002 | 4007UB | 05351 | 4028A | 05901 |
| 285 166A | 21004 | 4008A | 05401 | 40288 | 05951 |
| 2901A | 44001 | 40088 | 05451 | 4030A | 05303 |
| 2901C | 44001 | 4009A | 05501 | 40308 | 05353 |
| 2905 | 44101 | 4009UB | 05551 | 4031A | 05705 |
| 2906 | 44102 | 4010A | 05502 | 40318 | 05755 |
| 2907 | 44103 | 40108 | 05552 | 4034A | 05706 |
| 2915A | 44104 | 40106B | 17702 | 40348 | 05756 |
| 2916A | 44105 | 401078 | 17402 | 4041A | 05505 |
| 2917A | 44106 | 401098 | 17408 | 4041UB | 05555 |
| 2918 | 44201 | 4011A | 05001 | 4043A | 05103 |
| 29611 | 20402 | 40118 | 05051 | 40438 | 05153 |
| 29621 | 20805 | 4012A | 05002 | 4048A | 05304 |
| 29631 | 20904 | 40128 | 05052 | 4048B | 05354 |
| 29651 | 20902 | 4013 A | 05101 | 4049 A | 05503 |
| 29651 | 20908 | 4013 B | 05151 | 4049UB | 05553 |
| 29681 | 21002 | 4014A | 05702 | 4050A | 05504 |

MIL-HDBK-217(REV)
MICROELECTRONIC DEVICES

Table 5.1.2.7-22: Cross Reference for commercial Type to MIL-M-38510 Type (continued)

| COMMERCIAL | M38510/ | COMMERCIAL | M38510/ | COMMERCIAL | M38510/ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 40508 | 05554 | 4564 | 24401 | 535841 | 20902 |
| TMS4050 | 23502 | 4564 | 24402 | 535841 | 20908 |
| TMS4050 | 23504 | 4564 | 24403 | 5400 | 00104 |
| 4060A | $05 \times 01$ | 4741 | 11003 | 54100 | 02004 |
| TMS4060 | 23501 | 506 | 19001 | 54400 | 02304 |
| TMS4060 | 23503 | 506A | 19002 | 54500 | 07001 |
| 4066A | 05802 | 507 | 12003 | 54L500 | 30001 |
| 40668 | 05852 | 507A | 19004 | 54700 | 33001 |
| 4067B | 17801 | 508A | 19005 | 54ALS00 | 37001 |
| 406948 | 17401 | 509A | 19006 | 54 HCOO | 65001 |
| 40708 | 17203 | HPROM5 12 | 20101 | 5401 | 00107 |
| 40708 | 05353 | 51667 | 29103 | 54L01 | 02006 |
| 40718 | 17101 | 51667 | 29106 | $54 \mathrm{HO1}$ | 02306 |
| 40728 | 17102 | 52116. | 40301 | 5402 | 00401 |
| 40738 | 17003 | M M 5280 | 23505 | 54L02 | 02701 |
| 40758 | 17103 | M 45280 | 23506 | 54502 | 07301 |
| 4076B | 17501 | 5300-1 | 20301 | 54LS02 | 30301 |
| 40778 | 17204 | 5301-1 | 20302 | 54F02 | 33301 |
| 40818 | 17001 | MCM5303 | 20101 | 54ALS02 | 37301 |
| 40828 | 17002 | MCM5304 | 20102 | 5403 | 00109 |
| 40853 | 17201 | 5305-1 | 20401 | 54L03 | 02006 |
| 40868 | 17202 | 5306-1 | 20402 | 54503 | 07002 |
| 40938 | 17701 | 53 S 1680 | 21001 | 54LS03 | 30002 |
| 40958 | 17502 | 5351681 | 21002 | 5404 | 00105 |
| 40968 | 17503 | A0532S | 13903 | 54C04 | 17401 |
| MK84096 | 23602 | 5330 | 20701 | 54L04 | 02005 |
| MKB4096 | 23604 | 5331 | 20702 | 54H04 | 02305 |
| 40978 | 17802 | A0534T | 13901 | 54504 | 07003 |
| 40988 | 17504 | A0534S | 13902 | 54L504 | 30003 |
| 40998 | 17601 | 5340-1 | 20801 | 54 F 04 | 33002 |
| 4116 | 24001 | 5341-1 | 20802 | 54ALS04 | 37006 |
| 4116 | 24002 | 535440 | 20601 | 5405 | 00108 |
| 4116 | 24003 | 535441 | 20602 | 54505 | 07004 |
| 4136 | 11004 | 5348-1 | 20804 | 54LS05 | 30004 |
| 4156 | 11003 | 5349-1 | 20805 | 5406 | 00801 |
| 4213 | 13904 | 5352-1 | 20601 | 5407 | 00803 |
| 45028 | 17403 | 5353-1 | 20602 | 5408 | 01601 |
| 45088 | 17602 | 5380-1 | 20003 | 54508 | 08003 |
| 45148 | 17301 | 5380-2 | 20903 | 54408 | 15501 |
| 45158 | 17302 | 5381-1 | 20904 | 54408 | 15504 |
| 45328 | 17303 | 5381-2 | 20904 | 54LS08 | 31004 |
| 45558 | 17304 | 535840 | 20901 | $54 \mathrm{F08}$ | 34001 |
| 4556B | 17305 | 535840 | 20907 | 54ALS08 | 37401 |

MIL-HDBK-217(REV)
MICROELECTRONIC DEVICES

Table 5.1.2.7-22: Cross Reference for Commercial Type to MIL-M-38510 Type (continued)

| COMMERCIAL | M38510/ | COMMERCIAL | M38510/ | COMMERCIAL | M38510/ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 5409 | 01602 | 54116 | 01503 | 54F151 | 33901 |
| 54509 | 08004 | 5412 | 00106 | 54153 | 01403 |
| 54L509 | 31005 | S4LS12 | 30006 | 545153 | 07902 |
| 5410 | 00103 | 54121 | 01201 | 54LS153 | 30902 |
| 54L10 | 02003 | 541121 | 04201 | 54F153 | 33902 |
| 54, 10 | 02303 | 54122 | 01202 | 54154 | 15201 |
| 54510 | 07005 | 54L122 | 04202 | 54155 | 15202 |
| 54LS10 | 30005 | 54LS122 | 31403 | 54LS155 | 32601 |
| 54710 | 33003 | 54123 | 01203 | 54156 | 15203 |
| 54ALS 10 | 37002 | 54LS123 | 31401 | 54LS156 | 32602 |
| 54HC 10 | 65002 | 54LS124 | 31701 | 54157 | 01405 |
| 54ALS 1000 | 38401 | 54125 | 15301 | 545157 | 07903 |
| 54ALS 1002 | 38402 | 54LS125 | 32301 | 54L5157 | 30903 |
| 54ALS1003 | 38403 | 54LS 25. | 32301 | 54F157 | 33903 |
| 54ALS 1004 | 38409 | 54126 | 15302 | 545158 | 07904 |
| 54AL S1005 | 38410 | 54LS126 | 32302 | 54LS158 | 30904 |
| 54AL S1008 | 38404 | 5413 | 15101 | 54F158 | 33904 |
| 54 HIO 1 | 02205 | 54LS13 | 31301 | 5416 | 00802 |
| 54ALS 1010 | 38405 | 54132 | 15103 | 54160 | 01303 |
| 54ALS 1011 | 38406 | 54LS132 | 31303 | 54L5160 | 31503 |
| 54ALS1020 | 38407 | 54HC132 | 65005 | 54LSI60A | 31503 |
| 54H103 | 02206 | 545133 | 07009 | 54161 | 01306 |
| 54AL S1032 | 38408 | 54ALS133 | 37005 | 54LS161 | 31504 |
| 54ALS1034 | 38411 | 54 S 134 | 07010 | 54LSI61A | 31504 |
| 54ALS1035 | 38412 | 54S135 | 07502 | 54162 | 01305 |
| 54107 | 00203 | 545138 | 07701 | 54LS162 | 31511 |
| 54LS107 | 30108 | 54LS138 | 30701 | 54LS162A | 31511 |
| 54LS109 | 30109 | 54ALS138 | 37701 | 54163 | 01304 |
| 54F109 | 34102 | 54S139 | 07702 | 54LS163 | 31512 |
| 54ALS109 | 37102 | 54LS139 | 30702 | 54LS163A | 31512 |
| -54511 | 08001 | 5414 | 15102 | 54164 | 00903 |
| 54H11 | 15502 | 54 LS 14 | 31302 | 54L164 | 02902 |
| 54LST1 | 31001 | 545140 | 08101 | 54LS164 | 30605 |
| 54F11 | 34002 | 54145 | 01005 | 54165 | 00904 |
| 54ALS 11 | 37402 | 54147 | 15601 | 54LST65 | 30608 |
| 545112 | 07102 | 54148 | 15602 | 54LS165A | 30608 |
| 54LS 112 | 30103 | 54LS148 | 36001 | 54LS166 | 30609 |
| 54F112 | 34103 | 54515 | 08002 | 54LS 168 | 31505 |
| 54ALSI12A | 37103 | $54 L 515$ | 31002 | 54LS169 | 31506 31506 |
| 54S113 | 07103 | 54150 | 01401 | 54LS1698 | 31506 |
| 54LS113 | 30104 | 54151 | 01406 | 5417 | 00804 |
| 545114 | 07104 | 545151 | 07901 | 54170 5415170 | $01801$ |
| 54LS114 | 30105 | 54LSI51 | 30901 | 54LS170 | 31902 |

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MICROELECTRONIC DEVICES

Table 5.1.2.7-22: Cross Reference for Commercial Type to MIL-M-38510 Type
(continued)

| COMMERCIAL | M38510/ | COMMERCIAL | M38510/ | COMMERCIAL | M38510/ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 541.S173 | 36101 | 54H21 | 15503 | 54LS273 | 32501 |
| 54174 | 01701 | 54LS21 | 31003 | 54LS279 | 31602 |
| 54S174 | 01705 | $54 \mathrm{H22}$ | 02307 | 5428 | 16201 |
| 54LS174 | 30106 | 54522 | 07007 | 54LS28 | 30204 |
| 54F174 | 34107 | 54LS22 | 30008 | 54ALS28 | 38402 |
| 54ALS 174 | 37201 | 54LS221 | 31402 | 54 LS 280 | 32901 |
| 54175 | 01702 | 5423 | 00402 | 54F280 | 34901 |
| 54S175 | 07106 | 54LS240 | 32401 | 54LS283 | 31202 |
| 54LS175 | 30107 | 54F240 | 33201 | 54F283 | 34201 |
| 54F175 | 34104 | 54ALS240 | 38301 | 545287 | 20302 |
| 54ALS175 | 37202 | 54LS241 | 32402 | 545288 | 20702 |
| 54180 | 01901 | 54F241 | 33202 | 54LS290 | 32003 |
| 54181 | 01101 | 54AL | 38302 | 5445293 | 32004 |
| 545181 | 07801 | 54ALS242 | 38506 | 54LS295B | 30606 |
| 54LS181 | 30801 | 54ALS243 | 38507 | 54LS298 | 30909 |
| 54182 | 01102 | 54LS244 | 32403 | 5430 | 00101 |
| 545182 | 07802 | 54F244 | 33203 | 54L30 | 02001 |
| 54LS190 | 31513 | 54ALS244 | 38303 | 54H30 | 02301 |
| 54LS191 | 31509 | 5425 | 00403 | 54530 | 07008 |
| 54192 | 01308 | 545251 | 07905 | 54L530 | 30009 |
| 54LS192 | 31507 | 54LS251 | 30905 | 54ALS30 | 37004 |
| 54193 | 01309 | 54F251 | 33905 | 54HC30 | 65004 |
| 54L193 | 02503 | 545253 | 07908 | 5432 | 16101 |
| 54LSIO3 | 31508 | 54LS253 | 30908 | 54L532 | 30501 |
| 54194 | 00905 | 54F253 | 33908 | 54F32 | 33501 |
| 54S194 | 07601 | 54ALS253 | $3 \times \times 1$ | 54ALS32 | 37501 |
| 54LS 194 | 30601 | 545257 | 07906 | 54LS324 | 31702 |
| 54LS194A | 30601 | 54LS257 | 30906 | 54L5348 | 36002 |
| 54F194 | 33601 | 54LS257B | 30906 | 54F352 | 33909 |
| 54195 | 00906 | 54 F257 | 33906 | 54F353 | 33910 |
| 545195 | 07602 | 545258 | 07007 | 54365 | 16301 |
| 54LS195 | 30602 | 54LS258 | 30907 | 54LS365 | 32201 |
| 54LS195A | 30602 | 54LS2588 | 30007 | 54366 | 16302 |
| 54LS196 | 32001 | 54F258 | 33907 | 54L5366 | 32203 |
| 54LS107 | 32002 | 54L5259 | 31603 | 54367 | 16303 |
| 5420 | 00102 | 54LS259B | 31605 | 54L5367 | 32202 |
| 54120 | 02002 | 5426 | 00805 | 54368 | 16304 |
| 54 H 20 | 02302 | 54LS26 | 32102 | 5415368 | 32204 |
| 54520 | 07006 | 54LS261 | 31801 | 5437 | 00302 |
| 54LS20 | 30007 | 54LS266 | 30303 | 54LS37 | 30202 |
| 54720 | 33004 | 5427 | 00404 | 54ALS37 | 38401 |
| 54ALS20 | 37003 | 54LS27 | 30302 | 54L5373 | 32502 |
| 54HC2O | 65003 | 54ALS27 | 37302 | 54LS374 | 32503 |

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## MICROELECTRONIC DEVICES

Table 5.1.2.7-22: Cross Reference for Commercial Type toi MIL-M-38410 Type (continued)

| COMMERCIAL | M38510/ | COMMERCIAL | M38510/ | COMMERCIAL | M38510/ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 54F374 | 34105 | 54551 | 07401 | 54H74 | 02203 |
| 54L5375 | 31604 | 54LS51 | 30401 | 54574 | 07101 |
| 54L5377 | 32504 | 54F521 | 34701 | 54L574 | 30102 |
| 54F378 | 34108 | 5453 | 00503 | 54F74 | 34101 |
| 54F379 | 34109 | 54 H 53 | 04003 | 54ALS74 | 37101 |
| 5438 | 00303 | 54F534 | 34106 | 5475 | 01501 |
| 54L538 | 30203 | 5454 | 00504 | 54LS75 | 31601 |
| 54L5390 | 32701 | 54454 | 04004 | 5476 | 00204 |
| 54L5393 | 32702 | 54L54 | 04102 | 54H76 | 02204 |
| 54LS395A | 30607 | 54LS54 | 30402 | 541576 | 30110 |
| 5440 | 00301 | 54L5540 | 32404 | 54LS76A | 30110 |
| $54 \mathrm{H40}$ | 02401 | 54LS54 1 | 32405 | 5477 | 01502 |
| 54540 | 07201 | 54455 | 04005 | 54 L 78 | 02104 |
| 54LS40 | 30201 | 54L55 | 04103 | 5479 | 00207 |
| 54ALS40 | 38407 | 545570 | 20401 | 5480 | 00604 |
| 545412 | 42101 | 545571 | 20402 | 5482 | 00601 |
| 5442 | 01001 | 545572 | 20601 | 5483 | 00602 |
| 54142 | 02901 | 545573 | 20602 | 54LS83A | 31201 |
| 54L542 | 30703 | 54ALS574 | 37104 | 54585 | 08201 |
| 54LS424 | 42201 | 54ALS576 | 37105 | 5485 | 15001 |
| 545428 | 42301 | 54564 | 07402 | 54L585 | 31101 |
| 5443 | 01002 | 54764 | 33401 | 54ALS857 | 37901 |
| 54143 | 02902 | 54L5640 | 32804 | 5486 | 00701 |
| 5444 | 01003 | 54ALS640 | 38501 | 54L86 | 02601 |
| 54144 | 02903 | 54ALS641 | 38502 | 54586 | 07501 |
| 5445 | 01004 | 54AL S642 | 38503 | 54L86 | 30502 |
| 5446 | 01006 | 54ALS643 | 38504 | 54F86 | 34501 |
| 54146 | 02904 | 54ALS645 | 38505 | 54ALS874 | 37106 |
| 5447 | 01007 | 54LS646 | 32804 | 54ALS876 | 37107 |
| 54147 | 02905 | 54L5648 | 32805 | 5490 | 01307 |
| 54.547 | 30704 | 54565 | 07403 | 54L90 | 02501 |
| 545472 | 20805 | 54L5670 | 31901 | 54L590 | 31501 |
| 545473 | 20804 | 5470 | 00206 | 5492 | 01301 |
| 545474 | 20802 | 54671 | 02101 | 541592 | 31510 |
| 545475 | 20801 | 5472 | 00201 | 54C929 | 23901 |
| 5448 | 01008 | 54172 | 02102 | 5493 | 01302 |
| 5449 | 01009 | 54472 | 02201 | 54L93 | 02502 |
| 54L5490 | 32703 | 5473 | 00202 | 54L593 | 31502 |
| 5450 | 00501 | 54 L 73 | 02103 | 54L93A | 02502 |
| $54 \mathrm{H50}$ | 04001 | 54473 | 02202 | 54C930 | 23902 |
| 5451 | 00502 | 54L573 | 30101 | 5495 | 00961 |
| 54H51 | 04002 | 5474 | 00205 | 54L95 | 02801 |
| 54L51 | 04101 | 54L74 | 02105 | 54L595 | 30603 |

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Table 5.1.2.7-22: Cross Reference for Commercial Type to MIL-M-38510 Type (continued)

| COMMERCIAL | M38510/ | COMMERCIAL | M38510/ | COMMERCIAL | M38510/ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 54LS958 | 30603 | 6208 | 19008 | 7611 | 20302 |
| 54.6 | 00902 | 6216 | 19003 | 76160 | 21001 |
| 54LS96 | 30604 | 064 | 11903 | 76161 | 21002 |
| 55107 | 10401 | 6504 | 24501 | 76165 | 21005 |
| 55108 | 10402 | 6508 | 23901 | 7620 | 20401 |
| 55113 | 10405 | 6514 | 24502 | 7621 | 20402 |
| 55114 | 10403 | 6516 | 29102 | 76321 | 21101 |
| 55115 | 10404 | 65162 | 29101 | 7640 | 20801 |
| SMJ5517 | 29101 | 65162 | 29104 | 7641 | 20802 |
| SMJ5517 | 29105 | 65162 | 29105 | 761.42A | 02906 |
| 5532A | 13102 | 6518 | 23902 | 7642 | 20601 |
| 55325 | 13001 | 65262 | 29103 | 7643 | 20602 |
| 55326 | 13002 | MCM6604A | 23602 | 7644 | 20603 |
| 55327 | 13003 | MCM6604A | 23604 | 76170 | 02805 |
| 5534 A | 13101 | MCM6605 | 23601 | 7680 | 20903 |
| SE 5537 | 12502 | MCM6605 | 23603 | 7681 | 20904 |
| 55450 | 12901 | IM6654 | 21901 | 7684 | 20901 |
| 55451 | 12902 | 6665 | 24401 | 7685 | 20902 |
| 55452 | 12903 | 6665 | 24402 | 771 | 11004 |
| 55453 | 12904 | 6665 | 24403 | 775180 | 20903 |
| 55454 | 12905 | 6800 | 40001 | 775181 | 20904 |
| 55460 | 12906 | 6810 | 40201 | 775184 | 20901 |
| 55461 | 12907 | S6831B | 40301 | 775185 | 20902 |
| 55462 | 12908 | 68A316E | 40301 | 775190 | 21001 |
| 55463 | 12909 | $68316 E$ | 40301 | 775191 | 21002 |
| 55464 | 12910 | 071 | 11904 | 772 | 11905 |
| 555 | 10901 | 710 | 10301 | 774 | 11906 |
| 556 | 10902 | 14710 | 10301 | 78MG | 11701 |
| 557 | 10903 | 711 | 10302 | 78 G | 11702 |
| IM5603A | 20201 | LM711 | 10302 | 78M05 | 10702 |
| AD561 | 13301 | 714 | 13502 | 7805 | 10706 |
| IM5623 | 20202 | 7181 | 01101 | NC7810LC | 22501 |
| 568318 | 40301 | 072 | 11905 | 78M12 | 10703 |
| AD571 | 13401 | LM723 | 10201 | 7812 | 10707 |
| AD584S | 12801 | MM7280 | 23505 | 78M15 | 10704 |
| A0584T | 12802 | M17280 | 23506 | 7815 | 10708 |
| $061$ | 11901 | 074 | 11906 | 78 M 24 | 10705 |
| 6108 | 19007 | LM741A | 10101 | 7824 | 10709 |
| . 6116 | 19001 | LM747A | 10102 | 7831 | 10406 |
| 6116 | 29101 | 7558 | 10108 | 7832 | 10407 |
| 6116 | 29104 | 7602 | 20701 | 79ME | 11801 |
| 6116 | 29105 | 7603 | 20702 | 79G | 11802 |
| 062 | 11902 | 7610 | 20301 | 79M05 | 11501 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-22: Cross Reference for Commercial Type to MIL-M-38510 Type
(continued)

| COMMERCIAL | M38510/ | COMMERCIAL | M38510/ | COMMERCIAL | M38510/ |
| :---: | :---: | :---: | :---: | :---: | :---: |
| 7905 | 11505 | 825185 | 20902 | 93601 | 02907 |
| $79 \mathrm{M12}$ | 11502 | 825190 | 21001 | 9301 | 15206 |
| 7912 | 11506 | 825191 | 21002 | 9304 | 00603 |
| $79 \mathrm{M15}$ | 11503 | 8251018 | 21004 | 9308 | 01503 |
| 7015 | 11507 | 82523 | 20701 | 93108 | 04502 |
| 79 M 24 | 11504 | 8224 | 42201 | 9309 | 01404 |
| 7924 | 11508 | 8252708 | 20905 | 93699 | 04601 |
| OAC-08 | 11301 | 8228 | 42301 | 93610 | 02504 |
| DAC-D8A | 11302 | 8250 | 15204 | 9311 | 15201 |
| z-80 | 48002 | 8251 | 15205 | 9312 | 01402 |
| 2-80A | 48001 | 8252 | 15206 | 93612 | 04602 |
| Z80ACPU | 48001 | 8264 | 24401 | 9314 | 01504 |
| 2-808 | 48003 | 8264 | 24402 | 93614 | 04501 |
| 280CPU | 48002 | 8264. | 24403 | $93 L 16$ | 02505 |
| 2808CPU | 48003 | 9093 | 03304 | 9317 | 15802 |
| 28001 | 52001 | AM9130CFC | 23701 | $93 \mathrm{L18}$ | 04301 |
| 28001A | 52003 | AM9130AFC | 23702 | 9318 | 15603 |
| 28002 | 52002 | AM9130CDM | 23703 | 932 | 03101 |
| 28002A | 52004 | AM9130CFM | 23703 | 9321 | 15801 |
| 8088A | 42001 | AM9130ADM | 23704 | 9322 | 01405 |
| 82510 | 23101 | AM9130AFM | 23704 | 93622 | 04603 |
| 82510 | 23107 | AM91L30CF | 23705 | 93124 | 04401 |
| 82511 | 23102 | AM91L30AF | 23706 | 9324 | 15002 |
| 82511 | 23108 | AM91L30COM | 23707 | $93 L 28$ | 02803 |
| 825115 | 20803 | AM91L30CFM | 23707 | 9328 | 15902 |
| 8212 | 42101 | AM91L30ADM | 23708 | 933 | 03105 |
| 825123 | 20702 | AM91L30 AFM | 23708 | 9334 | 16001 |
| 825126 | 20301 | AM9140CFC | 23709 | 9338 | 15701 |
| 82S126A | 20303 | AM9140AFC | 23710 | 9341 | 01101 |
| 825129 | 20302 | AM9140CDM | 23711 | 93410 | 23001 |
| 82S129A | 20304 | AM9140CFM | 23711 | 93411 | 23003 |
| 825130 | 20401 | AM9140ADM | 23712 | 93412 | 23109 |
| 82S130A | 20403 | AM9140AFM | 23712 | 93L412 | 23111 |
| 825131 | 20402 | AM91L40CDC | 23713 | 93415 | 23101 |
| 825131 A | 20404 | AM91L 40 AFC | 23714 | 936415 | 23103 |
| 825136 | 20601 | AM91L40CDM | 23715 | 93415 | 23105 |
| 825137 | 20602 | AM91L40CFM | 23715 | 93415 | 23107 |
| 825137A | 20604 | AM91L40ADM | 23716 | 93417 | 20301 |
| 825140 | 20801 | AM91L40AFM | 23716 | 93419 | 23201 |
| 825141 | 20802 | 9218 | 40301 | 9342 | 01102 |
| 825180 | 20903 | 930 | 0300.1 | 936420 | 23004 |
| 825181 | 20904 | 93100 | 02804 | 93421 | 23002 |
| 825184 | 20901 | 9300 | 15901 | 93422 | 23110 |



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MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters

| M38510/ XXXXxxX | vec (v.) | $\begin{aligned} & p_{d} \\ & (w .) \end{aligned}$ | Complexity | No | M38510/ $\mathrm{xx} \times \mathrm{xx} \times \mathrm{x}$ | $\begin{aligned} & \text { vee } \\ & \text { (v.) } \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TLL |  |  |  |  | $T L$ |  |  |  |  |
| 00101-A | 7. | 0.04 | 16 | 14 | 00203-C | 7. | 0.22 | 156 | 11 |
| 00101-3 | 7. | 0.04 | 16 | 14 | 30204-5 | 7. | 0.72 | 150 | : |
| 00101-6 | 7. | 0.04 | 16 | 14 | 00294-5 | 7. | 0.22 | 166 | 15 |
| 00101-0 | 7. | 0.04 | 16 | 14 | 00205-A | 7. | 0.22 | 12 G | 14 |
| 00102-A | 7. | 0.08 | 2 G | 14 | 20295-3 | 7. | 0.22 | 12 G | 14 |
| 00102-8 | 7. | 0.08 | 25 | 14 | 00205-¢ | 7. | 0.22 | 12 G | 11 |
| 00102-6 | 7. | 0.08 | 2 c | 14 | 00205-3 | 7. | 0.72 | 125 | 14 |
| 00102-0 | 7. | 0.08 | 25 | 14 | 00206-A | 7. | 0.11 | 116 | 14 |
| 00103-A | 7. | 0.12 | 3 G | 14 | 00235-8 | 7. | 0.11 | 116 | 14 |
| 00103-8 | 7. | 0.12 | 36 | 14 | 00236-¢ | 7. | 0.11 | 116 | 14 |
| 00103-6 | 7. | 0.12 | 3 G | 14 | 00235-3 | 7. | 0.11 | 116 | 14 |
| 00103-0 | 7. | 0.12 | 36 | 14 | 00207-A | 7. | $0 . ? 2$ | 12 G | 14 |
| 20104-A | 7. | 0.16 | 4 G | 14 | 00207-8 | 7. | 0.22 | 12 G | 14 |
| 00104-3 | 7. | 0.16 | 46 | 14 | 00207-C | 7. | 0.22 | 126 | 14 |
| 00104-: | 7. | 0.16 | 4 G | 14 | 00707-0 | 7. | 0.22 | 126 | 14 |
| 00104-0 | 7. | 0.16 | ${ }^{4} \mathrm{G}$ | 14 | 00301-A | 7. | 0.20 | 26 | 14 |
| 20105-A | 7. | 0.24 | 6 G | 14 | 00301-8 | 7. | 0.20 | 2 G | 1.4 |
| 00105-3 | 7. | 0.24 | 6 G | 14 | 00301-C | 7. | 0.20 | 2 G | 14 |
| 00105-5 | 7. | 0.24 | 6 G | 14 | 00301-0 | 7. | 0.20 | 26 | 14 |
| 00105-2 | 7. | 0.24 | 56 | 14 | 30302-A | 7. | 0.40 | 4 G | 14 |
| 20106-1 | 7. | 0.12 | 3 G | 14 | 30302-9 | 7. | 0.40 | 4 G | 14 |
| 00106-3 | 7. | 0.12 | 36 | 14 | 00302-6 | 7. | 0.40 | $4{ }^{4}$ | 14 |
| 00106-6 | 7. | 0.12 | 36 | 14 | 30302-0 | 7. | 0.40 | ${ }^{4} \mathrm{G}$ | 14 |
| 00106-0 | 7. | 0.12 | 36 | 14 | 00303-A | 7. | 0.40 | 4 G | 14 |
| 00107-A | 7. | 0.15 | 46 | 14 | 00303-3 | 7. | 0.40 | 4 G | 14 |
| 20107-3 | 7. | 0.15 | 46 | 14 | 20302-6 | 7. | 0.40 | 4 G | 14 |
| 00107-6 | 7. | 0.16 | 4 G | 14 | 00303-0 | 7. | 0.40 | $\triangle \mathrm{G}$ | 14 |
| 00107-0 | 7. | 0.16 | 4 G | 14 | 00401-A | 7. | 0.74 | 46 | 12 |
| 00103-A | 7. | 0.24 | 66 | 14 | 00401-3 | 7. | 0.24 | 46 | 14 |
| 00108-3 | 7. | 0.24 | 66 | 14 | 00401-6 | 7. | 0.24 | $4{ }^{4}$ | 14 |
| 00108-¢ | 7. | 0.24 | 6 G | 14 | 00401-0 | 7. | 0.24 | 4 G | 14 |
| 00108-0 | 7. | 0.24 | 66 | 14 | 00802-E | 7. | 0.12 | 2 L | 15 |
| 00109-C | 7. | 0.16 | 46 | 14 | 00402-F | 7. | 0.12 | 26 | 15 |
| 00201-A | 7. | 0.11 | 86 | 13 | 00403-A | 7. | 0.12 | 26 | 14 |
| 00201-3 | 7. | 0.11 | 8 G | 13 | 00493-3 | 7. | 0.12 | 2 C | 14 |
| 00201-C | 7. | 0.11 | 8 G | 13 | 00403-6 | 7. | 0.12 | $2 G$ | 14 |
| 00201-0 | 7. | 0.11 | 86 | 13 | 00403-0 | 7. | 0.12 | 2 G | 14 |
| 00202-A | 7. | 0.22 | 166 | 14 | 00404-A | 7. | 0.18 | 3 G | 14 |
| 00202-8 | 7. | 0.22 | 166 | 14 | 00404-3 | 7. | 0.18 | 36 | 14 |
| 00202-5 | 7. | 0.22 | 166 | 14 | 00404-C | 7. | 0.18 | 36 | 14 |
| 00202-0 | 7. | 0.22 | 166 | 14 | 00404-0 | 7. | 0.18 | 36 | 14 |

## MIL-HDBK-217(REV) <br> microelectronic devices

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ xxxxxxx | $\begin{aligned} & \text { ves } \\ & \text { (v.) } \end{aligned}$ | $\begin{aligned} & \mathrm{Pd} \\ & \left(W_{0}\right) \end{aligned}$ | Complexity | Np | M38510/ <br> xxxxxxx | $\begin{aligned} & \text { ves } \\ & \text { v. } \end{aligned}$ | $\begin{aligned} & P_{d} \\ & (W .) \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TL |  |  |  |  | $\pi$ |  |  |  |  |
| 20501-A | 7. | 0.10 | 6G | 14 | 00803-3 | 7. | 0.32 | 66 | 14 |
| 20501-3 | 7. | 0.10 | 66 | 14 | 00803-6 | 7. | 0.32 | 6 G | 14 |
| 20501-: | 7. | 0.10 | 6 G | 14 | 20803-0 | 7. | 0.32 | 6 G | 14 |
| 20501-0 | 7. | 0.10 | 66 | 14 | 00804-A | 7. | 0.32 | 6 G | 14 |
| 30502-A | 7. | 0.10 | 66 | 14 | 00804-3 | 7. | 0.32 | 66 | 14 |
| 00502-3 | 7. | 0.10 | 56 | 14 | 00804-6 | 7. | 0.32 | 56 | 14 |
| 30502-: | 7. | 0.10 | 56 | 14 | 00804-0 | 7. | 0.32 | 66 | 14 |
| 30502-3 | 7. | 0.10 | 66 | 14 | 20805-A | 7. | 0.22 | 4 G | 14 |
| 00503-A | 7. | 0.07 | 56 | 13 | 00805-3 | 7. | 0.22 | 4 G | 14 |
| 20503-3 | 7. | 0.07 | 56 | 13 | 00805-\% | 7. | 0.22 | 4 G | 14 |
| 00503-: | 7. | 0.07 | 56 | 13 | 00805-0 | 7. | 0.22 | ${ }^{4 G}$ | 14 |
| 00503-0 | 7. | 0.07 | 56 | 13 | 20901-A | 7. | 0.42 | 376 | 14 |
| 00504-A | 7. | 0.07 | 46 | 14 | 00901-3 | 7. | 0.42 | 37 G | 14 |
| 00504-3 | 7. | 0.07 | 4 G | 14 | 00901-6 | 7. | 0.42 | 37 G | 14 |
| 20504-: | 7. | 0.07 | 4 G | 14 | 00901-0 | 7. | 0.42 | 37 G | 14 |
| 20504-3 | 7. | 0.07 | 56 | 14 | 00902-E | 7. | 0.40 | 396 | 16 |
| 20601-A | 7. | 0.29 | 216 | 14 | 90902-F | 7. | 0.40 | 396 | 15 |
| 20601-3 | 7. | 0.28 | 216 | 14 | 30903-4 | 7. | 0.32 | 366 | 14 |
| 00601-6 | 7. | 0.28 | 216 | 14 | 20903-3 | 7. | 0.32 | 366 | 14 |
| 20501-0 | 7. | 0.29 | 216 | 14 | 90903-6 | 7. | 0.32 | 36 G | 14 |
| 00602-E | 7. | 0.55 | 366 | 16 | 00903-0 | 7. | 0.32 | 364 | 14 |
| 20602-F | 7. | 0.55 | 366 | 16 | 20904-E | 7. | 0.37 | 626 | 15 |
| 20603-E | 7. | 0.30 | 225 | 16 | 20904-F | 7. | 0.37 | 525 | 15 |
| 20603-F | 7. | 0.30 | 22 G | 16 | 20905-E | 7. | 0.36 | 476 | is |
| 20604-7 | 7. | 0.17 | 14 G | 14 | 20905-F | 7. | 0.36 | 476 | 16 |
| 20604-3 | 7. | 0.17 | 146 | 14 | 00906-е | 7. | 0.37 | 416 | 16 |
| 20604-: | 7. | 0.17 | 14 G | 14 | 20906-F | 7. | 0.37 | 416 | 16 |
| 20604-0 | 7. | 0.17 | 146 | 14. | 01001-E | 7. | 0.23 | 186 | $: 6$ |
| 00701-A | 9. | 0.25 | 4 G | 14 | 01001-F | 7. | 0.23 | 186 | 16 |
| 20701-3 | 7. | 0.25 | 4 G | 14 | 01002-E | 7. | 0.23 | 18 G | 16 |
| 00701-6 | 7. | 0.25 | ${ }^{4 G}$ | 14 | 01002-F | 7. | 0.23 | 186 | 16 |
| 00701-3 | 7. | 0.25 | 4 G | 14 | 01003-E | 7. | 0.23 | 18 G | 15 |
| 00801-A | 9. | 0.32 | 66 | 14 | 01003-F | 7. | 0.23 | 186 | 15 |
| 00801-3 | 7. | 0.32 | 6 G | 14 | 21004-E | 7. | 0.34 | 186 | 15 |
| 00801-6 | 7. | 0.32 | 6 G | 14 | 01004-F | 7. | 0.34 | 18 G | 16 |
| 00801-0. | 7. | 0.32 | 6G | 14 | 01005-E | 7. | 0.34 | 136 | 16 |
| 20802-2 | 7. | 0.32 | ${ }_{56}$ | 14 | 01005-F | 7. | 0.34 | 13 G | $: 6$ |
| 30802-3 | 7. | 0.32 | 56 | 14 | 21006-E | 7. | 0.47 | 44 G | 15 |
| 00802- 6 | 7. | 0.32 | 66 | 14 | 21006-F | 7. | 0.47 | ${ }^{44 G}$ | is |
| 00802-0 | 7. | 0.32 | 6 G | 14 | 01007-E | 7. | 0.47 | ${ }^{44 G}$ | 15 |
| 00803-A | 7. | 0.32 | 6G | 14 | 01007-E | 7. | 0.47 | 44 G | 15 |

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MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ <br> $x \times x \times x \times x$ | vec (v.) | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | Np | M38510/ <br> $x \times x \times x \times x$ | $\begin{aligned} & v<c \\ & (v .) \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TL |  |  |  |  | TL |  |  |  |  |
| 01008-E | 7. | 0.47 | 376 | 16 | 01305-F | 7. | 0.50 | 606 | 15 |
| 01008-F | 7. | 0.47 | 37 G | 16 | 01306-E | 7. | 0.50 | 575 | 15 |
| 01009-A | 7. | 0.47 | 346 | 14 | $01306-F$ | 7. | 0.50 | 576 | 16 |
| 01009-8 | 7. | 0.47 | 346 | 14 | $01307-\mathrm{A}$ | 7. | 0.27 | 15 G | 14 |
| 01009-C | 7. | 0.47 | 34 G | 14 | 01307-6 | 7. | 0.27 | 156 | 14 |
| 01009-0 | 7. | 0.47 | 34 G | 14 | 01307-0 | 7. | 0.27 | 15 G | 14 |
| 01101-3 | 7. | 0.80 | 63G | 24 | 01308-E | 7. | 0.49 | 50G | 15 |
| 01101-K | 7. | 0.80 | 63 G | 24 | 01308-F | 7. | 0.49 | 50 G | 16 |
| 01101-L | 7. | 0.80 | 63 G | 24 | 01309-E | 7. | 0.49 | 48 G | 15 |
| 01101-2 | 7. | 0.80 | 63G | 24 | 01309-F | 7. | 0.49 | 48 G | 16 |
| 01102-E | 7. | 0.80 | 19G | 16 | 01401-J | 7. | 0.38 | 25G | 24 |
| 01102-F | 7. | 0.80 | 19G | 16 | 0140아 | 7. | 0.38 | 26 G | 24 |
| 01201-A | 7. | 0.22 | 8G | 14 | 01401-6 | 7. | 0.38 | 26 G | 24 |
| 01201-8 | 7. | 0.22 | 8 G | 14 | 01401-2 | 7. | 0.38 | 26G | 24 |
| 01201-¢ | 7. | 0.22 | 86 | 14 | 01402-E | 7. | 0.27 | 17 G | 16 |
| 01201-0 | 7. | 0.22 | 8 G | 14 | 01402-F | 7. | 0.27 | 176 | 15 |
| 01202-A | 7. | 0.17 | 10G | 14 | 01403-E | 7. | 0.29 | 16 G | 16 |
| 01202-8 | 7. | 0.17 | 10G | 14 | 01403-F | 7. | 0.20 | 16G | 16 |
| 01202-6 | 7. | 0.17 | $10 G$ | 14 | 01404-E | 7. | 0.25 | 16 G | 16 |
| 01202-0 | 7. | 0.17 | 10G | 14 | 01404-F | 7. | 0.25 | 166 | 16 |
| 01203-E | 7. | 0.38 | 20G | 16 | 01405-E | 7 | 0.28 | 196 | 15 |
| 01203-F | 7. | 0.38 | 20 G | 16 | 01405-F | 7. | 0.28 | 19 G | 16 |
| 01204-A | 7. | 0.14 | 8G | 14 | 01406-E | 7. | 0.27 | 17 G | 16 |
| 01204-8 | 7. | 0.14 | 8 G | 14 | 01406-F | 7. | 2.27 | 176 | 16 |
| 01204-C | 7. | 0.14 | 8G | 14 | O1501-E | 7. | 0.28 | 24 G | 15 |
| 01204-D | 7. | 0.14 | 8G | 14 | O1501-F | 7. | 0.28 | 24 G | 15 |
| 01205-E | 7. | 0.29 | 14G | 16 | 01502-A | 7. | 0.28 | 24 G | 14 |
| 01205-F | 7. | 0.29 | 14 G | 16 | 01502-8 | 7. | 0.28 | 24 G | 14 |
| 01301-A | 7. | 0.27 | 26 G | 14 | 01502-C | 7. | 0.28 | 246 | 14 |
| 01301-8 | 7. | 0.27 | 26 G | 14 | 01502-0 | 7. | 0.28 | 24G | 14 |
| 01301-C | 7. | 0.27 | 26 G | 14 | 01503-J | 7. | 0.63 | 56 G | 24 |
| 01301-0 | 7. | 0.27 | 26 G | 14 | 01503-K | 7. | 0.63 | 56 G | 24 |
| 01302-A | 7. | 0.27 | 256 | 14 | 01503-6 | 7. | 0.63 | 56 G | 24 |
| 01302-8 | 7. | 0.27 | 25 G | 14 | 01503-2 | 7. | 0.63 | 56 G | 24 |
| 01302-C | 7. | 0.27 | 25 G | 14 | 01504-E | 7. | 0.33 | $25 G$ | 15 |
| 01302-0 | 7. | 0.27 | 256 | 14 | 01504-F | 7. | 0.33 | 25 G | 15 |
| 01303-E | 7. | 0.50 | 606 | 16 | $01601-\mathrm{A}$ | 7. | 0.20 | ${ }_{4}^{4 G}$ | 14 |
| 01303-5 | 7. | 0.50 | 60G | 16 | 01601-8 | 7 | 0.20 | 4 G | 14 |
| 01304-E | 7. | 0.50 | 58 G | 16 | 01601-6 | 7. | 0.20 | 4 G | 14 |
| 01304-F | 7. | 0.50 | 58 G | 16 | 01601-0 | 7. | 0.20 | ${ }^{4 G}$ | 14 |
| O1305-E | 7. | 0.50 | 60G | 16 | $01602-A$ | 7 | 0.20 | $\Delta G$ | 11 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ <br> xxxxxxx | $\begin{aligned} & \text { Vec } \\ & \text { (V.) } \end{aligned}$ | $\begin{aligned} & \mathrm{Pd} \\ & \left(W_{0}\right) \end{aligned}$ | Complexity | Np | M38510/ <br> xxxxxxx | $\begin{aligned} & \text { Vce } \\ & \text { (V.) } \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & (\mathrm{W} .) \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\pi \mathrm{L}$ |  |  |  |  | LTTL |  |  |  |  |
| 01602-8 | 7. | 0.20 | 46 | 14 | 02101-8 | 8. | 0.01 | 86 | 14 |
| 01602-C | 7. | 0.20 | 4 G | 14 | 02101-6 | 8. | 0.01 | 8 G | 14 |
| 01602-0 | 7. | 0.20 | 4 G | 14 | 02101-0 | 8. | 0.01 | 8 G | 14 |
| 01701-E | 7. | 0.44 | 36 G | 16 | 02102-A | 3. | 0.01 | 86 | 14 |
| 01701-F | 7. | 0.44 | 366 | 16 | 02102-8 | 8. | 0.01 | 8 G | 14 |
| 01702-E | 7. | 0.26 | 24 G | 16 | 02102-C | 8. | 0.01 | 8 G | 14 |
| 01702-F | 7. | 0.26 | 24 G | 16 | 02102-0 | 3. | 0.01 | 8 G | 14 |
| 01801-E | 7. | 0.77 | 100 G | 15 | 02103-A | 8. | 0.02 | 14 G | 14 |
| $01801-F$ | 7. | 0.77 | 100G | 16 | 02103-8 | 8. | 0.02 | 14 G | 14 |
| -01901-A | 7. | 0.27 | 146 | 14 | 02103-C | 8. | 0.02 | 14 G | 14 |
| 01901-8 | 7. | 0.27 | 14 G | 14 | 02103-0 | 8. | 0.02 | 146 | 14 |
| 01901-C | 7. | 0.27 | 14 G | 14 | 02104-A | 8. | 0.02 | 16 G | 14 |
| 01901-0 | 7. | 0.27 | 14 G | 14 | 02104-8 | 8. | 0.02 | 16 G | 14 |
| $L T L$ |  |  |  |  | 02104-0 | 8. | 0.02 0.02 | 16 G 16 G | 14 14 |
|  |  |  |  |  | 02105-A | 3. | 0.02 | 12G | 14 |
| 02001-A | 3. | 0.00 | 16 | 14 | 02105-8 | 8. | 0.02 | 12 G | 14 |
| 02001-8 | 8. | 0.00 | 16 | 14 | 02105-6 | 8. | 0.02 | 126 | 14 |
| 02001-C | 8. | 0.00 | 16 | 14 | 02105-0 | 8. | 0.02 | 126 | 14 |
| 22001-0 | 8. | 0.00 | 16 | 14 |  |  |  |  |  |
| 02002 - A | 8. | 0.01 | 2 L | 14 | HTTL |  |  |  |  |
| 02002-8 | 8. | 0.01 | 2 G | 14 |  |  |  |  |  |
| 02002-C | 8. | 0.01 | 2 G | 14 | 02201-A | 7. | 0.14 | 86 | 14 |
| 02002-D | 8. | 0.01 | 2 G | 14 | 02201-8 | 7. | 0.14 | 8G | 14 |
| 02003-A | 8. | 0.01 | 3 G | 14 | 02201-6 | 7. | 0.14 | 8 G | 14 |
| 02003-8 | 8. | 0.01 | ${ }^{36}$ | 14 | 02201-0 | 7. | 0.14 | 9G | 14 |
| 02003-C | 8. | 0.01 | 36 | 14 | 02202-A | 7. | 0.27 | 16 G | 14 |
| 02003-0 | 8. | 0.01 | 3 G | 14 | 02202-8 | 7. | 0.27 | 16G | 14 |
| 02004-A | 3. | 0.02 | 4 G | 14 | 02202-6 | 7. | 0.27 | 16 G | 14 |
| 02004-8 | 8. | 0.02 | 4 G | 14 | 02202-0 | 7. | 0.27 | 16 G | 14 |
| 02004-C | 8. | 0.02 | 4 G | 14 | 02203-A | 7. | 0.27 | 126 | 14 |
| 02004-0 | 3. | 0.02 | 4 G | 14 | 02203-8 | 7. | 0.27 | 126 | 14 |
| 02005-A | 8. | 0.02 | 6G | 14 | 02203-¢ | 7. | 0.27 | 12 G | 14 |
| 02005-8 | 8. | 0.02 | 6G | 14 | 02203-0 | 7. | 0.27 | 12 G | 14 |
| 02005-C | 8. | 0.02 | 6G | 14 | 02204-E | 7. | 0.27 | 166 | 16 |
| 02005-0 | 8. | 0.02 | 6G | 14 | 02204-F | 7. | 0.27 | 16 G | 15 |
| 02006-A | 8. | 0.02 | 4 G | 14 | 02205-A | 7. | 0.21 | 10 G | 14 |
| 02006-8 | 8. | 0.02 | 4 G | 14 | 02205-8 | 7. | 0.21 | 106 | 14 |
| 02006-6 | 8. | 0.02 | 4 G | 14 | 02205-6 | 7. | 0.21 | 106 | 14 |
| 02006-0 | 8. | 0.02 | ${ }^{4 G}$ | 14 | 02205-0 | 7. | 0.21 | 10 G | 14 |
| 02101-A | 3. | 0.01 | 8G | 14 | 02206-A | 7. | 0.42 | 12 G | 14 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ <br> $x \times x \times x \times x$ | vee (V.) | $\begin{aligned} & \text { pg } \\ & \text { (w.) } \end{aligned}$ | Complexity | Np | $\begin{aligned} & M 38510 / \\ & x \times x \times x \times x \end{aligned}$ | vec (V.) | Pd (W.) | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| HTL |  |  |  |  | LTTL |  |  |  |  |
| 02206-3 | 7. | 0.42 | 12 G | 14 | 02501-0 | 8. | 0.07 | 15 G | 14 |
| 02206-¢ | 7. | 0.42 | 12 G | 14 | 02502-A | 8. | 0.06 | 256 | 14 |
| 02206-0 | 7. | 0.42 | 12 G | 14 | 02502-8 | 3. | 0.06 | 256 | 11 |
| 22301-4 | 7. | 0.20 | 16 | 14 | 02503-C | 9. | 0.06 | 25 G | 14 |
| 02301-3 | 7. | 0.20 | 16 | 14 | 02503-乏 | 9. | 0.13 | 48 G | 16 |
| 02301-C | 7. | 0.20 | 16 | 14 | 02503-F | 9. | 0.13 | 48 G | 16 |
| 02301-0 | 7. | 0.20 | 16 | 14 | 02504-0 | 8. | 0.06 | 25 G | 15 |
| 02302-A | 7. | 0.40 | 2 G | 14 | 02504-E | 8. | 0.17 | 38 G | 15 |
| 02302-8 | 7. | 0.40 | 2 G | 14 | 02504-F | 3. | 0.17 | 38 G | 15 |
| 02302-C | 7. | 0.40 | 2G | 14 | 02505-E | 9. | 0.17 | 38 G | 15 |
| 02302-0 | 7. | 0.40 | 2G | 14 | 02505.7 | 8. | 0.17 | 38 G | 16 |
| 02303-A | 7. | 0.59 | 3 G | 14 | 02601-A | 7. | 0.04 | 4 G | 14 |
| 02303-8 | 7. | 0.59 | 3 G | 14 | 02601-3 | 7. | 0.04 | 4 G | 14 |
| 02303-C | 7. | 0.59 | 3 G | 14 | 02601-C | 7. | 0.04 | 4 G | 14 |
| 02303-0 | 7. | 0.59 | 3 G | 14 | 02601-0 | 7. | 0.04 | 4 G | 14 |
| 02304-A | 7. | 0.80 | 4 G | 14 | 02701-A | 7. | 0.02 | 4 G | 14 |
| 02304-8 | 7. | 0.80 | 4 G | 14 | 02701-9 | 7. | 0.02 | 4 G | 14 |
| 02304-C | 7. | 0.80 | 4 G | 14 | 02701-C | 7. | 2.02 | Q $G$ | 14 |
| 02304-0 | 7. | 0.80 | 4 G | 14 | 02701-0 | 7. | 0.02 | ${ }^{4 G}$ | 14 |
| 02305-A | 7. | 1.20 | 6 G | 14 | 02801-A | 8. | 0.02 | 37 G | 14 |
| 02305-3 | 7. | 1.20 | 6 G | 14 | 02801-3 | 8. | 0.02 | 376 | 14 |
| 32305-6 | 7. | 1.20 | 6 G | 14 | 02801-C | 3. | 0.02 | 376 | 1 |
| 02305-0 | 7. | 1.20 | 6 G | 14 | 02801-0 | 9. | 0.02 | 37 G | 11 |
| 32306-A | 7. | 0.79 | 4 G | 14 | 02902-A | 7. | 0.12 | 36 G | id |
| 02306-8 | 7. | 0.79 | 46 | 14 | 02802-3 | 7. | 0.12 | 366 | 14 |
| 02306-C | 7. | 0.79 | 4 G | 14 | 02802-C | 7. | 0.12 | 35 G | id |
| 02306-0 | 7. | 0.79 | 4 G | 14 | 02802-0 | 7. | 0.12 | 356 | 14 |
| 32307-A | 7. | 0.40 | 26 | 14. | 02303-乏 | 7. | 0.27 | 726 | 15 |
| 02307-8 | 7. | 0.40 | 2 G | 14 | 02303.F | 7. | 0.27 | 72 G | 15 |
| 02307-6 | 7. | 0.40 | 2 G | 14 | 02804-E | 7. | 0.12 | 40 G | 15 |
| 02307-0 | 7. | 0.40 | 2 G | 14 | 02804-F | 7. | 0.17 | 40 G | 15 |
| 32401-A | 7. | 0.27 | 2 G | 14 | 02805-A | 7. | 0.05 | 36 G | 14 |
| 02401-5 | 7. | 0.27 | 2 G | 14 | 02805-3 | 7. | 0.05 | 36 G | 11 |
| 22401-C | 7. | 0.27 | 2 G | 14 | 02805-C | 7. | 0.05 | 36 G | 14 |
| 02401-0 | 7. | 0.27 | 2G | 14 | 02805-0 | 7. | 0.05 | 36 G | 11 |
| LTTL |  |  |  |  | 02901- $\mathcal{F}$ | $7{ }^{\circ}$ | 0.12 0.12 | 18 G 186 | ! 15 |
|  |  |  |  |  | 02902-E | 7. | $0.1 ?$ | 18G | :9 |
| 02501-A | 8. | 0.07 | 156 | 14 | 02902-F | 7. | 0.12 | 18 G | : 6 |
| 02501-3 | 3. | 0.07 | 156 | 14 | 02903-E | 7. | 0.12 | 18 G | 15 |
| 02501-C | 8. | 0.07 | 156 | 14 | 02903-F | 7. | 0.12 | 18 G | 5 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ xxxxxxx | $\begin{aligned} & \text { Ves } \\ & \text { (V.) } \end{aligned}$ | Pd (W.) | Complexity | No | M38510/ <br> $x \times x \times x \times x$ | $\begin{aligned} & \text { vee } \\ & \text { (V.) } \end{aligned}$ | Pd $\left(W_{.}\right)$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LTM |  |  |  |  | DTL |  |  |  |  |
| 02904-E | 7. | 0.24 | 44 G | 16 | 03103-C | 8. | 0.13 | 46 | 14 |
| 02904-F | 7. | 0.24 | 44 G | 16 | 03103-0 | 8. | 0.13 | 4 G | 14 |
| 02905-E | 7. | 0.24 | 44 G | 16 | 03104-A | 8. | 0.17 | 4 G | 14 |
| 02905-F | 7. | 0.24 | 44 G | 16 | 03104-B | 8. | 0.17 | 4 G | 14 |
| 02906-E | 7. | 0.03 | 18 G | 16 | 03104-C | 8. | 0.17 | 4 G | 14 |
| 02906-F | 7. | 0.03 | 18 G | 16 | 03104-0 | 3. | 0.17 | 4 G | 14 |
| 02907-E | 7. | 0.07 | 18G | 16 | 03105-A | 8. | 0.02 | 26 | 14 |
| 02907-F | 7. | 0.07 | 18G | 16 | 03105-8 | 9. | 0.02 | 2 G | 14 |
| OTL |  |  |  |  | 03105-C | 9. | 0.02 | 2 G | 14 |
|  |  |  |  |  | 03105-D | 3. | 0.02 | 2 G | 14 |
| 03001-A | 8. | 0.05 | 2 G | 14 | 03201-A $03201-8$ | 8. | 0.18 0.18 | 6 G 6 G | 14 |
| 03001-8 | 8. | 0.05 | 2 G | 14 | 03201-C | 8. | 0.18 | ${ }_{6 G}$ | 14 |
| 03001-C | 8. | 0.05 | 2 G | 14 | 03201-0 | 9. | 0.18 | 6 G | 14 |
| 03001-0 | 8. | 0.05 | 2 G | 14 | 03301-A | 8. | 0.07 | 8 G | 14 |
| 03002-A | 8. | 0.14 | 6 G | 14 | 03301-8 | 8. | 0.07 | 8G | 14 |
| 03002-8 | 8. | 0.14 | 6 G | 14 | 03301-C | 8. | 0.07 | 8 G | 14 |
| 03002-C | 9. | 0.14 | 6 G | 14 | 03301-0 | 8. | 0.07 | 8 G | 14 |
| 03002-0 | 8. | 0.14 | 6G | 14 | 03302-A | 8. | 0.07 | 8 G | 14 |
| 03003-A | 9. | 0.14 | 6 G | 14 | 03302-8 | 8. | 0.07 | 8 G | 14 |
| 03003-8 | 8. | 0.14 | 6 G | 14 | 03302-C | 8. | 0.07 | 86 | 14 |
| 03003-C | 8. | 0.14 | 6 G | 14 | 03302-0 | 9. | 0.07 | 86 | 14 |
| 03003-0 | 8. | 0.14 | 6 G | 14 | 03303-A | 3. | 0.07 | 86 | 14 |
| 03004-A | 8. | 0.09 | 4G | 14 | 03303-8 | 8. | 0.07 | 86 | 11 |
| 03004-8 | 8. | 0.09 | 4G | 14 | 03303-C | 8. | 0.07 | 8 G | 14 |
| 03004-C | 8. | 0.09 | 46 | 14 | 03303-0 | 9. | 0.07 | 86 | 14 |
| 03004-0 | 8. | 0.09 | 4 G | 14 | 03304-A | 8. | 0.14 | 16 G | 14 |
| 03005-A | 8. | 0.07 | 36 | 14 | 03304-8 | 8. | 0.14 | 16 G | 14 |
| 03005-B | 8. | 0.07 | 3 G | 14 | 03304-C | 8. | 0.14 | 16 G | 14 |
| 03005-C | 8. | 0.07 | 3 G | 14 | 03304-0 | 8. | 0.14 | $16 G$ | 14 |
| 03005-0 | 8. | 0.07 | 36 | 14 | 03501-C | 22. | 0.80 | 18 T | 14 |
| 03101-A | 8. | 0.13 | 2 C | 14 | 03501-G | 22. | 0.80 | 185 | 8 |
| 03101-8 | 8. | 0.13 | 2 G | 14 | 03501-M | 22. | 0.80 | 185 | 12 |
| 03101-C | 8. | 0.13 | 2 G | 14 |  |  |  |  |  |
| 03101-0 | 8. | 0.13 | 2 G | 14 | HTLL |  |  |  |  |
| 03102-A | 8. | 0.10 | 2 G | 14 |  |  |  |  |  |
| 03102-8 | 8. | 0.10 | 2 G | 14 | 04001-A | 7. | 0.14 | 6 G | 14 |
| 03102-C | 8. | 0.10 | 2 C | 14 | 04001-B | 7. | 0.14 | $6 G$ | 14 |
| 03102-0 | 8. | 0.10 | 2G | 14 | 04001-C | 7. | 0.14 | 6 G | 14 |
| 03103-A | 8. | 0.13 | 4 G | 14 | 04001-0 | 7. | 0.14 | 6 G | 14 |
| 03103-8 | 8. | 0.13 | 4 G | 14 | 04002-A | 7. | 0.14 | 66 | $1:$ |

## MIL-HDBK-217(REV) <br> miCROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| $\begin{aligned} & M 38510 / \\ & x \times x \times x \times x \end{aligned}$ | vec (v.) | $\begin{aligned} & P d \\ & (W .) \end{aligned}$ | Complexity | Np | $\begin{aligned} & M 38510 / \\ & X x \times X X X X \end{aligned}$ | Vec (V.) | $\begin{aligned} & \text { Pd } \\ & \left(W_{.}\right) \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| HTTL |  |  |  |  | LTTL |  |  |  |  |
| 04002-3 | 7. | 0.14 | 66 | 14 | 04502-J | 7. | 0.34 | 506 | 24 |
| 04002-6 | 7. | 0.14 | 66 | 14 | 04502-K | 7. | 0.34 | 506 | 21 |
| 04002-0 | 7. | 0.14 | 6 G | 14 | 04501-E | 7. | 0.15 | 16 G | 15 |
| 04003-A | 7. | 0.14 | 56 | 14 | 04601-F | 7. | 0.15 | 16 G | 15 |
| 04003-3 | 7. | 0.14 | 56 | 14 | 04602-E | 7. | 0.14 | 17 G | 15 |
| 04003-6 | 7. | 0.14 | 56 | 14 | 04602-F | 7. | 0.14 | 17 G | 16 |
| 04003-D | 7. | 0.14 | 56 | 14 | 04603-E | 7. | 0.13 | 19 G | 15 |
| 04004-A | 7. | 0.14 | 5 G | 14 | 04603-F | 7. | 0.13 | 196 | 16 |
| 04004-3 | 7. | 0.14 | 56 | 14 |  |  |  |  |  |
| 04004-6 | 7. | 0.14 | $5 G$ | 14 | CMOS |  |  |  |  |
| 04004-0 | 7. | 0.14 | 5G | 14 |  |  |  |  |  |
| 04005-A | 7. | 0.08 | 3 G | 14 | 05001-5 | 13. | 0.20 | 4G | 14 |
| 04005-8 | 7. | 0.08 | 3 G | 14 | 05001-0 | 13. | 0.20 | 4G | 14 |
| 04005-6 | 7. | 0.08 | 3G | 14 | 05002-A | 13. | 0.20 | 2G | 14 |
| 04005-0 | 7. | 0.08 | 3G | 14 | 05002-C | 13. | 0.20 | 2 G | 14 |
|  |  |  |  |  | 05002-0 | 13. | 0.20 | 2G | 14 |
| LTTL |  |  |  |  | $\begin{aligned} & 05003-A \\ & 05003-C \end{aligned}$ | 13. | 0.20 | 3G | 14 |
|  |  |  |  |  |  | 13. | 0.20 | 36 | 14 |
| 04101-A | 7. | 0.01 | 6G | 14 | 05003-0 | 13. | 0.20 | 3G | 14 |
| 04101-8 | 7. | 0.01 | 6G | 14 | 05051 -A | 15. | 0.20 | 4 G | 14 |
| 04101-C | 7. | 0.01 | 6G | 14 | 05051-C | 15. | 0.20 | 4G | 14 |
| 04101-0 | 7. | 0.01 | 6 G | 14 | 05051-0 | 15. | 0.20 | 4G | 14 |
| 04102-C | 7. | 0.01 | 5G | 14 | 05052-A | 15. | 0.20 | 2G | 14 |
| 04103-A | 7. | 0.01 | 3 G | 14 | 05052-C | 15. | 0.20 | 2 G | 14 |
| 04103-8 | 7. | 0.01 | 36 | 14 | 05052-0 | 15. | 0.20 | 2 C | 14 |
| 04103-C | 7. | 0.01 | 36 | 14 | $05053-\mathrm{A}$ | 15. | 0.20 | 3G | 14 |
| 04103-D | 7. | 0.01 | 3 G | 14 | 05053-C | 15. | 0.20 | 3G | 14 |
| 04201-A | 8. | 0.11 | 8G | 14 | 05053-D | 15. | 0.20 | 3G | 14 |
| 04201-3 | 8. | 0.11 | 8 G | 14 | $05101-A$ | 13. | 0.20 | 24G | 14 |
| 04201-C | 8. | 0.11 | 8G | 14 | 05101-6 | 13. | 0.20 | 28 G | 14 |
| 04201-0 | 8. | 0.11 | 8G | 14 | 05101-0 | 13. | 0.20 | 246 | 14 |
| 04202-A | 8. | 0.08 | 10G | 14 | 05102-A | 13. | 0.20 | 30 G | 16 |
| 04202-B | 8. | 0.08 | 106 | 14 | 05102-C | 13. | 0.20 | 306 | 16 |
| 04202-C | 8. | 0.08 | 10G | 14 | 05102-0 | 13. | 0.20 | 30 G | 16 |
| 04202-0 | 8. | 0.08 | 10G | 14 | 05103 - ${ }^{\text {a }}$ | 13. | 0.20 | 24 G | 15 |
| 04301-E | 7. | 0.12 | 246 | 16 | 05103-B | 13. | 0.20 | 24 G | 15 |
| 04301-F | 7. | 0.12 | 246 | 16 | 05103-0 | 13. | 0.20 | 24 G | 15 |
| 04401-E | 7. | 0.12 | 286 | 15 | 05151 -A | 15. | 0.20 | 24G | 14 |
| 04401-F | 7. | 0.12 | 28 G | 16 | 05151-6 | 15. | 0.20 | 24 G | 14 |
| 04501-E | 7. | 0.18 | 306 | 16 | 05151.0 | 15. | 0.20 | 246 | 14 |
| 04501-F | 7. | 0.18 | 30G | 16 | 05152-A | 15. | 0.20 | $30 G$ | 14 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ xxxxxxx | $\begin{aligned} & \text { Vce } \\ & \text { (V..) } \end{aligned}$ | $\begin{aligned} & \mathrm{Pd} \\ & \text { (W.) } \end{aligned}$ | Complexity | No | M38510/ <br> xxxxxxx | $\begin{aligned} & \text { Vec } \\ & \text { (V.) } \end{aligned}$ | $\begin{aligned} & \mathrm{Pd} \\ & \text { (W.) } \end{aligned}$ | Complexity | Np |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CMOS |  |  |  |  | cmos |  |  |  |  |
| 05152-C | 15. | 0.20 | 30G | 14 | 05353-A | 15. | 0.20 | 4 G | 14 |
| 05152-0 | 15. | 0.20 | 30G | 14 | 05353-C | 15. | 0.20 | 4 G | 14 |
| 05153-A | 15. | 0.20 | 24 G | 14 | 05353-0 | 15. | 0.20 | ${ }^{4 G}$ | 14 |
| 05153-C | 15. | 0.20 | 24G | 14 | 05354-E | 15. | 0.20 | 3G | 16 |
| 05153-0 | 15. | 0.20 | 24G | 14 | 05354-F | 15. | 0.20 | 3G | 16 |
| 05201-A | 13 | 0.20 | 3G | 12 | 05401-E | 13. | 0.20 | 58G | 16 |
| 05201-C | 13. | 0.20 | 3 G | 12 | 05401-F | 13. | 0.20 | 58 G | 16 |
| 05201-0 | 13. | 0.20 | 3G | 12 | 05451-E | 15. | 0.20 | 58 G | 16 |
| 05202-A | 13. | 0.20 | 4 G | 14 | 05451-F | 15. | 0.20 | 58G | 16 |
| 05202-C | 13. | 0.20 | 4 G | 14 | 05501-E | 13. | 0.20 | 6 G | 15 |
| 05202-0 | 13. | 0.20 | 4G | 14 | 05501-F | 13. | 0.20 | 6 G | 16 |
| 05203-A | 13. | 0.20 | 2 G | 12 | 05502-E | 13. | 0.20 | 6 G | 16 |
| 05203-C | 13. | 0.20 | 2G | 12 | 05502-F | 13. | 0.20 | 6 G | 16 |
| 05203-0 | 13. | 0.20 | 2G | 12 | 05503-E | 13. | 0.20 | 6 G | 16 |
| 05204-A | 13. | 0.20 | 3G | 14 | 05503-F | 13. | 0.20 | 6 G | 16 |
| 05204-C | 13. | 0.20 | 36 | 14 | 05504-E | 13. | 0.20 | 6G | 16 |
| 05204-0 | 13. | 0.20 | 3 G | 14 | 05504-F | 13. | 0.20 | 6 G | 16 |
| 05251-A | 15. | 0.20 | 3 G | 14 | 05505-A | 13. | 0.20 | 12 G | 14 |
| 05251-C | 15. | 0.20 | 36 | 14 | 05505-C | 13. | 0.20 | 12G | 14 |
| 05252-0 | 15. | 0.20 | 4 G | 14 | 05505-0 | 13. | 0.20 | 12G | 14 |
| 05253-A | 15. | 0.20 | 2 G | 14 | 05551-E | 15. | 0.20 | 6 G | 16 |
| 05253-C | 15. | 0.20 | 2G | 14 | 05551-F | 15. | 0.20 | 6G | 15 |
| 05253-0 | 15. | 0.20 | 2 G | 14 | 05552-E | 15. | 0.20 | 6 G | 16 |
| 05254-A | 15. | 0.20 | 3 G | 14 | 05552-F | 15. | 0.20 | 6 G | 16 |
| 05254-C | 15. | 0.20 | 3 G | 14 | 05553-E | 15. | 0.20 | 6 G | 15 |
| 05254-0 | 15. | 0.20 | 3 G | 14 | 05553-F | 15. | 0.20 | 6 G | 16 |
| 05301-A | 13. | 0.20 | 3G | 14 | 05554-E | 15. | 0.20 | 6 G | 16 |
| 05301-C | 13. | 0.20 | 3G | 14 | 05554-F | 15. | 0.20 | 66 | 15 |
| 05301-0 | 13. | 0.20 | 3 G | 14 | 05555-A | 15. | 0.20 | 12G | 14 |
| 05302-E | 13. | 0.20 | 12 G | 16 | 05555-C | 15. | 0.20 | 13 G | 14 |
| 05302-F | 13. | 0.20 | 126 | 15 | 05555-0 | 15. | 0.20 | 12 G | 14 |
| 05303-A | 13. | 0.20 | 46 | 14 | 05601-E | 13. | 0.20 | 476 | 16 |
| 05303-C | 13. | 0.20 | 4G | 14 | 05601-F | 13. | 0.20 | 476 | 16 |
| 05303-0 | 13. | 0.20 | 46 | 14 | 05602-E | 13. | 0.20 | 576 | 16 |
| 05304-E | 13. | 0.20 | 24 G | 16 | 05602-F | 13. | 0.20 | 57 G | 16 |
| 05304-F | 13. | 0.20 | 24G | 16 | 05603-E | 13. | 0.20 | 132 G | 16 |
| 05351-A | 15. | 0.20 | 3G | 14 | 05603-F | 13. | 0.20 | 132 G | 16 |
| 05351-¢ | 15. | 0.20 | 3 G | 14 | 05604-E | 13. | 0.20 | 39 G | 15 |
| 05351-D | 15. | 0.20 | 3 G | 14 | 05604-F | 13. | 0.20 | 39 G | 16 |
| 05352-E | 15. | 0.20 | 12 G | 14 | 05605-A | 13. | 0.20 | 816 | 14 |
| 05352-F | 15. | 0.20 | 12 G | 14 | 05605-C | 13. | 0.20 | 816 | 11 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)


MIL-HDBK-217(REV)
MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| $\underset{x X x \times x X X}{M 38510 /}$ | $\begin{aligned} & \text { Vce } \\ & \text { (v.) } \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & (W .) \end{aligned}$ | Complexity | No | M38510/ <br> xxxxxxx | $\begin{aligned} & \text { Vce } \\ & (V .) \end{aligned}$ | $\begin{aligned} & P d \\ & (W .) \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ECL |  |  |  |  | STTL |  |  |  |  |
| 06301-F | 7. | 0.15 | 4 G | 16 | 07010-F | 7. | 0.14 | 16 | 16 |
| 06302-E | 7. | 0.13 | 4 G | 16 | 07101-A | 7. | 0.27 | 12 G | 14 |
| 06302-F | 7. | 0.13 | 4 G | 16 | 07101-8 | 7. | 0.27 | 12 G | 14 |
|  |  |  |  |  | 07101-C | 7. | 0.27 | 12 G | 14 |
| STTL |  |  |  |  | 07101-0 | 7. | 0.27 | 12 G | 14 |
|  |  |  |  |  | 07102-E | 7. | 0.27 | 16G | 15 |
| 07001-A | 7. | 0.20 | 4G | 14 | 07102-F | 7. | 0.27 | 16 G | 16 |
| 07001-8 | 7. | 0.20 | 4G | 14 | 07103-A | 7. | 0.27 | 16G | 14 |
| 07001-C | 7. | 0.20 | 4 G | 14 | 07103-8 | 7. | 0.27 | 16 G | 14 |
| 07001-0 | 7. | 0.20 | 4G | 14 | 07103-C | 7. | 0.27 | 16 G | 14 |
| 07002-A | 7. | 0.20 | 4 G | 14 | 07103-0 | 7. | 0.27 | 16 G | 14 |
| 07002-8 | 7. | 0.20 | 4 G | 14 | 07104-A | 7. | 0.27 | 156 | 14 |
| 07002-C | 7. | 0.20 | 4 G | 14 | 07104-8 | 7. | 0.27 | 16 G | 14 |
| 07002-0 | 7. | 0.20 | 4 G | 14 | 07104-C | 7. | 0.27 | 16G | 14 |
| 07003-A | 7. | 0.30 | 6 G | 14 | 37104-0 | 7. | 0.27 | $15 G$ | 14 |
| 07003-8 | 7. | 0.30 | 6 G | 14 | 07105-E | 7. | 0.79 | 36 G | 16 |
| 07003-C | 7. | 0.30 | 6G | 14 | 07105.F | 7. | 0.79 | 36 G | 16 |
| 07003-0 | 7. | 0.30 | 6G | 14 | 07106-E | 7. | 0.52 | 24 G | 16 |
| 07004-A | 7. | 0.30 | 66 | 14 | 07106-F | 7. | 0.52 | 24 G | 15 |
| 07004-8 | 7. | 0.30 | 6G | 14 | 07201-A | 7. | 0.24 | 2 G | 14 |
| 07004-C | 7. | 0.30 | 6 G | 14 | 07201-8 | 7. | 0.24 | 2 G | 14 |
| 07004-0 | 7. | 0.30 | 6 G | 14 | 07201-C | 7. | 0.24 | 2 G | 14 |
| 07005-A | 7. | 0.15 | 3 G | 14 | 07201-0 | 7. | 0.24 | 2 G | 14 |
| 07005-8 | 7. | 0.15 | 3 G | 14 | 07301-A | 7. | 0.25 | 4 G | 14 |
| 07005-C | 7. | 0.15 | 3 G | 14 | 07301-3 | 7. | 0.25 | 4 G | 14 |
| 07005-0 | 7. | 0.15 | 3 G | 14 | 07301-C | 7. | 0.25 | 4 G | 14 |
| 07006-A | 7. | 0.10 | 2 G | 14 | 07301-0 | 7. | 0.25 | 4 G | 14 |
| 07006-C | 7. | 0.10 | 2 G | 14 | 07401-A | 7. | 0.12 | 56 | 14 |
| 07006-D | 7. | 0.10 | 2 G | 14 | 07401-8 | 7. | 0.12 | $6 G$ | 14 |
| 07006-D | 7. | 0.10 | 2 G | 14 | 07401-C | 7. | 0.12 | 56 | 14 |
| 07007-A | 7. | 0.10 | 2 G | 14 | 07401-0 | 7. | 0.12 | 6G | 11 |
| 07007-8 | 7. | 0.10 | 2 G | 14 | 07402-A | 7. | 0.09 | $5 G$ | 14 |
| 07007-C | 7. | 0.10 | 2 G | 14 | 07402-8 | 7. | 0.09 | 5 G | 14 |
| 07007-0 | 7. | 0.10 | 2 G | 14 | 07402-C | 7. | 0.09 | 5 G | 14 |
| 07008-A | 7. | 0.06 | 16 | 14 | 07402-0 | 7. | 0.09 | 5 G | 14 |
| 07008-3 | 7. | 0.06 | 1 G | 14 | 07403-A | 7. | 0.09 | 5 G | 14 |
| 07008-C | 7. | 0.06 | 16 | 14 | 07403-8 | 7. | 0.09 | 56 | 14 |
| 07008-D | 7. | 0.06 | 16 | 14 | 07403-C | 7. | 0.09 | 5 G | 14 |
| 07009-\% | 7. | 0.06 | 16 | 16 | 07403-0 | 7. | 0.09 | 5 G | 11 |
| 07009-F | 7. | 0.06 | 1 G | 16 | 07501-A | 7. | 0.55 | 4 G | 12 |
| 07010-E | 7. | 0.14 | 16 | 16 | 07501-3 | 7. | 0.55 | 4 G | id |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| $\begin{gathered} M 38510 / \\ x x \times x \times x \end{gathered}$ | $\begin{aligned} & V c e \\ & (V .) \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | Np | M38510/ xxxxxxx | ves (v.) | $\begin{aligned} & \mathrm{Pd} \\ & \left(\mathrm{~W}_{\mathrm{l}}\right) \end{aligned}$ | Compl exity | Np |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| STTL |  |  |  |  | STTL |  |  |  |  |
| 07501-C | 7. | 0.55 | 4 G | 14 | 08002-0 | 7. | 0.23 | 36 | 14 |
| 07501-0 | 7. | 0.55 | 4 G | 14 | 08003-A | 7. | 0.31 | 4 G | 14 |
| 07502-E | 7. | 0.42 | 8 G | 16 | 08003-8 | 7. | 0.31 | 4 G | 11 |
| 07502-F | 7. | 0.42 | 86 | 16 | 08003-C | 7. | 0.31 | 4 G | 14 |
| 07601-E | 7. | 0.70 | 47 G | 16 | 08003-0 | 7. | 0.31 | 4 G | 14 |
| 07601-F | 7. | 0.70 | 47 G | 16 | 08004-A | 7. | 0.31 | 46 | 14 |
| 07602-E | 7. | 0.70 | 41 G | 16 | 08004-8 | 7. | 0.31 | 4 G | 14 |
| 07602-F | 7. | 0.70 | 416 | 16 | 08004-C | 7. | 0.31 | 4 G | 14 |
| 07701-E | 7. | 0.33 | 16 G | 16 | 08004-0 | 7. | 0.31 | 4 G | 14 |
| 07701 -F | 7. | 0.33 | 16 G | 16 | 08101-A | 7. | 0.48 | 2 G | 14 |
| 07702-E | 7. | 0.41 | 18G | 16 | 08101-8 | 7. | 0.48 | 2 S | 14 |
| 07702-F | 7. | 0.41 | 18 G | 16 | 08101-C | 7. | 0.48 | 2 G | 14 |
| 07801-J | 7. | 0.99 | 63 G | 24 | 08101-0 | 7. | 0.48 | 2 G | 14 |
| 07801-K | 7. | 0.99 | 63G | 24 | 08201-E | 7. | 0.60 | 316 | 16 |
| 07801-L | 7. | 0.99 | 63 G | 24 | 08201-F | 7. | 0.60 | 31 G | 16 |
| 07801-2 | 7. | 0.99 | 63 G | 24 |  |  |  |  |  |
| 07802-E | 7. | 0.99 | 196 | 16 | LINEAR |  |  |  |  |
| 07802-F | 7. | 0.99 | 19G | 16 |  |  |  |  |  |
| 07901-E | 7. | 0.39 | 17 G | 16 | 10101-A | 22. | 0.35 | $23 T$ | 14 |
| 07901-F | 7. | 0.39 | 17G | 16 | 10101-8 | 22. | 0.35 | $23 T$ | 14 |
| 07902-E | 7. | 0.39 | 16 G | 16 | 10101-C | 22. | 0.40 | $23 T$ | 14 |
| 07902-F | 7. | 0.39 | 16 G | 16 | 10101-0 | 22. | 0.35 | $23 T$ | 14 |
| 07903-E | 7. | 0.43 | 15 G | 16 | 10101-G | 22. | 0.33 | $23 T$ | 3 |
| 07903-F | 7. | 0.43 | 15 G | 16 | 10101-H | 22. | 0.33 | $23 T$ | 10 |
| 07904-E | 7. | 0.34 | 15 G | 16 | 10101-P | 22. | 0.40 | $23 T$ | 3 |
| 07904-F | 7. | 0.34 | 15 G | 16 | 10102-A | 22. | 0.35 | $46 T$ | 14 |
| 07905-E | 7. | 0.47 | 176 | 16 | 10102-8 | 22. | 0.35 | $46 T$ | 14 |
| 07905-F | 7. | 0.47 | 17 G | 16 | 10102-C | 22. | 0.40 | $46 T$ | 14 |
| 07906-E | 7. | 0.55 | 15 G | 16 | 10102-0 | 22. | 0.35 | $46 T$ | 14 |
| 07906-F | 7. | 0.55 | 15 G | 16 | 10102-I | 22. | 0.35 | $46 T$ | 10 |
| 07907-E | 7. | 0.48 | 15 G | 16 | 10103-C | 22. | 0.40 | $21 T$ | 14 |
| 07907-F | 7. | 0.48 | 15 G | 16 | 10103-G | 22. | 0.33 | 217 | 3 |
| 07908-E | 7. | 0.55 | 16G | 16 | 10103-4 | 22. | 0.33 | 219 | 10 |
| 07908-F | 7. | 0.55 | 16G | 16 | 10103-P | 22. | 0.40 | 217 | 8 |
| 08001-A | 7. | 0.23 | 36 | 14 | 10104-C | 22. | 0.40 | 297 | 14 |
| 08001-8 | 7. | 0.23 | 36 | 14 | 10104-G | 22. | 0.33 | 297 | 3 |
| 08001-C | 7. | 0.23 | 3 G | 14 | 10104-H | 22. | 0.33 | 297 | 10 |
| 08001-0 | 7. | 0.23 | 3 G | 14 | 10104-P | 22. | 0.40 | 297 | 3 |
| 08002-A | 7. | 0.23 | 3G | 14 | 10105-E | 22. | 0.40 | $42{ }^{\top}$ | 16 |
| 08002-8 | 7. | 0.23 | 3 G | 14 | 10105-F | 22. | 0.40 | 42 T | 15 |
| 08002-¢ | 7. | 0.23 | 3G | 14 | 10106-E | 22. | 0.40 | 589 | 16 |

## MIL-HDBK-217(REV) <br> microelectronic devices

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| $\begin{aligned} & M 385101 \\ & x x \times x \times x \times x \end{aligned}$ | $\begin{aligned} & \text { Vce } \\ & \left(V_{.}\right) \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No | M38510/ $x \times x \times x x x$ | $\begin{aligned} & \text { Vec } \\ & (V .) \end{aligned}$ | Pd (W.) | Compl ex |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LINEAR |  |  |  |  | Linear |  |  |  |  |
| 10106-F | 22. | 0.40 | $58 T$ | 16 | 10407-F | 7. | 0.22 | 97 | 16 |
| 10107-C | 22. | 0.40 | $36 T$ | 14 | 10601-C | 36. | 0.40 | 197 | 14 |
| 10107-G | 22. | 0.33 | $36 T$ | 8 | 10601-G | 36. | 0.35 | 197 | 8 |
| 10107-H | 22. | 0.33 | $36 T$ | 10 | 10601-G | 36. | 0.35 | 197 | 8 |
| 10107-P | 22. | 0.40 | 367 | 8 | 10601-H | 36. | 0.33 | 197 | 10 |
| 10108-G | 22. | 0.33 | $46 T$ | 8 | 10602-C | 36. | 0.40 | 197 | 14 |
| 10201-A | 40. | 0.35 | $20 T$ | 14 | 10602-G | 36. | 0.35 | 197 | 8 |
| 10201-B | 40. | 0.35 | 207 | 14 | 10602-H | 36. | 0.33 | 197 | 7 |
| 10201-C | 40 | 0.40 | 209 | 14 | 10603-E | 36. | 0.40 | 38 T | 16 |
| 10201-0 | 40. | 0.35 | 207 | 14 | 10603-F | 36. | 0.40 | 387 | 16 |
| 10201-H | 40. | 0.35 | 209 | 10 | 10701-X | 35. | 0.89 | 197 | 3 |
| 10201-1 | 40. | 0.35 | 209 | 10 | 10701-Y | 35. | 3.60 | 19 T |  |
| 10301-C | 21. | 0.40 | $9 T$ | 14 | 10702-X | 35. | 0.89 | 18 T |  |
| 10301-G | 21. | 0.33 | 97 | 8 | 10703-X | 35. | 0.89 | 187 | 3 |
| 10301-H | 21. | 0.33 | $9 T$ | 10 | 10704-X | 35. | 0.89 | 18 T | 3 |
| 10302-C | 21. | 0.40 | 18 T | 14 | 10705-X | 40 | 0.89 | $18 T$ | 3 |
| 10302.F | 21. | 0.35 | 18 T | 16 | 10706-Y | 35. | 3.60 | $17 T$ | 3 |
| 10302-H | 21. | 0.33 | 18 T | 10 | 10707-Y | 35. | 3.60 | $17 T$ | 3 |
| 10303-A | 30. | 0.35 | $13 T$ | 14 | 10708-Y | 35. | 3.60 | $17 T$ | 3 |
| 10303-G | 30. | 0.33 | $13 T$ | 8 | 10709-Y | 40. | 3.60 | $17 T$ | 3 |
| 10304-G | 36. | 0.33 | $23 T$ | 8 | 10801-A | 15. | 0.35 | $4 T$ | 14 |
| 10304-H | 36. | 0.33 | $23 T$ | 10 | 10801-C | 15. | 0.40 | $4 T$ | 14 |
| 10305-E | 36. | 0.40 | $46 T$ | 16 | 10801-0 | 15. | 0.35 | $4 T$ | 14 |
| 10305-F | 36. | 0.35 | $16 T$ | 16 | 10801-M | 15. | 0.35 | $4 T$ | 14 |
| 10401-A | 7. | 0.55 | 295 | 14 | 10802-A | 15. | 0.35 | ¢T | 14 |
| 10401-8 | 7. | 0.55 | 297 | 14 | 10802-C | 15. | 0.40 | $5 T$ | 14 |
| 10401 -C | 7. | 0.55 | 295 | 14 | 10802-0 | 15. | 0.35 | $5 T$ | 14 |
| 10401-0 | 7. | 0.55 | 295 | $14^{\circ}$ | 10901-C | 18. | 0.40 | $23 T$ | 14 |
| 10402-A | 7. | 0.55 | 259 | 14 | 10901-G | 18. | 0.30 | $23 T$ | 8 |
| 10402-8 | 7. | 0.55 | 259 | 14 | 10901-P | 18. | 0.37 | 235 | 8 |
| 10402-C | 7. | 0.55 | 259 | 14 | 10902-C | 18. | 0.40 | $46 T$ | 14 |
| 10402-0 | 7. | 0.55 | 255 | 14 | 10903-C | 18. | 0.40 | 235 | 14 |
| 10403-E | 7. | 0.40 | $6 T$ | 16 | 11001-A | 22. | 0.35 | $88 T$ | 14 |
| 10403-F | 7. | 0.40 | $6 T$ | 16 | 11001-¢ | 22. | 0.40 | $88 T$ | 14 |
| 10404-E | 7. | 0.40 | 35 T | 16 | 11001-0 | 22. | 0.35 | $88 T$ | 14 |
| 10404-F | 7. | 0.40 | 359 | 16 | 11002-A | 22. | 0.35 | $88 T$ | 14 |
| 10405-E | 7. | 0.40 | $8 T$ | 16 | 11002-C | 22. | 0.40 | 985 | 14 |
| 10405-F | 7. | 0.40 | $8 T$ | 16 | 11002-0 | 22. | 0.35 | $88 T$ | 14 |
| 10406-E | 7. | 0.22 | 9 T | 16 | 11003-A | 22. | 0.35 | $68 T$ | 14 |
| 10406-F | 7. | 0.22 | $9 T$ | 16 | 11003-C | 22. | 0.40 | 68 T | 11 |
| 10407-E | 7. | 0.22 | $9 T$ | 16 | 11003-0 | 22. | 0.35 | $58 T$ | 11 |

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## MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ <br> xxxxxxx | $\begin{aligned} & \text { Vcc } \\ & (V .) \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | $N p$ | M38510/ $x x x x x x x$ | $\begin{aligned} & V c c \\ & (V .) \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LIMEAR |  |  |  |  | Linear |  |  |  |  |
| 11004-C | 22. | 0.40 | 609 | 14 | 11401-p | 22. | 0.40 | 197 | 8 |
| 11005-A | 36. | 0.35 | $102 T$ | 14 | 11402-G | 22. | 0.33 | 197 | 8 |
| 11005-C | 36. | 0.40 | $102 T$ | 14 | 11402-H | 22. | 0.33 | 19 T | 10 |
| 11005-0 | 36. | 0.35 | 102T | 14 | 11402-P | 22. | 0.40 | 197 | 8 |
| 11101-A | 36. | 0.35 | 229 | 14 | 11403-G | 22. | 0.33 | 197 | 8 |
| 11101-6 | 36. | 0.40 | 22 T | 14 | 11403-H | 22. | 0.33 | 197 | 10 |
| 11101-0 | 36. | 0.35 | $22 T$ | 14 | 11403-? | 22. | 0.40 | 197 | 8 |
| 11101-1 | 36. | 0.35 | 229 | 10 | 11404-G | 22. | 0.33 | 197 | 8 |
| 11102-A | 36. | 0.35 | 229 | 14 | 11405-G | 22. | 0.33 | 197 | 8 |
| 11102-C | 36. | 0.40 | 229 | 14 | 11405-H | 22 | 0.33 | 197 | 10 |
| 11102-0 | 36. | 0.35 | $22 T$ | 14 | 11405-P | 22. | 0.40 | 19 | 8 |
| 11102-1 | 36. | 0.35 | 229 | 10 | 11406-G | 22. | 0.33 | 19 T | 8 |
| 11103-A | 36. | 0.35 | 307 | 14 | 11406-H | 22. | 0.33 | 197 | 10 |
| 11103-0 | 36. | 0.35 | 307 | 14 | 11406-P | 22. | 0.40 | 197 | 8 |
| 11103-E | 36. | 0.40 | 307 | 16 | 11501-x | 10. | 0.89 | $23 T$ | 3 |
| 11104-A | 36. | 0.35 | 309 | 14 | 11502-X | 17. | 0.89 | 235 | 3 |
| 11104-0 | 36. | 0.35 | 309 | 14 | 11503-x | 20. | 0.89 | $23 T$ | 3 |
| 11104-E | 36. | 0.40 | 307 | 16 | 11504-x | 29. | 0.89 | 235 | 3 |
| 11105-A | 36. | 0.35 | $15 T$ | 14 | 11505-Y | 10. | 3.60 | 215 | 3 |
| 11105-C | 36. | 0.40 | $15 T$ | 14 | 11506-Y | 17. | 3.50 | 219 | 3 |
| 11105-0 | 36. | 0.35 | $15 T$ | 14 | 11507-Y | 20. | 3.60 | 215 | 3 |
| 11105-1 | 36. | 0.35 | $15 T$ | 10 | 11508-Y | 29. | 3.60 | 217 | 3 |
| 11106-A | 36. | 0.35 | $15 T$ | 14 |  |  |  |  |  |
| 11106-C | 36. | 0.40 | 159 | 14 | CMOS |  |  |  |  |
| 11106-0 | 36. | 0.35 | $15 T$ | 14 |  |  |  |  |  |
| 11106-1 | 36. | 0.35 | 159 | 10 | 11601-C | 15. | 0.40 | $42 T$ | 14 |
| 11107-A | 36. | 0.35 | 307 | 14 | 11601-0 | 15. | 0.35 | 42 T | 14 |
| 11107-C | 36. | 0.40 | 309 | 14. | 11601-1 | 15. | 0.25 | 429 | 10 |
| 11107-0 | 36. | 0.35 | 309 | 14 | 11602-C | 15. | 0.40 | 279 | 14 |
| 11108-A | 36. | 0.35 | 307 | 14 | 11602-0 | 15. | 0.35 | 279 | 14 |
| 11108-C | 36. | 0.40 | 309 | 14 | 11602-1 | 15. | 0.25 | 279 | 10 |
| 11108-0 | 36. | 0.35 | 309 | 14 | 11603-¢ | 15. | 0.40 | $54 T$ | 14 |
| 11201-A | 36. | 0.35 | 32 T | 14 | 11603-0 | 15. | 0.35 | 547 | 14 |
| 11201-C | 36. | 0.40 | 329 | 14 | 11604-C | 15. | 0.40 | 545 | 14 |
| 11201-0 | 36. | 0.35 | 32 T | 14 | 11604-0 | 15. | 0.35 | $54 T$ | 14 |
| 11202-G | 36. | 0.33 | $16 T$ | 3 | 11605-6 | 15. | 0.40 | 38 T | 14 |
| 11202-P | 36. | 0.40 | $16 T$ | 8 | 11605-0 | 15. | 0.35 | 38 T | 14 |
| 11301-E | 36. | 0.40 | $84 T$ | 16 | 11605-1 | 15. | 0.25 | 38 T | 10 |
| 11302-E | 36. | 0.40 | $84 T$ | 16 | 11606-C | 15. | 0.40 | 257 | 14 |
| 11401-G | 22. | 0.33 | 197 | 8 | 11606-0 | 15. | 0.35 | $25 T$ | 14 |
| 11401-4 | 22. | 0.33 | 197 | 10 | 11606-1 | 15. | 0.25 | $25 T$ | 10 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ $X X X X X X X$ | Vec (V.) | $\begin{aligned} & P_{d} \\ & \left(W_{.}\right) \end{aligned}$ | Comp lex | Np | $\begin{aligned} & \text { M38510/ } \\ & X X X X X X X \end{aligned}$ | VCe (V.) | Pd (W.) | Comp lex | $N p$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| GMOS |  |  |  |  | CMOS |  |  |  |  |
| 11607-C | 15. | 0.40 | 50 T | 14 | 12301-C | 15. | 0.40 | $36 T$ | 14 |
| 11607-0 | 15. | 0.35 | 50 T | 14 | 12301-I | 15. | 0.35 | $36 T$ | 10 |
| 11608-C | 15. | 0.40 | $50 T$ | 14 | 12302-E | 30. | 0.40 | $72 T$ | 16 |
| 11608-0 | 15. | 0.35 | 50 T | 14 | 12303-C | 15. | 0.40 | $18 T$ | 14 |
|  |  |  |  |  | 12303-I | 15. | 0.35 | 18 T | 10 |
| LINEAR |  |  |  |  | 12304-E | 15. | 0.40 | 18 T | 16 |
| $11701-X$$11702-X$$11703-X$$11704-Y$$11801-X$$11802-Y$$11803-X$$11804-Y$$11901-G$$11901-P$$11902-C$$11902-G$$11902-P$$11903-C$$11903-0$$11904-G$$11904-P$$11905-C$$11905-G$$11905-P$$11906-C$$11906-D$$12201-G$$12201-H$$12202-G$$12202-H$$12203-G$$12203-H$$12204-G$$12204-H$$12205-G$$12205-H$$12206-G$$12206-H$ | $\begin{aligned} & 40 . \\ & 40 . \end{aligned}$ | 0.89 | $17 T$ |  | LINEAR |  |  |  |  |
|  |  | 3.60 | $17 T$ | 4 |  |  |  |  |  |
|  | 40. | 0.89 | $26 T$ | 3 | 12401-X | 30. | 0.12 | 197 | 2 |
|  | 40. | 3.60 | $26 T$ | 3 | 12401-Y | 30. | 0.14 | 19 T | 4 |
|  | 40. | 0.89 | 23 T | 4 | 12401-G | 30. | 0.18 | 197 | 8 |
|  | 40. | 3.60 | $23 T$ | 4 | 12402-X | 30. | 0.12 | $8 T$ | 2 |
|  | 40. | 0.89 | $30 T$ | 3 | 12402-Y | 30. | 0.14 | $8 T$ | 4 |
|  | 40. | 3.60 | 30 T | 3 | 12402-6 | 30. | 0.18 | $8 T$ | 8 |
|  | 36. | 0.33 | $33 T$ | 8 | 12403-X | 30. | 0.12 | 217 | 2 |
|  | 36. | 0.40 | $33 T$ | 8 | 12403-Y | 30. | 0.14 | 215 | 4 |
|  | 36. | 0.40 | $66 T$ | 14 | 12403-G | 30. | 0.18 | $21 T$ | 8 |
|  | 36. | 0.33 | $66 T$ | 8 | 12404-X | 30. | 0.12 | 19T | 2 |
|  | 36. | 0.40 | $66 T$ | 8 | 12404-Y | 30. | 0.14 | 197 | 4 |
|  | 36. | 0.40 | 132 T | 14 | 12404-G | 30. | 0.18 | $19 T$ | 8 |
|  | 36. | 0.35 | 132 T | 14 | 12406-X | 30. | 0.12 | $8 T$ | 2 |
|  | 36. | 0.33 | $28 T$ | 8 | 12406-Y | 30. | 0.14 | 81 | 4 |
|  | 36. | 0.40 | $28 T$ | 8 | 12406-G | 30. | 0.18 | 87 | 8 |
|  | 36. | 0.40 | 54 T | 14 | 12501-G | 15. | 0.33 | $62 T$ | 8 |
|  | 36. | 0.33 | 54 T | 8 | 12501-P | 15. | 0.33 | 627 | 8 |
|  | 36. | 0.40 | $54 T$ | 8 | 12502-P | 15. | 0.40 | 617 | 8 |
|  | 36. | 0.40 | $124 T$ | 14 | 12601-E | 40. | 0.40 | 715 | 16 |
|  | 36. | 0.35 | 124 T | 14 | 12801-6 | 30. | 0.33 | $16 T$ | 8 |
|  | 40. | 0.30 | 50 T | 8 | 12802-G | 30. | 0.33 | $16 T$ | 8 |
|  | 40. | 0.30 | 50 T | 14 | 12901-6 | 7. | 0.27 | 107 | 14 |
|  | 40. | 0.30 | 40 T | 8 | 12901 -P | 7. | 0.21 | 107 | 8 |
|  | 40. | 0.30 | 40 T | 8 | 12902-C | 7. | 0.27 | 10 T | 14 |
|  | 40. | 0.30 | 40 T | 8 | 12902-P | 7. | 0.21 | 101 | 8 |
|  | 40. | 0.30 | 40 T | 8 | 12903-C | 7. | 0.27 | $14 T$ | 14 |
|  | 40. | 0.30 | 30 T | 8 | 12903-P | 7. | 0.21 | $14 T$ | 8 |
|  | 40. | 0.30 | 30 T | 8 | 12904-C | 7. | 0.27 | $14 T$ | 14 |
|  | 40. | 0.30 | 30 T | 8 | 12904-P | 7. | 0.21 | $14 T$ | 8 |
|  | 40. | 0.30 | 30 T | 8 | 12905-C | 7. | 0.27 | $18 T$ | 14 |
|  | 40. | 0.30 | 317 | 8 | 12905-P | 7. | 0.21 | 187 | 3 |
|  | 40. | 0.30 | 317 | 8 | 12906-C | 7. | 0.27 | $10 T$ | 14 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ $x x x x x x x$ | $\begin{aligned} & V \in e \\ & (y) \end{aligned}$ | $\begin{aligned} & \text { pg } \\ & \text { (W.) } \end{aligned}$ | Complex | Np | M38510/ xxxxxxx | $\begin{aligned} & \text { Vce } \\ & (\mathrm{V} .) \end{aligned}$ | Pd (w.) | Compl exity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LINEAR |  |  |  |  | $\pi \mathrm{L}$ |  |  |  |  |
| 12906 -P | 7. | 0.21 | $10 T$ | 8 | 15103 -A | 7. | 0.18 | 46 | 14 |
| 12907 -C | 7. | 0.27 | 107 | 14 | 15103-8 | 7. | 0.18 | 46 | 14 |
| $12907-\mathrm{P}$ | 7. | 0.21 | 107 | 8 | 15103-C | 7. | 0.18 | 4 G | 14 |
| 12908-C | 7. | 0.27 | $14 T$ | 14 | 15103-0 | 7. | 0.18 | 4 G | 14 |
| 12908-P | 7. | 0.21 | $14 T$ | 8 | 15201-J | 7. | 0.27 | 216 | 24 |
| 12909-C | 7. | 0.27 | $14 T$ | 14 | 15201-K | 7. | 0.27 | 216 | 24 |
| 12909-P | 7. | 0.21 | $14 T$ | 8 | 15201 -L | 7. | 0.27 | 216 | 24 |
| 12910-C | 7. | 0.27 | 185 | 14 | 15201-2 | 7. | 0.27 | 216 | 24 |
| 12910-P | 7. | 0.21 | 189 | 8 | 15202-E | 7. | 0.20 | 156 | 15 |
| 13001 -E | 25. | 1.40 | $32 T$ | 16 | 15202-F | 7. | 0.20 | 156 | 15 |
| $13002-E$ | 7. | 1.40 | $32 T$ | 16 | 15203-E | 7. | 0.20 | 156 | 1.6 |
| 13003 -E | 7. | 1.40 | 32 T | 16 | 15203.7 | 7. | 0.20 | 156 | 16 |
| 13101-G | 22. | 0.33 | 215 | 8 | 15204-A | 7. | 0.14 | 156 | 14 |
| 13101-P | 22. | 0.40 | 215 | 8 | 15204-8 | 7. | 0.14 | 156 | 14 |
| 13102-6 | 22. | 0.33 | 42 T | 8 | 15204-C | 7. | 0.14 | 156 | 14 |
| 13102-p | 22. | 0.40 | 42 T | 8 | 15204-0 | 7. | 0.14 | 156 | 14 |
| $13301-E$ | 16.5 | 0.50 | 96 G | 16 | 15205-E | 7. | 0.19 | 18G | 16 |
| 13301-2 | 16.5 | 0.50 | 96 G | 16 | 15205-F | 7. | 0.19 | 186 | 16 |
| $13401-V$ | 7. | 0.80 | 1736 | 19 | 15206-E | 7. | 0.19 | 18G | . 16 |
| 13901-1 | 22. | 0.33 | 49 T | 10 | 15206-F | 7. | 0.19 | 18G | 16 |
| 13901-C | 22. | 0.40 | 495 | 14 | 15301-C | 7. | 0.30 | 4G | 14 |
| 13902-1 | 22. | 0.33 | 495 | 10 | 15301-0 | 7. | 0.30 | 4 G | 14 |
| 13902-6 | 22. | 0.40 | 495 | 14 | 15302-C | 7. | 0.35 | 46 | 14 |
| 13903-1 | 22. | 0.33 | 285 | 10 | 15302-0 | 7. | 0.35 | 4 G | 14 |
| 13903-C | 22. | 0.40 | $28 T$ | 14 |  |  |  |  |  |
| 14103-E | 50. | 1.00 | 75 | 16 | HTL |  |  |  |  |
| TL |  |  |  |  | $\begin{aligned} & 15501-A \\ & 15501-8 \\ & 15501-6 \end{aligned}$ | 7. | 0.35 | 4 G | 14 |
| 15001-E | 7. | 0.49 | 316 | 16 |  | 7. | 0.35 | ${ }_{4}^{4 G}$ | 14 |
| $15001-\mathrm{F}$ | 7. | 0.49 | 316 | 16 | 15501-0 | 7. | 0.35 | 4 G | 14 |
| 15002-E | 7. | 0.49 | 32 G | 16 | $15502-A$ | 7. | 0.26 | 3G | 14 |
| 15002-F | 7. | 0.49 | 32 G | 16 | 15502-8 | 7. | 0.26 | 3 G | 14 |
| 15101 -A | 7. | 0.18 | 2 G | 14 | 15502-C | 7. | 0.26 | 3 G | 14 |
| 15101-8 | 7. | 0.18 | 2 G | 14 | 15502-0 | 7. | 0.26 | 3 C | 14 |
| 15101-6 | 7. | 0.18 | 2 G | 14 | 15503 -A | 7. | 0.18 | 2 G | 14 |
| 15101-0 | 7. | 0.18 | $2 G$ | 14 | 15503-8 | 7. | 0.18 | 2 C | 14 |
| 15102-A | 7. | 0.18 | 6 G | 14 | 15503-C | 7. | 0.18 | 2 G | 14 |
| 15102-8 | 7. | 0.18 | 6 G | 14 | 15503-0 | 7. | 0.18 | 2 G | 14 |
| 15102-C | 7. | 0.18 | 6 G | 14 | 15504-A | 7. | 0.35 | 4 G | 11 |
| 15102-0 | 7. | 0.18 | 6 G | 14 | 15504-8 | 7. | 0.35 | 4 G | 14 |

MIL-HDBK-217(REV)
miCROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| $\begin{gathered} M 38510 / \\ x x \times x x x x \end{gathered}$ | $\begin{aligned} & V e e \\ & (v .) \end{aligned}$ | $\begin{aligned} & \text { pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | Np | M38510/ $x \times x \times x \times x$ | $\begin{aligned} & \text { Vce } \\ & (v .) \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \left(W_{.}\right) \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| HTLL |  |  |  |  | CMOS |  |  |  |  |
| 15504-0 | 7. | 0.35 | 4 G | 14 | $\begin{aligned} & 17001-A \\ & 17001-C \\ & 17001-0 \\ & 17002-C \\ & 17002-0 \end{aligned}$ | 15. 15. 15. 15. | 0.20 | 4 G | 14 |
| Th |  |  |  |  |  |  | 0.20 | ${ }_{4}{ }_{4}$ G | 14 14 |
| $\begin{array}{lllll}15601-8 & 7.39 & 316\end{array}$ |  |  |  |  |  |  | 0.20 | 2 C | 14 |
|  |  |  |  |  |  | 15. | 0.20 | 2 G | 14 |
| 15601 -F | 7. | 0.39 | 316 | 16 | $\begin{aligned} & 17002-0 \\ & 17003-6 \end{aligned}$ | 15. | 0.20 | 3 G | 14 |
| 15602-E | 7. | 0.33 | 296 | 16 | 17003-0 | 15. | 0.20 | 36 | 14 |
| 15602-F | 7. | 0.33 | 296 | 16 | 17101 -A | 15. | 0.20 | 4 G | 14 |
| 15603-E | 7. | 0.42 | 24 G | 16 | $17101-6$ | 15. | 0.20 | 4 G | 14 |
| 15603.7 | 7. | 0.42 | 24G | 16 |  | 15. | 0.20 | 4 G | 14 |
| 15701-E | 7. | 0.74 | 98 G | 16 | $\begin{aligned} & 17101-0 \\ & 17102-A \end{aligned}$ | 15. | 0.20 | 2 G | 14 |
| 15701-F | 7. | 0.74 | 98 G | 16 |  | 15. | 0.20 | 2 G | 14 |
| 15801-E | 7. | 0.28 | 18 G | 16 | $\begin{aligned} & 17102-6 \\ & 17102-0 \end{aligned}$ | 15. | 0.20 | 2 G | 14 |
| $15801-7$ | 7. | 0.28 | 18G | 16 | 17103 -A | 15. | 0.20 | 3 G | 14 |
| 15802-E | 7. | 0.40 | 46 G | 16 | $\begin{aligned} & 17103-6 \\ & 17103-0 \end{aligned}$ | 15. | 0.20 | 3 G | 14 |
| 15802-F | 7. | 0.40 | 46 G | 16 |  | 15. | 0.20 | 3 G | 14 |
| 15901-E | 7. | 0.47 | 40 G | 16 | $\begin{aligned} & 17103-0 \\ & 17201-A \end{aligned}$ | 15. | 0.20 | 66 | 14 |
| 15901.5 | 7. | 0.47 | 40 G | 16 | $\begin{aligned} & 17201-6 \\ & 17201-0 \end{aligned}$ | 15. | 0.20 | 6 G | 14 |
| 15902-E | 7. | 0.42 | 726 | 16 |  | 15. | 0.20 | 66 | 14 |
| 15902 -F | 7. | 0.42 | 726 | 16 | $\begin{aligned} & 17201-0 \\ & 17202-A \end{aligned}$ |  | 0.20 | 56 | 14 |
| 16001-E | 7. | 0.47 | 596 | 16 | $\begin{aligned} & 17202-A \\ & 17202-G \end{aligned}$ | 15. | 0.20 | 56 | 14 |
| 16001 -F | 7. | 0.47 | 596 | 16 | $\begin{aligned} & 17202-0 \\ & 17203-A \end{aligned}$ | 15. | 0.20 | $5 G$ | 14 |
| 16101 -A | 7. | 0.21 | 46 | 14 |  | 15. | 0.20 | 4 G | 14 |
| 16101-3 | 7. | 0.21 | 46 | 14 | $\begin{aligned} & 17203-A \\ & 17203-C \end{aligned}$ |  | 0.20 | 4 G | 14 |
| 18101 -6 | 7. | 0.21 | 46 | 14 | 17203-0 | 15. | 0.20 | 4 G | 14 |
| 16101-0 | 7. | 0.21 | 46 | 14 | $\begin{aligned} & 17204-A \\ & 17204-C \end{aligned}$ | 15. | 0.20 | 4 G | 14 |
| 16201 -A | 7. | 0.32 | 4 G | 14 |  | 15. | 0.20 | ${ }^{4} \mathrm{G}$ | 14 |
| 16201-8 | 7. | 0.32 | 4 G | 14 | $\begin{aligned} & 17204-C \\ & 17204-0 \end{aligned}$ |  | 0.20 | 4 G | 14 |
| 16201 -6 | 7. | 0.32 | 4 G | 14 | 17301-J | 15. | 0.20 | 120 G | 24 |
| 16201-0 | 7. | 0.32 | 4 G | 14 | $\begin{aligned} & 17301-x \\ & 17301-x \end{aligned}$ | $15^{\circ}$ | 0.20 | 120 G | 24 |
| 16301-E | 7. | 0.28 | 7 G | 16 |  | $15$ | 0.20 | 120 G | 24 |
| 16301 -F | 7. | 0.28 | 76 | 16 | $\begin{aligned} & 17301-x \\ & 17301-Y \end{aligned}$ | 15. | 0.20 | 120 G | 24 |
| 16302 - E | 7. | 0.55 | 7 G | 16 | $\begin{aligned} & 17301-Y \\ & 17302-J \end{aligned}$ | 15. | 0.20 | 104 G | 24 |
| 16302-F | 7. | 0.55 | 7 G | 18 |  | 15. | 0.20 | 104 G | 24 |
| $16303-8$ | 7. | 0.28 | 86 | 16 | $\begin{aligned} & 17302-x \\ & 17302-x \end{aligned}$ | 15. | 0.20 | 104 G | 24 |
| 16303 -f | 7. | 0.28 | 8 G | 16 | $\begin{aligned} & 17302-x \\ & 17302-y \end{aligned}$ | 15. | 0.20 | 104 G | 24 |
| 16304 -E | 7. | 0.16 | 8 G | 16 | $\begin{aligned} & 17302-Y \\ & 17303-E \end{aligned}$ | 15. | 0.20 | 34G | 15 |
| 16304 -F | 7. | 0.16 | 8G | 16 | $\begin{aligned} & 17303-F \\ & 17304-E \end{aligned}$ | $\begin{aligned} & 15 . \\ & 15 . \end{aligned}$ | 0.20 | 34G | 15 |
|  |  |  |  |  |  |  | 0.20 | 34 G | 16 |
|  |  |  |  |  | 17304 - ${ }^{\text {F }}$ | $15 .$ | 0.20 | 34 G | 16 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ xxxxxxx | Vec (v.) | $\begin{aligned} & \mathrm{Pd} \\ & \text { (W.) } \end{aligned}$ | Complexity | Np | M38510/ <br> xxxxxxx | Vec (v.) | Pd (w.) | Complexity | Np |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| CMOS |  |  |  |  | c.mOs |  |  |  |  |
| 17305-E | 15. | 0.20 | 266 | 16 | 19001-x | 30. | 1.20 | 529 | 29 |
| 17305-F | 15. | 0.20 | 26 G | 16 | 19002-x | 30. | 1.20 | 529 | 29 |
| 17401-A | 15. | 0.20 | 66 | 14 | 19003-x | 30. | 1.20 | $36 T$ | 29 |
| 17401-C | 15. | 0.20 | 66 | 14 | 19004-X | 30. | 1.20 | $36 T$ | 29 |
| 17401-0 | 15. | 0.20 | 6 G | 14 | 19005-E | 30. | 0.73 | 28 T | 16 |
| 17402-A | 15. | 0.20 | 66 | 14 | 19006-E | 30. | 0.73 | 187 | 16 |
| 17402-C | 15. | 0.20 | 66 | 14 |  |  |  |  |  |
| 17402-0 | 15. | 0.20 | 6 G | 14 | TTL PROM |  |  |  |  |
| 17403-E | 15. | 0.20 | 12G | 16 |  |  |  |  |  |
| 17403-F | 15. | 0.20 | 12G | 16 | 20101-J | 7. | 0.58 | 5129 | 24 |
| 17404-E | 15. | 0.20 | 32G | 16 | 20101-K | 7. | 0.58 | 5128 | 24 |
| 17404-F | 15. | 0.20 | 32 G | 16 | 20101-2 | 7. | 0.58 | 5123 | 24 |
| 17501-E | 15. | 0.20 | 52 G | 16 | 20102-J | 7. | 0.58 | 5128 | 24 |
| 17501-F | 15. | 0.20 | 52 G | 16 | 20102-K | 7. | 0.58 | 5123 | 24 |
| 17502-C | 15. | 0.20 | 20 G | 14 | 20102-2 | 7. | 0.58 | 5129 | 24 |
| 17502-0 | 15. | 0.20 | 206 | 14 | 20201-E | 7. | 0.72 | 10248 | 15 |
| 17503-C | 15. | 0.20 | 216 | 14 | 20201-F | 7. | 0.72 | 10248 | 16 |
| 17503-0 | 15. | 0.20 | 216 | 14 | 20202-E | 7. | 0.72 | 10248 | 16 |
| 17504-E | 15. | 0.20 | 206 | 16 | 20202-F | 7. | 0.72 | 1024B | 16 |
| 17504-F | 15. | 0.20 | 20G | 16 | STTL PROM |  |  |  |  |
| 17505-E | 15. | 0.20 | 36 G | 16 |  |  |  |  |  |
| 17505-F | 15. | 0.20 | 36 G | 16 |  |  |  |  |  |
| 17601-E | 15. | 0.20 | 76 G | 16 | 20301-E | 7. | 0.74 | 1024B | 16 |
| 17601-5 | 15. | 0.20 | 76 G | 16 | 20301-F | 7. | 0.74 | 10248 | 16 |
| 17502-J | 15. | 0.20 | 56G | 24 | 20302-E | 7. | 0.74 | 10248 | 16 |
| 17602-K | 15. | 0.20 | 56G | 24 | 20302-F | 7. | 0.74 | 10248 | 15 |
| 17602-2 | 15. | 0.20 | 56G | 24 | 20303-E | 7. | 0.74 | 10248 | 15 |
| 17701-A | 15. | 0.20 | 4 G | $14^{\circ}$ | 20303-F | 7. | 0.74 | 10248 | 16 |
| 17701-C | 15. | 0.20 | 46 | 14 | 20304-E | 7. | 0.74 | 10248 | 16 |
| 17701-0 | 15. | 0.20 | 4 G | 14 | 20304-F | 7. | 0.74 | 10248 | 15 |
| 17702-A | 15. | 0.20 | 6 G | 14 | 20401-E | 7. | 0.79 | 20488 | 15 |
| 17702-C | 15. | 0.20 | 6 G | 14 | 20401-F | 7. | 0.79 | 20488 | 16 |
| 17702-0 | 15. | 0.20 | 6G | 14 | 20402-E | 7. | 0.79 | 20488 | 16 |
| 17801-J | 15. | 0.20 | 80G | 24 | 20402-F | 7. | 0.79 | 20483 | 15 |
| 17801-K | 15. | 0.20 | 80 G | 24 | 20601-V | 7. | 0.79 | 4096B | 18 |
| 17801-2 | 15. | 0.20 | 80G | 24 | 20601-2 | 7. | 0.79 | 40963 | 18 |
| 17802-J | 15. | 0.20 | 926 | 24 | 20602-V | 7. | 0.79 | 4096B | 18 |
| 17802-K | 15. | 0.20 | 92 G | 24 | 20602-2 | 7. | 0.79 | 4096B | 13 |
| 17802-2 | 15. | 0.20 | 92 G | 24 | 20603-E | 7. | 0.79 | 40968 | 15 |
| 17803-E | 15. | 0.20 | 416 | 16 | 20603-F | 7. | 0.79 | 40968 | $!5$ |
| 17803-F | 15. | 0.20 | 416 | 15 | 20701-E | 7. | 0.74 | 2568 | 15 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ <br> xxxxxxx | $\begin{aligned} & \text { vee } \\ & \text { (V.) } \end{aligned}$ | $\begin{aligned} & \mathrm{Pd} \\ & (W .) \end{aligned}$ | Complextty | Np | M38510/ xxxxxxx | Vee (V.) | $\begin{aligned} & \text { Pd } \\ & (W .) \end{aligned}$ | Complex | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| STTL PROM |  |  |  |  | CMOS EPROM |  |  |  |  |
| 20701-F | 7. | 0.74 | 2568 | 16 | 21901-J | 8. | 1.80 | 4096B | 24 |
| 20702-E | 7. | 0.74 | 2568 | 16 | NMOS EPROM |  |  |  |  |
| 20702-F | 7. | 0.74 | 2568 | 16 |  |  |  |  |  |
| 20801-K | 7. | 1.00 | 40968 40968 | 24 | 22001-J | 30. | 1.80 | 81928 | 24 |
| 20801-X | 7. | 1.00 | 40968 | 24 | 22101-J | 6. | 1.90 | 163848 | 24 |
| 20802-J | 7. | 1.00 | 40968 | 24 | 22201-J | 6. | 1.00 | 327688 | 24 |
| 20802-K | 7. | 1.00 | 40968 | 24 | 22202-J | 6. | 1.00 | 327688 | 24 |
| 20802-X | 7. | 1.00 | 40968 | 24 | 22601-J | 6. | 1.00 | 163848 | 24 |
| 20803-J | 7. | 1.00 | 40968 | 24 |  |  |  |  |  |
| 20803-K | 7. | 1.00 | 40963 | 24 | TTL RAM |  |  |  |  |
| 20803-x | 7. | 1.00 | 40968 | 24 |  |  |  |  |  |
| 20804-Y | 7. | 1.00 | 4096B | 20 | 23001-E | 7. | 0.80 | 2568 | 16 |
| 20805-Y | 7. | 1.00 | 4096B | 20 | 23001-F | 7. | 0.80 | 2568 | 16 |
| 20901-V | 7. | 0.72 | 81928 | 18 | 23002-E | 7. | 0.80 | 2568 | 16 |
| 20902-V | 7. | 0.72 | 81928 | 18 | 23002-F | 7. | 0.80 | 2568 | 16 |
| 20903-J | 7. | 1.40 | 81928 | 24 | 23003-E | 7. | 0.80 | 2568 | 15 |
| 20903-K | 7. | 1.40 | 81928 | 24 | 23003-F | 7. | 0.80 | 2568 | 16 |
| 20904-J | 7. | 1.40 | 81928 | 24 | 23004-E | 7. | 0.41 | 2568 | 16 |
| 20904-K | 7. | 1.40 | 81928 | 24 | 23004-F | 7. | 0.41 | 2568 | 15 |
| 20905-J | 7. | 1.40 | 81928 | 24 | 23'1:- | 7. | 0.94 | 10248 | 15 |
| 20905-K | 7. | 1.40 | 81928 | 24 | 23101-F | 7. | 0.94 | 10248 | 15 |
| 20906-3 | 7. | 1.40 | 81928 | 24 | $23101-4$ | 7. | 0.94 | 10248 | 24 |
| 20906-K | 7. | 1.40 | 81928 | 24 | 23102-E | 7. | 0.94 | 10248 | 16 |
| 20907-J | 7. | 1.40 | 81928 | 24 | 23102-F | 7. | 0.94 | 19248 | 15 |
| 20907-K | 7. | 1.40 | 81928 | 24 | 23102-Y | 7. | 0.94 | 10248 | 24 |
| 20908-J | 7. | 1.40 | 81928 | 24 |  |  |  |  |  |
| 20908-K | 7. | 1.40 | 81928 | 24 | LSTTL RAM |  |  |  |  |
| 21001-J | 7. | 1.00 | 163848 | 24 |  |  |  |  |  |
| 21001-K | 7. | 1.00 | 163848 | 24 | 23103-E | 7. | 0.41 | 10248 | 15 |
| 21002-J | 7. | 1.00 | 163848 | 24 | $23103-F$ | 7. | 0.41 | 10248 | 15 |
| 21002-K | 7. | 1.00 | 163848 | 24 | 23103-Y | 7. | 0.41 | 10248 | 21 |
| 21003-J | 7. | 1.00 | 163848 | 24 | 23104-E | 7. | 0.41 | 10248 | 15 |
| 21003-X | 7. | 1.00 | 163848 | 24 | 23104-F | 7. | 0.41 | 10248 | 16 |
| 21004-J | 7. | 1.00 | 163848 | 24 | 23104-Y | 7. | 0.41 | 10248 | 24 |
| 21004-K | 7. | 1.00 | 163848 | 24 | STTL RAM |  |  |  |  |
| 21005-J | 7. | 1.00 | 163848 | 24 |  |  |  |  |  |
| 21005-K |  |  |  |  | 23105-E | 7. | 0.94 | 19248 | 16 |
|  |  |  |  |  | 23105-F | 7. | 0.94 | 10248 | 16 |
|  |  |  |  |  | 23105-Y | 7. | 0.94 | 10248 | 3.4 |

## MIL-HDBK-217(REV) MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)


## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ xxxxxxx | $\begin{aligned} & \text { vec } \\ & \text { (v.) } \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | Np | M38510/ <br> xxxxxxx | $\begin{aligned} & \text { Vec } \\ & \text { (V.) } \end{aligned}$ | $\begin{aligned} & \mathrm{Pd} \\ & (\mathrm{~W} .) \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| NMOS RAM |  |  |  |  | CMOS |  |  |  |  |
| 23716-W | 7. | 0.44 | 40968 | 22 | 29101-X | 7. | 1.00 | 163848 | 32 |
| 23716-X | 7. | 0.44 | 40968 | 22 | 29102-J | 7. | 1.00 | 163848 | 24 |
| 23801-V | 7. | 1.20 | 40968 | 18 | 29102-x | 7. | 1.00 | 163848 | 32 |
| 23801-2 | 7. | 1.20 | 40968 | 18 | 29103-R | 7. | 1.00 | 163848 | 20 |
| 23802-V | 7. | 1.00 | 40968 | 18 | 29103-Y | 7. | 1.00 | 163848 | 20 |
| 23802-2 | 7. | 1.00 | 40968 | 18 | 29104-J | 7. | 1.00 | 163848 | 24 |
| 23803-V | 7. | 1.20 | 40968 | 18 | 29104-x | 7. | 1.00 | 163848 | 32 |
| 23804-V | 7. | 1.00 | 40968 | 18 | 29105-J | 7. | 1.00 | 163848 | 24 |
| 23805-V | 7. | 1.20 | 40968 | 18 | 29105-X | 7. | 1.00 | 153848 | 32 |
| 23806-V | 7. | 1.20 | 40968 | 18 | 29106-R | 7. | 1.00 | 163848 | 30 |
| 23807-V | 7. | 1.20 | 4096B | 18 | 29106-Y | 7. | 1.00 | 163848 | 20 |
| CMOS RAM |  |  |  |  | LSTTL |  |  |  |  |
| 23901-E | 7. | 0.20 | 10248 | 16 | 30001-A | 7. | 0.02 | 4 G | 14 |
| 23901-F | 7. | 0.20 | $1024 B$ | 16 | 30001-B | 7. | 0.02 | 4 G | 14 |
| 23902-V | 7. | 0.20 | 10248 | 18 | 30001-C | 7. | 0.02 | 4 G | 14 |
| nMOS RAM |  |  |  |  | 30001-0 | 7. | 0.02 | ${ }^{4 G}$ | 14 |
|  |  |  |  |  | 30002-A | 7. | 0.02 | 4 G | 14 |
| 24001-E | 20. | 1.00 | 163848 | 16 | $30002-8$ $30002-C$ | 7. | 0.02 | ${ }^{4 G}$ | 14 |
| 24001-F | 20. | 1.00 | 163848 | 16 | 30002-0 | 7. | 0.02 | 4 G | 14 |
| 24001-2 | 20. | 1.00 | 163848 | 18 | 30003-A | 7. | 0.04 | 66 | 14 |
| 24002-E | 20. | 1.00 | 163848 | 16 | 30003-B | 7. | 0.04 | 6 G | 14 |
| 24002-F | 20. | 1.00 | 163848 | 16 | 30003-C | 7. | 0.04 | 6 G | 14 |
| 24002-2 | 20. | 1.00 | 163848 | 18 | 30003-0 | 7. | 0.04 | 66 | 14 |
| 24003-E | 20. | 1.00 | 163848 | 16 | 30004-A | 7. | 0.04 | 56 | 14 |
| 24003-F | 20. | 1.00 | 163848 | 16 | 30004-B | 7. | 0.04 | 66 | 14 |
| 24003-2 | 20. | 1.00 | 16384B | 18 | 30004-C | 7. | 0.04 | 6G | 14 |
| 24401-E | 7. | 1.00 | 65536B | 16 | 30004-0 | 7. | 0.04 | 6 G | 14 |
| 24401-2 | 7. | 1.00 | 65536B | 18 | 30005-A | 7. | 0.02 | 3 G | 14 |
| 24402- | 7. | 1.00 | 655368 | 16 | 30005-B | 7. | 0.02 | 3 G | 14 |
| 24402-2 | 7. | 1.00 | 65536B | 18 | 30005-C | 7. | 0.02 | 3 G | 14 |
| 24403-E | 7. | 1.00 | 655368 | 16 | 30005-0 | 7. | 0.02 | 3 G | : 1 |
| 24403-2 | 7. | 1.00 | 65536B | 18 | 30006-A | 7. | 0.02 | 3 G | 14 |
| cmos |  |  |  |  | 30006-B | 7. | 0.02 | 36 | 14 |
|  |  |  |  |  | 30006-C | 7. | 0.02 | 3 G | 14 |
| 24501-V | 7. | 0.20 | 40968 | 18 | $30006-0$ $30007-A$ | 7. | 0.02 | 3 C 2 G | 14 |
| 24502-V | 7. | 0.20 | 40968 | 18 | 30007-8 | 7. | 0.01 | 2 G | 14 |
| 29101-J | 7. | 1.00 | 153848 | 24 | 30007-C | 7. | 0.01 | 2 G | 4 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ $x \times x \times x \times x$ | $\begin{aligned} & V \subset c \\ & (V .) \end{aligned}$ | $\begin{aligned} & P d \\ & (W .) \end{aligned}$ | Complexity | Np | M38510/ $x x x x x x x$ | Vec (V.) | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LSTTL |  |  |  |  | LSTTL |  |  |  |  |
| 30007-0 | 7. | 0.01 | 26 | 14 | 30201-C | 7. | 0.03 | 2 C | 14 |
| 30008-A | 7. | 0.01 | 2 G | 14 | 30201-0 | 7. | 0.03 | 2 G | 14 |
| 30008-8 | 7. | 0.01 | 2 G | 14 | 30202-A | 7. | 0.07 | 4 G | 14 |
| 30008-C | 7. | 0.01 | 2 G | 14 | 30202-8 | 7. | 0.07 | 4 G | 14 |
| 30008-3 | 7. | 0.01 | 2 G | 14 | 30202-C | 7. | 0.07 | 4 G | 14 |
| 30009-A | 7. | 0.01 | 16 | 14 | 30202-0 | 7. | 0.07 | 4 G | 14 |
| 30009-8 | 7. | 0.01 | 1 G | 14 | 30203-A | 7. | 0.07 | 46 | 14 |
| 30009-C | 7. | 0.01 | 16 | 14 | 30203-8 | 7. | 0.07 | 4 G | 14 |
| 30009-0 | 7. | 0.01 | 16 | 14 | 30203-C | 7. | 0.07 | 4 G | 14 |
| 30101-A | 7. | 0.05 | 16 G | 14 | 30203-0 | 7. | 0.07 | 4 G | 14 |
| 30101-3 | 7. | 0.05 | 16 G | 14 | 30204-A | 7. | 0.07 | 4 G | 14 |
| 30101-6 | 7. | 0.05 | 16 G | 14 | 30204-3 | 7. | 0.07 | 4 G | 14 |
| 30101-0 | 7. | 0.05 | 16 G | 14 | 30204-С | 7. | 0.07 | 4 G | 14 |
| 30102-A | 7. | 0.05 | 12 G | 14 | 30204-0 | 7. | 0.07 | 4 G | 14 |
| 30102-8 | 7. | 0.05 | 126 | 14 | 30301-A | 7. | 0.03 | 4 G | 14 |
| 30102-C | 7. | 0.05 | 126 | 14 | 30301-8 | 7. | 0.03 | 4 G | 14 |
| 30102-0 | 7. | 0.05 | 12 G | 14 | 30301-6 | 7. | 0.03 | ${ }^{4 G}$ | 14 |
| 30103-E | 7. | 0.05 | 16 G | 16 | 30301-0 | 7. | 0.03 | 4 G | 14 |
| 30103-F | 7. | 0.05 | 16G | 16 | 30302-A | 7. | 0.04 | 3 G | 14 |
| 30104-A | 7. | 0.05 | 16 G | 14 | 30302-8 | 7. | 0.04 | 3 G | 14 |
| 30104-3 | 7. | 0.05 | 16G | 14 | 30302-C | 7. | 0.04 | 3 G | 14 |
| 30104-C | 7. | 0.05 | $16 G$ | 14 | 30302-0 | 7. | 0.04 | 3 G | 14 |
| 30104-0 | 7. | 0.05 | 16 G | 14 | 30303-A | 7. | 0.07 | 4 G | 14 |
| 30105-A | 7. | 0.05 | 16 G | 14 | 30303-8 | 7. | 0.07 | $\triangle \mathrm{G}$ | 14 |
| 30105-8 | 7. | 0.05 | 16 G | 14 | 30303-C | 7. | 0.07 | 46 | 14 |
| 30105-C | 7. | 0.05 | 16 G | 14 | 30303-0 | 7. | 0.07 | 4 G | 14 |
| 30105-0 | 7. | 0.05 | 16 G | 14 | 30401-A | 7. | 0.02 | 6 G | 14 |
| 30106-E | 7. | 0.15 | 366 | 16 | 30401-3 | 7. | 0.02 | 6 G | 14 |
| 30106-F | 7. | 0.15 | 36 G | 16 | 30401-C | 7. | 0.02 | 6 G | 14 |
| 30107-E | 7. | 0.10 | 24 G | 16 | 30401-0 | 7. | 0.02 | 6G | 14 |
| 30107-F | 7. | 0.10 | 24 G | 16 | 30402-A | 7. | 0.01 | 5 G | 14 |
| 30108-A | 7. | 0.05 | 16 G | 14 | 30402-8 | 7. | 0.01 | $5 G$ | 14 |
| 30108-8 | 7. | 0.05 | 166 | 14 | 30402-C | 7. | 0.01 | 56 | 14 |
| 30108-6 | 7. | 0.05 | 16 G | 14 | 30402-0 | 7. | 0.01 | 5 G | 14 |
| 30108-0 | 7. | 0.05 | 16 G | 14 | 30501-A | 7. | 0.06 | 4 G | 14 |
| 30109-E | 7. | 0.05 | 16 G | 16 | 30501-B | 7. | 0.06 | 4 G | 14 |
| 30109-F | 7. | 0.05 | 16G | 16 | 30501-C | 7. | 0.06 | 4 G | 14 |
| 30110-E | 7. | 0.05 | 16 G | 16 | 30501-0 | 7. | 3.06 | 4 G | 14 |
| 30110-F | 7. | 0.05 | 16 G | 16 | 30502-A | 7. | 0.06 | 4 G | 14 |
| 30201-A | 7. | 0.03 | 2G | 14 | 30502-8 | 7. | 0.05 | 4 G | 14 |
| 30201-8 | 7. | 0.03 | 2 G | 14 | 30502-C | 7. | 0.06 | 4 G | 14 |

MIL-HDBK-217(REV)
MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ $x \times x \times x \times x$ | Vec (v.) | $\begin{aligned} & \text { Pd } \\ & (W .) \end{aligned}$ | Complexity | No | M38510/ <br> xXXXXXX | $\begin{aligned} & \text { vec } \\ & \text { (v.! } \end{aligned}$ | $\begin{aligned} & \text { pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LSTTL |  |  |  |  | LSTTL |  |  |  |  |
| 30502-0 | 7. | 0.06 | 4 G | 14 | 30903-E | 7. | 0.09 | $15 G$ | 16 |
| 30601-E | 7. | 0.13 | 47 G | 16 | 30903-F | 7. | 0.09 | 15G | 16 |
| 30601-F | 7. | 0.13 | 47 G | 16 | 30904-E | 7. | 0.04 | 156 | 15 |
| 30602-E | 7. | 0.12 | 41 G | 16 | 30904-F | 7. | 0.04 | 15G | 16 |
| 30602-F | 7. | 0.12 | 41 G | 16 | 30905-E | 7. | 0.07 | 17 G | 16 |
| 30603-A | 7. | 0.12 | 37 G | 14 | 30905-F | 7. | 0.07 | 176 | 16 |
| 30603-8 | 7. | 0.12 | 37 G | 14 | 30906-E | 7. | 0.11 | 156 | 16 |
| 30603-С | 7. | 0.12 | 37 G | 14 | 30906-F | 7. | 0.11 | 15 G | 16 |
| 30603-0 | 7. | 0.12 | 37 G | 14 | 30907-E | 7. | 0.11 | 15 G | 16 |
| 30604-E | 7. | 0.11 | 39 G | 15 | 30907-F | 7. | 0.11 | 156 | 16 |
| 30604-F | 7. | 0.11 | 396 | 16 | 30908-E | 7. | 0.08 | 16 G | 16 |
| 30605-A | 7. | 0.15 | 36 G | 14 | 30908-F | 7. | 0.08 | 16 G | 16 |
| 30605-8 | 7. | 0.15 | 36 G | 14 | 30909-E | 7. | 0.12 | 15 G | 16 |
| 30605-C | 7. | 0.15 | 36 G | 14 | 30909-F | 7. | 0.12 | 15G | 16 |
| 30605-0 | 7. | 0.15 | 36 G | 14 | 31001-A | 7. | 0.04 | 3 G | 14 |
| 30606-A | 7. | 0.16 | 48 G | 14 | 31001-8 | 7. | 0.04 | 3G | 14 |
| 30606-8 | 7. | 0.16 | 48 G | 14 | 31001-6 | 7. | 0.04 | 3 G | 14 |
| 30606-C | 7. | 0.16 | 48 G | 14 | 31001-0 | 7. | 0.04 | 3 G | 14 |
| 30606-0 | 7. | 0.16 | 48 G | 14 | 31002-A | 7. | 0.04 | 3G | 14 |
| 30607-E | 7. | 0.16 | 48 G | 15 | 31002-8 | 7. | 0.04 | 3 G | 14 |
| 30607-F | 7. | 0.16 | 48 G | 16 | 31002-C | 7. | 0.04 | 3 G | 14 |
| 30608-E | 7. | 0.20 | 62 G | 16 | 31002-0 | 7. | 0.04 | 3 G | 14 |
| 30608-F | 7. | 0.20 | 62 G | 16 | 31003-A | 7. | 0.02 | 2 G | 14 |
| 30609-E | 7. | 0.21 | 68 G | 16 | 31003-8 | 7. | 0.02 | 2 G | 14 |
| 30609-F | 7. | 0.21 | 68 G | 16 | 31003-¢ | 7. | 0.02 | 2 G | 14 |
| 30701-E | 7. | 0.06 | 16 G | 16 | 31003-0 | 7. | 3.02 | 2 G | 14 |
| 30701-F | 7. | 0.06 | 16 G | 16 | 31004-A | 7. | 0.04 | 4 G | 14 |
| 30702-E | 7. | 0.06 | 186 | 16 | 31004-3 | 7. | 0.04 | 4 G | 14 |
| 30702-F | 7. | 0.06 | 18 G | 16 | 31004-С | 7. | 0.05 | 4 G | 14 |
| 30703-E | 7. | 0.07 | 18 G | 16 | 31004-D | 7. | 0.05 | 4 G | 14 |
| 30703-F | 7. | 0.07 | 18G | 16 | 31005-A | 7. | 0.04 | 4 G | 14 |
| 30704-E | 7. | 0.07 | 446 | 16 | 31005-8 | 7. | 0.04 | 4 G | 14 |
| 30704-F | 7. | 0.07 | 44 G | 16 | 31005-C | 7. | 0.04 | ${ }^{4 G}$ | 14 |
| 30801-J | 7. | 0.19 | 63G | 24 | 31005-0 | 7. | 0.04 | 4 G | 14 |
| 30801-K | 7. | 0.19 | 63G | 24 | 31101-E | 7. | 0.11 | 316 | 16 |
| 30801-6 | 7. | 0.19 | 636 | 24 | 31101-F | 7. | 0.11 | 316 | 16 |
| 30801-2 | 7. | 0.19 | 636 | 24 | $31201-E$ | 7. | 0.21 | 42 G | 16 |
| 30901-E | 7. | 0.06 | 17 G | 16 | 31201-F | 7. | 0.21 | 42 G | $!5$ |
| 30901-F | 7. | 0.06 | 17 G | 16 | $31202-E$ | 7. | 0.21 | 426 | 16 |
| 30902-E | 7. | 0.06 | 16 G | 16 | 31202-5 | 7. | 0.21 | 42 G | 16 |
| 30902-F | 7. | 0.06 | 16G | 16 | 31301-A | 7. | 0.04 | 2 S | 14 |

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Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ <br> xxxxxxx | Vee (v.) | Pd (w.) | Complex | No | M385101 $x x x x x x x$ | Vec (v.) | $\begin{aligned} & \text { Pd } \\ & \left(W_{0}\right) \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LSTTL |  |  |  |  | LSTTL |  |  |  |  |
| 31301-8 | 7. | 0.04 | 26 | 14 | 31510-A | 7. | 0.08 | $26 G$ | 14 |
| 31301-6 | 7. | 0.04 | 2 G | 14 | 31510-8 | 7. | 0.08 | 266 | 14 |
| 31301-0 | 7. | 0.04 | 2 G | 14 | 31510-6 | 7. | 0.08 | 256 | 14 |
| 31302-A | 7. | 0.12 | 6G | 14 | 31510-0 | 7. | 0.08 | 266 | 14 |
| 31302-8 | 7. | 0.12 | 6G | 14 | 31511-E | 7. | 0.18 | 606 | 15 |
| 31302-C | 7. | 0.12 | 6 G | 14 | 31511-F | 7. | 0.18 | 60 G | 15 |
| 31302-0 | 7. | 0.12 | 6 G | 14 | 31512-E | 7. | 0.18 | 58G | 15 |
| 31303-A | 7. | 0.08 | 46 | 14 | 31512-F | 7. | 0.18 | 58G | 16 |
| 31303-8 | 7. | 0.08 | 4 G | 14 | 31513-E | 7. | 0.19 | 62G | 16 |
| 31303-C | 7. | 0.08 | 4 G | 14 | 31513-F | 7. | 0.19 | 62 G | 16 |
| 31303-0 | 7. | 0.08 | 4 G | 14 | 31601-E | 7. | 0.07 | 246 | 16 |
| 31401-E | 7. | 0.11 | 20 G | 16 | 31609-F | 7. | 0.07 | 246 | 16 |
| 31401-F | 7. | 0.11 | 206 | 16 | 31602-E | 7. | 0.04 | 8 G | 16 |
| 31402-E | 7. | 0.15 | 16 G | 16 | 31602-F | 7. | 0.04 | 8 G | 16 |
| 31402-F | 7. | 0.15 | 16 G | 16 | 31603-E | 7. | 0.20 | 596 | 16 |
| 31403-A | 7. | 0.06 | 10 G | 14 | 31603-F | 7. | 0.20 | 596 | 16 |
| 31403-8 | 7. | 0.06 | 106 | 14 | 31604-E | 7. | 0.07 | 246 | 15 |
| 31403-6 | 7. | 0.06 | 10 G | 14 | 31604-F | 7. | 0.07 | 24 G | 15 |
| 31403-0 | 7. | 0.06 | 10 G | 14 | 31605-E | 7. | 0.20 | 596 | 15 |
| 31501-A | 7. | 0.08 | 156 | 14 | 31605-F | 7. | 0.20 | 59G | 16 |
| 31501-3 | 7. | 0.08 | 15 G | 14 | 31801-E | 7. | 0.21 | 46 G | 16 |
| 31501-6 | 7. | 0.08 | 156 | 14 | 31801-F | 7. | 0.21 | 45 G | 16 |
| 31501-0 | 7. | 0.08 | 156 | 14 | 31901-E | 7. | 0.28 | 305 G | 16 |
| 31502-A | 7. | 0.08 | 256 | 14 | 31901-F | 7. | 0.28 | 305 G | 16 |
| 31502-8 | 7. | 0.08 | 256 | 14 | 31902-E | 7. | 0.22 | 100G | 15 |
| 31502-6 | 7. | 0.08 | 25 G | 14 | 31902-F | 7. | 0.22 | 100 G | 16 |
| 31502-0 | 7. | 0.08 | 25 G | 14 | 32001-A | 7. | 0.08 | 43 G | 14 |
| 31503-E | 7. | 0.18 | 60G | 16 | 32001-8 | 7. | 0.08 | 436 | 14 |
| 31503-F | 7. | 0.18 | 606 | 16 | 32001-¢ | 7. | 0.08 | 43 G | 14 |
| 31504-E | 7. | 0.18 | 576 | 16 | 32001-0 | 7. | 0.08 | 43 G | 14 |
| 31504-F | 7. | 0.18 | 57 G | 16 | 32002-A | 7. | 0.08 | 42 G | 14 |
| 31505-E | 7. | 0.19 | 63 G | 16 | 32002-8 | 7. | 0.08 | 42 G | 14 |
| 31505-F | 7. | 0.19 | 63 G | 16 | 32002-6 | 7. | 0.08 | 42 G | 14 |
| 31506-E | 7. | 0.19 | 60 G | 16 | 32002-0 | 7. | 0.08 | 42 G | 14 |
| 31506-F | 7. | 0.19 | 606 | 16 | 32003-A | 7. | 0.08 | 19G | 14 |
| 31507-E | 7. | 0.19 | 50 G | 16 | 32003-8 | 7. | 0.08 | 196 | 14 |
| 31507-F | 7. | 0.19 | 50 G | 16 | 32003-6 | 7. | 0.08 | 196 | 14 |
| 31508-E | 7. | 0.19 | 48 G | 16 | 32003-0 | 7. | 0.08 | 196 | 14 |
| 31508-F | 7. | 0.19 | 48 G | 16 | 32004-A | 7. | 0.08 | 25 G | 14 |
| 31509-E | 7. | 0.19 | 596 | 16 | 32004-8 | 7. | 0.08 | 25 G | 14 |
| 31509-F | 7. | 0.19 | 59 G | 15 | 32004-6 | 7. | 0.08 | 256 | 14 |

## MIL-HDBK-217(REV) <br> miCROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ <br> xxגxxxx | $\begin{aligned} & \text { Vec } \\ & \text { (v.) } \end{aligned}$ | $\begin{aligned} & \text { pd } \\ & \text { (w.) } \end{aligned}$ | Complextity | No | M38510/ <br> x $x \times x \times x \times$ | Vee (V.) | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LSTTL |  |  |  |  | LSTTL |  |  |  |  |
| 32004-0 | 7. | 0.08 | 256 | 14 | 32702-A | 7. | 0.14 | 66 G | 14 |
| 32102-A | 7. | 0.02 | 4 G | 14 | 32702-8 | 7. | 0.14 | 66G | 14 |
| 32102-8 | 7. | 0.02 | 4 G | 14 | 32702-С | 7. | 0.14 | 66G | 14 |
| 32102-C | 7. | 0.02 | 4 G | 14 | 32702-0 | 7. | 0.14 | 66G | 14 |
| 32102-0 | 7. | 0.02 | 4 G | 14 | 32703-E | 7. | 0.14 | 82 G | 16 |
| 32201-E | 7. | 0.13 | 7 F | 16 | 32703-F | 7. | 0.14 | 826 | 16 |
| 32201-F | 7. | 0.13 | 7 G | 16 | 32801-C | 7. | 0.30 | 10 G | 14 |
| 32202-E | 7. | 0.12 | 7 G | 16 | 32801-0 | 7. | 0.30 | 106 | 14 |
| 32202-F | 7. | 0.12 | 7 G | 16 | 32802-6 | 7. | 0.30 | 106 | 14 |
| 32203-E | 7. | 0.13 | 8 G | 16 | 32802-0 | 7. | 0.30 | 106 | 14 |
| 32203-F | 7. | 0.13 | 8 G | 16 | 32803-2 | 7. | 0.52 | 186 | 20 |
| 32204-E | 7. | 0.12 | 8 G | 16 | 32803-5 | 7. | 0.52 | 186 | 20 |
| 32204-F | 7. | 0.12 | 8 G | 16 | 32901-A | 7. | 0.15 | 46 G | 14 |
| 32301-6 | 7. | 0.11 | 4 G | 14 | 32901-8 | 7. | 0.15 | 46 G | 14 |
| 32301-0 | 7. | 0.11 | 4 G | 14 | 32901-6 | 7. | 0.15 | 46 G | 14 |
| 32302-C | 7. | 0.12 | 4 G | 14 | 32901-0 | 7. | 0.15 | 46 G | 14 |
| 32302-0 | 7. | 0.12 | 4G | 14 |  |  |  |  |  |
| 32401-2 | 7. | 0.28 | 10 T | 20 | ASTTL |  |  |  |  |
| 32401-5 | 7. | 0.28 | 10T | 20 |  |  |  |  |  |
| 32402-2 | 7. | 0.30 | 10T | 20 | 33001-A | 7. | 0.06 | 4 G | 14 |
| 32402-5 | 7. | 0.30 | 107 | 20 | 33001-3 | 7. | 0.06 | 4 G | 14 |
| 32403-2 | 7. | 0.30 | 109 | 20 | 33001-C | 7. | 0.06 | 4 G | 14 |
| 32403-5 | 9. | 0.30 | 107 | 20 | 33001-0 | 7. | 0.06 | 4 G | 14 |
| 32404-2 | 7. | 0.30 | 129 | 20 | 33001-x | 7. | 0.06 | 4 G | 20 |
| 32404-5 | 7. | 0.30 | 129 | 20 | 33001-Y | 7. | 0.06 | 4 G | 20 |
| 32405-2 | 7. | 0.30 | 125 | 20 | 33002-A | 7. | 0.08 | 6 G | 14 |
| 32405-5 | 7. | 0.30 | 129 | 20 | 33002-8 | 7. | 0.08 | 66 | 14 |
| 32501-2 | 7. | 0.15 | 806 | 20 | 33002-6 | 7. | 0.08 | 6 G | 14 |
| 32501-5 | 7. | 0.15 | 806 | 20 | 13002-0 | 7. | 0.08 | 6 G | 14 |
| 32502-R | 7. | 0.22 | 746 | 20 | 33002-x | 7. | 0.08 | 6 G | 20 |
| 32502-5 | 7. | 0.22 | 746 | 20 | 33002-Y | 7. | 0.08 | 6G | 20 |
| 32503-2 | 7. | 0.22 | 80 G | 20 | 33003-A | 7. | 0.04 | 3G | 14 |
| 32503-S | 7. | 0.22 | 80 G | 20 | 33003-8 | 7. | 0.04 | 3 G | 14 |
| 32504-2 | 7. | 0.15 | 906 | 20 | 33003-C | 7. | 0.04 | 3 G | 14 |
| 32504-5 | 7. | 0.15 | $90 G$ | 20 | 33003-0 | 7. | 0.04 | 3 G | 14 |
| 32601-E | 7. | 0.06 | 156 | 16 | 33003-x | 7. | 0.04 | 36 | 20 |
| 32601-F | 7. | 0.06 | 15 G | 16 | 33003-Y | 7. | 0.04 | 3 G | 20 |
| 32502-E | 7. | 0.06 | 15 G | 15 | 33004-A | 7. | 0.03 | 2 G | 14 |
| 32502-F | 7. | 0.06 | 156 | 16 | 33004-9 | 7. | 0.03 | 2 S | 14 |
| 32701-E | 7. | 0.14 | 606 | 16 | 33004-C | 7. | 0.03 | 26 | 14 |
| 32701-F | 7. | 0.14 | 606 | 16 | 33004-0 | 7. | 0.03 | 2 G | 14 |

## MIL-HDBK-217(REV) MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ $x x x x x x x$ | $\begin{aligned} & \text { vec } \\ & \text { (v.) } \end{aligned}$ | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | Np | $\begin{gathered} \text { M385 } \\ x \times x \times x \times 1 \end{gathered}$ | Vee (V.) | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ASTTL |  |  |  |  | ASTTL |  |  |  |  |
| 33004-X | 7. | 0.03 | 2 G | 20 | 33905-F | 7. | 0.13 | 176 | 16 |
| 33004-Y | 7. | 0.03 | 2 G | 20 | 33906-E | 7. | 0.13 | 156 | 16 |
| LSTTL |  |  |  |  | 33906-F | 7. | 0.13 | 156 | 16 |
|  |  |  |  |  | 33907-E | 7. | 0.14 | 156 | 15 |
| 33106-E | 7. | 0.15 | 36G | 16 | $33907-F$ $33908-E$ | 7. | 0.14 0.12 | 156 166 | 15 16 |
| 33106-F | 7. | 0.15 | 36 G | 16 | 33908-F | 7. | 0.12 | 156 | 16 |
| 33107-E | 7. | 0.10 | 246 | 15 | 34001-A | 7. | 0.07 | 46 | 14 |
| 33107-F | 7. | 0.10 | 24 G | 16 | 34001-8 | 7. | 0.07 | 4 G | 14 |
| ASTTL |  |  |  |  | 34001-C | 7. | 0.07 | 4 G | 14 |
|  |  |  |  |  | 34001-0 | 7. | 0.07 | 4 G | 14 |
| 33201-R | 7. | 0.41 | 10G | 20 | 33002-A | 7. | 0.05 | $3{ }^{3} 6$ | 14 |
| 33201-5 | 7. | 0.41 | 10 G | 20 | 34002-C | 7. | 0.05 | 3 G | 14 |
| 33202-R | 7. | 0.50 | 106 | 20 | 34002-0 | 7. | 0.05 | 3 G | 14 |
| 33202-5 | 7. | 0.50 | 10 G | 20 | 34101-A | 7. | 0.09 | 12 G | 14 |
| 33203-R | 7. | 0.50 | 10 G | 20 | 34101-3 | 7. | 0.09 | 12 G | 14 |
| 33203-5 | 7. | 0.50 | 10G | 20 | 34101-6 | 7. | 0.09 | 12 G | 14 |
| 33301-A | 7. | 0.07 | 4 G | 14 | 34101-0 | 7. | 0.09 | 12 G | $\cdot 14$ |
| 33301-8 | 7. | 0.07 | 4 G | 14 | 34102-E | 7. | 0.09 | 156 | 15 |
| 33301-6 | 7. | 0.07 | 4 G | 14 | $34102-F$ | 7. | 0.09 | 156 | 15 |
| 33301-0 | 7. | 0.07 | 4 G | 14 | 34103-E | 7. | 0.11 | 166 | 16 |
| 33401-A | 7. | 0.03 | $5 G$ | 14 | 34103-F | 7. | 0.11 | 166 | 15 |
| 33401-8 | 7. | 0.03 | 56 | 14 | 34501 -A | 7. | 0.15 | 4 G | 14 |
| 33401-6 | 7. | 0.03 | 56 | 14 | 34501-8 | 7. | 0.15 | 4 G | 14 |
| 33401-D | 7. | 0.03 | 56 | 14 | 34501-C | 7. | 0.15 | 4 G | 14 |
| 33501-A | 7. | 0.09 | 46 | 14 | 34501-0 | 7. | 0.15 | 4 G | 14 |
| 33501-3 | 7. | 0.09 | 4 G | 14 | 34501-X | 7. | 0.15 | 4 G | 23 |
| 33501-6 | 7. | 0.09 | 4 G | 14 | 34701-R | 7. | 0.18 | 256 | 20 |
| 33501-0 | 7. | 0.09 | 4 G | 14 | 34701-5 | 7. | 0.18 | 26 G | 20 |
| 33601-E | 7. | 0.25 | 47 G | 16 |  |  |  |  |  |
| 33601-F | 7. | 0.25 | 476 | 16 | LSTTL |  |  |  |  |
| 33901-E | 7. | 0.12 | 17 G | 16 |  |  |  |  |  |
| 33901-F | 7. | 0.12 | 176 | 15 | 36001-E | 7. | 0.11 | 296 | 16 |
| $33902-E$ | 7. | 0.11 | 16 G | 16 | 36001-F | 7. | 0.11 | 296 | 16 |
| 33902-F | 7. | 0.11 | 16 G | 16 | 36002-E | 7. | 0.14 | 30 G | 16 |
| 33903-E | 7. | 0.13 | 196 | 16 | 36002-F | 7. | 0.14 | 30G | 16 |
| 33903-F | 7. | 0.13 | 196 | 15 |  |  |  |  |  |
| 33904-E | 7. | 0.08 | 15 G | 16 | ALSTTL |  |  |  |  |
| 33904-F | 7. | 0.08 | 156 | 16 |  |  |  |  |  |
| $33905-\mathrm{E}$ | 7. | 0.13 | 176 | 16 | 37001-A | 7. | 0.07 | 4 G | 14 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ <br> xxxxxxx | $\begin{aligned} & \text { Vce } \\ & \text { (V.) } \end{aligned}$ | $\begin{aligned} & \mathrm{Pd} \\ & \text { (W.) } \end{aligned}$ | Complexity | Np | M38510/ <br> xxxxxxx | Vce (V.) | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | Np |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ALSTTL |  |  |  |  | ALSTTL |  |  |  |  |
| 37001-8 | 7. | 0.07 | 4 G | 14 | 37302-A | 7. | 0.07 | 36 | 14 |
| 37001-C | 7. | 0.07 | 4G | 14 | 37302-8 | 7. | 0.07 | 3 L | 14 |
| 37001-0 | 7. | 0.07 | 4 G | 14 | 37302-C | 7. | 0.07 | 3G | 14 |
| 37002-A | 7. | 0.04 | 3G | 14 | 37302-0 | 7. | 0.07 | 3G | 14 |
| 37002-8 | 7. | 0.04 | 3G | 14 | 37401-A | 7. | 0.09 | 4 G | 14 |
| 37002-C | 7. | 0.04 | 3G | 14 | 37401-3 | 7. | 0.09 | 4 G | 14 |
| 37002-0 | 7. | 0.04 | 3G | 14 | 37401-C | 7. | 0.09 | 4 G | 14 |
| 37003-A | 7. | 0.02 | 2G | 14 | 37401-0 | 7. | 0.09 | 4 G | 14 |
| 37003-8 | 7. | 0.02 | 2 G | 14 | 37402-A | 7. | 0.04 | 3 G | 14 |
| 37003-C | 7. | 0.02 | 2G | 14 | 37402-8 | 7. | 0.04 | 3 G | 14 |
| 37003-0 | 7. | 0.02 | 2 G | 14 | 37402-C | 7. | 0.04 | 36 | 14 |
| 37004-A | 7. | 0.00 | 16 | 14 | 37402-0 | 7. | 0.04 | 3G | 14 |
| 37004-8 | 7. | 0.00 | 16 | 14 | 37501-A | 7. | 0.11 | ${ }^{4} \mathrm{G}$ | 14 |
| 37004-C | 7. | 0.00 | 16 | 14 | 37501-8 | 7. | 0.11 | 46 | 14 |
| 37004-0 | 7. | 0.00 | 16 | 14 | 37501-C | 7. | 0.11 | 4G | 14 |
| 37005-E | 7. | 0.00 | 16 | 16 | 37501-0 | 7. | 0.11 | 4 G | 14 |
| 37005-F | 7. | 0.00 | 16 | 16 | 3770.1-E | 7. | 0.06 | 16G | 16 |
| 37006-A | 7. | 0.14 | 6G | 14 | 37701-F | 7. | 0.06 | 16 G | 15 |
| 37006-8 | 7. | 0.14 | 6G | 14 | 37901-K | 7. | 0.20 | 44 G | 24 |
| 37006-C | 7. | 0.14 | 6G | 14 | 37901-L | 7. | 0.20 | 44 G | 24 |
| 37006-0 | 7. | 0.14 | 6G | 14 | 38301-R | 7. | 0.14 | IOG | 23 |
| 37101-A | 7. | 0.01 | 6G | 14 | 38301-5 | 7. | 0.14 | 10G | 23 |
| 37101-8 | 7. | 0.01 | 6G | 14 | 38302-R | 7. | 0.17 | 10G | 20 |
| 37101-6 | 7. | 0.01 | 6G | 14 | 38302-5 | 7. | 0.17 | 10G | 20 |
| 37101-0 | 7. | 0.01 | 6 G | 14 | 38303-R | 7. | 0.17 | 10G | 20 |
| 37102-E | 7. | 0.01 | 8G | 15 | 38303-5 | 7. | 0.17 | 10G | 20 |
| 37102 -F | 7. | 0.01 | 8 G | 16 | 38401-A | 7. | 0.03 | 4 G | 14 |
| 37103-E | 7. | 0.01 | 8G | 16 | 38401-8 | 7. | 0.03 | 4 G | 14 |
| 37103-F | 7. | 0.01 | 8 G | 16 | 38401-C | 7. | 0.03 | 4 G | 14 |
| 37104-R | 7. | 0.02 | 42 G | 20 | 38401-0 | 7. | 0.03 | 4 G | 14 |
| 37104-5 | 7. | 0.02 | 42 G | 20 | 38402-A | 7. | 0.04 | 4 G | 14 |
| 37105-R | 7. | 0.02 | 42 G | 20 | 38402-8 | 7. | 0.04 | 4 G | 14 |
| 37105-5 | 7. | 0.02 | 42 G | 20 | 38402-C | 7. | 0.04 | 4 G | 14 |
| 37106-L | 7. | 0.02 | 62 G | 24 | 38402-0 | 7. | 0.04 | 4 G | 14 |
| 37106-K | 7. | 0.02 | 62 G | 24 | 38403-A | 7. | 0.03 | 4 G | 14 |
| 37107-L | 7. | 0.02 | 62 G | 24 | 38403-8 | 7. | 0.03 | 4 G | 14 |
| 37107-K | 7. | 0.02 | 62 G | 24 | 38403-C | 7. | 0.03 | 46 | 14 |
| 37301-A | 7. | 0.09 | 4 G | 14 | 38403-D | 7. | 0.03 | 46 | 14 |
| 37301-8 | 7. | 0.09 | 4G | 14 | 38404-A | 7. | 0.04 | 4 G | 14 |
| 37301-6 | 7. | 0.09 | 4G | 14 | 38404-3 | 7. | 0.04 | 4G | 14 |
| 37301-0 | 7. | 0.09 | 4G | 14 | 38404-C | 7. | 0.04 | 4 G | 14 |

MIL-HDBK-217(REV)
MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters

## (continued)

| M38510/ XXXXXXX | $\begin{aligned} & \text { Vce } \\ & \text { (V.) } \end{aligned}$ | $\begin{aligned} & \mathrm{Pd} \\ & (\mathrm{~W} .) \end{aligned}$ | Complexity | No | M38510/ <br> xxxxxxx | Vec (v.) | $\begin{aligned} & \mathrm{Pd} \\ & (\mathrm{~W} .) \end{aligned}$ | Complexity | Np |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| ALSTTL |  |  |  |  | ALSTTL |  |  |  |  |
| 38404-0 | 7. | 0.04 | 4 G | 14 | 38505-R | 7. | 0.35 | 18G | 20 |
| 38405-A | 7. | 0.03 | 3G | 14 | 38505-S | 7. | 0.35 | 18G | 30 |
| 38405-8 | 7. | 0.03 | 3 G | 14 | 38506-C | 7. | 0.18 | 10G | 14 |
| 38405-С | 7. | 0.03 | 3G | 14 | 38506-0 | 7. | 0.18 | 106 | 14 |
| 38405-0 | 7. | 0.03 | 3 G | 14 | 38507-6 | 7. | 0.18 | 10G | 14 |
| 38406-A | 7. | 0.03 | 3G | 14 | 38507-0 | 7. | 0.18 | 10G | 14 |
| 38406-8 | 7. | 0.03 | 36 | 14 |  |  |  |  |  |
| 38406-С | 7. | 0.03 | 36 | 14 | NMOS |  |  |  |  |
| 38406-0 | 7. | 0.03 | 3 G | 14 |  |  |  |  |  |
| 38407 - A | 7. | 0.02 | 26 | 14 | 40001-Q | 7. | 1.00 | 1300G | 40 |
| 38407-8 | 7. | 0.02 | 2G | 14 | 40201-J | 7. | 1.00 | 1024G | 24 |
| 38407-C | 7. | 0.02 | 2 G | 14 | 40301-J | 7. | 1.00 | 15384 G | 24 |
| 38407-0 | 7. | 0.02 | 2 G | 14 | 42901-9 | 20. | 1.70 | 1100 g | 40 |
| 38408-A | 7. | 0.06 | 4G | 14 |  |  |  |  |  |
| 38408-8 | 7. | 0.06 | 4 G | 14 | STLL |  |  |  |  |
| 38408-C | 7. | 0.06 | 4 G | 14 |  |  |  |  |  |
| 38408-0 | 7. | 0.06 | ${ }^{4 G}$ | 14 | 42101-3 | 7. | 0.80 | 70 G | 24 |
| 38409-A | 7. | 0.07 | 6 G | 14 | 42101-K | 7. | 0.80 | 70 G | 24 |
| 38409-3 | 7. | 0.07 | 6 G | 14 | 42101-L | 7. | 0.80 | 706 | 24 |
| 38409-C | 7. | 0.07 | ${ }^{6 G}$ | 14 | 42201-E | 7. | 0.79 | 70 G | 16 |
| 38409-0 | 7. | 0.07 | 6G | 14 | NMOS |  |  |  |  |
| 38410-A | 7. | 0.07 | 6 G | 14 |  |  |  |  |  |
| 38410-8 | 7. | 0.07 | 6G | 14 |  |  |  |  |  |
| 38410-C | 7. | 0.07 | 6G | 14 | 42301-2 | 7. | 1.20 | 120G | 29 |
| 38410-0 | 7. | 0.07 | 6 G | 14 |  |  |  |  |  |
| 38411 - | 7. | 0.08 | 6 G | 14 | LSTTL |  |  |  |  |
| 38411 -8 | 7. | 0.08 | 6 G | 14 |  |  |  |  |  |
| 38411-6 | 7. | 0.08 | 6 G | 14 | 44001-Q | 7. | 1.60 | 5376 | 40 |
| 38411-0 | 7. | 0.08 | 6 G | 14 | 44001-2 | 7. | 1.60 | 5376 | 42 |
| 38412-A | 7. | 0.08 | 6 G | 14 | 44101-T | 7. | 1.00 | 776 | 24 |
| 38412-8 | 7. | 0.08 | 6G | 14 | 44101-2 | 7. | 1.00 | 776 | 24 |
| 38412-C | 7. | 0.08 | 6 G | 14 | 44102-J | 7. | 1.00 | 856 | 24 |
| 38412-0 | 7. | 0.08 | 6 G | 14 | 44102-? | 7. | 1.00 | 856 | 24 |
| 38501-R | 7. | 0.26 | 18 G | 20 | 44103-R | 7. | 1.00 | 776 | 20 |
| 38501-S | 7. | 0.26 | 18G | 20 | 44. 33-5 | 7. | 1.00 | 776 | 20 |
| 38502-R | 7. | 0.25 | 18 G | 20 | 44104-J | 7. | 1.00 | 776 | 24 |
| 38502-S | 7. | 0.25 | 18 G | 20 | 44104-2 | 7. | 1.00 | 776 | 24 |
| 38503-R | 7. | 0.15 | 186 | 20 | 44105-J | 7. | 1.00 | 856 | 24 |
| 38503-S | 7. | 0.15 | 18 G | 20 | 44105-2 | 7. | 1.00 | 856 | 24 |
| 38504-R | 7. | 0.29 | 18G | 20 | 44106-R | 7. | 1.00 | 776 | 22 |
| 28504-S | 7. | 0.29 | 18G | 20 | 44106-5 | 7. | 1.00 | 77 G | 22 |

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-23: Microelectronic Parameters
(continued)

| M38510/ $x x x x x x x$ | $\begin{aligned} & \text { Vce } \\ & (V .) \end{aligned}$ | Pd (W.) | Complexity | No | $\begin{aligned} & \text { M38510/ } \\ & \text { Xxxxxxx } \end{aligned}$ | vec (v.) | $\begin{aligned} & \text { Pd } \\ & \text { (W.) } \end{aligned}$ | Complexity | No |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LSTTL |  |  |  |  | STTL |  |  |  |  |
| $\begin{aligned} & 44201-E \\ & 44201-F \end{aligned}$ | 7. | 0.83 | 24 G | 16 | $\begin{aligned} & 50401-R \\ & 50401-Y \\ & 50407-R \\ & 50407-Y \\ & 50501-1 \\ & 50501-3 \end{aligned}$ | 12. | 0.10 | 986 | 20 |
|  | 7. | 0.83 | 246 | 16 |  | 12. | 0.10 | 986 | 20 |
| IIL |  |  |  |  |  | 12. | 0 | 986 | 20 20 |
|  |  |  |  |  |  | 12. | 1.20 | 100G | 24 |
| 46001-Y | 6. | 0.75 | 31006 | 64 |  | 12. | 1.20 | 100G | 23 |
| cmos |  |  |  |  | NMOS |  |  |  |  |
| 47001-0 | 11. | 0.50 | 1375 G | 40 | $\begin{aligned} & 52001-Q \\ & 52001-x \\ & 52002-Q \\ & 52002-X \\ & 52003-Q \\ & 52003-X \\ & 52004-Q \\ & 52004-x \end{aligned}$ | 7. | 2.20 | 58336 | 40 |
| 47201-J | 11. | 0.50 | 4096 G | 24 |  | 7. | 2.20 | 5833 G | 19 |
| 47201 -K | 11. | 0.50 | 4096 G | 24 |  | 7. | 2.20 | 58336 | 40 |
| 47401-E | 11. | 0.50 | 27 G | 16 |  | 7. | 2.20 | 58336 | 48 |
| $47401-F$ | 11. | 0.50 | 27 G | 16 |  | 7. | 2.20 | 5833 G | 40 |
| NMOS |  |  |  |  |  | 7. | 2.20 2.20 | 58336 58336 | 48 40 |
|  |  |  |  |  |  | 7. | 2.20 | 58336 | 48 |
| $\begin{aligned} & 48001-Q \\ & 48002-Q \\ & 48003-Q \end{aligned}$ | $\begin{aligned} & 5 . \\ & 5 . \end{aligned}$$5 .$ | $\begin{aligned} & 1.00 \\ & 1.00 \\ & 1.00 \end{aligned}$ | $\begin{aligned} & 2833 G \\ & 28336 \\ & 28336 \end{aligned}$ | $\begin{aligned} & 40 \\ & 40 \\ & 40 \end{aligned}$ |  |  |  |  |  |
|  |  |  |  |  | cmos |  |  |  |  |
|  |  |  |  |  | 55001-C 65001-2 65002-C | 7. | 0.30 |  | 11 |
| STTL |  |  |  |  |  | 7. | 0.30 | 4 G | 29 |
| 50301-R 12. 2.00 34G 20 |  |  |  |  |  | 7. | 0.30 0.30 | 36 36 | 12 20 |
| 50301-Y | 12. | 2.00 | 346 | 20 | 65003-6 | 7. | 0.30 | 2 G | 11 |
| 50203-R | 12. | 2.00 | 36 G | 20 | 55003-2 | 7. | 0.30 | 2 G | 23 |
| 50302-Y | 12. | 2.00 | 36 G | 20 | 65004-C | 7. | 0.30 | 16 | 14 |
| 50303-R | 12. | 2.00 | 34 G | 20 | 65004-2 | 7. | 0.30 | 16 | 20 |
| 50303-Y | 12. | 2.00 | 34 G | 20 | 65005-C | 7. | 0.30 | 4 G | 14 |
| 50304-R | 12. | 2.00 | 34 G | 20 | 65005-2 | 7. | 0.30 | ${ }^{4} \mathrm{G}$ | 23 |
| 50304-Y | 12. | 2.00 | 34 G | 20 |  |  |  |  |  |
| 50305-R | 12. | 2.00 | 35 G | 20 |  |  |  |  |  |
| 50305-Y | 12. | 2.00 | 35 G | 20 |  |  |  |  |  |
| 50306-R | 12. | 2.00 | 346 | 20 |  |  |  |  |  |
| 50306-Y | 12. | 2.00 | 34 G | 20 |  |  |  |  |  |
| 50307-R | 12. | 2.00 | 34 G | 20 |  |  |  |  |  |
| 50307-Y | 12. | 2.00 | $34 G$ | 20 |  |  |  |  |  |
| 50308-R | 12. | 2.00 | 346 | 20 |  |  |  |  |  |
| 50208-Y | 12. | 2.00 | $34 G$ | 20 |  |  |  |  |  |
| 50309-R | 12. | 2.00 | 34 G | 20 |  |  |  |  |  |
| 50309-Y | 12. | 2.00 | 34 G | 20 |  |  |  |  |  |

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### 5.1.2.8 Example Failure Rate Calculations for Monolithic Devices.

Example One: Bipolar VLSI

Description: A custom gate array with 54,000 gates implemented in a five year old TTL bipolar process. The package is a 64-pin hermetic DIP with solder seal for use in a space application at an average case temperature of $45^{\circ} \mathrm{C}$. The device dissipates 150 mW at 5 volts, and the die size is 130,000 square mils. The part is screened to S-level quality per MIL -M-38510.

From Section 5.1.2.1, the operating failure rate model is:

$$
\begin{aligned}
& \lambda_{P}\left(t_{0}\right)=\lambda_{A C}+\lambda_{E M}\left(t_{0}\right) \\
& \lambda_{A C}=\pi_{Q}\left(C_{1} \pi_{T}+C_{2} \pi_{E}\right) \pi_{L} \\
& \text { Quality Level } \mathrm{S}: \pi_{Q}=0.71 \\
& C_{1}=0.08 \\
& T_{J}=T_{C}+\theta_{J C} \times P \\
& \\
& =45^{\circ} \mathrm{C}+\left(28^{\circ} \mathrm{C} / \mathrm{W}\right) \times 0.150 \mathrm{~W}=49.2^{\circ} \mathrm{C} \\
& \pi_{T}
\end{aligned}=0.329 \begin{aligned}
C_{2} & =0.025 \\
\pi_{E} & =0.9 \\
\pi_{L} & =0.37 \\
\lambda_{A C} & =(0.71)[(0.08)(0.32)+(0.025)(0.9](0.37) \\
& =0.0126 \text { failures } / 10^{\dot{\sigma}} \text { hours }
\end{aligned}
$$

Table 5.1.2.7-17, Note 2
Table 5.1.2.7-17

$$
\begin{aligned}
& J=.13 \mathrm{Ma} / \mathrm{cm}^{2} \quad \text { (default value) } \\
& \lambda_{E M}\left(10 \mathrm{~K} \text { hours) }=0 \text { failures } / 10^{6}\right. \text { hours } \\
& \lambda_{P}(10 \mathrm{~K} \text { hours })=0.0126 \text { failures } / 10^{6} \text { hours }
\end{aligned}
$$

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Example Two: CMOS MSI

Description: A CMOS digital timing chip (4046) in an airborne inhabited application, case temperature of $45^{\circ} \mathrm{C}, 75 \mathrm{~mW}$ power consumption at 10 volts. The device is procured with normal manufacturer's screening consisting of final electrical test, temperature cycling, B-level burn-in and seal test. The package is a 24 pin CERDIP with glass seals. The die size is $48.4 K$ square mils, has 1000 transistors, and an 800 angstrom gate oxide in a seven year old process.

From Section 5.1.2.2

Table 5.1.2.7-1

Section 5.1.2.2
Equation 5.1.2.7.4
Table 5.1.2.7-49
Table 5.1.2.7-9
Table 5.1.2.7-15
Table 5.1.2.7-3
Table 5.1.2.7-2

$$
\lambda_{p}\left(t_{0}\right)=\lambda_{A C}+\lambda_{T D D B}\left(t_{0}\right)+\lambda_{E M}\left(t_{0}\right)
$$

$$
\lambda_{A C}=\pi_{Q}\left(c_{1} \pi_{T}+c_{2} \pi_{E}\right) \pi_{L}
$$

Quality level calculated by:

$$
\text { Temp Cycling } \quad-11.6 \text { points }
$$

$$
\text { Burn-in } \quad-10.9 \text { points }
$$

$$
\text { Electrical Test - } 10.9 \text { points }
$$

$$
\text { Seal Test } \quad-7.8 \text { points }
$$

$$
\text { Total } \quad-40.7 \text { points }
$$

$$
\pi_{Q}=71.3 / 40.7=1.75
$$

$$
C_{1}=.02(1000 \text { transistors } \simeq 250 \text { gates })
$$

$$
T_{J}=T_{C}+\theta_{J C} \times P
$$

$$
=45^{\circ} \mathrm{C}+\left(28^{\circ} \mathrm{C} / \mathrm{W}\right) \times 0.075 \mathrm{~W}=47.1^{\circ} \mathrm{C}
$$

$$
\pi_{T}=0.26
$$

$$
C_{2}=0.011
$$

$$
\pi_{E}=4.4
$$

$$
\pi_{L}=0.01 \exp (5.35-0.35(Y))=0.18
$$

$$
\lambda_{A C}=(1.75)[(.02)(.26)+(.011)(4.4)](.18)
$$

$$
=0.0169 \text { failures } / 10^{6} \text { hours }
$$

$\begin{array}{ll}\text { Table 5.1.2.7-16, Note } 1 & E_{S}=.1 V_{O P} / t_{O X} \\ & V_{O P}=10 \text { volts }\end{array}$

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

Table 5.1.2.7-19
Table 5.1.2.7-18, Note 1

Table 5.1.2.7-16

$$
\begin{aligned}
& \mathrm{t}_{0 x}=1.10 \mathrm{KA} \quad \text { (worst case for } 1000 \text { transistors) } \\
& E_{S}=0.9 \mathrm{MV} / \mathrm{cm} \\
& A=\log \left(6(T R) 10^{-.58(\log (T R)-5.78)}\right) \\
& =5.39 \log {\mu m^{2}}^{2} \\
& \lambda_{T D D B}\left(10 \mathrm{~K} \text { hours) }=0.0 \text { failures } / 10^{6}\right. \text { hours } \\
& J=.13 \mathrm{Ma} / \mathrm{cm}^{2} \quad \text { (default value) } \\
& \lambda_{E M}\left(10 \mathrm{~K} \text { hours) }=0.0 \text { failures } / 10^{6}\right. \text { hours } \\
& \lambda_{P}\left(10 \mathrm{~K} \text { hours) }=0.0169 \text { failures } / 10^{6}\right. \text { hours }
\end{aligned}
$$

## Example 3: MOS Digital Microprocessor

Description: A CMOS 80386 microprocessor (three year old process) in a 124-pin pin grid array used in an office environment and screened to D-1 level. The average junction temperature is $60^{\circ} \mathrm{C}$, and average power consumption is 2 watts at 5 volts. The die size is $76 \mathrm{~K} \mathrm{mils}^{2}$ and it contains 275 K transistors.

From Section 5.1.2.3, the part failure rate model is:

$$
\begin{aligned}
& \lambda_{P}\left(t_{0}\right)=\lambda_{A C}+\lambda_{E M}\left(t_{0}\right)+\lambda_{T D D B}\left(t_{0}\right) \\
& \lambda_{A C}=\pi_{Q}\left(C_{1} \pi_{T}+C_{2} \pi_{E}\right) \pi_{L} \\
& \pi_{Q} \text { for } D-1 \text { quality level } 1=6.5 \\
& C_{1} \text { for }>16 \text { bits }=0.56 \\
& \pi_{T} \text { for } 60^{\circ} T_{J}=0.42 \\
& C_{2}(124 \text { pin PGA })=0.051 \\
& \pi_{E}=0.5 \\
& \pi_{L}=0.67 \\
& \lambda_{A C}=(6.5)[(.56)(.42)+(.051)(.5)](.67) \\
& =1.1353 \text { failures } / 10^{6} \text { hours }
\end{aligned}
$$

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Table 5.1.2.7-17
Table 5.1.2.7-17

Equation 5.1.2.7.14
Table 5.1.2.7-19

Table 5.1.2.7-18

Table 5.1.2.7-16
$\qquad$

$$
\begin{aligned}
& \mathrm{J}=.125 \mathrm{Ma} / \mathrm{cm}^{2} \quad \text { (default value) } \\
& \lambda_{E M}(10 \mathrm{~K} \text { hours })=0.0 \text { failures } / 10^{6} \text { hours }
\end{aligned}
$$

$$
E_{S}=.1 V_{O p} / t_{o x}
$$

$$
t_{o x}=10^{-0.405(\log (T R)-3.68)}
$$

$$
=1.931 \mathrm{KA}
$$

$$
E_{S}=2.59 \mathrm{Mv} / \mathrm{cm}_{7}
$$

$$
A=\log \left(4(T R)^{-.774(\log (T R)-5.5)}\right)
$$

$$
=6.09 \log \mu \mathrm{~m}^{2}
$$

$$
\lambda_{T D D B}(10 \mathrm{~K} \text { hours })=0.0
$$

$$
\lambda_{P}(10 \mathrm{~K} \text { hours })=1.1353 \text { failures } / 10^{6} \text { hours }
$$

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## Example Four:

Description: A 128 K FLOTOX EEPROM that is expected to have a $\mathrm{T}_{\mathrm{j}}$ of $80^{\circ} \mathrm{C}$, and experience 10000 read/write cycles during its lifetime. The part is exposed to an operating voltage of 5 v , is " $B$ " level quality, and has been in production for three years. It is packaged in a hermetic 28 pin DIP (glass seal), and will operate in an uninhabited aircraft environment.

1) Determine the Electromigration failure rate ( $\lambda_{E M}$ ) from Table 5.1.2.7-17. Using the default value of $.125 \mathrm{MA} / \mathrm{cm}^{2}$ yields a failure rate of $\underline{0}$ for $90^{\circ} \mathrm{C}$.
2) Determine $\lambda_{T D D B}$ :

Obtain the oxide area value from Table 5.1.2.7-20. Choosing the most conservative value (largest area) yields $1,209,000 \mu^{2}$ (6.1 Log $\mu m^{2}$ ).
Obtain the gate oxide thickness from Table 5.1.2.7-21. Choosing the most conservative value (smallest thickness) yields 340 Angstroms, or $340 \times 10^{-8} \mathrm{~cm}$.
Determine the field stress by dividing the operating voltage by the oxide thickness. The result is $1.5 \mathrm{MV} / \mathrm{cm}$.

Determine the $\lambda_{\text {TDDB }}$ by referring to Table 5.l.2.7-16 (estimate using the $6.0 \log \mu^{2}$ table). The result is $\underline{0}$.
3) Determine the defect failure rate $C_{1} \pi_{T}$ Refer to section 5.1.2.3.2 for $C_{1}$. Checking the appropriate table provides a value of .00339 for a 128K EEPROM.
Refer to Table 5.1.2.7-10 for $\pi_{T}$. This equals 12.73 for $80^{\circ} \mathrm{C}$ The total defect failure rate is (.00339)(12.73) $=\underline{0.0432}$.
4) Determine $\lambda_{c y c}$

For a Flotox device, we need only consider the $A_{1} B_{1}$ term

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Refer to Table 5.1.2.4-4. For a Flotox device that will be reprogrammed 10000 times, the $A_{1}$ value is .0682
Refer to Table 5.1.2.4-6. For $80^{\circ} \mathrm{C}$ and a 128 K device, $\mathrm{B}_{1}=3.7977$
$\lambda_{c y c}=(.0682)(3.7977)=\underline{.2590}$
5) Determine $C_{2}$ value from 5.1.2.7-15. For a hermetic 28 pin DIP, the value is . 014
6) Determine the $\pi_{E}$ value from Table 5.1.2.7-3. $\pi_{E}$ is $\underline{5.5}$ for an uninhabited aircraft environment.
7) Determine $\pi_{Q}$ from Table 5.1.2.7-1. $\pi_{Q}=\underline{1.0}$ for a "B" level part
8) Determine $\pi_{L}$ from Table 5.1.2.7-2. $\pi_{L}=\underline{0.67}$
9) Determine the total device failure rate:

$$
\begin{aligned}
\lambda_{P} & =\left[\left(C_{1}\right)\left(\pi_{T}\right)+\lambda_{C y C}+\left(C_{2}\right)\left(\pi_{E}\right)\right]\left(\pi_{Q}\right)\left(\pi_{L}\right)+\lambda_{T D D B}+\lambda_{E M} \\
& =[(.0432)+(.2590)+(.077)](1.0)(0.67)+0+0 \\
& =.2541 \text { Failures Per Million Hours }
\end{aligned}
$$

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## Example Five:

Description: A 64K MOS SRAM "D" level quality part, has been in production for 2 years, has an operating voltage of 5 v , and is expected to operate at a $T_{j}$ of $90^{\circ} \mathrm{C}$. It is packaged in a hermetic 24 pin DIP (glass seal), and will operate in an uninhabited aircraft environment.

1) Determine the Electromigration failure rate $\left(\lambda_{E M}\right)$ from Table 5.1.2.7-17. Using the default value of $.125 \mathrm{MA} / \mathrm{cm}^{2}$ yields a failure rate of $\underline{0}$ for $90^{\circ} \mathrm{C}$.
2) Determine $\lambda_{T D D B}$ :

Obtain the oxide area value from Table 5.1.2.7-20. Choosing the most conservative value (largest area) yields $2,482,600 \mu \mathrm{~m}^{2}$ (6.4 Log $\mu m^{2}$ )
Obtain the gate oxide thickness from Table 5.1.2.7-21. Choosing the most conservative value (smallest thickness) yields 250 Angstroms, or $250 \times 10^{-8} \mathrm{~cm}$
Determine the field stress by dividing the operating voltage by the oxide thickness. The result is $2.0 \mathrm{MV} / \mathrm{cm}$
Determine the $\lambda_{T D D B}$ by referring to Table 5.1.2.7-16 (estimate using the $6.5 \log \mu \mathrm{~m}^{2}$ table). The result is $\underline{0}$.
3) Determine the defect failure rate $C_{1} \pi_{T}$

Refer to Table 5.1.2.4-1 for $C_{1}$. Checking the appropriate table provides a value of .0105 for a 64 K SRAM Refer to Table 5.1.2.7-10 for $\pi_{T}$. This equals 26.25 for $90^{\circ} \mathrm{C}$ The total defect failure rate is $(.0105)(26.25)=\underline{0.2756}$
4) $\lambda_{\mathrm{CYC}}$ value is $\underline{0}$.

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5) Determine $C_{2}$ value from 5.1.2.7-15. For a hermetic 24 pin DIP, the value is . 011
6) Determine the $\pi_{E}$ value from 5.1.2.7-3. $\pi_{E}$ is $\underline{5.5}$ for an uninhabited aircraft environment.
7) Determine $\pi_{Q}$ from Table 5.1.2.7-1. $\pi_{Q}=\underline{3.3}$ for a "D" level part
8) Determine $\pi_{L}$ from Table 5.1.2.7-2. $\pi_{L}=\underline{1.05}$
9) Determine the total device failure rate:
$\lambda_{P}=\left[\left(C_{1}\right)\left(\pi_{T}\right)+\lambda_{C y C}+\left(C_{2}\right)\left(\pi_{E}\right)\right]\left(\pi_{Q}\right)\left(\pi_{L}\right)+\lambda_{T D O B}+\lambda_{E M}$
$=[(.2756)+(0)+(.0605)](3.3)(1.05)+0+0$
$=1.1646$ Failures Per Million Hours

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## Example Six: PAL

Description: A data book shows a PAL to have 150 gates, and 24 pins. The operating junction temperature is $100^{\circ} \mathrm{C}$, and operates in a ground benign environment. It is "B" Level Quality, and has been in production for four years. It is hermetically packaged in a DIP with a glass seal.

1) Determine the electromigration failure rate ( $\lambda_{E M}$ ) from Table 5.1.2.7-17. Using the default value of $.125 \mathrm{~mA} / \mathrm{cm}^{2}$ yields a failure rate of $\underline{0}$ for $100^{\circ} \mathrm{C}$.
2) $\lambda_{T D D B}=\underline{0}$
3) Determine the defect failure rate $C_{1} \pi_{T}$. Refer to Table 5.1.2.4-1 for $C_{1} . C_{1}=0.01047$ for a 150 gate PAL. Refer to Table 5.1.2.7-10 for $\pi_{T} . \quad \pi_{T}=52.05$ at $100^{\circ} \mathrm{C}$. The total defect failure rate is (.01047)(52.05) $=.5450$
4) $\lambda_{\mathrm{CYC}}=\underline{0}$
5) Determine the $C_{2}$ value from Table 5.1.2.7-15 for a hermetic 24 pin DIP, $C_{2}=.011$.
6) Determine $\pi_{E}$ from Table 5.1.2.7-3. $\pi_{E}=0.5$ for a ground benign environment.
7) Determine $\pi_{Q}$ from Table 5.1.2.7-1. $\pi_{Q}=1.0$
8) Determine $\pi L$ from Table 5.1.2.7-2. $\pi L=0.52$
9) Determine total device failure rate.

$$
\begin{aligned}
\lambda_{P} & =\left[\left(C_{1}\right)\left(\pi_{T}\right)+\lambda_{C Y C}+\left(C_{2}\right)\left(\pi_{E}\right)\right]\left(\pi_{Q}\right)\left(\pi_{L}\right)+\lambda_{T D D B}+\lambda_{E M} \\
& =[(.5450)+0+(.011)(0.5)](1.0)(0.52)+0+0 \\
& =.2863 \text { Failures Per Million Hours }
\end{aligned}
$$

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## Example Seven: Gas Digital

Description: 10G000A Quad 3 Input Nor Gate, SSI, $P_{D}=875 \mathrm{mw}, 36$ II LCD package, maximum ${ }^{\top} \mathrm{CH}=125^{\circ} \mathrm{C}$ in a ground benign environment. The process is three years old and the device is a B-level part.

$$
\pi T A=0.1 e^{-16220\left(\frac{1}{125+273}-\frac{1}{423}\right)}=8.994 \times 10^{-3}
$$

Table 5.1.2.7-13

$$
\begin{aligned}
& \text { Table 5.1.2.7-14 } \quad \pi T P=0.1 e^{-4980}\left(\frac{1}{125+273}-\frac{1}{423}\right) \\
& \text { Table 5.1.2.7-15 } C_{2}=0.013 \\
& \text { Table 5.1.2.7-3 } \pi_{E}=0.5 \\
& \text { Table 5.1.2.7-1 } \pi_{Q}=1.0 \\
& \text { Table 5.1.2.7-2 } \pi_{L}=0.67 \\
& \text { Table 5.1.2.5-1 } C_{1 A}=25.3 \\
& \text { Table 5.1.2.5-1 } C_{1 P}=0.687 \\
& \begin{aligned}
\lambda_{D}=\left[\left(C_{1 A} \pi_{T A}+C_{1 P} \pi_{T P}+C_{2} \pi_{E}\right] \pi_{Q} \pi_{L}(\text { From Section } 5.1 .2 .5)\right. \\
=\left[25.3\left(8.994 \times 10^{-3}\right)+0.687\left(4.773 \times 10^{-2}\right)+0.013(0.5)\right](1.0)(0.67) \\
=.1788 \text { failures } / 10^{6} \text { hours }
\end{aligned}
\end{aligned}
$$

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Example Eight: GaAs MMIC

Description: MA4GM212 SPDT Switch, DC-12 GHz, 4 transistors, 4 inductors, 4 resistors, Maximum Input $P_{D}=30 \mathrm{dbm}, 4$ pin hermetic can, Maximum $T_{C H}=$ $145^{\circ} \mathrm{C}$ in a ground benign environment. The process is three years old and the device is a B-level part.

$$
-17380\left(\frac{1}{145+273}-\frac{1}{423}\right)=6.117 \times 10^{-2}
$$

$$
\begin{aligned}
& \text { Table } 5.1 .2 .7-14) \quad \pi T P=0.1 \mathrm{le} \quad \overline{145+273 \quad 423}=8.686 \times 10^{-2} \\
& \text { Table } 5.1 .2 .7-15 C_{2}=0.0005 \\
& \text { Table } 5.1 .2 .7-3 \quad \pi_{E}=0.5 \\
& \text { Table } 5.1 .2 .7-1 \quad \pi_{Q}=1.0 \\
& \text { Table } 5.1 .2 .7-2 \quad \pi_{L}=0.67 \\
& \text { Table } 5.1 .2 .6-2 \quad \pi_{A}=3.0 \\
& \text { Table } 5.1 .2 .6-1 \quad C_{1 A}=4.51 \\
& \text { Table } 5.1 .2 .6-1 \quad C_{1 P}=2.26 \\
& \begin{aligned}
\lambda_{M} & =\left[\left(C_{1 A} \pi T A+C_{1 P} \pi T P\right) \pi A+C_{2} \pi E\right] \pi L \pi_{Q}(\text { From Section 5.1.2.6) } \\
& =\left[\left\{4.51\left(6.117 \times 10^{-2}\right)+2.26\left(8.686 \times 10^{-2}\right)\right\} 3.0+0.5(0.0005)\right] 0.67(1) \\
= & .9492 \text { failures/106 hours }
\end{aligned}
\end{aligned}
$$

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### 5.1.2.9 Hybrid Microcircuits

The hybrid failure rate model is:

$$
\lambda_{P}=\left[\varepsilon \lambda_{C} N_{C}\left(1+.2 \pi_{E}\right)\right] \pi_{Q} \pi_{L} \pi_{F}
$$

where:
$\lambda_{p}$ is the hybrid failure rate in failures $/ 10^{6}$ hours
$N_{C}$ is the number of each particular component
$\lambda_{C}$ is the specific component failure rate
$\pi_{L}$ is the experience (learning factor) from Table 5.1.2.7-2
$\pi_{F}$ is the circuit function factor from Table 5.1.2.9-1
$\pi_{Q}$ is the quality factor from Table 5.1.2.7-1
$\pi_{E}$ is the environmental factor from Table 5.1.2.7-3

### 5.1.2.9.1 Active Components and Capacitors

The sum of the adjusted failure rates for the active components and capacitors shall be calculated as follows:
$N_{C}$ is the number of each particular component
${ }^{\lambda} C$ is the failure rate contribution for a particular component predicted using the correct model from the following sections in this handbook:

```
                Integrated Circuits Section 5.1.2
```

                Discrete Semiconductors Section 5.1.3
                Capacitor
                    Section 5.1.7
    Note: Inductor and Resistor failure rates are insignificant and are not included.

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When calculating $\lambda_{C}$ for integrated circuits, use quality factor "B". For discrete semiconductors, use quality factor "JANTXV." For capacitors, use quality factor level "M." Use the environmental factor corresponding to the application environment of the hybrid, and assume a component ambient temperature equal to the temperature of the hybrid package. For IC dice let $\mathrm{C} 2=0$ when calculating $\lambda_{C}$.

If the maximum rated stress for a die is unknown, it shall be assumed to be the same as that for a discretely packaged die of the same type. If the same die has several ratings based on the discrete package type, the lower value will be assumed. Power rating used should be based on case temperatúre for discrete semiconductors.

Table 5.1.2.9-1
Circuit Function Factor

| TYPE | $\pi F$ |
| :---: | :---: |
| Digital |  |
| Video, $10 \mathrm{MHz}<\mathrm{f}<1 \mathrm{GHz}$ | 1.0 |
| Microwave, $\mathrm{f}<\mathrm{GHz}$ | 1.2 |
| Linear, f $<10 \mathrm{MHz}$ | 2.6 |
| Power | 5.8 |

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## 5.l.2.9.2 Chip Junction Temperature Calculation

A hybrid is normally made up of one or more substrate assemblies mounted within a sealed package. Each substrate assembly consists of active and passive chips with thick or thin film metallization mounted on the substrate, which in turn may have multiple layers of metallization and dielectric on the surface. Figure 5.1.2.9-1 is a cross-sectional view of a hybrid with a single multi-layered substrate. The layers within the hybrid are made up of various materials with different thermal characteristics. Table 5.1.2.9-2 provides a list of commonly used hybrid materials with typical thicknesses and corresponding thermal conductivities (K). The thermal resistance of each layer is determined by the expression,
$\theta=(1 / K)(L / A)$, where:
$\theta$ is the thermal resistance of a layer in ${ }^{\circ} \mathrm{C} /$ Watt $\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right)$
$K$ is the thermal conductivity of the material in watts $/{ }^{\circ} \mathrm{C}$-in
$L$ is the material thickness in inches from Table 5.1.2.9-2 (or user provided)
$A$ is the top surface area of the chip (user provided or estimated by the following expression:

$$
\begin{equation*}
A=\left[27.8\left(1.5 \times 10^{-3}+10^{-4} \mathrm{p}\right)\right]^{2} \text { (square inches), } \tag{5.1.2.9.1}
\end{equation*}
$$

where $P$ is the number of active device pin/wire terminals)

An estimated thermal resistance value for junction to case ( $\theta_{J C}$ ) can be developed for each chip in the hybrid by summing the resistances of all the material layers of the hybrid structure from the chip down to the case:

where $n$ is the number of material layers. Then,

$$
\begin{equation*}
T_{J}=T_{C}+0.9\left(\theta_{J C}\right)\left(P_{D}\right) \text {, where } \tag{5.1.2.9.3}
\end{equation*}
$$

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

$T_{j}$ is the junction temperature of the chip $\left({ }^{\circ} \mathrm{C}\right)$
${ }^{\top} C$ is the case temperature of the hybrid ( ${ }^{\circ} \mathrm{C}$ )
$\theta_{J C}$ is defined as above ( $\left.{ }^{\circ} \mathrm{C} / \mathrm{W}\right)$, and
$P_{D}$ is the power dissipated by the chip ( $W$ )

The factor of 0.9 in equation 5.1.2.9.3 represents the cosine of $26^{\circ}$. This angle accounts for the fact that the heat is not all conducted vertically from the chip to the case, but rather "spreads" radially as well as downward.

Table 5.1.2.9-2 Hybrid Materials

| MATERIAL |  | TYPICAL | FEATURE FROM \| | $k$ |
| :---: | :---: | :---: | :---: | :---: |
|  | TYPICAL USAGE | THICKNESS (") | FIG. 5.1.2.9-1 | ( $\mathrm{W} /{ }^{\circ} \mathrm{C}$-in) |
|  |  |  | 1 \| |  |
| Silicon | chip device | 0.01 | A | 2.20 |
| GaAs | chip device | 0.007 | A | 0.76 |
| Au Eutectic | chip attach | 0.0001 | B | 6.91 |
| Solder | chip/substrate attach | 0.003 | B/E | 1.27 |
| Epoxy (diel) | chip/substrate attach | 0.0035 | $B / E$ | 0.006 |
| Epoxy |  |  |  |  |
| (Conductive) | chip attach | 0.0035 | B | 0.15 |
| Thick film | glass insulating | 0.003 | C | 0.66 |
| dielectric | layer |  | 1 |  |
| Alumina | Substrate, MHP | 0.025 | D | 0.64 |
| Be0 | Substrate, PHP | 0.025 | D | 6.58 |
| Kovar | Case, MHP | 0.02 | F | 0.425 |
| Aluminum | Case, MHP | 0.02 | F | 4.58 |
| Copper | Case, PHP | 0.02 | F | 9.96 |

If the hybrid internal structure cannot be determined, use the following default values for the temperature rise from case to junction: microcircuits, $10^{\circ} \mathrm{C}$; transistors, $25^{\circ} \mathrm{C}$; diodes, $20^{\circ} \mathrm{C}$. Assume capacitors are at ${ }^{\top} \mathrm{C}$.

MIL-HDBK-217(REV)<br>MICROELECTRONIC DEVICES

Figure 5.1.2.9-1


## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

### 5.1.2.9.3 Example Failure Rate Calculations for a Hybrid Device.

Microcircuit Description: Driver, Linear MHP in a hermetically sealed Kovar package. The substrate is alumina and there are two dielectric layers. The die- and substrate- attach materials are conductive epoxy and solder, respectively.

Active Components: 1 - LM106
1- LM741A
2 - Si NPN Transistor, $60 \%$ stress ratio (power and voltage), linear application < 1 watt. 2 - Si PNP Transistor, $60 \%$ stress ratio (power and voltage), linear application < 1 watt.

2 - Si General Purpose Diodes, $60 \%$ stress ratio (power and voltage), small signal, metallurgically bonded.
Passive Components: 2 - Ceramic Chip Capacitors, $60 \%$ stress ratio, 1000 pf. 17 - Thick Film Resistors
Environment: Naval Unsheltered, $65^{\circ} \mathrm{C}$ package case temperature Maturity: $\quad 2.1$ Years in production, $\pi_{L}=1.0$

Screened to MIL-STD-883, Method 5008, in accordance with Appendix $G$ to MIL-M-38510. From Table 5.1.2.7-1, $\pi_{Q}=1.0$

## Example Calculation:

1. Calculate Active Device Junction Temperatures.

Since all chips are silicon, $\sum_{i=1}^{n} L_{i} / K_{i}$ is the same for each. From Table 5.1.2.9-2,

| MIL-HDBK-217(REV) |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| MICROELECTRONIC DEVICES |  |  |  |  |  |
| Layer | $L_{i} / \underline{K}$ |  | ${ }^{\circ} \mathrm{C}$-in |  |  |
| Chip | 0.01 | 2.20 | $=.00$ |  |  |
| Epoxy (Cond) | 0.00 | 5/0.15 | $=.02$ |  |  |
| Dielectric(2) | (2) | .003/0.6 | $=.00$ |  |  |
| Substrate | 0.02 | 10.64 | $=.03$ |  |  |
| Solder | 0.00 | 11.27 | $=.002$ |  |  |
| Kovar case | 0.02 | 0.425 | $=.04$ |  |  |
| Total |  |  | $=.12$ |  |  |
|  | LM106 | LM741A | SINPN | SiPNP | SIDIODE |
| No. Pins from Tables |  |  |  |  |  |
| $P_{D}(\max ) \text { from }$ |  |  |  |  |  |
| Area of Chip (sq. in.) |  |  |  |  |  |
| $\theta_{J C}\left({ }^{\circ} \mathrm{C} / \mathrm{W}\right) \text {, from }$ |  |  |  |  |  |
| $T_{j}\left({ }^{\circ} \mathrm{C}\right)$ from |  |  |  |  |  |
| culate Failure Rates. |  |  |  |  |  |
| $\lambda_{P}=\left[\sum N_{C} \lambda_{C}\left(1+.2 \pi_{E}\right)\right] \pi_{Q} \pi_{L} \pi_{F}$ |  |  |  |  |  |
| die, 13 transistors, page 5.1.2.2-1: |  |  |  |  |  |
| $\pi_{Q}\left[C_{1} \pi_{T}+C_{2} \pi_{E}\right] \pi_{L}$ |  |  |  |  |  |

2. Calculate Failure Rates.

$$
\lambda_{P}=\left[\Sigma N_{C} \lambda_{C}\left(1+.2 \pi_{E}\right)\right] \pi_{Q} \pi_{L} \pi_{F}
$$

Failure Rates for Components ( $\lambda_{C}$ ):
LM106 die, 13 transistors, page 5.1.2.2-1:

$$
\begin{aligned}
& \pi_{Q}\left[C_{1} \pi_{T}+C_{2} \pi_{E}\right] \pi_{L} \\
& 1.0[(0.01 \times 3.6)+(0 \times 5.7)] 1=\underline{0.036}
\end{aligned}
$$

## MIL-HDBK-217(REV) <br> MICROELECTRONIC DEVICES

LM741A die, 23 transistors, page 5.1.2.2-1 (same model as LM106 above):
$1.0[(0.01 \times 2.9)+(0 \times 5.7)] 1=0.029$
Si NPN transistor die, $60 \%$ stress ratio, Section 5.1.3, where $\mathrm{T}+\Delta \mathrm{T}(\mathrm{S})=92.1^{\circ} \mathrm{C}$ :

$$
\begin{aligned}
& \lambda_{b}\left(\pi E E^{\pi} A^{\pi} Q^{\pi} R^{\pi} S 2 \pi C\right) \\
& (.0019)(21)(1.5)(0.12)(1.0)(0.88)(1.0)=0.0063
\end{aligned}
$$

Si PNP transistor die, $60 \%$ stress ratio, Section 5.1.3: (same model as NPN transistor above):

$$
(.0018)(21)(1.5)(0.12)(1.0)(0.88)(1.0)=0.0060
$$

Si general purpose diode die, $60 \%$ stress ratio, Section 5.l.3 where $T+\Delta T(S)=84.3^{\circ} \mathrm{C}:$

$$
\begin{aligned}
& \lambda_{b}\left(\pi E \pi Q^{\pi} R \pi A \pi S 2 \pi C\right) \\
& (.0005)(21)(.15)(1.0)(1.0)(0.7)(1.0)=0.0011
\end{aligned}
$$

Ceramic chip capacitor, $60 \%$ stress ratio, 1000 pf., Section 5.1.3, where $\mathrm{T}=65^{\circ} \mathrm{C}$ case temperature:

$$
\begin{aligned}
& \lambda_{b}\left(\pi E^{\pi} Q^{\pi} C V\right) \\
& (.0063)(12.4)(1.0)(1.0)=\underline{0.075}
\end{aligned}
$$

$\pi_{E}=5.7$, Table 5.1.2.7-3
$\pi_{Q}=1.0$, Table 5.1.2.7-1
$\pi_{L}=1.0$, Table 5.1.2.7-2
$\pi_{F}=5.8$, Table 5.1.2.9-1

$$
\begin{aligned}
\lambda_{P}= & \{[.36+.029+2(.0063)+2(.0060)+2(.0011)+2(.075)] \\
& {[1+(.2)(5.7)\}(1.0)(1.0)(5.8) } \\
= & 3.00 \text { failures } / 10^{6} \text { nours }
\end{aligned}
$$

## MICROELECTRONIC DEVICES

5.1.2.10 Magnetic Bubble Memories*. The magnetic bubble memory device in its present form is a non-hermetic assembly of two major structural segments:
a. A basic bubble chip or die consisting of a memory or a storage area (e.g., an array of minor loops), and required control and detection alements (e.g., generators, various gates and detectors), and,
b. A magnetic structure to provide controlled magnetic fields consisting of permanent magnets, coils, and a housing.

These two structural segments of the device are interconnected by a mechanical substrate and lead frame. The interconnect substrate in the present technology is normally a printed circuit board. It should be noted that this model does not include external support microelectronic devices require for magnetic bubble memory operation. The general form of the operating failure rate model is:

$$
\lambda_{p}=\lambda_{1}+\lambda_{2}
$$

where:
$\lambda_{p}=$ operating failure rate in failures $/ 10^{6} \mathrm{hrs}$.
$\lambda_{1}=$ failure rate of the control and detection structure.
$\lambda_{2}=$ failure rate of the memory storage area.
*See Bibliography Item No. 60

## MIL-HDBK-217E

MICROELECTRONIC DEVICES
5.1.2.10.1 Failure Rate of the Control and Detection Structure $\left(\lambda_{1}\right)$.

The expansion of $\lambda_{1}$ is:

$$
\lambda_{1}=\pi_{Q}\left[{ }_{N} C^{C} 11 \pi_{T 1} \pi_{W}+\left(N_{C} C_{21}+C_{2}\right) \pi_{E}\right] \pi_{D} \pi_{L}
$$

where:
$\pi_{Q}=q u a l i t y$ factor, Table 5.1.2.7-1
$N_{C}=$ number of bubble chips per packaged device
$C_{11} \& C_{21}=$ device complexity failure rates for the control and detection elements, Table 5.1.2.10-1
$C_{2}=$ package complexity failure rate, Table 5.1.2.7-16
$\pi T_{1}=$ temperature acceleration factor. Use the values in Table 5.1.2.7-12. Use $T_{J}=T_{\text {CASE }}+10$ (all in ${ }^{\circ} \mathrm{C}$.)
$\pi_{W}=$ write duty cycle factor, Table 5.1.2.10-4
$\pi_{\dot{E}}=$ application environment factor Table 5.1.2.7-3
$\pi_{D}=$ duty cycle factor, Table 5.1.2.10-3
$\pi_{b}=$ device learning factor, Table 5.1.2.7-2. Because this is a relatively new technology, justification should be given for use of $\pi_{L}=1$.
5.1.2.10.2 Failure Rate of the Memory Storage Area $\left(\lambda_{2}\right)$.

The expansion of $\lambda_{2}$ is:

$$
\lambda_{2}=\pi_{Q}^{N} C\left(C_{12 \pi^{2} T 2}+C_{22 \pi_{E}}\right) \pi_{L}
$$

where:

$$
\begin{aligned}
& \pi_{Q}=q u a l i t y \text { factor, Table 5.1.2.7-1 } \\
& N_{C}=\text { number of bubble chips per packaged device } \\
& C_{12} \& C_{22}=\text { device complexity failure rates Table } \\
& \text { 5.9.2.10-2. } \\
& \pi_{2}=\text { temperature acceleration factor. Use the values in } \\
& \text { Table 5.1.2.7-8. Use } T_{J}=T_{\text {CASE }}+10\left(\text { all in }{ }^{\circ} \mathrm{C}_{\mathrm{C}}\right)
\end{aligned}
$$

## MIL-HDBK-217E

## MICROELECTRONIC DEVICES

$\pi_{E}=$ application environment factor, Table 5.1.2.7-3
$\pi_{1}=$ device learning factor, Table 5.1.2.7-2. Because this is a relatively new technology, justification should be given for use of $\pi_{L}=1$.

TABLE 5.1.2.10-1: $C_{1} \& C_{2}$, DEVICE COMPLEXITY FAILURE RATES FOR CONTROL \& OETECTION STRUCTURE IN MAGNETIC BUBBLE DEVICES IN FAILURES PER $10^{\circ}$ HOURS.

| $N_{1}$ | $C_{11}$ | $C_{21}$ | $N_{1}$ | $C_{11}$ | $C_{21}$ |
| ---: | :--- | :--- | :--- | :--- | :--- |
| 4 | .0017 | .00014 | 500 | .011 | .00041 |
| 50 | .0045 | .00024 | 550 | .012 | .00042 |
| 100 | .0060 | .00028 | 600 | .012 | .00042 |
| 150 | .0070 | .00031 | 650 | .013 | .00043 |
| 200 | .0079 | .00033 | 700 | .013 | .00044 |
| 250 | .0086 | .00035 | 750 | .013 | .00045 |
| 300 | .0093 | .00036 | 800 | .014 | .00046 |
| 350 | .0099 | .00038 | 850 | .014 | .00046 |
| 400 | .010 | .00039 | 900 | .014 | .00047 |
| 450 | .011 | .00040 | 950 | .015 | .00047 |
|  |  |  | 1000 | .015 | .00048 |

Tabulated values are determined from the following equations:

$$
c_{11}=.00095\left(N_{1}\right)^{.40} \& C_{21}=.0001\left(N_{1}\right) .226
$$

where:
$N_{1}=$ the number of dissipative elements on a chip (gates, detectors, generators, etc.) and is $\leq 1000$.

## MICROELECTRONIC DEVICES

TABLE 5.1.2.10-2: $C_{12} \& C_{22}$ DEVICE COMPLEXITY FAILURE RATES FQR MEMORY storage structure for magnetic bubble devices in failures per $10^{6}$ hours.

| NO. BITS <br> IN $\left(10^{3}\right)$ | $C_{12}$ | $C_{22}$ | NO. BIT§ |  |  |
| :---: | :--- | :--- | :---: | :--- | :--- |
| IN $(10)^{3}$ | $C_{12}$ | $C_{22}$ |  |  |  |
| 66 | .0020 | .00028 | 1049 | .0045 | .00064 |
| 92 | .0022 | .00031 | 2097 | .0055 | .00079 |
| 131 | .0024 | .00035 | 4194 | .0068 | .00097 |
| 262 | .0030 | .00042 | 8389 | .0084 | .0012 |
| 524 | .0036 | .00052 |  |  |  |

Tabulated values are determined from the following equations:

$$
C_{12}=.00007\left(N_{2}\right) \cdot 3 \& C_{22}=.00001\left(N_{2}\right) \cdot 3
$$

where:

$$
N_{2}=\text { the number of bits and is } \leq 9(10)^{6} \text {. }
$$

TABLE 5.1.2.10-3: $\pi_{0}$, DUTY CYCLE FACTOR, FOR MAGNETIC BUBBLE DEVICES

| $\mathrm{D} \star$ | 0 | .1 | .2 | .3 | .4 | .5 | .6 | .7 | .8 | .9 | 1.0 |
| :--- | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| $\pi_{\mathrm{D}}$ | .10 | .19 | .28 | .37 | .46 | .55 | .64 | .73 | .82 | .91 | 1.0 |

*     - The tabulated values are determined from

$$
\pi_{0}=.90+0.1 \text { for } 0 \leq D \leq 1.0
$$

$D$ is the device duty cycle and is application dependent. It is a function of the usage the bubble device experiences during the time the power is applied to the equipment using the device.

Average device data rate for the application $D=$ $\qquad$ $\leq 1$.
manufacturer's maximum rated data-rate
where: the application data rate is averaged over the time that the power is applied to the using equipment.

## MIL-HDBX-217E <br> microelectronic devices

TABLE 5.1.2.10-4. $\pi_{\text {M }}$, WRITE-DUTY CYCLE FACTOR FOR MAGNETIC BUBBLE DEVICES.

| 0 |  |  | R/W |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 1 | 10 | 100 | 1000 | $>2154$ |  |
| 1.0 | 10 | 5.0 | 2.5 | 1.3 | 1 |  |
| .9 | 9.1 | 4.6 | 2.4 | 1.2 | 1 |  |
| .8 | 8.2 | 4.2 | 2.2 | 1.2 | 1 |  |
| .7 | 7.3 | 3.8 | 2.1 | 1.2 | 1 |  |
| .6 | 6.4 | 3.4 | 1.9 | 1.2 | 1 |  |
| .5 | 5.5 | 3.0 | 1.8 | 1.1 | 1 |  |
| .4 | 4.6 | 2.6 | 1.6 | 1.1 | 1 |  |
| .3 | 3.7 | 2.2 | 1.5 | 1.1 | 1 |  |
| .2 | 2.8 | 1.8 | 1.3 | 1 | 1 |  |
| .1 | 1.9 | 1.4 | 1.2 | 1 | 1 |  |
| .05 | 1.5 | 1.2 | 1.1 | 1 | 1 |  |
| $<.03$ | 1 | 1 | 1 | 1 | 1 |  |

Tabulated values are determined from the following equations:

$$
\pi_{W}=\left(0 \frac{10}{(R / W)} \cdot 3-1\right)+1 \text { for } 1 \leq R / W<2154
$$

$=1$ for $R / W<1$ and $R / W \geq 2154$
where:

$$
R / W=\text { no. of reads per write }
$$

$D=$ device duty cycle (see footnote in Table 5.1.2.10-3) For seed-bubble generator use table value divided by 4 , or use 1 , whichever is greater.

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5.1.2.10.3 Example Failure Rate Calculations.

Example One: Find the operating failure rate for a single chip 92K bit magnetic bubble memory, $40^{\circ} \mathrm{C}$ case temperature, ground benign environment. The device has a 14 pin nonhermetic DIP enclosure with 10 pins connected, one major loop, three dissipative control elements (generate, replicate and detector bridge), and 144 transfer gates. Device has been in continuous production for two years and is used at $D=1.0$ and $R / W=10$.

For control and detection structure, Section 5.1.2.10.1,

Table 5.1.2.7-1 $\quad$ Quality level $D-1, \pi_{Q}=6.5$
Section 5.1.2.10.1

$$
\begin{aligned}
N_{C} & =1 \\
N_{1} & =1 \text { major } 100 p+3 \text { dissipative elements }+144 \text { gates } \\
& =148,
\end{aligned}
$$

Table 5.1.2.10-1
Table 5.1.2.10-5
Table 5.1.2.10-4
Table 5.1.2.7-15
Table 5.1.2.7-3
Table 5.1.2.10-3
$C_{11}=.007, C_{21}=.00031$
$T_{J}=40+10=50^{\circ} \mathrm{C}, \pi_{T_{1}}=1.1$
$D=1, R / W=10 ; \pi W=5$
Nonhermetic, 10 pins, $C_{2}=.0034$
For $G_{B}, \pi_{E}=.5$
$D=1, \pi_{D}=1$
Table 5.1.2.7-2
$\pi_{L}=1.05$
$\lambda_{1}=6.5\{[(1)(.007)(1.1)(5)]+[(1)(.00031)+.0034]$
(.5) \}(1)(1.05)
$=6.5(.0385+.0019) 1.05$
$=0.28$ failures $/ 10^{6}$ hours.

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For magnetic storage area, Section 5.1.2.10.2,

$$
\lambda_{2}=\pi_{Q} N_{C}\left(C_{12} \pi_{T 2}+C_{22} \pi_{E}\right) \pi_{L}
$$

Table 5.1.2.7-1
Quality level $D-1, \pi_{Q}=6.5$
Section 5.1.2.10.1

$$
N_{C}=1
$$

$$
\text { No. of bits }=92,000
$$

Table 5.1.2.10-2 $\quad C_{12}=.0022, C_{22}=.00031$
Table 5.1.2.10-6 $\quad T_{J}=40+10=50^{\circ} \mathrm{C}, \pi_{T 2}=.53$
Table 5.1.2.7-3 For $G_{B}, \pi_{E}=.5$
Table 5.1.2.7-2

$$
\begin{aligned}
\pi_{L} & =1.05 \\
\pi_{2} & =(6.5)(1)[(.0022)(.53)+(.00031)(.5)](1.05) \\
& =6.5[.001166+.000155] 1.05 \\
& =.009 \text { failures } / 10^{6} \text { hours. }
\end{aligned}
$$

From Section 5.1.2.10,

$$
\begin{aligned}
\lambda_{p} & =\lambda_{1}+\lambda_{2} \\
& =.28+.009 \\
& =.29 \text { failures } / 10^{6} \text { hours. }
\end{aligned}
$$

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Example Two: Find the operating failure rate for a single chip one megabit magnetic bubble memory at $40^{\circ} \mathrm{C}$ case temperature in a benign ground environment. The device has two generators, eight detector elements, 512 replicate/swap gates, four boot loop gates and is contained in a nonhermetic DIP with 19 pins connected. The application requires 10 reads per write and a data rate equal to the maximum rated value of 100 kHz . The device uses a seed generator and is in early production.

For control and detection structure, Section 5.1.2.10.1,
$\lambda_{1}=\pi_{0}\left[N_{C} C_{11} \pi_{11} \pi_{W}+\left(N_{C} C_{21}+C_{2}\right) \pi_{E}\right] \pi_{0} \pi_{L}$
Table 5.1.2.7-1
Quality level $D-1, \pi_{Q}=6.5$
Section 5.1.2.10.1

Table 5.1.2.10-1
Table 5.1.2.10-5
Table 5.1.2.10-4

Table 5.1.2.7-15
Table 5.1.2.7-3
Table 5.1.2.10-3
Table 5.1.2.7-2
$N_{C}=1$
$N_{1}=2$ generators +8 detector elements +512 replicate /swap gates +4 boot loop gates $=526$
$C_{11}=.012 \quad C_{21}=.00041$.
$T_{j}=40+10=50^{\circ} \mathrm{C}, \pi_{T_{1}}=1.1$
$D=100 \mathrm{kHz} . / 100 \mathrm{kHz}=1, \mathrm{R} / \mathrm{W}=10$
$\pi_{W}=5 / 4=1.25$ for seed bubble generator
Nonhermetic, 19 pins, $\mathrm{C}_{2}=.0075$
For $G_{B}, \pi_{E}=.5$
$D=1, \pi_{D}=1$
Early production, $\pi_{L}=2.1$
$\lambda_{1}=6.5\{[(1)(.012)(1.1)(1.25)]+[(1)(.00041)+.0075]$ (.5) $\}(1)(2.1)$
$=6.5(.0165+.004) 2.1$
$=0.28$ failures $/ 10^{6}$ hours.

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For magnetic storage area, section 5.1.2.10.2,

Table 5.1.2.7-1
Section 5.1.2.10.1
Table 5.1.2.10-2
Table 5.1.2.10-6
Table 5.1.2.7-3
Table 5.1.2.7-2

$$
\begin{aligned}
& \lambda_{2}=\pi_{Q} N_{C}\left(C_{12} \pi_{T 2}+C_{22} \pi_{E}\right) \pi_{L} \\
& \text { Quality level } D-1, \pi_{Q}=6.5 \\
& N_{C}=1 \\
& C_{12}=.0045, C_{22}=.00064 \\
& T_{J}=40+10=50^{\circ} \mathrm{C}, \pi_{T 2}=.53 \\
& \text { For } G_{B}, \pi_{E}=.5 \\
& \text { Early production, } \pi_{L}=2.1 \\
& \begin{aligned}
\lambda_{2} & =(6.5)(1)[(.0045)(.53)+(.00064)(.5)](2.1) \\
& =6.5(.002385+.00032) 2.1 \\
& =.037 \text { failures } / 10^{6} \text { hours. }
\end{aligned}
\end{aligned}
$$

From Section 5.1.2.10,

$$
\begin{aligned}
\lambda_{p} & =\lambda_{1}+\lambda_{2} \\
& =0.28+.037 \\
& =0.32 \text { failures } / 10^{6} \text { hours. }
\end{aligned}
$$

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5.1.2.11 Surface Acoustic Wave (SAW) Devices. The part operating failure rate model ( $\lambda_{p}$ ) is:

$$
\lambda_{P}=2.1 \pi_{Q} \pi_{E} \text { failures } / 10^{6} \text { hours. }
$$

where:

```
\pi}E= environmental factor (Table 5.1.2.11-1)
#
        (-55*}\textrm{C}\mathrm{ to }12\mp@subsup{5}{}{\circ}\textrm{C})\mathrm{ with end point electrical test
\piQ}=1.0 commercial par
```

TABLE 5.1.2.11-1 Environmental Mode Factor

| Environment | $\pi_{E}$ |
| :---: | ---: |
| $A_{U}$ | 15.0 |
| $A_{I}$ | 11.7 |
| $N_{U}$ | 16.0 |
| $N_{I}$ | 8.8 |
| $N_{U U}$ | 17.0 |
| $N_{U L}$ | 31.0 |
| $M_{F}$ | 18.0 |
| $S_{F}$ | 1.6 |
| $G_{B}$ | 1.2 |
| $G_{M}$ | 10.5 |
| $G_{F}$ | 3.9 |
| $C_{L}$ | 600.0 |

## APPENDIX B

## MATHEMATICAL DERIVATIONS

## B. 1 Probabllity of Success for Ln-Normal Failure Distributions

The failure density functions for many failure mechanisms are modeled by In-normal distributions. This density function is described mathematically by

$$
\begin{equation*}
f(t)=\frac{1}{\sigma t \sqrt{2 \pi}} \exp \left[(-1 / 2)\left(\frac{\ln t-\mu)}{\sigma} 2\right]\right. \tag{B.1.1}
\end{equation*}
$$

where:

$$
\begin{align*}
& \mu=\ln \left(t_{50 \%}\right)  \tag{B.1.2}\\
& \sigma=\ln \left(t_{50 \%}\right)-\ln \left(t_{16 \%}\right)=\ln \left(t_{50 \%} / t_{16 \%}\right) . \tag{B.1.3}
\end{align*}
$$

The probability of failure at time $t, F(t)$, is

$$
\begin{equation*}
F(t)=\int_{0}^{t} f(x) d x \tag{B.1.4}
\end{equation*}
$$

The probability of success at time $t, P(t)$, is

$$
\begin{equation*}
P(t)=1-F(t)=1-\int_{0}^{t} f(x) d x . \tag{B.1.5}
\end{equation*}
$$

The probability of success at time $t$ for the $1 n$-normal probability density function is the same as the probability of success at $\ln (t)$ for the normal density function. By making the substitution

$$
\begin{equation*}
y=\ln x ; d y=(1 / x) d x \tag{B.1.6}
\end{equation*}
$$

equation B.l. 5 can be rewritten

$$
\begin{equation*}
P(t)=1-\frac{1}{\sigma \sqrt{2 \pi}} \int_{-\infty}^{\ln t} \exp \left[(-1 / 2)\left(\frac{y-\mu}{\sigma}\right) 2\right] d y \tag{B.1.7}
\end{equation*}
$$

which is the probability of success for the normal density function, $N(\mu, \sigma)$, with random variable $\ln (t)$. The integral in equation B.l. 7 can be approximated by use of tables provided by a comprehensive statistics text, or by the computer software program in appendix $C$.

The mechanism models that are described by ln-normal density functions are often described in terms of $\log (t)$ instead of $\ln (t)$. It is again possible to use the probability of success for the normal distribution to evaluate the probability of success for the $1 n$-normal distribution in terms of $\log (t)$. Using the relationships between $\ln (t)$ and $\log (t)$,

$$
\begin{align*}
\ln (t) & =\ln (10) * \log (t)  \tag{B.1.8}\\
\mu & =\ln \left(t_{50 \%}\right)  \tag{B.1.2}\\
& =\ln (10) * \log \left(t_{50 \%}\right) \\
& =\ln (10) * m  \tag{B.1.9}\\
\alpha & =\ln \left(t_{50 \%} / t_{16 \%}\right)  \tag{B.1.3}\\
& =\ln (10) * \log \left(t_{50 \%} / t_{16 \%}\right) \\
& =\ln (10) * s, \tag{B.1.10}
\end{align*}
$$

and the substitution

$$
\begin{equation*}
z=\log (x) ; d z=(1 / \ln (10)) *(1 / x) d x \tag{8.1.11}
\end{equation*}
$$

an expression similar to B.1.7 can be derived,

$$
\begin{equation*}
P(t)=1-\frac{1}{\sigma \sqrt{2 \pi}} \int_{-\infty}^{\log t} \exp \left[(-1 / 2)\left(_{\sigma-m}^{z}\right)^{2}\right] d z . \tag{3.1.12}
\end{equation*}
$$

which is probability of success for the normal density function, $N(m, s)$, with random variable log(t). Again, the integral in equation B.l. 12 can be approximated by use of tables provided by a comprehensive statistics text, or by the computer software program in appendix $C$. Note that $\mu, \sigma$, and upper evaluation limit of the integral, $\ln (t)$, of equation B.l.7 have been changed to $m, s$, and $\log (t)$, respectively in equation B.l. 12 .

## B. 2 Hazard (Failure) Rate Determination for Ln-Normal Failure Distributions

The hazard rate at time $t$ for any failure distribution is given by

$$
\begin{equation*}
h(t)=f(t) /(1-F(t))=f(t) / P(t) . \tag{3.2.1}
\end{equation*}
$$

For the ln-normal distribution, the functions $f(t)$ and $P(t)$ are given by equations B.i.l and B.l.5, respectively. These equations must be evaluated in terms of $\ln (t)$, not $\log (t)$.

In order to evaluate these equations in terms of $\log (t)$, the relationships of B.1.8 to B.l. 10 must be used to develop $f(t)$ in terms of $\log (t)$,

$$
\begin{equation*}
f(t)=\frac{1}{\ln (10)} \frac{1}{s t \sqrt{2 \pi}} \exp \left[(-1 / 2)\left(\frac{\log t-m)^{2}}{s}\right]\right. \tag{3.2.2}
\end{equation*}
$$

Equations B.2.2 and B.1.12 can be used to determine hazard rate for the In-normal distribution evaluated using $\log (t)$.

## B. 3 Derivation of Worst Case (Maximum) Current Density

According to Mil-M-38510, the maximum current density allowed, by design, is $0.5 \mathrm{MA} / \mathrm{cm}^{2}$. Assuming a microcircuit was designed to this limit, and also realizing the worst case step coverage would be $50 \%$ of the flat coverage, the maximum current density not at a step would be $0.25 \mathrm{MA} / \mathrm{cm}^{2}$. Since electromigration does not occur at a step, or any other location on a microcircuit where there is a change in metal direction, because of electron flux divergence in these areas, the worst case current density is 0.25 $\mathrm{MA} / \mathrm{cm}^{2}$. Since most integrated circuits operate with complementary logic, on average only half the metallization is affected by current pulse in any one instance of time. The effective duty cycle is $<=50 \%$. Assuming a worst case duty cycle of $50 \%$, it has been shown ${ }^{[26]}$ that the effective current density is decreased by 0.5. Therefore, the maximum effective current density for $a_{1}$ microcircuit designed to the $0.5 \mathrm{MA} / \mathrm{cm}^{2}$ limit is actually $0.125 \mathrm{MA} / \mathrm{Cn}^{2}$.

## APPENDIX C

```
    PROGRAM TDDB_TABLE
C
C*###################################**************************
    values, another of hazard rate values and one of effective
    hazard' rate values for a user supplied amount of total gate
    area. Each page has a temperature and electric field axis.
C
C
C
C
    WRITE (20,200) ES
    URITE (30,200) ES
C
    DO 2 \=1,36
        DO 1 K=1,16
            CALL TDDB(AS,TS(J),ES(K),TIME,U,S,PS(K),HR(K),EHR(K))
            HR(K)=HR(K)* 1.06
                EHR(K)=EHR(K):1.06
                IF (HR(K).GE.999.00) HR(K) = 999.00
    IF (EHR(K).GE.999.00) EHR(K) = 999.00
        CONTINUE
        WRITE (*,20) TS(J),PS
        URITE (10,1000) TS(J),PS
        WRITE (20,2000) TS(J),HR
        WRITE (30,2000) TS(J),EHR
C
    I=(J/10)*10
    IF (J.EQ.I) THEN
            WRITE (10,100)
            URITE (20,100)
            URITE (30,100)
        ENDIF
    continue
    write(10,500) time, a
        write(20,600)time,a
        write(30,700)time, a
        STOP
20
200
    ( (1)mar (//I//25x,57(-), celectric field Stress (MV/cm) ,43
```



```
        FORMAR (25x,'.-...-',16(1x,'........'))
        FORMAT (///65X,'TDDS: PROBABILITY OF SUCCESS AT',F7.0,' HOURS ',
    *'FOR AREA = ',F5.2,' LOG SQUARE MICRONS')
    FORMAT (///65X,'TDDB: HAZARD RATE (X 10E-6) AT',F7.0,
    * 'HOURS FOR ARÉA = ',F5.2,' log SQuare MICRONS')
    FORMAT (///60X,'TDDB: EFFECTIVE HAZARD RATE (x 10E-6) AT',F7.0,
    * ' HOURS FOR AREA = ',F5.2,' LOG SQUARE MICRONS')
    FORMAT (25x,F5.0,16F8.5)
    FORMAT (25x,F5.0,16F8.3)
    END
```

```
        PROGRAM EM_TABLE
C Generates a one page table of probability of success
    values, another of hazard rate values and one of effective
    hazard rate values. Each page has a temperature and
    current density axis.
C
    IMPLICIT REAL*8 (A-H,O-Z), INTEGER*4 (I-N)
    DIMENSION TS(36),CDS(16),PS(16),HR(16),EHR(16)
C
C
    * .2500,.300,.400,.500,.600,.800,1.00,1.300/
    NOTE: LIMITS ON DO STATEMENTS ARE ARRAY DIMENSIONS
    DO 400 J=0,35
        TS(J+1) = 0.DO + 5.DO * DBLE(J)
    CONTINUE
    WRITE (***) 'ENTER TIME, HOURS'
    READ (***) TIME
C
    WRITE (10,200) CDS
    WRITE (20,200) CDS
    WRITE (30,200) CDS
C
    DO 2 J=1,36
        DO 1 K=1,16
            CALL EM(TS(J),CDS(K),TIME,U,S,PS(K),HR(K),EHR(K))
            HR(K)=HR(K)*1.06*
            EHR(K) = EHR(K) * 1.06
            IF (HR(K).GE.999.DO) HR(K) = 999.D0
            IF (EHR(K).GE.999.DO) EHR(K) =999.00
        CONTINUE
        WRITE (*,20) TS(J),PS
        WRITE (10,1000) TS(J),PS
        URITE (20,2000) TS(J),HR
        WRITE (30,2000) TS(J),EHR
C
        l=(J / 10)* 10
        IF (J.EQ.I) THEN
            WRITE (10,100)
            WRITE (20,100)
            WRITE (30,100)
            ENDIF
    CONTINUE
        write (10,500)time
        write (20,600)time
        write (30,700)time
    STOP
    FORMAT (25X,F5.0,16F4.2)
        FORMAT (//////25x,57(1-1),' Current Density (MA/cm2) ',48('-1)/
        * 25x,'T(C)',F7.2,15(1x,F7.2)/25x,'.....1,16(1x,1.......-1)//)
        FORMAT(25X,'...--1,16(1x,'......--'))
        FORMAT (///70X,'ELECTROMIGRATIOW: PROBABILITY OF SUCCESS AT'.
        * F7.0,' HOURS')
        FORMÁT (///70X,'ELECTROMIGRATION: HAZARD RATE (x 10E-6) AT',F7.0,
    * (HOURS')
    FORMAT (///65X,'ELECTROMIGRATION: EFFECTIVE HAZARD RATE ',
    * '(x 10E-6) AT',F7.0,' HOURS')
    FORMAT (25x,F5.0,16F8.5)
    FORMAT (25x,F5.0,16F8.3)
    END
```

|  | SUBROUTINE M(AO, AS, UO, ACC) |
| :---: | :---: |
| C |  |
|  |  |
| $c$ SUBROUTINE AA |  |
|  |  |
| $\stackrel{C}{C}$ | PURPOSE: |
| C |  |
| C Calculate the acceleration factor due to dielectric area |  |
| C relative to a reference area. |  |
| C |  |
| $C$ | USAGE: |
| C C |  |
| C | CALL AA (AO,AS, UO, ACC) |
| C CALL An (AO,AS, NO,ACC) |  |
| $C$ | DESCRIPTION OF PARAMETERS: |
| C |  |
| C AO - reference area (square microns) |  |
| C AS - operating area (square microns) |  |
| ${ }^{\text {c }}$ | U0 - log of median time of reference distribution (hours) |
|  | $C$ ACC - acceleration factor |
| C |  |
| C | SUBROUTINES AND FUNCTION SU8PROGRAMS REQUIRED: |
| C |  |
| C | ZVAL - calculates number of sigmas from the mean |
|  |  |
|  |  |
| C |  |
|  | IMPLICIT REAL*8 ( $A-\mathrm{H}, \mathrm{O}-2$ ), INTEGER*4 (I-N) |
| $F=A O /(A O+A S)$ |  |
| CALL $2 V A L(F, 2)$ |  |
| $A C C=1 . D 0$ + (2/U0) |  |
|  | RETURN |
|  | END |

SUBROUTIME AEF(EO,ES,B,ACC)

## C



```
    SUBROUTINE AJ(CDO,COS,N,ACC)
C
C*****************************************************************************
    IMPLICIT REAL*8 (A-H,O-2), INTEGER*4 (I-N)
    ACC = (CDS / CDO) ** N
    RETURN
    END
```

```
SUBROUTINE AT(TO,TS,EA,ACC)
C
```



```
C
SUBROUTINE AT
PURPOSE:
        Calculate the acceleration factor due to temperature stress
        relative to a reference temperature
    USAGE:
        CALL AT (TO,TS,Ea,ACC)
    DESCRIPTION OF PARAMETERS:
        TO - reference temperature
        TS - operating temperature
        Es - activation energy (eV/deg K)
        ACC - acceleration factor
    SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED:
        NONE
C
C
    IMPLICIT REAL*8 (A-H,O-Z), INTEGER*4 (I-N)
    = =8.6970-5
    ACC = DEXP((EA/B)*(1.D0/(T0+273.D0) - 1.00/(TS+273.D0)))
    RETURN
    END
```



```
C
```



```
    SUBROUTINE EM
    PURPOSE:
        Calculate u, s, probability of success, hazard rate and
        effective hazard rate at any time t, given operating
        temperature, and current density.
    USAGE:
        CALL EM (TS,CDS,TIME,U,S,PS,FR,EFR)
    DESCRIPTION OF PARAMETERS:
        TS - operating temperature (degrees C)
        CDS - current density stress (MA/cm2)
        TIME - time at which probaility of success, hazard rate and
        effective hazard rate is to be calculated
        U - log of failure distribution median
        S - square root of the variance of the failure
                distribution (log hours)
        PS - probability of success calculated at time TIME
        FR - hazard rate calculated at time TIME
        EHR - effective hazard rate calculated at time TIME by the
            equation: EHR = -In(TIME)/PS
    SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED:
        AT - temperature acceleration calculation
        AJ - current density acceleration calculation
        CNDA - cumulative normal distribution approximation
    IMPLICIT REAL*8 (A-H,O-2), INTEGER*4 (I-N)
C
    UO = 1.39800
    SO = 0.00800
    TO = 175.D0
    Ea=0.500
    COO = 1.DO
    N=2
C
c
    CALL AT(TO,TS,Ea,ACCAT)
    CALL AJ(CDO,CDS,N,ACCAJ)
c
    U = UO - DLOG10(ACCAT*ACCAJ)
    S = So
c
    z = (STIME - U) / S
    CALL CNDA(2,F,IFLAG)
C
    IF (IFLAG) 2,2,1
C
    CONTINUE
    PS = 0.00
    HR =999.00
    EHR =999.00
    RETURN
C
    CONTINUE
    PS = 1.DO - F
    IF (IFLAG.EQ.-1) PS = 1.000
    COEF = 1.DO / (DSORT(2.DO*3.141592653589793)*TIME*DLOG(10.DO))
    Ht = COEF*DEXP(-.5DO*2**2)
    HR = Ht / PS
    EHR = -1.00*DLOG(PS)/TIME
    RETURN
c
    EMD
```

```
    SUBROUTINE TDDB(AS,TS,ES,TIME,U,S,PS,HR,EHR)
C
C*************************
    PURPOSE:
        Calculate U, s, probability of success, hazard rate and
        effective hazard rate at any time t, given total gate area,
        operating temperature, and electric field stress.
    USAGE:
        CALL TODB (AS,TS,ES,TIME,U,S,PS,FR,EFR)
    DESCRIPTION OF PARAMETERS:
        AS - total gate area (square microns)
        IS - operating temperature (degrees C)
        ES - electric field stress
        TIME - time at which probaility of success, hazard rate and
            effective hazard rate is to be calculated
        U - log of failure distribution median
    S - square root of the variance of the failure
        distribution (log hours)
    PS - probability of success calculated at time TIME
    FR - hazard rate calculated at time TIME
    EHR - effective hazard rate calculated at time TIME by the
        equation: EHR = - ln(TIME)/PS
    SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED:
    AA - area acceleration calculation
    AT - temperature acceleration calculation
    AEF - electric field acceleration calculation
    CNDA - cumulative normal distribution approximation
C****************************************************************************
    IMPLICIT REAL*8 (A-H,O-2), INTEGER*4 (I-N)
C
    UO = 8.400
    SO = 0.400
    AO = 1.781605
    TO = 22.00
    Ea=0.300
    EO =2.22200
    BETA = 4.500
C
C
    CALL AA(AO,AS,UO,ACCAA)
    CALL AT(TO,TS,EA,ACCAT)
    CALL AEF(EO,ES,BETA,ACCAEF)
C
    U = ACCAA * (UO - OLOG10(ACCAT*ACCAEF))
    S = SO
C
    z=(STIME - U) / S
    CALL CNDA(Z,F,IFLAG)
C
    If (IFLAG) 2,2,1
C
    continue
    PS = 0.00
    HR = 999.00
    EHR =999.DO
    RETURN
C
    CONTINUE
```

```
PS = 1.00-F
If (IFLAG.EQ.-1) PS = 1.000
COEF = 1.DO /(DSQRT(2.DO*3.141592653589793)*TIME*DLOG(10.00))
Ht = COEF*DEXP(-.5DO*2**2)
HR = Ht / PS
EHR = -1.DO*DLOG(PS)/TIME
RETURN
END
```

c

```
SUBROUTINE ZVAL(F,2)
SUBROUTINE ZVAL
PURPOSE:
Calculates the number of sigmas away from the mean of a normal distribution for a given probability of failure (cumulative percent failure in decimal). This subroutine uses the Newton-Raphson method of finding roots.
USAGE:
CALL \(\operatorname{ZVAL}(F, Z)\)
DESCRIPTION OF PARAMETERS:
F - probability of failure (cumulative percent failure in decimal)
2 - number of sigmas from the mean of the normal distribution
SUBROUTINES AND FUNCTION SUBPROGRAMS REQUIRED:
CNDA - cumulative normal distribution approximation
    IMPLICIT REAL*8 (A-H,O-2), INTEGER*4 (I-N)
IF (F.LE. O. 500) \(2 \mathrm{NEW}=-0.500\)
IF (F.GT.0.500) ZNEW \(=0.500\)
\(2=2\) NEW
C
DO \(5 \mathrm{~N}=1,100\)
CALL CNDA ( \(2, F N E W, I\) FLAG)
1F (IFLAG.EQ.-1) FNEW \(=0.00\)
[F (IFLAG.EQ.1) FNEW \(=1.00\)
PHI = FNEW - F
PHIPRI = \(1.00 /(\) DSQRT (2.00*3.141592653589793)*DEXP (.500*2**2))
ZNEW = 2
\(Z=Z\) - PHI / PHIPRI
IF (DABS(Z-ZNEW)/DABS (Z).LT. 0.000000100 ) RETURN
continue
RETURN
END
```


## APPENDIX D

PROBABILITY OF SUCCES AND hAZARD RATE TABLES

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| 5 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99999 | . 99974 | . 99445 | . 94560 | . 74796 | . 39454 | . 11447 | . 01623 |
| 10. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99999 | . 99941 | . 98953 | . 91522 | . 66933 | . 30941 | . 07592 | . 00893 |
| 15. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99996 | . 99875 | . 98156 | . 87526 | . 58552 | . 23591 | . 04895 | . 00479 |
| 20. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99991 | . 99751 | . 96945 | . 82567 | . 50064 | . 17516 | . 03077 | . 00251 |
| 25 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99980 | . 99535 | . 95209 | . 76728 | . 41853 | . 12689 | . 01891 | . 00130 |
| 30 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99999 | . 99958 | . 99182 | . 92855 | . 70178 | . 34235 | . 08986 | . 01139 | . 00066 |
| 35 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99998 | . 99916 | . 98634 | . 89817 | . 63142 | . 27427 | . 06233 | . 00673 | . 00033 |
| 40. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99995 | . 99843 | . 97826 | . 86071 | . 55880 | . 21545 | . 04242 | . 00392 | . 00016 |
| 45. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99990 | . 99722 | . 96691 | . 81639 | . 48648 | . 16616 | . 02839 | . 00225 | . 00008 |
| 50 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.0000 | 1.00000 | 1.00000 | . 99979 | . 99529 | . 95165 | . 76593 | . 41681 | . 12597 | . 01871 | . 00128 | . 00004 |
| 55 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99999 | . 99961 | . 99236 | . 93193 | . 71045 | . 35165 | . 09401 | . 01216 | . 00072 | . 00002 |
| 60 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99998 | . 99930 | . 98810 | . 90735 | . 65138 | . 29235 | . 06915 | . 00781 | . 00040 | . 00001 |
| 65 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99996 | . 99880 | . 98211 | . 87776 | . 59028 | . 23969 | . 05020 | . 00496 | . 00022 | . 00000 |
| 70. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99993 | . 99800 | . 97401 | . 84321 | . 52877 | . 19396 | . 03601 | . 00312 | . 00012 | . 00000 |
| 75. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99988 | . 99681 | . 96341 | . 80405 | . 46835 | . 15505 | . 02555 | . 00195 | . 00007 | . 00000 |
| 80. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99978 | . 99506 | . 94996 | . 76079 | . 41032 | . 12256 | . 01796 | . 00121 | . 00004 | . 00000 |
| 85. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99999 | .99963 | . 99259 | . 93335 | . 71419 | . 35572 | . 09586 | . 01251 | . 00074 | . 00002 | . 00000 |
| 90. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99998 | . 99939 | . 98921 | . 91340 | . 66510 | . 30532 | . 07427 | . 00865 | . 00046 | . 00001 | . 00000 |
| 95. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 999997 | . 99902 | . 98470 | . 89000 | . 61446 | . 25959 | . 05703 | . 00594 | . 00028 | . 00001 | . 00000 |
| 100. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99995 | . 99849 | . 97884 | . 86318 | . 56321 | . 21874 | . 04345 | . 00405 | . 00017 | . 00000 | . 00000 |
| 105. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99992 | . 99773 | . 97141 | . 83307 | .51228 | . 18279 | . 03286 | . 00275 | . 00010 | . 00000 | . 00000 |
| 110. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99987 | . 99666 | . 96221 | . 79993 | . 46247 | . 15156 | . 02469 | . 00186 | . 00006 | . 00000 | . 00000 |
| 115. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99979 | .99521 | . 95106 | . 76411 | . 41450 | . 12475 | . 01844 | . 00125 | . 00004 | . 00000 | . 00000 |
| 120. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99999 | . 99967 | . 99328 | . 93779 | . 72606 | . 36894 | . 10200 | . 01370 | . 00084 | . 00002 | . 00000 | . 00000 |
| 125. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99999 | . 99950 | . 99077 | . 92231 | . 68625 | . 32623 | . 08289 | . 01013 | . 00056 | . 00001 | . 00000 | . 00000 |
| 130. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99998 | . 99926 | . 98757 | . 90456 | . 64521 | . 28666 | . 06697 | . 00746 | . 00038 | . 00001 | . 00000 | . 00000 |
| 135. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99997 | . 99893 | . 98356 | . 88453 | . 60348 | .25041 | . 05383 | . 00547 | . 00025 | . 00001 | . 00000 | . 00000 |
| 140. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99995 | . 99847 | . 97862 | . 86226 | . 56158 | . 21752 | . 04306 | . 00400 | . 00017 | . 00000 | . 00000 | . 00000 |
| 145. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99993 | . 99786 | . 97265 | . 83787 | .52000 | . 18796 | . 03430 | . 00292 | . 00011 | . 00000 | . 00000 | . 00000 |
| 150. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99989 | . 99706 | . 96554 | . 81149 | .47919 | . 16163 | . 02722 | . 00213 | . 00007 | . 00000 | . 00000 | $.00000$ |
| 155. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99983 | . 99603 | . 95719 | . 78331 | . 43954 | . 13836 | . 02152 | . 00154 | . 00005 | . 00000 | . 00000 | $.00000$ |
| 160. | 1.00000 | 1.00000 | 1.00000 | 1.00000 | . 99976 | . 99472 | . 94753 | . 75358 | . 40138 | . 11794 | . 01696 | . 00112 | . 00003 | . 00000 | . 00000 | . 00000 |
| 165. | 1.00000 | 1.00000 | 1.00000 | . 99999 | . 99966 | . 99308 | . 93649 | . 72253 | . 36497 | . 10014 | .01333 | . 00081 | . 00002 | . 00000 | . 00000 | . 00000 |
| 170. | 1.00000 | 1.00000 | 1.00000 | . 99999 | . 99952 | . 99106 | . 92403 | . 69045 | . 33053 | . 08472 | . 01045 | . 00059 | . 00001 | . 00000 | . 00000 | . 00000 |
| 175. | 1.00000 | 1.00000 | 1.00000 | . 99998 | . 99934 | . 98861 | . 91012 | . 65761 | . 29818 | . 07143 | . 00818 | . 00042 | . 00001 | . 00000 | . 00000 | . 00000 |








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| (C) | 2.0 | 2.2 | 2.4 | 2.6 | 2.8 | 3.0 | $3.2{ }^{\text {Ele }}$ | ${ }_{3.4}^{\text {ric }}$ Fi | ld str | ${ }_{3.8}$ | ${ }_{4.0}$ | 4.2 | 4.4 | 4.6 | 4.8 | 5.0 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 0. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 028 | . 942 | 8.851 | 32.299 |
| 5. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 079 | 1.865 | 13.235 | 40.674 |
| 10. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 003 | . 194 | 3.340 | 18.531 | 49.459 |
| 15. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 009 | . 428 | 5.486 | 24.599 | 58.492 |
| 20. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 025 | . 858 | 8.368 | 31.282 | 67.647 |
| 25. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 061 | 1.574 | 11.989 | 38.425 | 76.832 |
| 30. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 002 | . 137 | 2.672 | 16.301 | 45.891 | 85.976 |
| 35. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 005 | . 282 | 4.232 | 21.218 | 53.56 | 95.032 |
| 40. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 013 | . 538 | 6.310 | 26.639 | 61.358 | 103.964 |
| 45. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 029 | . 956 | 8.928 | 32.460 | 69.198 | 112.748 |
| 50. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 062 | 1.594 | 12.076 | 38.584 | 77.030 | 121.368 |
| 55. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 002 | . 124 | 2.508 | 15.715 | 44.925 | 84.814 | 129.812 |
| 60. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 004 | . 232 | 3.747 | 19.792 | 51.411 | 92.519 | 138.074 |
| 65. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 009 | . 411 | 5.347 | 24.242 | 57.982 | 100.123 | 146.151 |
| 70. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 018 | . 688 | 7.325 | 28.999 | 64.592 | 107.609 | 154.042 |
| 75. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 035 | 1.096 | 9.683 | 33.999 | 71.202 | 114.967 | 161.747 |
| 80. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 067 | 1.669 | 12.405 | 39.186 | 77.782 | 122.188 | 169.267 |
| 85. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 002 | . 119 | 2.439 | 15.465 | 44.507 | 84.310 | 129.268 | 176.601 |
| 90. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 003 | . 202 | 3.433 | 18.826 | 49.921 | 90.769 | 136.204 | 183.747 |
| 95. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 006 | . 330 | 4.673 | 22.451 | 55.390 | 97.144 | 142.995 | 190.695 |
| 100. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 012 | . 518 | 6.169 | 26.298 | 60.884 | 103.427 | 149.641 | 197.419 |
| 105. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 022 | . 784 | 7.926 | 30.329 | 66.379 | 109.610 | 156.143 | 203.859 |
| 110. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 038 | 1.145 | 9.937 | 34.506 | 71.856 | 115.689 | 162.501 | 209.878 |
| 115. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 064 | 1.620 | 12.192 | 38.797 | 77.297 | 121.659 | 168.717 | 215.179 |
| 120. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 103 | 2.227 | 14.673 | 43.173 | 82.691 | 127.519 | 174.793 | 219.128 |
| 125. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 002 | . 162 | 2.981 | 17.360 | 47.607 | 88.028 | 133.269 | 180.738 | 220.429 |
| 130. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 004 | . 247 | 3.893 | 20.230 | 52.078 | 93.300 | 138.907 | 186.518 | 216.638 |
| 135. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 007 | . 365 | 4.972 | 23.259 | 56.568 | 98.501 | 144.434 | 192.158 | 203.835 |
| 140. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 012 | . 525 | 6.221 | 26.424 | 61.060 | 103.626 | 149.851 | 197.630 | 999.000 |
| 145. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 020 | . 737 | 7.641 | 29.703 | 65.541 | 108.673 | 155.160 | 202.89 | 999.000 |
| 150. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 031 | 1.010 | 9.227 | 33.07 | 70.002 | 113.639 | 160.361 | 207.898 | 999.000 |
| 155. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 049 | 1.354 | 10.973 | 36.521 | 74.432 | 118.523 | 165.456 | 212.501 | 99.000 |
| 160. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 073 | 1.777 | 12.870 | 40.025 | 78.825 | 123.324 | 170.447 | 216.471 | 999.000 |
| 165. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 108 | 2.289 | 14.908 | 43.570 | 83.175 | 128.042 | 175.334 | 219.380 | 99.000 |
| 170. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 002 | . 155 | 2.896 | 17.072 | 47.144 | 87.477 | 132.676 | 180.118 | 220.478 | 999.000 |
| 175. | . 000 | . 000 | . 000 | . 000 | . 000 | . 00 | . 004 | . 218 | 3.603 | 19.352 | 50.735 | 91.727 | 137.228 | 184.798 | 218.515 | 999.000 |




|  |  | . 000 | .000 | . 000 |  | . 000 | . 000 | .000 | . 000 | . 018 | . 367 | 3.283 | 14.050 | 35.460 | 65.009 | 99.243 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| 5 | . 000 | . 0000 | .000 | . 000 | . 0000 | . 000 |  |  | . 0001 | -0, 01 | ${ }_{1}^{.6173}$ |  |  |  |  |  |
| 10. | . 0000 | .000 | .000 | 000 | . 000 | .000 | .000 | .000 | . 007 | 180 | 1.129 | 10.199 | 28.908 |  |  |  |
| $2{ }^{2}$ | -000 | .000 | -.000 | .000 | O00 | .000 | .000 | .000 | . 016 | 337 | 3.094 | 13.526 | 34.607 | 63. | 98.072 |  |
| 25 | 000 | .000 | O00 | .000 | . 000 | .000 | O00 | 001 | . 033 | 591 | 4.546 | 17.300 | 40.530 |  | 106.029 |  |
| 30. | .000 | .000 | . 000 | . 000 | . 000 | .000 | .000 | . 002 | . 066 | 979 | 6.379 | 21.459 | 4.604 | 93 | 113.8 |  |
| 35. | . 000 | .000 | S00 | . 000 | 000 | . 000 | .000 | .064 | . 124 | 1.539 | 8.599 |  | 52.760 |  | 121.448 |  |
| 40. | .000 | . 000 |  |  | 00 | . 000 | 000 | . 009 | 221 | 2.307 | 11.192 | 30.668 | 58.970 | 92.526 | . 89 | 166.786 |
| 45. | . 000 | . 000 | .000 | . 000 | O | 00 | 000 | 18 | . 372 | 14 | 14.133 | 35.594 | 65.176 | 99 |  | 174.255 |
| 50 | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 001 | . 034 | . 598 | 4.582 | 17. | 40.661 | 71.354 |  |  |  |
| 55. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 002 | . 061 | 223 |  |  | ${ }^{45} 5823$ |  |  |  |  |
| 60. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | .003 | . 105 | ${ }^{1.363}$ | ${ }^{7.942}$ | -24.600 | 51.042 | ${ }^{83.536}$ |  |  |  |
| 65. | . 000 | . 000 | . 000 | . 000 | . 000 | . 000 | . 01 | 23 | 2.692 | 12.3 |  | ${ }_{6} 51.533$ |  |  |  |  |
| 70 | . 000 | .000 | . 000 | . 0 | . 000 | .000 | .012 | . 22 | 3.612 | 12.036 | 7 | 6 | 101 |  |  |  |
| 3 | . 000 | .000 | . | . 0 | 000000 | .000 | . 03 | 422 | 3.718 |  |  | 71.946 |  |  |  |  |
| 80 | . 0000 | .000 | .000 | .000 | 000 | . 002 | . 059 | 886 | 6.015 | 20.673 | 45.485 | 7.083 | 112.411 | 149.73 | 188.100 |  |
| 8 |  |  |  |  |  | . 003 |  | 1.251 |  |  |  |  |  |  |  |  |
| ${ }_{95}$ | . 0000 | . 0000 | . 000 | . 000 | . 000 | . 005 | . 143 | 1.699 | 9.176 | 27.028 | 54.223 | 87.169 | 退12.826 |  | 199.3 | 6 |
|  |  |  |  |  | . 000 | . 009 | 13 | 2.254 | 11.025 | 30.375 | 58.594 | 92. | 128.450 | 186.3 | 24.631 | . 488 |
| 105. | . 000 | . 000 | . 000 | . 000 | . 000 | . 014 | . 310 | 2.923 | 13.039 | 33.805 | 62.948 | 96.961 | 133.575 |  |  |  |
| 110 | . 000 | . 000 | S00 | . 000 | . 000 | . 022 | . 49 | 3.713 | 15.203 | 37.298 | 67. | 01.73 | 138.5 | 77.73 |  |  |
|  | . 000 | . 000 | . 000 | . 00 | . 001 | . 035 |  | 4.630 | 17.502 | 40.836 | 71. | 106, | 43.49 |  |  |  |
|  |  |  | . 000 | . 000 | . 001 | . 032 | 821 | 5.67 | 19.92 | 4.403 | 7.810 | H1 | 18.30 |  |  |  |
|  | . 000 | . 000 | . 000 | . 000 | . 002 | . 077 | 1.089 | 6.846 | 22.443 | 47.988 | 80.006 | 115 | ${ }^{53} 3.001$ |  |  |  |
| 130. | . 00 | . 000 | . 000 | . 000 | . 004 | . 111 | 1.416 | 8.142 | ${ }^{25}$ | 51.57 | 84.12 |  |  |  |  |  |
|  | . 00 | . 000 | . 000 | . 000 | . 006 | . 156 | 1.809 | 9.558 | 27.339 | 55.161 | 88.23 | 124.347 |  |  |  |  |
| 140 | .000 | 000 | 000 |  | . 093 | . 216 | 2.273 | ${ }^{11.087}$ | ${ }^{30.484}$ | ${ }^{58.735}$ | 92.26 | 128.615 |  |  |  |  |
| 145. | . 000 | . 000 | . 000 | . 000 | . 013 | . 293 | 2.813 | 12.721 | 33.27 | 62.285 | 96 |  |  |  |  |  |
|  |  |  |  |  |  |  |  | 14.453 | 36.107 |  |  |  |  |  |  |  |
| 155 | . 000 | . 000 | . 000 | . 001 | . 028 | . 513 | 4.131 | ${ }^{16.273}$ | 38.96 |  |  |  |  |  |  |  |
|  | . 000 | .000 | . 000 | . 00 | . 035 | . 63 | 5. | 20 | 4. |  | 111.44 |  |  |  |  |  |
| 165 | . 000 | .000 | . 000 | . 01 | . 034 | 退 |  | ${ }^{2} 2173$ |  | 5.50 |  |  |  |  |  |  |
| 170 | O00 | .000 | . 000 | . 002 | 09 | 1.311 | 7.741 |  |  |  |  |  |  |  |  |  |
| 175. | . 000 | . 000 |  |  |  | 1.311 | 7.741 | 24.263 | 50.30 | 82.913 |  |  |  |  |  |  |


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## APPENDIX E

MEMORY LIFE TEST DATA

| IYPE | Partmum | TECH | MBITS | arrayte | TECH |  | TEST | YR | OUR | devhrs | MTEST | mfall | fdesc | fmechmsw |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| EEPROM | 28160 | -mos | 16K | flgate $5 v$ | fx | flga | 1250LIfE | 84 |  | $7.72 E 5$ |  | 1 |  |  |
| EEPROM | 52813 | -mos | 16K | flgate $5 V$ |  | flga | 1250LIfe | 84 |  | 6.84E5 |  | 1 |  |  |
| EEPROM | 52833 | - MOS | 646 | flgate 5V | FX | flga | 125DLIfe | 84 |  | $6.58 E 5$ |  | 1 |  |  |
| EEPROM | x2816A | mos | 16K | flcate $5 V$ | TP | flga | 1250LIfE | 87 |  | 1.2666 |  | 2 | ?. 1 retention | 1 IOMCOwtan, $?$ |
| EEPROM | $\times 28168$ | mos | 16K | flgate <br> $5 V$ | IP | flga | 125DLIfe | 87 |  | 7.7366 |  | 0 |  |  |
| EEPROM | $\times 2404$ | mos | 4K | flgate $5 V$ | 1 P | flga | 1250LIfE | 87 |  | 1.4956 |  | 2 | ?, ? | 2 OXIDE BRKDUM |
| EEPROM | x2864a | mos | 64k | flcate <br> $5 V$ | ${ }_{\text {T }} \mathrm{P}$ | flga | 125DLIfE | 87 |  | 3.2966 |  | 5 | ?.7.?.? 1 REIENTIOM | 4 IOwCOwTAM, ? |
| fPGA | 825103 | IIL | 297 | Wicr fuse | fuse | NiCr | ohtlife | 80 | 1000 |  | 50 | 0 |  |  |
| fPLA | 825101 | IIL | 1832 | NiCr fuse | fuse | NiCr | dhtlife | 84 | 1000 |  | 48 | 0 |  |  |
| FPLA | 825101 | ITL | 1832 | NiCr | fuSE | NiCr | DhtLIfE | 84 | 1000 |  | 50 | 0 |  |  |
| fPLA | 825153 | IIL | 1842 | wicr | fuSE | Nicr | DHILIFE | 83 | 1000 |  | 48 | 1 | 1 Shorted hire | 1 Assy error |
| fPLA | PLS153 | ITL | 1842 | WiCr fust | fuse | NiCr | Dhilife | 86 | 1000 |  | 100 | 0 |  |  |
| fPLA | plsis3 | TIL | 1842 | micr fuse | fuse | NiCr | DHTLIfE | 87 | 1000 |  | 88 | 0 |  |  |
| fPLA | PLS153 | TIL | 1852 | NiCr | fuSE | NiCr | DHTLIfE | 87 | 1000 |  | 100 | 0 |  |  |
| FPLA | PLS153 | 17 | 1852 | MiCr fus | fuSE | MiCr | DHILIFE | 87 | 1000 |  | 109 | 0 |  |  |
| fPLA | 825100 | It | 1928 | micr fus | fuse | NiCr | ohtife | 80 | 1000 |  | 53 | 0 |  |  |
| fPLA | 825100 | ITL | 1928 | wicr fuse | fuSE | Nicr | DHTLIFE | 82 | 1000 |  | 50 | 0 |  |  |
| fPLA | 82s100 | IIL | 1928 | Micr fusm | fuSE | Micr | DHILIFE | 84 | 1000 |  | 50 | 0 |  |  |
| fPLA | 82S100 | IIL | 1928 | wicr | fuse | wicr | dhtife | 85 | 1000 |  | 99 | 0 |  |  |
| fPLA | PLS100 | TIL | 1928 | NiCr fust | fuSE | NiCr | DHILIfE | 85 | 1000 |  | 100 | 0 |  |  |
| fPLA | PLS100 | IIL | 1928 | nicr fust | fuse | NiCr | Dhtlife | 88 | 1000 |  | 100 | 0 |  |  |
| fPLA | PLS100 | IIL | 1928 | WiCr fus | fuSE | Wicr | Dhtlife | 88 | 1000 |  | 100 | 0 |  |  |
| fPLA | PLS100 | TIL | 1928 | micr fus | fuSE | MiCr | OHTLIfE | 88 | 1000 |  | 100 | 0 |  |  |
| fPLA | PLS100 | IIL | 1928 | MiCr | fuSE | NiCr | Dhtlife | 88 | 1000 |  | 100 | 0 |  |  |
| fPLA | PLS100 | Iti | 1928 | Nicr fuse | fuSE | Nicr | Dhtlife | 88 | 1000 |  | 100 | 0 |  |  |
| fPLA | PLS100 | IIL | 1928 | wicr | fuse | NiCr | dhilife | 88 | 1000 |  | 100 | 0 |  |  |
| fPLA | PLS100 | III | 1928 | wicr fus | fuse | Nicr | Dhilife | 88 | 1000 |  | 100 | 1 | 1 acparam | ? |
| fPLA | PLS100 | TIL | 1928 | nicr fust | fuSE | MiCr | DHTLIFE | 88 | 1000 |  | 51 | 0 |  |  |
| fPLA | PLS100 | IIL | 1928 | NiCr fus | fuSE | Nicr | dhtlife | 88 | 1000 |  | 99 | 0 |  |  |
| fPLA | PLS173 | TIL | 2618 | NiCr fust | fuSE | NiCr | Dhtlife | 86 | 1000 |  | 100 | 0 |  |  |
| fPLA | PLS151 | IIL | 566 | wicr fus | fuSE | Wicr | Dhtlife | 86 | 1000 |  | 99 | 1 | 1 acfunc | ? |
| fPLS | PLS159 | Iti | 2011 | NiCr fust | fuse | NiCr | dhtlife | 86 | 1000 |  | 94 | 0 |  |  |
| FPLS | PLS157 | IIL | 2016 | WiCr fub | fuSE | NiCr | DHILIfE | 86 | 1000 |  | 95 | 0 |  |  |
| fPLS | 82S167 | IIL | 3360 | wicr fust | fuse | Nicr | dhtlife | 84 | 1000 |  | 50 | 0 |  |  |
| FPLS | 825105 | IIL | 3552 | NiCr fust | fuSE | NiCr | Dhtlife | 82 | 1000 |  | 40 | 0 |  |  |
| fPLS | 82S 105 | IIL | 3552 | micr fus | fuse | NiCr | dhillfe | 83 | 1000 |  | 50 | 0 |  |  |
| FPLS | 82S105 | IIL | 3552 | WiCr fusm | fuSE | Micr | DHTLIfE | 83 | 1000 |  | 50 | 0 |  |  |
| FPLS | 825105 | IIL | 3552 | WiCr fus | FUSE | Wicr | DHTLIFE | 83 | 1000 |  | 50 | 0 |  |  |
| fPLS | 82s105 | ITL | 3552 | wicr fust | fuse | Nicr | dhtlife | 83 | 1000 |  | 50 | 0 |  |  |
| FPLS | 82s 105 | It | 3552 | WiCr fu | fuSE | NiCr | Dhtlife | 83 | 1000 |  | 50 | 2 | 2 SHORTED HIRE | 2 ASSY ERROR |
| FPLS | 82s105 | IIL | 3552 | NiCr fus | fuSE | NiCr | dhtilfe | 84 | 1000 |  | 50 | 0 |  |  |


| TECH | MBITS | arrayt | TECH | test | YR | DUR | OEvHRS | MTEST | mfail | FDESC | FMECHMSM |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| IIL | 3552 | micr F | fuse micr | Dhilife | 84 | 1000 |  | 50 | 1 | 1 OPEM WIRE | 1 defect hirebowo |
| ITL | 3552 | miCr f | fuse micr | dhtlife | 86 | 1000 |  | 99 | 0 |  |  |
|  |  | fuse | FUSE | Hidilfe | 87 | 1000 |  | 88 | 0 |  |  |
| cnos | 256K | $\begin{aligned} & \text { FLGATE } \\ & \text { 12.5v } \end{aligned}$ | E FLGA | 1250LIfE | 87 |  | 1.2965 |  | 0 |  |  |
| cmos | 256K | $\begin{aligned} & \text { FLGATE } \\ & 12.5 \mathrm{~V} \end{aligned}$ | E FlGa | 1250LIfe | 87 |  | 9.53 ES |  | 5 | 4 grossflum, 1 leakage | ?, ? |
| ECL |  |  |  | Shtlife | 80 | 1000 |  | 46 | 0 |  |  |
| ECL |  |  |  | SHTLIFE | 80 | 1000 |  | 50 | 0 |  |  |
| mos | 128x | $\begin{aligned} & \text { FLGate } \\ & \text { 12.5v } \end{aligned}$ | E flca | 1250LIfE | 84 |  | $8.51 E 5$ |  | 0 |  |  |
| mos | 128x | $\begin{aligned} & \text { FLGATE } \\ & \text { 12.5v } \end{aligned}$ | E flga | 125volife | 87 |  | 4.6856 |  | 7 | 1 SPEED, 1 MBCG, 3 MACL, 2 SBCL | ?, ?, 7, ? |
| mos | 128x | $\begin{aligned} & \text { LLGATE } \\ & \text { 12.5v } \end{aligned}$ | e flga | 6.5VOLIFE | 87 |  | 1.05 E 5 |  | 0 |  |  |
| mos | 256x | $\begin{aligned} & \text { FLGATE } \\ & 12.5 \mathrm{~F} \end{aligned}$ | e floa | 1250LIfe | 87 |  | 3.5456 |  | 8 | $\begin{aligned} & 2 \text { SBCL, } 3 \text { deccooe, } 2 \text { SACG, } 1 \\ & \text { MACG } \end{aligned}$ | ?, 2. 2, ? |
| mosos | 256k | $\begin{aligned} & \text { FIGNTE } \\ & 12.5 v \end{aligned}$ | E FlGa | 6.5volife | 87 |  | 4.75E4 |  | 1 | 1 sbCl | ? |
| mos | 32x | flgate | e 21vflga | 1250LIfE | 84 |  | 3.47 E 6 |  | 4 | 1 ty deccoen, 3 rse charge loss | ? 7 |
| mos | 64K | $\begin{aligned} & \text { FLEATE } \\ & 12.5 V \end{aligned}$ | E flga | 1250LIfE | 84 |  | 8.94E6 |  | 0 |  |  |
| ITL |  | FUSE | FUSE | htolife | 88 | 1000 |  | 100 | 0 |  |  |
| IIL |  | FUSE | FUSE | hTOLIFE | 88 | 1000 |  | 99 | 0 |  |  |
| IIL |  | fuse | FUSE | DHTLIFE | 81 | 1000 |  | 63 | 0 |  |  |
| ITL |  | fuse | FUSE | DHTLIFE | 80 | 1000 |  | 50 | 0 |  |  |
| ITL |  | FUSE | FUSE | DHTLIFE | 81 | 1000 |  | 50 | 0 |  |  |
| ITL |  | fuse | fuse | DHTLIFE | 84 | 1000 |  | 40 | 0 |  |  |
| ITL |  | fuse | FUSE | htolife | 87 | 1000 |  | 96 | 0 |  |  |
| ITL |  | FUSE | FUSE | DHILIFE | 84 | 1000 |  | 90 | 0 |  |  |
| ITL |  | FUSE | FUSE | DHTLIFE | 86 | 1000 |  | 50 | 0 |  |  |
| IIL |  | FUSE | fuSE | DHILIFE | 84 | 1000 |  | 54 | 0 |  |  |
| ITL | 16 K | fuse | fuse | Dhtlife | 81 | 1000 |  | 44 | 0 |  |  |
| IIL | 16K | FUSE | fuse | DHTLIFE | 82 | 1000 |  | 45 | 0 |  |  |
| IIL | 16K | FUSE | fuse | DHTLIFE | 84 | 1000 |  | 50 | 0 |  |  |
| IIL | 16K | FUSE | FUSE | DHTLIFE | 84 | 1000 |  | 50 |  |  |  |
| ITL | 16K | FUSE | FUSE | DHILIFE | 84 | 1000 |  | 66 | 0 |  |  |
| IIL | 16K | FUSE | FUSE | DHILIFE | 85 | 1000 |  | 100 | 0 |  |  |
| IIL | 16K | FUSE | FUSE | htolife | 87 | 1000 |  | 71 | 0 |  |  |
| ITL | 16K | FUSE | FUSE | htolife | 88 | 1000 |  | 100 | 0 |  |  |
| TIL | 16K | FUSE | FUSE | DHTLIFE | 84 | 1000 |  | 50 | 0 |  |  |
| ITL | 16K | FUSE | fuse | DHILIFE | 85 | 1000 |  | 100 | 0 |  |  |
| IIL | 16K | FUSE | FUSE | DHILIFE | 85 | 1000 |  | 100 | 0 |  |  |
| IIL | 16K | FUSE | FUSE | Dhilife | 85 | 1000 |  | 90 |  |  |  |
| TIL | 16K | FUSE | FUSE | DHTLIFE | 85 | 1000 |  | 90 | 1 | 1 Param fall | ? |
| TIL | 16 K | FUSE | FUSE | DHTLIFE | 85 | 1000 |  | 99 | 0 |  |  |
| TIL | 16K | fuse | FUSE | dhilffe | ${ }^{86}$ | 1000 |  | 90 | 2 | 2 limit failures (icc marg) | ? |
| TIL | 16K | fuSE | FUSE | ohtlife | 85 | 1000 |  | 89 | 0 |  |  |

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|  | DESC | FAECHNSM |
| :---: | :---: | :---: |
|  | AC PARAM SLO PATT | 7 |
| 2 | ACFUNC SLOPATT | $?$ |
|  | FUNC FAIL | $?$ |
|  | INTERMIT BIT， 1 UNK | ？， 1 ELECTRONIG |
|  | AC FUNC（BAKE RECON） | $?$ |
|  | FAILS AC | 7 |
|  | IN LEAK FAIL | 1 THR VOLT SHIFT |
|  | FUNC FAIL | 1 THR VOLT SHIFT |
|  | FUNC FAIL | 1 OXIDE DEFECT |
|  | VCCSUB SHORT | 1 JUNC LEAK MONION |




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| 1 umk | 1 fab offect |
| 1 unk | 1 fab defect |
| 1 Sbit chrge loss | 1 oxide brkdum |
| 1 grssfunc, 2 sbit chrceloss, 1 outleak, 1 melt Chrgecaim | 1 OPEM COWTACT, ?, 1 OXIDE BRKDW, ? |
| 1 ICC Stey Pur | $?$ |
| 1 SBIt Chrce gaim, 1 ROW | 7.7 |
| 1 machrgeloss, 1 grssfuwc. | 2. 2, 1 Pass hole |
| 3 SBIt Chrge loss |  |
| 2 Chrge gaim, 1 chrge loss, 1 OUTPUT FAIL | 2,7,7 |
| 2 sBCL | 1 Oxide brkow |
| 14 Imp LxGE, 8 CMRGE GaIm. 2 fuse lxge, 1 DECOO, 3 | 14 COWINM, 8 COWTAM, P, P, 1 COWTM, $1, ?$ |
| 2 mait chrge loss, 2 umx | ?, 2 COMTAM |
| 4 meit chrce cain | 4 COWIAN |
| 1 UNK | 1 OXIDE DEFECT |
| 1 ROUFAIL, 1 SPEED, 1 UWK | ?. ?, 1 Passoefect |



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| IYPE | PARTMM |
| :---: | :---: |
| UVEPROM | 27C64A |
| UVEPROM | 27c64A |
| UEPROM | 27c64a |
| UVEPROM | 27HC64 1 |
| UNEPROM | 27HC64 1 |
| UVEPROM | 27 HCS 41 |
| UVEPROM | $274 C 641$ |
| UVEPROM | 27HC64 1 |
| UVEPROW | 27 HCS 41 |
| UVEPROM | $27 \mathrm{CHC64}$ |
| UVEPROM | $27 \mathrm{HC6} 1$ |
| UVEPROW | $21 C 128$ |
| UVEPROM | 27C256 |
| UNEPROM | $27 C 256$ |
| UVEPROM | 876257 |
| UVEPROM | 27c64 |
| UVEPROM | 27c64 |
| UVEPRCM | 27c64 |
| uneprom | 27c6 |
| UVEPROM | P/M2764 |
| UVEPROM | P/M27c64 |
| UVEPROM | 27128 |
| UVEPROW | 27128A |
| UVEPROM | 27128A |
| UVEPROM | 27128A |
| UVEPROM | 271288 |
| UVEPROM | 271288 |
| UVEPROM | 27010 |
| UVEPROM | 27010 |


| IYPE | Partimen |
| :---: | :---: |
| UNEPRCM | 27210 |
| UVEPROM | 27210 |
| UMEPRCM | 27256 |
| UVEPROM | 27256 |
| UVEPROM | 2732A |
| UVEPROM | 2732A |
| UNEPROM | 2732a |
| UNEPROM | 27512 |
| UNEPROM | 27512 |
| UVEPROM | 27512 |
| UVEPROM | 27512xx |
| UVEPROM | 275120x |
| UVEPROM | 27640 |
| UVEPram | 27640 |
| UNEPROM | 27680 |

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[^5]APPENDIX F
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Wire bonding is a process which is accomplished by bringing two conductors to be joined into intimate contact such that the atoms of the materials diffuse together. The materials used for wires include silver, copper, aluminum and palladium. The materials used for pads are aluminum, gold, silver, nickel, copper and chromium. The wires serve to connect the small pads on the die to the external package leads (figure $F-1$ ).

Large compressive stresses along with ultrasonic vibrations or thermal energy are applied at the wire-pad interface during the bonding process. Cracks in the bond pad or in the substrate may result if the bonding stress is exceedingly high. ${ }^{[1]}$ Cracks are difficult to detect visually unless the bond is detached and must prevented before such parts are utilized in electronic equipment. Proper control of the bonding parameters usually assures reliable wire bonds. When bonding is achieved by a wire from the package lead to the cavity metallization, it is known as a substrate bond. ${ }^{[3]}$

When one lead is connected to another without going through the substrate metallization, it is called a control bond. Both destructive and non-destructive tests are used to ensure good performance. The first is the destructive Bond pull test. The purpose of this test is to measure the bond strengths, evaluate the bond strength distribution or to determine compliance with specified bond strength. In this test an external force is applied to the bond until failure occurs. If the bonding parameters are discrepant the bond would fail below the specified value as a result of the bond pull test. The location of the failure is an important clue for the initiation of the corrective action to prevent failure recurrence. The failure could be a wire break at the neckdown point due to a reduction of the cross-sectional area as a result of the bonding process. The failure could also be a break at a wire defect site other than the neckdown region, a failure at the interface between wire and metallization at the substrate or the package post, an interface failure between the pad metallization and the substrate, fracture of the die beneath the bond pad, or fracture of the substrate.

Another test is the non-destructive bond pull test. The purpose of this
method is to reveal unacceptable wire bonds. This procedure is usable for bonds made by either ultrasonic or thermal compression techniques. Any bond pull which results in separation of the bonds at the bond interface or breakage of the wire or interconnect anywhere along the entire length including the bond heels, at an applied force less than the specified force for the applicable material and wire diameter, constitutes a failure. The magnitude of the non-destructive pull force is around $80 \%$ of the minimum bond strength for the particular material unless otherwise specified.

A variation of the destructive or non-destructive bond pull test is the bond pull after bake test. In this test the devices are baked at a high temperature and then subjected to the bond pull test. The exposure to temperature accelerates crack propagation if microcracks in the die or substrate already exist.

A common destructive test is the "etch back analysis" test, whereby an aqua-regia solution is used to etch away the ball and metallization, exposing the underlying layers of the bond pad. Any cracks on the oxides or substrate are revealed by such a test.

Wire bond failures are a result of shear of the bond pad and the wire, flexure of the wire, excessive intermetallics, manufacturing parameters, galvanic corrosion and chip outs in $\mathrm{Si} / \mathrm{SiO}_{2}$. Plastic encapsulated packages also fail as result of stresses resulting from the differential expansion of the epoxy encapsulation and the wire if a low modulus buffer coating is not placed between the encapsulant and the wire.

MIL-HDBK-217E was developed by the Department of Defense in order to standardize the methods employed for reliability prediction procedures. The handbook provides uniform methods for predicting the reliability of military electronic equipment and systems and estabilishes a common basis for comparing and evaluating reliability predictions of designs.

The "Part Stress Analysis" prediction method of MIL-HDBK-217E is applicable during the later design phase where actual hardware and circuits have been
designed. The part operating failure rate model $\lambda_{p}$ is based on the following equation

$$
\lambda_{p}=\pi_{Q}\left(C_{1} \pi_{T}+C_{2} \pi_{E}\right) \pi_{L}
$$

where $C_{1}$ is the circuit complexity factor, $C_{2}$ is the package complexity factor and the $\pi$ terms account for the influences of environment, application, complexity, quality, production maturity of the process and relative stress level.

MIL-HDBK-2I7E does not explicitly discuss how wire bond failure contributes to the device failure rate. The package related term $\left(C_{2}\right)$ of the model depends only on the number of operational terminal pins in the microelectronic device. This term is not affected by any other factors such as temperature change or the rate of temperature change, manufacturing process, fatigue or thermal cycling differential expansion between the wire and the pad; but these factors have been found to affect the wire bond failures. This report presents an alternative to the MIL-HDBK-217E model. A statistical deterministic approach to failure modeling has been used for reliability prediction. This can then be used for design of microelectronic packages.

F2. THE WIRE BOND

F2.1. The Wire.

Wire is usually made of gold or aluminum. The wire bonding process may be thermocompression or ultrasonic. The thermocompression process typically uses a gold wire while the aluminum wire is utilized in the ultrasonic process. Gold tends to age in the amorphous state with a consequential decrease in tensile strength. The hard drawn gold wire ages significantly at room temperature so the softer and relatively more stable stress-relieved wire is recommended. Pure aluminum cannot be hardened sufficiently to allow it to be drawn to a diameter of 1 mil . Therefore aluminum is usually hardened by adding about $1 \%$ of an alloying element such as silicon or, less frequently, magnesium.

## F2.2. Wire Materials.

Wire materials include gold, copper, aluminum and palladium, with gold and aluminum being the more commonly used. The characteristics of the wire materials are of vital importance to the strength of the wire bond. These include wire dimensions, tensile strength, elongation and contamination.

It is important to have a wire of constant dimensions and known cross-sectional area because the bonding process conditions depend on the mass of the wire involved in making the bond. The tensile strength is an important specification both for ultrasonic as well as for thermocompression bonds. A bond wire is attached at two or more conductor pad or lead frame locations. After formation of the final bond, the continuously fed wire must be broken to permit moving the bonding head to the initial location of the next bond. Breaking the wire induces a very high tensile stress that could cause bond failure. A lower tensile strength wire would reduce the bonding time for satisfactory bonding. Also a softer wire is more difficult to align under the tool. Elongation is required so that the wire may be broken off after the second bond of the wire bond is made. A large elongation would result in an undue deformation of the wire which is used in the first bond of the next wire. This would cause the bond to be inferior. Too great a elongation may result in an excessively long tail in the second bond. Contamination would cause the corrosion of aluminum metallization or later device degradation due to water or ionic contaminants that may be included in the lubricants.

## F2.3. Bonding Surface.

The materials for pads on the semiconductor die include gold, aluminum, silver, nickel, copper and chromium. Aluminum is the most commonly used material in semiconductor dice. Gold is used to avoid problems in the formation of gold-aluminum intermetallics. Gold does not adhere well to silicon dioxide and a direct contact between gold and silicon is avoided. Therefore, other metals are used to form a multilayer metallization system. Bonding to the die and the terminal is affected by many film related factors which include surface smoothness, film hardness and thickness, film
preparation and surface contamination. Howell and Slemmons ${ }^{[27]}$ indicated that for thermocompression bonds the uniformity, composition and the thickness of metallization were important and that, in particular, surface irregularities could prevent adequate diffusion across the wire-metallization interface and hence interfere in the bonding process. Hil1 ${ }^{[28]}$ reported that by improving the uniformity of the metallization the reliability of the bond was increased. The hardness of the aluminum metallization is also said to be important. The metallization should be somewhat softer than the wire so that the surface irregularities may be easily smeared out to better conform to the wire. Too soft a metallization may cause other problems. The thickness of the metallization can have an effect on the bondability and the subsequent reliability of the bond. An excessively thick metallization may be very soft which would be very difficult to bond. To avoid subsequent bond failure due to intermetalic compound growth and metallurgical (Kirkendall, see F4.2) voids at the interface, Philofsky ${ }^{[29]}$ suggested that the thickness of the metal film be minimized, consistent with good bonding and device design. This suggestion applied both when bonding gold wire to aluminum on the semiconductor and when bonding aluminum wire to gold plated terminals.

When the device is subjected to thermal or power cycling, wire flexing at the neel will occur. Philofsky ${ }^{[29]}$ suggested that under these circumstances the thickness of the aluminum metallization should be less than one sixth the wire thickness at the heel of the gold wire wedge or stitch bonds to avoid the growth of intermetallic compounds into this region and the consequent failure of the wire at the heel of the bond. For the case of aluminum wire bonds to gold plated terminals it was suggested that the plating thickness be less than one third the wire thickness at the heel of the bond.

Excessive roughness of the bonding surfaces has been demonstrated to influence the quality of the wire bonds. The bonding surface roughness should be such that the area of the bond be large compared to the peak to peak variations in the surface. ${ }^{[24]}$

Contamination on the wire bonding surface should be avoided. For thermocompression bonding, it interfers with the intimate contact and the
interdiffusion of the wire and the metal film and contributes to making poorer bonds. The problem of contamination may be considered less for ultrasonic bonding because of the ultrasonic agitation. The contaminants could include residues of chemicals used in the photoresist and packaging plating operations, water spots, silicon monoxide, silicon dust and aluminum oxide. ${ }^{[24]}$

## F2.4. Gold-Aluminum Intermetallics.

In bimetallic bonds, a gold-aluminum interface exists at the wire/bond pad interface. Gold-aluminum compounds form at this interface at a rate which increases with temperature. Above a temperature of about $125-150^{\circ} \mathrm{C}$ the growth becomes significant with respect to long term reliability of the wire bonds. [24]

The compounds are formed by diffusion of gold and aluminum across the interface. Gold has a greater diffusion rate and as a result will leave behind vacancies on the gold side. The process of the Kirkendall void formation can lead to two types of failure: a mechanical stress-induced failure along the locus of the voids, and an electrical open circuit caused by the coalescence of the voids. Five different compounds appear in the region where the interface exits. These include $A u_{2} A I_{2}, A u_{5} A I_{2}, A u_{2} A l$, AuAl , and $\mathrm{AuAl}_{2} .{ }^{[24]}$

The kind of reliability problems which appear from gold/aluminum interactions depend on the wire bond type and whether a direct or expanded contact is used. Electrical failure occurs when gold wire ball bonds are made to aluminum bond pads because of the formation of an annular Kirkendall opening about the bond. The development of voids at the perimeter of the bond is accompanied by increases in the electrical resistance of the bond with time. The rate of increase in resistance with the exposure to elevated temperature is larger for thinner aluminum metallization. The bond adherence of these ball bonds is unimpaired by intermetallic compounds which react to the oxide. The intermetallic compounds adhere well to the silicon dioxide and, though brittle, can sustain a greater tensile stress than either gold or aluminum.

Mechanical failure can occur when gold ball bonds are made to thick aluminum films. This is because the supply of aluminum for reaction with the gold ball is practically unlimited. The process of void formation therefore continues uninterrupted. In this case the void formation at the interface results in a mechanically fragile bond after high temperature storage. Similar degradation can occur if an aluminum wire bond is made to a gold plated terminal where gold plating is too thick. [24]

Thus to minimize the degradation effects due to gold aluminum interactions, bonding to thick films and excessive bond deformation should be avoided.

## F2.5. Bond Types.

There are several different type of wire bonds including wedge bond, ball bond, and stitch bond. ${ }^{[4]}$ Wedge bonds (figure $\mathrm{F}-3$ ), are made with a wedge or chisel-shaped tool. The end of this tool is rounded with a radius one to four times that of the wire being bonded and is made of sapphire or similar hard material. This tool is used to apply pressure to the lead wire located on the bonding pad which has been heated to the bonding temperature. Different methods are provided for precisely coaligning the bonding pad, wire, and wedge. Difficulties with wedge bonding include imprecise temperature control, poor wire quality, inadequately mounted silicon chips, or a poorly finished bonding tool.

Ball bonding is a process in which a small ball is formed on the end of the wire and deformed under pressure against the pad area on the silicon chip (figure $\mathrm{F}-5$ ). The lead wire is perpendicular to the silicon chip as it leaves the bond area. The number of steps in this bonding operation are few and the strength of the bond obtained is strong. Aluminum wire cannot be used because of its inability to form a ball when severed with a flame. However, gold wire is an excellent electric conductor, is more ductile than aluminum, and is chemically inert. For ball bonding, hard gold wire may be used since the balling process determines the ductility of the gold to be deformed. Among the disadvantages of ball bonding is the fact that a relatively large bonding pad is required (see Appendix $\mathrm{H}-5$ ).

Stitch bonding combines some of the advantages of both wedge and ball bonding. The wire is fed through the bonding capillary, the bonding area is smaller than for ball bonds, and no hydrogen flame is required. Either gold or aluminum wires can be bonded at a high rate.

## F3. MANUFACTURING METHODS

There are several manufacturing methods for wire bonding to thick-film circuits. The most common are thermocompression bonding, ultrasonic bonding and combination of both. All these lead-bonding techniques depend upon obtaining intimate contact between the materials to obtain an atomic interface at the connection. ${ }^{\text {[5] }}$

## F3.1. Thermocompression Wire Bonds.

Thermocompression wire bonding, as the name indicates, depends upon heat and pressure. In general, the bonding equipment contains a microscope, a heated stage, and a heated wedge or capillary that will apply pressure to the wire at the interface of the bonding surface as shown in figure $F-4$. In addition, a wire-feed mechanism is required, as is some method for manipulation and control. Bonds can be accomplished utilizing thermocompression techniques which will exceed the wire-breaking point in strength, i.e., instead of the bond breaking, the wire will break during a pull test.

Three primary conditions in thermocompression bonding are force, temperature and time. The primary conditions are interdependent and are effected by other conditions and factors. Minor changes in these variables can cause significant differences in the bonding characteristics. It is necessary to optimize the primary conditions to obtain a satisfactory bond. Short bonding time is desirable for production purposes. Low bonding temperature is desirable to avoid the degradation of the wire bonds due to goldaluminum interactions of the device resulting from alloying effects. Low pressures are desirable to avoid fracturing or otherwise damaging the silicon beneath the bond. Too large a force may damage the semiconductor substrate or excessively deform the wire and too small a force may prevent adequate bonding. In
addition to the bond, the wire may also be the weaker link. In the ball bond the weakest link occurs in the high temperature annealed wire leading to the bond. In the stitch and wedge bonds it occurs in the region of the wire in which the cross-section has been reduced by the bonding tool. The bonding tool used in the process may of tungsten carbide, titanium carbide, sapphire and ceramics. ${ }^{\text {[24] }}$

## F3.2. Ultrasonic Wire Bonds.

Ultrasonic wire bonding also involves heat and pressure, but the heat is supplied by ultrasonic energy rather than by heated stage or capillaries as shown in figure $F-6$. In addition, with aluminum wire, the ultrasonic energy and the acoustical high-frequency movement of the wire against the conductor pad breaks the refracting oxides surrounding the aluminum wire. Pressure is also used but is incidental to the effect of the ultrasonic energy. The ultrasonic vibratory energy causes a temperature rise at the wire-conductor interface that can approach 30 to 50 percent of the melting point of the metal. One of the advantages of ultrasonic aluminum wire bonding is the absolute avoidance of purple plague. Purple plague, which is the embrittlement of the bond, has been found to be a result of the combination of aluminum, gold, silicon, and heat. Hence it is avoided by eliminating gold and heat.

The three primary conditions are force, time and ultrasonic power. The ultrasonic power available to make the bond is dependent on the power setting of the oscillator power supply and the frequency adjustment of the tool. The force used is large enough to hold the wire in place without slipping and to couple the ultrasonic energy into the bonding site without causing deformation of the wire. It is generally of the order of tens of grams force. The specific values selected depends on the size and the design of the bonding tool face, the size and the hardness of the wire and the sensitivity of the substrate. High power and a short bonding time is usually preferred to avoid metal fatigue and to prevent the initiation of internal cracks. Lower power nevertheless gives a large pull strength when a good surface finish exists.

## F3.3. Combination of Thermocompression and Ultrasonic Bonding.

The third method is the combination of ultrasonic and thermocompression wire bonding. In ultrasonic ball bonders the ultrasonic heat is identical to the usual type except a straight-wire capillary is used, as on a thermocompression bonder. Also included is the flame-off device necessary to form the ball on the gold wire. Whereas in straight ultrasonic gold-wire bonding it is difficult to bond gold wire of less than 0.002 in. diameter, on an ultrasonic ball bonder 0.001 in . diameter gold wire is usually used. The differences are in the capillary design and the fact that, in general, a heated stage is used. This process is almost a complete combination of both thermocompression and ultrasonic bonding, i.e., a heated stage, a capillary-type tool, and an ultrasonic transducer. The only thing missing is the heated capillary, which becomes unnecessary with an ultrasonic transducer.

## F4. BOND FAILURE MECHANISMS

Wire bonds involve $20-30 \%$ of the microelectronic package failures. [14] bond failures can be divided into two categories. The first are the failures that result from a poorly controlled or poorly designed manufacturing process that may result in an early device failure. The second category consists of the failure modes that cause adequately made bonds to fail by contamination and/or environmental stresses during the operating life of the device.

F4.1. Failure Mechanisms Due to the Manufacturing Process.

The bond strength depends on the materials and process variables associated with the substrate-metallization-wire composite structure. For example an adequate gold bond requires a bonding load large enough to produce a good interfacial conformity and a bond interface temperature high enough to effect contaminant dispersal. The purpose of compression in the bonding process is always to increase the area of contact, so as to produce a bond between area elements of fresh metal. The surface films get disrupted during the process and the bond occurs between patches of fresh metal. In the process of thermocompression bonding English ${ }^{[22]}$ discovered that the bonding
temperature or the tool load substantially lower than optimum values resulted in an inadequate bond. It was found that if bonding was attempted at an extra low temperature with a corresponding load increase, little or no bonding took place. It was found that heating was not required for welding of very clean surfaces. These observations are consistent with the view that heating is required for dispersing surface contaminants. Alternatively, use of very low tool loads and high bond temperatures also resulted in bond failure and/or low bond strength. The bonding process was found to be due to a shear displacement at the intended bond interface which disrupted the contaminant layers and contributed to the bond formation. English ${ }^{[22]}$ noted that leads and metallized substrates were stored in air typically for days, prior to interconnection. The surface therefore carried many adsorbed gases and, in particular, water vapor. When the substrate and the lead frame were heated the bond strength increased with temperature and the time of bake. Post-bond baking did not increase the bond strength significantly if the tool load was too low. It, however, did increase the bond strength of bonds made at low bonding temperatures.

Lang and Pinamaneni ${ }^{[16]}$ identified parameters affecting wire bond strength during manufacture. These included cleaning and copper plating of the lead frames, die attach cure conditions, atmosphere during bonding, surface finish of the lead frame, bonding time, bonding force, bonding pressure, and temperature. They identified that the presence of an inert atmosphere was essential to prevent oxidation of the lead frame. Further, it was found that a lead frame with a coarse surface finish gave greater bond strengths compared to that with a smooth surface.

Weiner and Clatterbaugh ${ }^{[18]}$ defined those machine parameters that could affect the shear strength of ball bonds. It was found that an increase in the ultrasonic power resulted in an increase in the shear strength of the bond. The substrate temperature was also found to affect the bond shear strength. The pedestal which supports the substrate during bonding is heated to enhance the formation of metallurgically sound bonds. The increase in pedestal temperature increases the shear strength. Occasionally it was found necessary to leave the substrate on the heated pedestal for periods longer than can be
considered normal. The effect of the extended residence on the pedestal was determined. The results indicated that that even with times up to three hours, there was no significant change in the bond shear strength. The effect of contamination, cleaning techniques and burn in on the ball shear strength was observed. It was observed that an increase in the contaminant concentration resulted in a decrease in the shear strength. The cleaning procedures used to remove the contaminants were found to vary in effectiveness, as measured by the restoration of the shear strength, depending on both the metallization and the contaminant type. Solvent cleaning was found to be the least effective method for restoring the ball shear strength to uncontaminated levels. UV-ozone used for the cleaning process was found to improve the bond shear strength most significantly. The shear strength of the bonds was found to increase after burn-in. The change in the bond shear strength, as a result of burn-in, was found to be highly dependent on both the type of the contaminant and the substrate metallization.

Poonawala ${ }^{[20]}$ identified the failure of wire bonds in cannon launched devices as result of long wire distances, which caused large wire bonds and die misalignment from the center of the package cavity, skewing the wire routing and bringing some wires too close to the adjacent bond pads on the package. Two failures mechanisms were discovered during the centrifugal testing: wires collapsed straight down and created a possibility of shorting to the cavity bottom, and wires collapsed sideways and created a possibility of shorting to adjacent bond pads or adjacent wire bonds.

Deroian ${ }^{[17]}$ stated that a low bond pull force couid result from bonding tool pressure not uniformly compressing the wire onto the pad. Further, the organic films on the bonding surfaces were found to impair the bond strength. Koch, Richling, Whitlock and Hal1 ${ }^{[2]}$ conducted experiments on the molding process of epoxy encapsulation of a 28 lead DIP package using a chase mold. The molding parameters considered were transfer time, mold temperature, mold compound preheat temperature and transfer pressure. Other factors considered included material flow characteristics and the kinetics of the molding compound. The experimental data showed that too fast a transfer time as measured with the mold compound in the mold increases the number of bond
failures. Further it was evident that high material preheat temperatures and high transfer pressure increased the number of bond failures. The results showed that the temperature variations across the cavities increased the variation of bond failures from one cavity to the next. It was also found that these parameters were interdependent because viscosity and flow characteristics are dependent on heat transfer and hydrostatic pressure. Also, the analysis of the material inside the mold showed that greater than $90 \%$ of the failures occurred on the opposite side of the die from the mold gate (figure F-7).

Ching and Schroen ${ }^{[1]}$ Reported a theoretical bond stress model developed by Dr. L.T. Beng. The model is based on the Hertz theory of contact pressure between two spheres modified to represent the geometry of a ball bond/bond pad interface, as depicted in figure $F-8$. The following simplifying assumptions were made to facilitate solution:
(1) The ball was assumed to be in contact with a silicon pad.
(2) The ball was assumed to be fully formed to a spherical shape at point of first contact with the pad.
(3) The ball was assumed to maintain a spherical shape during application of the bonding force and resultant deformation of the bond pad surface.
(4) The Al-Si diffusion zone was assumed to be . OOl inch thick and fully formed at time of inital contact.
(5) The ball/pad contact area was assumed to be circular and equal in diameter to either 2 or 3 times the wire diameter.
(6) Both ball and intermetallic were assumed to be elastic and to possess the mechanical properties of the gold wire.
(7) The intermetallic diffusion zone was assumed to form a spherical interface with the underlying silicon.
(8) The effects of applied ultrasonic energy on local bulk temperature and stresses were neglected.

The magnitude of the compression, tension and shear stress as a function of depth below the contact surface was evaluated at two values of bond force. As
expected, the maximum compressive and tensile stresses occurred at the surface and the maximum shear stress occurred at a depth below the surface that was considerably less than the assumed thickness of the intermetallic diffusion zone, i.e. all maximum stresses occurred in the intermetallic zone. The model predicted the existence of significant shear stress levels at the interface between the intermetallic zone and the underlying silicon, suggesting that excessive bonding force was a probable source of microcracks in the silicon. The data obtained from the model at 5 grams and 50 grams bonding force are shown in figure F-8.

The conclusion drawn from this model was that to reduce bond pad cracking the bonding force must be minimized to the lowest feasible value. The manufacturing data included parameters such as time to reach touchdown after ball formation, the moisture content, etc. It was shown that hardness of the gold ball at touch down also contributed to stress exerted on the pad. The factors that contributed to the hardness of the gold ball were the wire impurity level, the temperature of the gold ball at touch down, and the grain size as determined by the rate of cooling.

F4.2. Failure Mechanisms Due to Environmental Stresses and Other Conditions During Operating Life.

One of the failure mechanisms is the cracking of the bond pad. The bond failure in this mechanism is characterized by cracking of the underlying pad structure. Koch and Richling found that silicon nodule precipates from the metallization in the pad acted as points of high stress during the bonding of wire to the pad regions. Si nodules with about 1 um-diameter, which grew by annealing after metal deposition, were distributed uniformly before bonding. After the bonding process was complete it was observed that Si nodules decreased in the area of bonding and damage on the insulator was observed.

Another failure mechanism is the lifting of the bond. In this mechanism the gold aluminum intermetallic that has been formed during bonding continues its growth during baking and consumes all the aluminum that is left on the pad into a solid solution. The bond pads have oxides below the metallization
which act as insulating media. This permits the MLO (multi-level-oxide) to come into direct contact with the Au-Al intermetallic. As the devices are subject to additional shear stress during temperature cycling, the adhesion between these two materials weakens, the ball is lifted during bond pull test or other loading conditions, and the oxide is exposed.

Metallurgical cracks in the heel of the first bond of the Al ultrasonic bonds was found to be a failure mechanism in bonds by Harman. [21] Cracks were found to be a result of excessively flexed wire during loop formation especially when the second bond was significantly lower than the first. The flexure was caused by operator motion of the micropositioner or by bonding machine vibration just before or during bonding tool lift-up from the first bond. The sharp metallurgical microcracks were hypothesized to propagate through the wire and cause failure during device operating life. Another metallurgical failure identified by Harman was crystallographic damage to silicon under the bonding pad caused as a result of overbonding. This is often referred to as cratering because in severe cases a hole is left in the silicon substrate after a bond is removed. Cratering in thermocompression bonding was found to result from using too high a bonding force or too great an impact velocity of the tool with respect to the substrate. Cratering could also be caused by too small a ball which allows the hard bonding tool to contact the metallization. In ultrasonic bonding, cratering was found to be a result of too hard a wire which required high power and large bonding force. Wire bond failures resulting from poor process control during wafer fabrication were found to occur if bond pad metallization was poorly adherent or was far too soft or too hard. Poor metallization adherence was found to be a result of improper sintering time and temperature and lack of substrate cleanliness. Another cause for poor bond adhesion was found to be incomplete removal of glassivation or other surface contamination from the bonding pads. Thermocompression bonds were found to be more susceptible to failure from this cause than ultrasonic bonds.

Panousis and Bonham ${ }^{[23]}$ reported thermocompression bondability degradation with tantalum nitride-chromium-gold metallizations after a two hour air stabilization bake at a temperature of over $250^{\circ} \mathrm{C}$. The problem was traced to
a layer of chromium-oxide resulting from diffusion of chromium through the 3 $\mu \mathrm{m}$ layer gold and its subsequent oxidation at the surface.

Electrical leakaje failure during functional test constitutes another failure mechanism of wire bonds. Bonds with no visible evidence of damage or mechanical weakness were found to have intermittent electrical leakage. Leakage failure became significant in devices with an MLO-free bond pad. Failure analysis of these leakage failures revealed that there were no cracks on the pad. The leakage problem is the result of poor insulation from the Si substrate due to the lack of an MLO layer underneath the bond pad.

Cunningham ${ }^{[25]}$ suggested that metallurgical (Kirkendall) voids, were a cause of bond failure. These voids were formed by the different diffusion rates of gold and aluminum as each diffuses into the other. Under various circumstances the voids may appear on either the gold or on the aluminum side of the bond region.

Aluminum wire bonded to a conventional gold metallization cavity in cerdips (ceramic dual in-line packages) ${ }^{[9]}$ has been a well known reliability hazard due to "Purple plague" which is a brittle gold aluminum intermetallic which sometimes forms at an interface of a gold-aluminum thermocompression bond. This intermetallic appears purple in the crystalline form. Two types of plague-induced bond failures have been observed. In the first, the bond may be mechanically strong, but it can have a high electrical resistance or even be open circuited. In this case, which typically occurs with gold-wire bonded to thin aluminum metallization, voids form around the periphery limiting the available conduction paths. In the second type of failure, the voids lie beneath the bond. In this case the bond can fail due to mechanical weakness.

The Ag-Al system failure is very different in nature compared to Au-Al system, which is known to fail due to Kirkendall voiding of the diffusion front. ${ }^{[9]}$ The high resistance in the $\mathrm{Ag}-\mathrm{Al}$ bond occurs due to oxidation of the $\mathrm{Ag}-\mathrm{Al}$ alloy, resulting in a thin, insulating oxide layer which completely envelops the alloyed zone.

According to Griffith's theory of brittle fracture, the fracture stress is directly related to Young's modulus of the material. The phospho-silicate glass (PSG) layer beneath the bond pad has a lower Young's modulus than the thermal oxide layer due to the inherently lower density and high impurity concentration of phosphorous in the PSG oxide (figure $\mathrm{F}-9$ ). The number of bond failures increases as a function of phosphorous concentration in the PSG film. The PSG layer will fracture and the cracks will propagate through the PSG at a lower applied stress compared to the thermally grown $\mathrm{SiO}_{2}$ layer.

A failure mechanism in dry air was found to be due to selective oxidation of the Ag-Al alloy and activation energies were measured for various
atmospheres. ${ }^{[3]}$ Moisture was shown to decrease the activation energy. When the package absorbs much water before soldering, soldering heat stress causes a peeling off phenomenon of the wire ball from the Si substrate or insulator. The quality of bond will affect the bond failure rate. The Ag-Al substrate bond system has been studied and demonstrated to show an increasing resistance with time. This process is a thermally activated process and was used to assess the long term reliability of microcircuits. The resistance of the bond in this system was shown to change from negligible ( 0.1 ohm) to 20 ohms or higher. Forrest ${ }^{[8]}$ found that there was no discernable resistance change until a critical time is reached when it rises in a dramatic manner to bond resistance values ranged as high as 20 ohms or more.

Shukla and Deo ${ }^{[3]}$ found that the failure mechanism in dry air to be due to selective oxidation of the Ag-Al alloy. The expression for critical time was given as

$$
t_{c r}=t_{0}^{*} \exp (\Delta H / K T)
$$

where:

$$
\begin{aligned}
t_{0} & : \text { a temperature independent constant } \\
\Delta H & : \text { activation energy } \\
K & : \text { Boltzmann constant } \\
T & : \text { absolute temperature }
\end{aligned}
$$

The change in the resistivity of the Ag-Al binary system was found to be negligible till a particular critical time is reached, after which it rose to a very large value.

Koyama and Shiozaki ${ }^{[6]}$ stated that the number, size of the damage and cratering were affected by the applied ultrasonic energy which caused Si nodule damage to the insulator material.

Forrest ${ }^{[8]}$ noted that another failure mechanism was that of corroded wire bonds. Corrosion opened one end of the wire completely and occasionally both ends of the wire permitting the wire to move freely within the package volume causing intermittent electrical short circuits. It was found that chlorine ions had concentrated around wire bonds during the high purity water rinse. Capillary action of the wire bond to water interface concentrated any dissolved chlorine at that point causing the formation of $\mathrm{AlCl}_{3}$ during elevated temperature encountered during burn-in. Exposure of the conductor material to a chlorine environment caused a replacement chemical reaction converting copper oxide to copper chloride at the substrate interface, the presence of which caused the Al wire bonds to corrode or develop high resistance intermetallics. Another failure mechanism noted was electrical noise in the output of the circuit. The cause was detected to be the formation of intermetallics due to high chlorine concentration around bonds in a ball and socket configuration. This type of bond exhibits high mechanical strength in conjunction with low conductivity due to formation of resistive compounds at the interface. When such a bond was subjected to non-destructive bond pull test, an apparent healing of noise occurred due to reduction of the bonding resistance by motion of the wire relative to the bonding surface.

Moore ${ }^{[19]}$ found that hybrid circuit metallization was very susceptible to aqueous corrosion. A few contributing factors include the applied potential of the circuit power source to drive the corrosion reaction, the close proximity of the biased circuit conductors, ionic process residuals, microscopic and macroscopic galvanic couples and the small mass of the conductors. It was stated that under these conditions any quantity of electrolyte to provide ionic transport could present a significant reliability
problem. The corrosion reaction, dissolution and plating, was found to proceed at a distance up the wire from the die surface. The effect was due to a thin layer of die coat which had wicked up the wire surface. Another failure mechanism was that of silver dendrite growth from the wire bond pads of an integrated circuit. An epoxy was used to attach the gold backed die to the chip carrier die pad. After the epoxy cure the package was oxygen plasma cleaned and rinsed in DI water. The wet package was then placed in an oven to dry. It was at the drying stage that silver dendrite growth was observed. The dendrites extended out over the glass passivation layer. Another site for the corrosion was the copper winding of the chip coil. This was a type of the localized attack called pitting. The ionic process residues participated in the localized attack of the copper at the pitting sites.

Harman ${ }^{[21]}$ found that vibration forces that occur in the field are seldom severe enough to cause metallurgical fatigue or other bond damage. In general, large components of assembled systems were found to fail before such forces were sufficient to damage the bonds. Schafft ${ }^{[24]}$ calculated the resonant frequency as well as centrifuge induced forces for gold and aluminum wire bonds having various geometries. The minimum excitation frequency that might induce resonance and thus damage to gold wire bonds having typical geometries was found to be in the range of 3 to 5 kHz . For most aluminum wire bond geometries, the resonant frequencies required to damage the bonds were found to be greater than 10 kHz . Excitation frequencies encountered in military electronic equpment during ground operation and transportation are between 5 Hz and 55 Hz , and in airborne operation and transportation are between 5 Hz and 2000 Hz . Hence, for usually employed bond wire materials, diameters and span lengths, the wire resonance is unlikely to be excited.

Harman ${ }^{[21]}$ stated that in the case of hermetic devices, even if the package does not contain any corrosive materials, metallurgical bond failure modes may result from the effect of high temperature or cyclic temperature changes. If the external temperature is greater than about $150^{\circ} \mathrm{C}$ for long periods of time, the wire bond will partially anneal, producing a bond that is mechanically weaker in a bond pull test. Coucoulas ${ }^{[35]}$ however found that in the case of ultrasonic bonds, the work hardening and other strains in the thinned layer
were partially annealed, resulting in a more reliable bond.

Wire bond failures due to temperature cycling were studied by Gaffney, [31] Villella, ${ }^{[32]}$ Ravi, ${ }^{[33]}$ and Phillips. ${ }^{[34]}$ All of them worked on 0.001 in diameter aluminum, $1 \%$ silicon, wire bond metallurgical flexure-fatigue failures that resulted from repeated wire flexing due to the different coefficient of thermal expansion between the aluminum wire and the header as the device heated up and cooled down. The maximum flexure, and therefore the failure, was found to occur at the thinned bond heels. The heel of the chip bond was found to experience a greater temperature excursion and therefore was more prone to fail than the heel of the pad bond. Villella ${ }^{[32]}$ ran extensive statistical tests with cycled devices and determined that aluminum ultrasonic bonds were more reliable in this service than aluminum thermocompression bonds. Ravi ${ }^{[33]}$ experimentally investigated the metallurgical flexure fatigue of a number of aluminum alloy wires and showed that aluminum, $.1 \%$ magnesium alloy wires was superior to the commonly used aluminum, $1 \%$ silicon alloy. Philips ${ }^{[34]}$ calculated wire bond geometry effects and recommended that the 100 p height be at least $25 \%$ of the bond to bond spacing to minimize the bond flexure.

Another wire bond metallurgical failure mode was identified by Adams ${ }^{[26]}$ for gold wire in plastic encapsulated devices. A typical case of metal fatigue was encountered when the device was made to undergo thermal cycling. Adams calculated that for a $\Delta T$ of $100^{\circ} \mathrm{C}$ the stress due to different expansion coefficients of the wire and plastic would almost equal the breaking load of the wire, assuming that the plastic was bonded to the wire. At Westinghouse, this falure mode has been observed in packages which have been epoxy-filled.

Mantese and Alcini ${ }^{[15]}$ found that accelerated Al oxidation occurs as the temperature of the bond material is elevated causing the degradation of contact. Al melts at $660^{\circ} \mathrm{C}$ and oxidizes readily at lower temperatures, making it unsuitable for devices which experience high temperature. Other parameters found to affect bond quality are the bonding time, ultrasonic power, tool length, tool wear and type of substrate material.

It is clear that a considerable effort has been expended to analyze bond failure mechanisms. Yet, in spite of all the work done, a unifying deterministic failure rate model for wire bonds has not been proposed. Presently, MIL-HDBK-217E serves as a standard for reliability prediction of microelectronic packages but, except in the case of hybrid microcircuits, it does not account for the role of wire bonds in device failure. This report presents an alternative to the MIL-HDBK-2l7E model. A deterministic approach to failure modeling has been used so that the model can be used to predict the reliability of microelectronic packages during the design phase. This will permit reliability optimization prior to the committal of a design to production.

## F5. MODEL DEVELOPMENT

In this study wire bond failure models have been developed. The models address single metal bonds and the fatigue related damage which occurs when bonds between two dissimilar materials (bi-metal bonds) are formed. The models determine the number of cycles to failure as a result of the various bond failure mechanisms. The failure mechanism for which the predicted number of cycles to failure is the least value is the probable failure mechanism for the wire bond being analyzed.

## F5.1. Concept of Failure Prediction Using the Cycles to Failure Approach.

Failure of the wire bond occurs predominantly as a result of fatigue caused by repeated flexure of the wire, shear stresses generated between the bond pad and the wire and shear stresses generated between the bond pad and the substrate, all resulting from temperature cycling. Flexure of the wire will produce stresses at the heel of the bond in the case of wedge bonds and stitch bonds. Reversals in the bending stresses cause the eventual fatigue (breakage) of the wire at the heel. Due to the absence of any reduced section on the ball bond failure due to flexure is uncommon for the ball bond figure F-10).

Shear stresses between the bond pad and the substrate result from the
differences in the coefficients of thermal expansion between the substrate and the bond pad. This in turn results in the eventual detachment of the bond pad from the substrate, increase in the thermal resistance between the die and the substrate or the cratering of the substrate.

Shear stresses between the wire and the bond pad result from the differential thermal expansion between these two elements.

In encapsulated packages, if the encapsulant is in contact with the wire, the differential thermal expansion between the encapsulant and the wire can cause axial fatigue of the wire. This failure mechanism will not occur in encapsulated packages with a low modulus coating covering the wire. Since encapsulation without a low modulus buffer coating is an unacceptable practice, this mechanism is not further considered. The number of cycles to failure of a microelectronic package depends on the environmental conditions, the geometry of the wire bond and the materials of the substrate, wire and the bond pad. The fatigue failure prediction models take into account the environmental conditions and the geometry of the bond, which is consistent with the fact that the number of failures vary with the environmental conditions to which the wire bond is subjected. The stresses generated are a function of the geometry of the wire bond, the temperature fluctuation and the material properties.

The number of cycles to failure as a result of each of these mechanisms are calculated, compared, and the lowest value is the dominant failure mechanism. Any component subjected to temperature change would be acted upon by each of these failure modes simultaneously. These failure mechanisms act independent of each other. A component failure would result if the bond fails due to any of these mechanisms. The dominant mechanism would depend on the operating environment, the materials in consideration and the condition of the bond which is an implicit function of the the operating conditions.

## F5.2. Failure Prediction Models for Wire Bonds.

F5.2.1. Flexure Induced Failure Prediction Model for Wire Bonds.

A wire bond subjected to temperature cycling undergoes flexure fatigue. An increase or decrease in temperature causes the wire to expand and contract. This, coupled with the differential expansion between the wire and the bond pad, would cause the wire to flex as result of temperature cycling. Inherent as it is in the process, the cross-section of the wire is greatly reduced near the bond site. This makes it the weakest point on the wire and hence the most probable site for failure due to flexing in the wire.

Consider a wedge bond as shown in figure $F-11$. The two positions shown in the figure indicate the bond wire orientation before and after being subjected to the temperature change, $\Delta T$. If the curved length of the wire considered was to be assumed the same before and after flexure, then

$$
\begin{equation*}
\rho \psi=\rho_{0} \psi_{0} \tag{F5.1}
\end{equation*}
$$

where:

```
\rho is the initial radius of curvature
\rho
\psi is the initial angle subtended by the wire with the
substrate.
*
substrate.
```

The theory of curved bending was applied to evaluate the stresses in the wire. The stresses would be maximum in the outer portion of the wire towards the center of curvature. The stresses at this inner portion of the surface of the wire would be

$$
\begin{align*}
& \sigma=\frac{E(\bar{r}-\rho) d \psi}{\rho_{O} \psi_{O}}  \tag{F5.2}\\
& \sigma=\frac{E r\left(\psi-\psi_{O}\right)}{\rho_{O} \psi_{O}} \tag{F5.3}
\end{align*}
$$

where:

```
\overline{r}}\mathrm{ is the radius of the centroidal axis.
\rho is the radius at a desired section of the wire.
r = the radius of the wire (figure F-12)
```

$=\bar{r}-\rho$
Schafft ${ }^{[24]}$ derived the relation between the initial angle and the final "alue of the angle subtended by the wire.

$$
\begin{equation*}
\operatorname{Cos} \psi=\left(\operatorname{Cos} \psi_{O}\right)\left(1-\left(\alpha_{W}-\alpha_{S}\right) \Delta T\right) \tag{F5.4}
\end{equation*}
$$

On substituting equation (5.4) into equation (5.3) we get,

$$
\begin{equation*}
\sigma=\frac{E r\left(\left(\operatorname{Cos}^{-1}\left(\left(\operatorname{Cos} \psi_{O}\right)\left(1-\left(\alpha_{W}-\alpha_{S}\right) \Delta T\right)\right)\right)-\psi_{O}\right)}{\rho_{O} \psi_{0}} \tag{F5.5}
\end{equation*}
$$

where $E, \alpha_{w}, \alpha_{s}$ and $\Delta T$ are defined following equation F5.8.

$$
\begin{equation*}
\varepsilon_{f}=\frac{r\left(\left(\operatorname{Cos}^{-1}\left(\left(\operatorname{Cos} \psi_{O}\right)\left(1-\left(\alpha_{W}-\alpha_{S}\right) \Delta T\right)\right)\right)-\psi_{O}\right)}{\rho_{0} \psi_{0}} \tag{F5.6}
\end{equation*}
$$

where $\varepsilon_{f}=$ wire strain

$$
=\sigma / E
$$

This can be simplified into

$$
\begin{equation*}
\varepsilon_{f}=\frac{r}{\rho_{0}}\left|\frac{\operatorname{Cos}^{-1}\left(\left(\operatorname{Cos} \psi_{0}\right)\left(1-\left(\alpha_{W}-\alpha_{S}\right) \Delta T\right)\right)}{\psi_{0}}-1\right| \tag{F5.7}
\end{equation*}
$$

Examination of the geometry of typical bond wire installations suggests that a value of $\psi_{0}=15$ degrees suitably represents this parameter for most microcircuit wire bond configurations. In Appendix $\mathrm{F}-1$ it is shown that $p_{0}=35.1 \mathrm{~mm}$ ( 1.382 in ) suitably represents this parameter.

Incorporating the above values simplifies equation $F 5.7$ as follows:

$$
\begin{align*}
& \varepsilon_{f}=\frac{r}{35.1}\left|\frac{\cos ^{-1}\left(0.966\left(1-\left(\alpha_{W}-\alpha_{S}\right) \Delta T\right)\right)}{15}-1\right| \\
& \text { If } \Delta \alpha=\alpha_{W}-\alpha_{S}=0 \text {, then } \varepsilon=0 \\
& \text { If } \Delta T=0 \text {, then } \varepsilon=0
\end{align*}
$$

The strains reduce to zero when the temperature difference or the difference in the coefficients of thermal expansion reduce to zero. This is a $\Delta \alpha, \Delta T$ driven failure mechanism.

The number of cycles to failure can be related to the stress in fatigue calculated using this cycles to failure model, by Basquin's relation ${ }^{[37]}$ :

$$
\begin{equation*}
\left.N_{f(f) e x}\right)=A_{1}\left(\varepsilon_{f}\right)^{n_{1}} \text { (cycles to failure) } \tag{F5.8}
\end{equation*}
$$

where:
$N_{f(f l e x)}$ is the number of cycles to failure in flexure.
$\varepsilon_{f}$ is the strain computed from equation (F5.7)
$A_{1}$ is a constant for a particular material.
$n_{1}$ is a constant for a particular material.
A, is the constant for a particular material combination, Table 4.5-4
$n$, is a constant for particular material combination, Table 4.5-4.
$E$ is Young's modulus, from Table 4.5-1.
$r$ is the radius of the wire.
$\psi_{0}$ is the angle of the wire with the substrate.
$\alpha_{w}$ is the coefficient of thermal expansion of wire from Table 4.5-1.
$\alpha_{5}$ is the coefficient of thermal expansion of the substrate from Table 4.5-2
$\Delta T$ is the temperature difference encountered from Table 4.5-17.
$\rho_{0}$ is the initial radius of curvature of the wire.

F5.2.2. Failure Prediction Model for Shear Between the Bond Pad and the Substrate.

A component subjected to a temperature change would experience shear stresses between the bond pad and the substrate as a result of the differential expansion. These shear stresses are a result of the large difference in the coefficients of thermal expansion.

Ravi and Philofsky ${ }^{[30]}$ related the shear strain in fatigue to the temperature change encountered by the relation

$$
\begin{equation*}
\varepsilon_{\mathrm{fs}}=K \Delta T \tag{F5.9}
\end{equation*}
$$

where:
$\Delta T$ is the temperature change encountered by the component, Table 4.5-17.
$K$ is the material constant from Table 4.5-6.
$\varepsilon_{f s}$ is the strain as a result of shear between the bond pad and the substrate.

The constant $K$ is an experimental value which was estimated for other bond pad material-substrate combinations. The value of $K$ was calculated theoretically for the aluminum-silicon dioxide combination, for which the experimental value was given in [30]. A ratio of the theoretical value to the experimental value would therefore factor out the parameters which were not accounted for in the theoretical calculation. The calculated factor, if applied to the theoretically calculated value for other material combinations, would yield a value close to the true experimental value. This strategy was used to calculate the value of the constant $K$ for the various bond pad material and substrate combinations as shown in Table 4.5-6.

The shear stress in fatigue can be related to the number of cycles to failure using Basquin's relation.

$$
\begin{equation*}
N_{f(s h e a r) s}=A_{2}\left(\varepsilon_{f s}\right)^{n_{2}} \text { (cycles to failure) } \tag{F5.10}
\end{equation*}
$$

where:
$N_{f(s h e a r) s}$ is the number of cycles to failure as result of shear
between the bond pad and the substrate.

F5.2.3. Failure Prediction Model for Shear Between the Wire and the Bond Pad.

Bi-metal bonds experience large stresses as a result of differential thermal expansion between the wire and the bond pad. The bond is thus subjected to large shear stresses (figure $F-13$ ). The shear stresses vary in magnitude along the surface of the bond pad. They are maximum on the boundary of the bond pad and sharply decrease to more or less a constant value a short distance from the edge. The complex mechanics of the shear mechanism and the lack of experimental data forced the modeling effort to use a uniaxial model for the situation. From classical thermal analysis,

$$
\begin{equation*}
1_{\text {sub }}(\Delta T) \alpha_{\text {sub }}-\frac{p l_{\text {sub }}}{A_{\text {sub }} E_{\text {sub }}}=1_{\text {wire }}(\Delta T) \alpha_{\text {wire }}+\frac{\text { plwire }}{A_{\text {wire }} E_{\text {wire }}} \tag{F5.11}
\end{equation*}
$$

The substrate being in the bulk, the stresses are evaluated between the substrate and the wire instead.
where:
$l_{\text {sub }}$ is the contacting length of the bond.
${ }^{1}$ wire is the contacting length of the wire with the bond pad.
$p$ is the force generated as a result of the differential
expansion between the bond pad and the wire.
$A_{\text {wire }}$ is the area of contact of the wire and the bond pad.
$A_{\text {sub }}$ is the area on which the force due to differential expansion acts on the substrate.
$E_{\text {wire }}$ is Young's modulus of the material of the wire.
$E_{\text {sub }}$ is Young's modulus of the material of the substrate.
$\Delta T \quad$ is the temperature change encountered due to the operating conditions.

$$
\begin{align*}
& \alpha_{\text {sub }}, \alpha_{\text {wire }} \text { are the thermal coefficients of expansion of the substrate } \\
& \text { and wire, respectively. } \\
& \sigma_{\text {wire }}=\frac{(\Delta T)\left(\alpha_{w i r e}-\alpha_{\text {sub }}\right)\left(1 / A_{W i r e}\right)}{\left(1 /\left(A_{W i r e} E_{W i r e}\right)\right)+\left(1 /\left(A_{s u b} E_{s u b}\right)\right)} \tag{F5.11a}
\end{align*}
$$

Young's modulus of silicon is $15.5 \times 10^{6} \mathrm{psi}$ and the silicon being in bulk $A_{\text {sub }} E_{\text {sub }} \gg A_{\text {wire }} E_{\text {wire }}$. The second term in the denominator is therefore neglected. Since $E=\sigma / E$, the expression for the strain in the wire is reduced to

$$
\begin{equation*}
\varepsilon_{\text {wire }}=\Delta T\left(\alpha_{\text {wire }}-\alpha_{\text {sub }}\right) \tag{F5.12}
\end{equation*}
$$

The strain generated in the wire can be given as

$$
\begin{equation*}
\varepsilon=\left|\alpha_{W}-\alpha_{s}\right| \Delta T \tag{F5.13}
\end{equation*}
$$

where $\alpha_{w}=\alpha_{\text {wire }}$ and $\alpha_{s}=\alpha_{\text {sub }}$.
This strain is a tensile strain therefore the shear strain from the Mohr circle is

$$
\begin{equation*}
\varepsilon_{f s}=(1 / 2)\left|\alpha_{w}-\alpha_{s}\right| \Delta T \tag{F5.14}
\end{equation*}
$$

The number of cycles to failure can be calculated from Basquin's relation using equation F5. 10.

The model in usable form is:

$$
\begin{equation*}
N_{\text {fshear }}=A_{2}\left(\varepsilon_{f s}\right)^{n_{2}} \text { (cycles to failure) } \tag{F5.10}
\end{equation*}
$$

where:

$$
\begin{equation*}
\varepsilon_{f s}=(1 / 2)\left|\alpha_{w}-\alpha_{s}\right| \Delta T \tag{F5.14}
\end{equation*}
$$

where:
$N_{\text {fshear }}$ is the number of cycles to failure due to shear.


## F6. FAILURE PREDICTION STRATEGY FOR WIRE BONDS.

The number of cycles to failure as a result of each of these mechanisms is calculated, and compared. The lowest value represents the dominant failure mechanism. All these mechanisms act simultaneously and independent of each other; nevertheless, a failure as result of any of these mechanisms would constitute a failure of the wire bond. The dominant mechanism would depend on the operating environment, the materials in consideration and the condition of the bond which is an implicit function of the operating conditions. The dominant mechanism would, therefore, shift with a change in operating environment and the materials under consideration. The analysis methodology is illustrated in Figure $F-14$.

## F7. FUTURE WORK

1. The manufacturing parameters need to be evaluated to account for their effect on the failure prediction.
2. Coffin-Manson relations, parameters that need to be evaluated are $A_{1}$, $A_{2}, n_{1}$ and $n_{2}$
3. Evaluation of the constant $K$ for the biaxial stress state.
4. Finite element methods are required for more detailed analysis.
5. Fracture mechanics concepts are required to address interface failures.

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Figure F-1


Figure F-2


Figure F-3 The Wedge Bond


Figure $\mathrm{F}-4$ Thermocompression Wedge Bonding

Figure F-5 THE BALL BONDING OPERATION



Figure F-6 Ultrasonic wedge bonding


Fig. F-7 Location of falled bonds in relation to the incoming material flow during molding. Most of the failures occured on the Vent side of the die.



Figure F-9 SCHEMATIC CROSS-SECTION OF THE BOND PAD STRUCTURE


[^6]

## Figure F-11 FLEXURE OF THE WIRE DUE TO TEMPERATURE/POWER CYCLING



Figure F-12 THEORY OF CURVED BEAMS APPLIED TO THE WIRE BOND


Fig. F-13 Schematic for the shearing of the gold bell bonds on Al-Au thin film diffusion couples


Figure F-14 Failure prediction atrateg for wire assemblies

## APPENDIX F-1

EVALUATION OF BOND WIRE BEND RADIUS $\rho_{o}$

Consider a wire of length 2 L , cross-sectional moment of inertia 1 , made of an elastic material of stiffness $E$, bonded at two points separated by a span distance 2D, with a loop height $h$ and wire diameter $d$, as shown in Figure F-15. When the second attachment bond is completed the curvilinear configuration of the wire induces elastic strain energy in the wire as it settles to a stable configuration. The elastic strain energy stored in the wire is principally due to bending of the wire. It is required to determine the radius of curvature $\rho_{0}$ at the wire ends and the stress relief height $h$.

The profile of the wire in its stable configuration can be approximated with a polynominal series. The coefficients in this series will be determined by satisfying all geometric constraints and minimizing the strain energy of the wire. The minimization can be accomplished by using a standard variational scheme such as the Raleigh-Ritz method. Geometric constraints can be imposed by specifying closed form constraints between constant coefficients in the polynominal series and by introducing Lagrange parameters when closed-form constraints are infeasible.

The wire profile is assumed to be approximated by:

$$
\begin{equation*}
y=\sum_{i=0}^{n} a_{i} u^{2 i} \tag{F5.16}
\end{equation*}
$$

where

$$
u=x / D
$$

Only even powers of $x$ are considered to ensure symmetry about the $y$-axis.
Then $y^{\prime}=\frac{d y}{d x}=\frac{d y}{d u} \cdot \frac{d u}{d x}=\left[\sum_{i=0}^{n}(2 i) a_{i} u^{2 i-1}\right] \frac{1}{D}$

$$
\begin{equation*}
=\sum_{i=0}^{n}(2 i) b_{i} u^{(2 i-1)} \tag{F5.17}
\end{equation*}
$$

where $\quad b_{i}=\frac{a_{i}}{D}$

Therefore $\quad y^{\prime \prime}=\frac{d^{2} y}{d x^{2}}=\frac{d}{d x}\left(y^{\prime}\right)=\frac{d}{d u}\left(y^{\prime}\right) \frac{d u}{d x}$

$$
\begin{equation*}
=\left[\sum_{i=0}^{n}(2 i)(2 i-1) b_{i} u^{(2 i-2)}\right] 1 / D \tag{F5.18}
\end{equation*}
$$

The potential energy of the system can be written as:

$$
\begin{equation*}
\pi_{p}=U-W=\frac{1}{2} \int_{V} E \epsilon_{x x}^{2} d V-\int_{x} u_{x} F_{x}^{*} d x \tag{F5.19}
\end{equation*}
$$

where
$U=$ strain energy
$W=$ work done by applied traction $F_{x}^{*}$
but $W=0$ since $F_{x}^{*}=0$
Therefore $\pi_{p}=U=\frac{1}{2} \int_{V} E \epsilon_{x x}^{2} d V=\frac{E I_{x x}}{2} \int_{-L}^{L} k^{2} d s$
where

$$
\begin{aligned}
& K=\text { curvature }=\frac{y^{\prime \prime}}{\left[1+\left(y^{\prime}\right)^{2}\right]^{3 / 2}} \\
& d s=\sqrt{1+\left(y^{\prime}\right)^{2}} d x
\end{aligned}
$$

Then

$$
\begin{align*}
& \left.\pi_{p}=\frac{t T_{z}}{2} \int_{=0}^{D} \frac{\left(y^{\prime \prime}\right)^{2}}{\left[1+\left(y^{1}\right)\right]^{3}}[1+(y))^{1 / 2}\right]^{1 / 2} d x \tag{F5.21}
\end{align*}
$$

$$
\begin{equation*}
\text { or } \frac{2 \pi_{p} D}{E I_{z z}} \int_{-1}^{1} \frac{v_{1}\left(b_{i}, u\right)}{v_{2}\left(b_{i}, u\right)} d u \tag{F5.23}
\end{equation*}
$$

Where $V_{1}$ and $V_{2}$ are functions of $b_{i}$ and $u$ as given in equation $F 5.22$.

Integration of equation 55.23 is done numerically using a fifteen point Gaussian Quadrature scheme. We note that minimizing $\pi_{p}$ is the same as minimizing the fuctional;

$$
\frac{2 \pi}{E I_{z Z}} \frac{D}{}
$$

The following geometric constraints are applicable:

$$
\begin{equation*}
y=0 \text { at } x=0 \tag{F5.24a}
\end{equation*}
$$

$$
\begin{align*}
& \text { which implies that } B_{0}=a_{0}=0 \\
y^{\prime}= & 0 \text { at } x=0 \tag{F5.24b}
\end{align*}
$$

which is automatically satisfied

$$
\begin{equation*}
y^{\prime}=0 \text { at } x= \pm D \text {, or } u= \pm 1 \tag{F5.24C}
\end{equation*}
$$

which implies that $i \sum_{i=1}^{n}$ (Li) $b_{i}=0$ when equation $5.24 c$ is imposed on $b_{i}$ The following displacement boundary conditions are applicable:

$$
\begin{equation*}
2 L=\int_{-L}^{L} d s=\int_{-D}^{D} \sqrt{1+\left(y^{\prime}\right)^{2}} d x \tag{F5.25}
\end{equation*}
$$

$$
\begin{gather*}
=\int_{-1}^{1} \sqrt{1+\left[\sum_{i=1}^{n}(2 i) b_{i} u^{(2 i-1)}\right]^{2}} D d u  \tag{F5.26}\\
\text { or } 2\left(\frac{2}{D}\right)-\int_{-1}^{1} \sqrt{1+\left[\sum_{i=1}^{n}(2 i) b_{i} u^{(2 i-1)}\right]^{2}} d u=G=0 .
\end{gather*}
$$

The functional $G(=0)$ can now be introduced into our variational formulation through a Lagrange parameter $\lambda$. Thus, the new functional to be minimized is the functional H , where

$$
\begin{equation*}
H=\frac{2 d}{E I_{Z Z}} \pi_{p}+\lambda G \tag{F5.27}
\end{equation*}
$$

It is noted that $\lambda$ has the physical interpretation of being the force along the $x$ axis at the bond.

The function $H$ is minimized by seeking its stationary value.

Therefore $\delta H=0$

Which implies that $\frac{\partial H}{\partial b_{i}}=0, i=1$ to $n$
and

$$
\begin{equation*}
\frac{\partial H}{\partial \lambda}=0=G \tag{F5.29b}
\end{equation*}
$$

However, noting from equation $F 5.24 c$ that the $b_{i}$ are not independent, we rewrite equation $F 5.29 \mathrm{a}$ as follows:

$$
\begin{equation*}
\frac{\partial H}{\partial b_{i}}=\frac{\partial H}{\partial b_{i}}+\frac{\partial H}{\partial b_{n}} \frac{\partial b_{n}}{\partial b_{i}}=0, i=1 \text { to }(n-1) \tag{F5.29C}
\end{equation*}
$$

Equations F5.29b and F5.29c now constitute a set of $n$ coupled non-linear algebraic equations in $b_{i}(i=1$ to $n-l)$ and $\lambda$. These can be solved
iteratively for the unknowns $b_{i}$ and $\lambda$, using any standard solver software. The routine used in this study is the NEQNF subroutine from the IMSL math library. ${ }^{[35]}$ This subroutine utilizes the Levenberg-Marquardt algorithm.

When the unknowns are determined, $\rho_{\rho}$ and $h$ can be computed as follows:

$$
\begin{align*}
\rho_{\mathrm{D}} & =\frac{1}{D K_{0}}=\frac{1}{D}\left[\left.\frac{\left[1+\left(y^{\prime}\right)^{2}\right]^{3 / 2}}{y^{\prime \prime}} \right\rvert\, 0 u= \pm 1\right. \\
= & \frac{\left\{1+\left[\sum_{i=1}^{n}(2 i) b\right]^{2}\right\}^{3 / 2}}{\left\{\sum_{i=1}^{n}(2 i)(2 i-1) b_{i}\right\}}
\end{align*}
$$

Values of ( C ) are plotted vs ( $\frac{L}{\mathrm{D}}$ ) in Figure F-15.
We note that $\frac{h}{D}=\left.\frac{y}{D}\right|_{0} u= \pm 1=\sum_{i=1}^{n} b_{i}$
Noting that $y$ is negative everwhere for our choice of coordinate frame, the absolute value of $\left(\frac{h}{D}\right)$ is plotted vs ( $\frac{L}{D}$ ) in Figure $\mathrm{F}-17$.

It is now necessary to obtain a geometric perspective of the range of $h$ and D. We observe that for typical microcircuit package geometry:

$$
\begin{align*}
& 2.54 \mathrm{~mm}<2 D<10.16 \mathrm{~mm}(0.100 \mathrm{in}<20<0.400 \mathrm{in}) \\
& \text { or } \quad 1.3 \mathrm{~mm}<0<5.1 \mathrm{~mm} \tag{F5.32}
\end{align*}
$$

We also note that MIL-STD-883 visual inspection criteria prohibits a bond wire atachment without a visible loop height $h$, and establishes an effective maximum loop height for a specific package size by requiring a 0.127 mm ( 5 mi ) minimum clearance between the package lid inside surface and the wire. No minimum loop height is specified. However, differential thermal expansion of the wire, die and package materials effectively establishes a desireable minimum loop height to prevent axial stress in the wire at maximum temperature
difference. It is common practice for visual inspection purposes to express bond wire clearances and loop height in multiples of the wire diameter, as follows:

$$
\begin{equation*}
h=k d \quad(k>1) \tag{F5.33}
\end{equation*}
$$

where $d$ and $h$ are defined in Figure $F-15$.

It can be shown that axial stress will not occur in typical microcircuits for the span distance range shown in equation 55.32 when $3<k<8$. This result suggests that the typical loop height range is:
$0.08 \mathrm{~mm}<h<0.25 \mathrm{~mm}(0.003 \mathrm{in}<h<0.010 \mathrm{in})$

Then the ratio h/D range will be approximately as follows:
$0.016<h / D<0.192$
From Figure F-16 we obtain an L/D range for equation 55.35 as follows:
$1.00016<L / D<1.0229$
Then from Figure F-17:
$1.00<\rho_{0} / D<13.5$
(F5.37)
Substituting equation 55.32 into equation $F 5.37$ :
$1.3 \mathrm{~mm}<\rho_{0}<68.85 \mathrm{~mm}\left(0.051 \mathrm{in}<\rho_{0}<2.711 \mathrm{in}\right)$
Choosing a median value: $\rho_{0}=35.1 \mathrm{~mm}(1.382 \mathrm{in})$


FIGURE F-15
BOND WIRE GEOMETRY



F1-10

APPENDIX G
MECHANICAL FAILURES OF DICE, DIE-ATTACH AND SUBSTRATE ATTACH IN MICROELECTRONIC PACKAGES
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The die attach unit (figure G-l) of a microelectronic component package consists of the die or chip, the die attach, the substrate, the substrate attach and the case. The die is the medium which houses the integrated circuit. Silicon, gallium arsenide and indium phosphide are common die materials. The die attach material bonds the die to the substrate. Common die attach and substrate attach materials include gold-silicon and gold-germanium eutectics, epoxies, polyimides and many solder alloys. Common case materials are ceramic, kovar, aluminum and copper. Most frequently, the die is attached directly to the case. Occasionally, a substrate is used to provide mechanical support for the die, and to provide a thermal path for heat dissipation from the die to the die package case. Common materials used for substrates are alumina, silicon, copper and beryllium dioxide. The failure mechanisms in the die, die attach and substrate attach are interdependent and are governed by the component materials, dimensions, temperature range of thermal cycles, environments and assembly processes.

The die, the substrate and the case have different thermal expansion coefficients. As the temperature rises during manufacture and power cycling, tensile stresses are developed in the central portion and shear stresses are developed at the edges of the die. Therefore, microcracks nucleate at the top surface and at the edges of the die. If the initial crack, after the manufacture of the die, is equal to or greater than the critical crack size, then the die would fail in the first cycle. If the initial crack size is smaller than the critical crack size, then it may propagate during power and thermal cycling due to fluctuations in temperature. Brittle failure of the die follows when this crack reaches the critical size. Vertical cracking of the die is caused by tensile stresses and horizontal cracking is caused by the high shear stresses at the edges.

The most common die attach defects are voids. The presence of edge voids in the die attach induces high longitudinal (shear) stresses during thermal cycling. These voids may act as microcracks, which may propagate during power and thermal cycling resulting in debonding of the die from the substrate or
the substrate from the case. This appendix discusses the failure mechanisms of the die, die attach and substrate attach and the parameters which contribute to the failure of the die attach unit.

Failure rate prediction models for die, die attach and substrate attach are then developed which consider the failure factors from a coupled mechanistic, empirical and statistical approach. The fracture mechanics approach is taken to calculate the critical crack size in the die. If the initial crack size is smaller than the critical crack size then Paris's law is used to calculate the number of cycles to failure. The die attach and substrate attach materials fail by ductile mechanisms and hence the fracture mechanics approach is not very appropriate in this situation. The Manson-Coffin relationship is used to calculate the number of cycles to failure in die attach and substrate attach.

## G2. FAILURE MODELS

The development of a useful prediction model which can aid in design requires an evaluation of the of the fatigue life of the die, die attach and substrate attach due to stresses induced by thermal mismatch.

## G2.1 The die failure model

## G2.1.1 Stresses due to thermal mismatch

Die materials such as silicon or gallium arsenide have different thermal expansivities than commonly used substrate and case materials. Thus at manufacture, during cool down after the die attachment or during power cycling, the die attach becomes thermally stressed as shown in figures $G-2(a)$, (b) and (c). [l] Tensile stresses are developed at the top central portion of the die and shear stresses are developed near the edges of the die. These stresses increase with the size of the chip and are responsible for the initiation and propagation of microcracks. Ultimate fracture of the brittle die can occur suddenly, without any plastic deformation, when surface cracks at the center of the die or at the edge of the die propagate during thermal cycling and become equal to the critical crack size.

Figure G-3 shows the tensile force in the die and how it drops to zero near the edge of the joint. ${ }^{[2]}$ Figure G-4 shows the maximum shear stresses for different joint thicknesses of . 051, . $076, .127$ and $.178 \mathrm{~mm} .{ }^{[2]}$ It
illustrates that as the thickness increases by 3.5 times, the shear stress decreases by a factor of 1.8 only. The tensile stresses in the die are responsible for vertical cracking of the die due to surface cracks and vertical edge cracks and the shear stresses in the die are responsible for the horizontal cracking of the die as shown in Figure G-2.

## Q2.1.2 Effect of thickness of the die

The thickness of the die affects the stress distribution inside the die. For a silicon die attached to an alumina substrate, increasing the thickness of a die increases the average stresses inside the die. ${ }^{[3]}$ The total tensile stress near the interfacial voids also increases as the thickness of the die increases. These results indicate that a thin die is less likely to fail either due to tensile stress in the active circuit region or due to voids at the die attach interface as shown in figure G-5. ${ }^{\text {[3] }}$

Lowering the die thickness clearly reduces die cracking. However, excessive reduction of die thickness lowers the mechanical strength of the die and the die becomes prone to cracking during fabrication and handing.

Die and substrate attach thickness varies dependet upon the attach material type and fabrication process used to apply it. The values given in Table 4.5-18 are obtained from reference [27] and can be considered to be typical practice for die and substrate attachment in hybrid microcircuit design.

## G2.1.3 Brittle fracture of the die

Three separate modes of crack surface displacement are recognized in fracture mechanics methodology ${ }^{[20]}$ and are illustrated in figure $G-12$. Surface displacements in Mode I cracks are perpendicular to the crack plane. Tensile stresses in the material open the crack and stress concentrations at the crack tip cause crack propagation when the local allowable yield stress is exceeded.

Modes II and III cracks are caused by shearing displacements in the crack plane. Mode II is caused by an in-plane shearing force in which the crack surfaces slide perpendicular to the crack front, and Mode III is caused by an out-of-plane shearing force in which the crack surfaces produce tearing displacements that slide parallel to the crack front. Only Mode I crack displacements are of concern in microelectronic dice.

MIL-STD-883 , Method 2010 visual inspection criteria define: three types of Mode I cracks viz: surface cracks, vertical edge cracks and horizontal edge cracks as illustrated in Figure G-2 and in MIL-STD-883, Figure 2010-8. The inspection criteria specifies examination of die surfaces and edges at magnification and rejection of surface cracks in active circuit areas and of edge cracks that exceed specified geometry limits. The greatest allowable crack is a Mode I vertical edge crack (see Figures $G-2$ and $G-12$ ) extending more than $3 \mathrm{mils}\left(7.6 \times 10^{-5} \mathrm{~cm}\right)$ from the edge for Class $S$ devices, and 5 $\mathrm{mils}\left(1.3 \times 10^{-2} \mathrm{~cm}\right)$ for Class $B$ devices. This magnitude of allowable crack will propagate to die fracture earlier than any other acceptable crack.

In his classic 1939 paper on cracks in a two dimensional infinite solid, Westergaard ${ }^{[22]}$ used a complex variable approach to show that

$$
\begin{equation*}
K_{I}=\sigma_{a p p}(\pi a)^{1 / 2} \tag{G-1a}
\end{equation*}
$$

where:
$\mathrm{K}_{\mathrm{I}}=$ Mode I crack stress intensity factor
$\sigma_{a p p}=$ Mode I nominal far-field applied stress
$a \quad=1 / 2$ crack penetration depth

In 1946 Sneddon ${ }^{[23]}$ showed that for a circular penny-shaped surface crack in an infinite three dimensional solid

$$
\begin{equation*}
K_{I}=\frac{2}{\pi} \sigma_{a p p}(\pi a)^{1 / 2} \tag{G-1b}
\end{equation*}
$$

George Irwin ${ }^{[24]}$ used energy methods in 1962 to extend Sneddon's results to
semi-elliptical surface flaws on a three dimensional solid to demonstrate that

$$
\begin{equation*}
K_{I_{\max }}=\frac{1.12}{(Q)} 1 / 2 \sigma_{a p p}(\pi a)^{1 / 2} \tag{G-1c}
\end{equation*}
$$

where

$$
\begin{equation*}
Q=\phi^{2}-0.212\left(\frac{\sigma_{\partial p p}}{\frac{\sigma}{y s}}\right)^{2} \tag{G-2a}
\end{equation*}
$$

The geometry of the crack considered by Irwin was a surface flaw of $2 c$ length along the surface with a semi-elliptical shape penetrating to depth "a" below the surface as shown in figure $G-13$, section $A-A$.

For a brittle solid it was shown that

$$
\begin{equation*}
Q=\phi^{2} \tag{G-2b}
\end{equation*}
$$

where

$$
\phi=f\left(\frac{a}{c}\right) \text { and is given in terms of elliptic integrals. }
$$

In 1982 Brock ${ }^{[25]}$ derived the result

$$
\phi^{2}=1.41 \text { when } a / c \simeq 0.4
$$

Expressing the ratio $(Q)^{1 / 2} / 1.12$ as a surface elliptical flaw shape parameter, $m_{1}$, we obtain $m_{1}=1.06$ when $a / c \simeq 0.4$. Hence for surface flaws approximating this geometry equation $G-1 c$ becomes

$$
\begin{equation*}
K_{I_{\max }}=\frac{\sigma_{a p p}}{m_{1}}(\pi a)^{1 / 2} \tag{G-1d}
\end{equation*}
$$

A final correction factor $M_{K}$ was introduced in 1965 by Kobayashi et. al. [8] to account for the free surface ahead of the crack to the far surface of the body in the thickness dimension, resulting in the following expression for the crack stress intensity factor:

$$
\begin{equation*}
K_{\max }=\frac{M_{k}}{m_{1}} \sigma_{a p p}(\pi a)^{1 / 2} \tag{G-1e}
\end{equation*}
$$

where

$$
\begin{equation*}
M_{K}=0.953-2.369(\mathrm{a} / \mathrm{h})+2.74 \operatorname{Tan}(\mathrm{a} / \mathrm{h}) \tag{G-3}
\end{equation*}
$$

and
$h=$ Thickness of die

Note that equation $G-3$ is valid for semi-elliptical surface cracks for which a/c is approximately equal to 0.4.

Figure G-13 is based on figures 1 and 2 from ${ }^{[21]}$ and demonstrates the concept of a critical crack size. When repeated stress cycles cause a crack of initial penetration depth $a_{i}$ to reach a critical penetration depth $a_{c}$ (or critical surface length $c_{c}$ ), the crack will rapidly propagate to complete fracture of the die. The rapid propagation stage can be considered to be instantaneous.

Required visual screening of dice used in military microelectronic devices assures that all surface cracks of visually detectable size under magnification will be rejected. However, the acceptance criteria also assures that vertical edge cracks will be present in most dice. The acceptance criteria for horizontal edge cracks is much smaller than for vertical edge cracks. Hence, the model for prediction of the number of cycles to fracture for the die cracking mechanism need consider only Mode I vertical edge cracks as depicted in Section $B-B$ of figure $G-13$.

The brittle failure criterion can be represented by the size of the critical crack on the external die edge. Microcracks are developed in the die during manufacture. In some cases these microcracks may be large enough to cause brittle failure of the die. Fracture of the die would occur when the crack size is equal to or greater than the critical crack size. Hence, brittle failure of the die will occur in the first stress cycle if

$$
\begin{equation*}
\mathrm{a}_{i} \geq \mathrm{a}_{\mathrm{c}} \tag{G-4}
\end{equation*}
$$

where:

$$
\begin{align*}
& a_{i}=\text { initial crack length } \\
& a_{c}=\text { critical crack size needed to cause the brittle failure of the die } \\
& a_{c}=\frac{K_{I c^{2}}}{\sigma_{a p p^{2}} \pi} \tag{G-5}
\end{align*}
$$

where:

$$
\begin{aligned}
& K_{I C}=\text { fracture toughness of the die material, Table 4.5-7 } \\
& \sigma_{a p p}=\text { maximum applied stress }
\end{aligned}
$$

The thermomechanical stress level $\sigma_{a p p}$ in the die has been investigated by many authors $[1,2,4-6]$ who have derived equations for stresses developed in the die. An equation proposed by Bolger ${ }^{[1]}$ is:

$$
\begin{equation*}
\sigma_{a p p}=10^{-6} \mathrm{k}\left|\alpha_{s}-\alpha_{d}\right| \Delta T \sqrt{E_{s} E_{a} L / x} \mathrm{MPa} \tag{G-6}
\end{equation*}
$$

where:

```
k = geometric constant, dimensionless
\mp@subsup{\alpha}{S}{}}=\mathrm{ thermal coefficient of expansion of substrate or case,
        Table 4.5-9 or Table 4.5-1.0
\mp@subsup{\alpha}{d}{}}=\mathrm{ thermal coefficient of expansion of die, Table 4.5-7
E
Es}=\mathrm{ substrate or case tensile modulus, Table 4.5-9 or Table 4.5-10
x = adhesive bond thickness, Table 4.5-18
L = diagonal length of die
\DeltaT = maximum temperature change, Table 4.5-17
```

The geometric constant $K$ is a function of die shape and the amount of die attach filleting. A preliminary finite element study of a square die with normal production filleting practices was conducted to evaluate $k$. The study suggested that $K \simeq 0.2$ was a reasonable value.

It has been found that a highly correlated functional relationship exists between the die diagonal length $L$ and the number of I/O connections on the
die. ${ }^{[19]}$ A Reliability Analyst will usually know the number of active pins for a packaged microcircuit, and it can be reasonably assumed that the number of active pins is approximately equal to the number of I/O connections on the die. Reference [19] provides the following relationship:

$$
\begin{equation*}
\mathrm{L}=1.5 \times 10^{-3}+1.0 \times 10^{-4} \mathrm{P} \text { meters } \tag{G-7}
\end{equation*}
$$

where: $P=$ number of microcircuit active pins

Using equation G-7 for $L$, equation $G-6 a$ becomes:

$$
\begin{equation*}
\sigma_{a p p}=2 \times 10^{-7}\left|\alpha_{s}-\alpha_{d}\right| \Delta T \sqrt{E_{s} E_{a}\left(1.5 \times 10^{-3}+1.0 \times 10^{-4} p\right) / x} \tag{G-6b}
\end{equation*}
$$

Equations G-5 and G-6b assume that the adhesive bond thickness is less than the thickness of either the die or the substrate, the die shape is rectangular, the die and substrate are at the same temperature, and the moduli and thermal coefficients of expansion are not temperature dependent. In this equation the shear modulus of the adhesive $G_{a}$ has been replaced by the tensile modulus $E_{a}$ because it is very difficult to measure the shear modulus of the adhesives as compared to the tensile modulus. ${ }^{[1]}$ It is assumed that the numerical differences can be absorbed into the geometric constant $k$.

Many terms in equation G-5 are temperature dependent. Young's modulus for two typical die attach adhesives, a silver filled epoxy and a polyimide as a function of temperature are shown in figure G-7. [7] If the die size is constant, but the adhesive type is varied, then:

$$
\begin{equation*}
\frac{\sigma_{a p p 1}}{\sigma_{a p p 2}}=\frac{T_{g 1}-T}{T_{g 2}-T} \frac{\sqrt{E_{a 1} X_{a 2}}}{\sqrt{E_{a 2} X_{a 1}}} \tag{G-8}
\end{equation*}
$$

where:

$$
\begin{aligned}
& \sigma_{a p p}=\text { applied stress in die using adhesive die attach } \\
& T_{g}=\text { glass transition temperature for adhesive die attach } \\
& T=\text { ambient temperature }\left({ }^{\circ} \mathrm{C}\right)
\end{aligned}
$$

Subscripts 1 and 2 identify the adhesive die attach materials being evaluated.

Figure G-8 shows the use of equation $G-8$ to compare the stresses produced for different adhesives. ${ }^{[1]}$ Highest stresses are produced by glass adhesives and lowest stresses are produced by epoxy.

## G2.1.4 Fatigue crack propagation in the die

A pre-existing defect may develop into a crack under the influence of thermal cycling in the die. This crack may not be of critical size at the applied service stress, but may grow to critical size gradually by stable fatigue propagation.

In 1961, Paris et. al. ${ }^{[9]}$ proposed a power law to predict fatigue crack propagation based on the stress intensity factor $K$ at or near the crack tip in the plane of propagation. As the stress varies during thermomechanical cycling, $K$ will proportionately vary as follows:

$$
\begin{equation*}
\Delta K=K_{\max }-K_{\min } \tag{G-9}
\end{equation*}
$$

Then the rate of fatigue crack propagation, da/dN, will be given by Paris's law:

$$
\frac{d \mathrm{~d}}{d N}=A(\Delta K)^{n}
$$

where

```
a = instaneous crack size
```

$N=$ number of cycles
$A=$ material dependent coefficient
$n=$ material dependent exponent

Assuming that equation $G-6 b$ expresses the magnitude of the stress amplitude at the crack tip in completely reversed loading and equation $G-l a$ describes the proportionate $\Delta K$, then equation $G-10$ becomes:

$$
\begin{equation*}
\frac{d a}{d N}=A\left({ }^{\sigma} a p p(\pi a)^{1 / 2}\right)^{n} \tag{G-10a}
\end{equation*}
$$

rearranging: $\quad d N=\frac{d a}{A\left(\sigma_{a p p}(\pi a)^{1 / 2}\right)^{n}}$
integrating: $\int_{a_{i}}^{d_{f}} \frac{d a}{A\left(\sigma_{a p p}(\pi a)^{1 / 2}\right)^{n}}=\int_{0}^{N_{f}} d N=n_{f}$
where

$$
\begin{aligned}
& a_{i}=\text { initial flaw size } \\
& a_{f}=\text { final flaw size } \\
& N_{f}=\text { number of cycles to catastrophic failure }
\end{aligned}
$$

The final flaw size $a_{f}$ is seen to be identical to the critical flaw size $a_{c}$ defined in equation $G-5$ for the given $\sigma_{a p p}$. Hence

$$
\begin{equation*}
a_{f}=a_{C}=\frac{K_{I C^{2}}}{\sigma_{a p p^{2}} \pi} \tag{G-5}
\end{equation*}
$$

Then $N_{f}=\left(\frac{1}{A}\right)^{n} \frac{1}{\pi^{n / 2}} \frac{1}{\sigma_{a p p}} \int_{a_{i}}^{a_{c}} \frac{d a}{a^{n / 2}}$
$=\left(\frac{1}{A}\right)^{n} \frac{1}{\pi^{n / 2}} \frac{1}{\sigma_{a p p^{n}}}\left[\frac{a^{1-n / 2}}{(1-n / 2)}\right]_{a}^{d} c$
or $N_{f}=\frac{2}{(n-2) A \sigma^{n} \pi^{n / 2}}\left[\frac{1}{a_{i}(n-2) / 2}-\frac{1}{a_{f}(n-2) / 2}\right]$
for $n<>2$
where:

$$
\begin{aligned}
A= & \text { die material coefficient, Table } 4.5-7 \\
n= & \text { die material exponent, Table } 4.5-7 \\
\sigma= & \text { stress range, same as } \sigma_{a p p} \text {, equation } G-6 b \\
a_{i}= & \text { initial crack size, for MIL-STD-883, Class } S \\
a_{f}= & \text { the final crack length at failure, which may be taken to be } \\
& \text { equal to the critical crack size defined by equation } G-5
\end{aligned}
$$

## G2.2 The die-attach failure model

A common reason for failure of the die attach is fatigue resulting from power
cycling and environmental temperature cycling. In a typical power cycle, when the die is energized, the junction temperature rises. Later the device is turned off and cooled down. Because the die, the die attach, the die substrate and the package experience temperature differences and have different coefficients of thermal expansion, the die attach bonding the die to the substrate can experience cumulative fatigue damage.

## G2.2.1 Stresses due to the presence of voids

The most common die attach and substrate attach defects are voids. Voids are responsible for weak adhesion, die lifting (figure G-9a), increased thermal resistance, and poor power cycling performance. Voids can form from meiting anomalies associated with oxides or organic films on the bonding surfaces, outgassing of the die attach, trapped air in the bonds, and shrinkage of solder during solidification. Insufficient plating, improper storage, lack of cleaning, or even diffusion of oxidation prone elements from an underlying layer can generate voids during melting of die attaches. In other instances, dewetting of solder results in excessive voiding, especially when a solderable surface, a poor solderable underlying metal, or excess soldering time produces an intermetallic compound not readily wetted by the solder. Even under ideal production conditions, voids are of ten present due to solvent evaporation or normal outgassing during cooling of organic adhesives. Although voids can form from a number of sources, they are normally limited to an acceptable level through process control. The package construction, the die attach materials and the overall void concentration determine the actual effect of voiding on device reliability.

The formation of randomly distributed voids at the die substrate interface is generally unavoidable during the die attach process. The local stresses introduced in the die due to voids are very much dependent on the location of the voids. A finite element study done by Chiang and Shukla ${ }^{[3]}$ reveals that an edge void at the interface experiences tensile longitudinal stresses while a center void experiences compressive stresses, less in magnitude than the average stress obtained in the absence of the voids, as shown in figure G-10. It is shown that the edge voids are most likely to produce die cracking due to
high longitudinal stresses. The compressive nature of the stress near the center void greatly reduces the possibility for the crack to propagate. Die cracking statistics results for two samples of equal size with edge and center voids subjected to 10 cycles of thermal shock are summarized in reference [3]. The devices with center voids show no cracks, while devices with edge voids show nearly 50\% failure rate due to die cracks.

The size of the voids may reduce the thermal performance of the device by creating a large temperature gradient. ${ }^{[10]}$ In poorer performing thermal packages, small concentrations of random voids have little effect on the peak junction temperature. When a relatively large contiguous void is present, the heat must flow around the void creating a large temperature gradient in the silicon and severely degrading the package's thermal performance. If a large void is instead broken up into many smaller voids, the perturbation to heat flow is less with a much smaller temperature gradient induced in the silicon surface. Figure G-1l shows the temperature drop across the silicon chip, the die bond and the package materials.

Van Kessel ${ }^{[26]}$ pointed out the potential benefit of a small controlled. amount of voids formed due to solvents in the die attach adhesive. Small voids formed during cure may reduce stresses by reducing the modulus of adhesive by an expansion effect, which increases the bond thickness as shown in figure G-9b. Fig G-9c shows the case with no voids, resulting in high modulus.

## G2.2.2 Fatigue failure in die attach materials

Epoxy, solder, polyimide and silver filled glass materials are commonly used as die-attach materials. In today's market $80 \%$ of the materials used are epoxies, $10 \%$ are gold-eutectic solders and the remaining $10 \%$ are other materials. The response of a die attach material to the thermal stresses introduced during die bonding, power and temperature cycling is directly related to its mechanical properties. Therefore, an understanding of the mechanical behavior of each die-attach material as a function of temperature is essential because both the properties and responses of the die-attach change dramatically over a typical temperature range. The mechanisms by which
a die attach adhesive can contribute to the failure of a hermetic microcircuit are by the release of $\mathrm{Cl}^{-}, \mathrm{Na}^{+}, \mathrm{K}^{+}$or other extractable ions, by the release of $\mathrm{NH}_{3}, \mathrm{BF}_{3}$, or other corrosive vapors, by die cracking or distortion due to thermal stresses and by void formation under the die due to outgassing of solvents or other volatiles.

## Q2.2.2.1 Epoxy and polyimide die attaches

The mechanisms by which an epoxy die attach adhesive can cause or contribute to the failure of a plastic encapsulated component are discussed in paragraph G2.2.2. Some of these failures show up during production. Most, however, introduce the more serious possibility of causing failure after final packaging and inspection.

The gold and silver-filled epoxy die attach adhesives which were introduced during the 1970's offered important cost savings and process improvements over gold eutectic solders. These generally gave excellent bond strengths, good toughness and thermal shock resistance and could be cured rapidly, in one step, at temperatures of $150^{\circ} \mathrm{C}$ or below. These early epoxies were sold as " 100 percent solids" adhesives. They contained little or no organic solvent which had to be driven off during cure. However, these first generation epoxy die attach adhesives contained relatively high concentrations of water extractable ionic contaminants. These impurities, whether generated from the die attach adhesive or from the encapsulation compound, can severely shorten the operating lifetime of a microcircuit. Silver-filled epoxies used for die attach can be responsible for corrosion failure which occurs during humid conditions. Ions present in the epoxy can migrate in the presence of water vapor to the die surface and initiate a corrosion reaction with aluminum metallization which leads to electrical failure.

Unlike epoxy resins, which are made by a process which yields $\mathrm{Na}^{+}, \mathrm{Cl}^{-}$and $\mathrm{H}_{2} \mathrm{O}$ as undesirable by-products, polyimide resins are made by a process which does not include ionic impurities. Silver filled polyimide die attach adhesives can be made to a very high degree of ionic purity. Polyimides yield no other corrosive gases, such as $\mathrm{NH}_{3}$, as by-products of cure. Hence the
use of conductive polyimides for die attach, together with a parallel effort to convert to cleaner epoxy molding compounds, can essentially eliminate the previous possibility that a plastic encapsulated component will fail in service by a corrosion or dielectric breakdown mechanism.

## G2.2.2.2 Gold-eutectic solders

Gold-based eutectics Au-Si, Au-Sn and Au-Ge are expensive hard solders which do not degrade from fatigue or creep damage during thermal cycling. They are still widely used in military applications and most hermetic packages, where the demand for high performance and reliability overrides the cost, but their high residual stresses lead to cracked dies.

The rigid gold-eutectic systems can not absorb the dimensional changes due to different thermals expansion rates between the die and the substrate material, causing cracks in the die and eventually device failures, mostly during thermal cycling. Fracture in Au-Si eutectic mounting of large chips in ceramic packages have been reported in the literature by several
workers. ${ }^{[11-14]}$ Contributing factors such as voids, non-wetting, improper anneal techniques and preform thickness are discussed and several solutions have been proposed.

## G2.2.3 Fatigue failure of die attach

The Manson-Coffin equation ${ }^{[15-18]}$ relates the number of cycles to failure and the plastic strain per cycle,

$$
\begin{equation*}
N_{f}=0.5\left[\frac{Y_{a}}{Y_{f}^{\prime}}\right] 1 / c \tag{G-11}
\end{equation*}
$$

where:

$$
\begin{aligned}
N_{f}= & \text { number of cycles to failure } \\
Y_{a}= & \text { plastic strain amplitude, equation } G-12 \\
Y_{f}^{\prime}= & \text { fatigue ductility coefficient, defined as shear strain } \\
& \text { required to cause failure in one load reversal, (Table } 4.5-8 \text { ) }
\end{aligned}
$$

$$
\begin{align*}
c= & \text { Manson-Coffin fatigue exponent } \\
= & \text { slope of low cycle fatigue curve of log shear } \\
& \text { strain vs. log cycles to failure, (Table 4.5-8) } \\
& Y_{a} \text { is given by, } \\
Y_{d}= & \frac{L \alpha_{s}-\alpha_{d} \mid \Delta T}{x} \tag{G-12}
\end{align*}
$$

where:

$$
\begin{aligned}
L= & \text { diagonal die length, meters, (see paragraph G2.1.3 and equation } \\
& G-7 \text { ) } \\
\alpha_{s}= & \text { substrate expansion coefficient, (Table 4.5-9) } \\
\alpha_{d}= & \text { die expansion coefficient, (Table 4.5-7) } \\
\Delta T= & \text { temperature excursion per cycle, (Table } 4.5-17 \text { ) } \\
x= & \text { height of the die attach }
\end{aligned}
$$

## G2.3 The substrate attach failure model

Fatigue failure of the substrate attach is similar to the fatigue failure of die attach, except that in this case the dimensions and the materials are different.

Number of cycles to failure in the substrate attach is given by the Manson-Coffin relationship,

$$
\begin{equation*}
N_{f}=0.5\left[\frac{L_{S}\left|\alpha_{C}-\alpha_{S}\right| \Delta T}{x_{S a} \gamma^{\prime} \frac{1 / C}{f}}\right]^{1 / C} \tag{G-13}
\end{equation*}
$$

where:

$$
\begin{aligned}
& L_{S}=\text { diagonal length of substrate, meters } \\
& \alpha_{C}=\text { thermal expansion coefficient of the case, (Table 4.5-10) } \\
& \alpha_{S}=\text { thermal expansion coefficient of substrate, (Table 4.5-9) } \\
& \Delta T=\text { temperature excursion per cycle, (Table 4.5-17) } \\
& x_{s a}=\text { thickness of the substrate attach, meters }
\end{aligned}
$$

```
\mp@subsup{Y}{}{\prime}}=\mathrm{ fatigue ductility coefficient of substrate attach defined
    by shear strain intercept at one load reversal, (Table 4.5-8)
c = slope of low cycle fatigue curve of log shear strain vs. log
    cycles to failure, (Table 4.5-8)
```


## G3. CONCLUSIONS

1. The stresses in the die can be reduced by reducing the size of the die, by increasing the die attach thickness, by choosing the substrate to match thermal expansion coefficients, by reducing the temperature fluctuations, and by reducing the tensile modulus of die attach, and substrate.
2. The stresses in the die attach can be reduced by reducing the die size, increasing the die attach thickness, by matching the thermal expansion coefficients of die and substrate, and by reducing the edge voids.
3. Traditionally, the substrate covers more than $90 \%$ of the area of the case and therefore it has a large diagonal length, resulting in the smallest number of cycles to failure of the substrate attach. Therefore, the substrate should be divided into many small pieces to reduce the diagonal length of substrate. Also thermal expansion coefficients of the case and the substrate must be matched.

## G4. RECOMMENDATIONS

1. TESTING THE MATERIAL PROPERTIES DIE MATERIALS:

FRACTURE TOUGHNESS $\mathrm{K}_{1 \mathrm{c}}$
A, $n$ (FOR FATIGUE CRACK PROPAGATION LAW EQN. FOR DIE)
$\alpha_{d}(T), v_{d}$ (TO COMPUTE STRESSES IN THE DIE)
DIE ATTACH MATERIALS:
$E_{a}(T), v_{a}(T)$ (TO COMPUTE STRESSES IN DIE)
$Y_{f}, c$ (FOR LOW CYCLE FATIGUE IN DIE ATTACH)
SUBSTRATE MATERIALS:

$$
E_{S}(T), v_{S}(T), \alpha_{S}(T)
$$

2. FINITE ELEMENT STUDY
3. TO PREDICT THE INDUCED STRAINS
4. TO STUDY THE EFFECT OF DIE THICKNESS DUE TO BENDING-STRETCHING COUPLING
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DIE MATERIALS: SI, FOAB, InP
DIE ATTACH AND SUJBSTRATE ATTACH
MATERIALS: EDOxies, Polyimides, Gold-outectics, Sllver Filled Gless
SUBSTRATE MATERIALS: Alumina, Aluminium
CASE MATERIALS: Kover, Aluminlum, Copper
FIGURE G-1
DIAGRAM SHOWING THE DIE AND THE SUBSTRATE MOUNTED IN A HYBRID CASING

DIE IN ZERO STRESS STATE AFTER CURE


## AFTER COOL DOWN TO LOWER TEMPERATURE



FIGURE G-2

THERMAL STRESSES IN BONDED DIE DEVELOPED AFTER CURE

## TENSILE FORCES INDUCED IN THE DIE DUE TO THERMAL EXPANSION



FIGURE G-3
tensile forces induced in the die due to thermal expansion


FIGURE G-4

SHEAR STRESS DISTRIBUTION OVER WIDTH OF JOINT
FOR DIFFERENT JOINT THICKNESSES



FIGURE G-5

$$
\begin{gathered}
\text { VARIATIONS IN THE NUMBER OF DIE CRACKS AS } \\
\text { A FUNCTION OF DIE THICKNESS }
\end{gathered}
$$



FIGURE G-6

EFFECT OF DIE DIAGONAL LENGTH (L) AND
ADHESIVE THICKNESS ON THERMAL STRESS OF DIE


FIGURE G-7

ADHESIVE TENSILE MODULUS VS. TEMPERATURE


FIGURE G-8

MAXIMUM STRESSES FROM EQUATION 2(a)


Excessive volds, low shear strength, low thermal conductivity, die cracking or "popping"
(a)

(b)

No volds, high modulus, high strength adhesive, possible fallure by die cracking with large dies
(c)

FIGURE G-9

EFFECT OF VOID CONTENT AND SIZE ON DIE LIFT, die strengit and die cracking


FIGURE G-10

VARIATIONS OF THE LONGITUDINAL TENSILE STRESSES, along the die attach interface for the situations OF A 10 MIL EDGE AND A 10 MIL CENTER VOID


FIGURE G-11

SCHEMATIC DIAGRAM SHOWING TEMPERATURE DROPS ACROSS
the silicon chip, the die bond and the package materials.


BASIC CRACK SURFACE DISPLACEMENT MODES

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CORROSION IN MICROELECTRONIC PACKAGES
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## APPENDIX H

## CORROSION IN MICROELECTRONIC PACKAGES

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HI. BACKGROUND

## HI.l Introduction

The corrosion failure mechanism has become more significant as component sizes have been miniaturized with increased functionality, higher component density and faster signal processing, resulting in smaller components with closer spacings and thinner metallic sections. With width, separations, and thicknesses of components measured in micrometers; even small amounts of corrosion can cause problems and device failure.

The presence of water, one of the necessary elements for corrosion, is often a consequence of the materials and processes used for packaging integrated circuits. Consequently, controlling the access of moisture to and ionic contamination of integrated circuit chips has been the chief means of minimizing corrosion as a circuit failure mode. Water vapor may be entrapped within the cavity of hermetic parts at sealing. It may also be released within the cavity by package materials after sealing. At a constant temperature, most hermetic package cavities will contain a moisture level in equilibrium with the cavity walls. Temperature excursions will shift the equilibrium. In particular, an extreme drop in temperature will cause the sealed cavity to attain its dew point, and condensation will form on the inner surfaces of the cavity.

In recent years there has been a rapid increase in the use of plastic encapsulated semiconductor devices. This is primarily because plastics serve as a rugged, durable and low-cost packaging material. However, most plastic molding compounds offer less resistance to moisture ingress from the outside environment than their hermetic counterparts.

In the following sections, the corrosion mechanisms in microelectronic packages are modeled mathematically to provide the time to failure, $\tau$, of the metallization and bond pad in a package. The results provide a prediction of the reliability of the package in actual operation.

## H1.2 Corrosion In Microelectronic Packages

Corrosion is broadly defined as material deterioration caused by chemical or electro-chemical attack. Although direct chemical attack can occur with most materials, electro-chemical attack usually occurs only with metals. In microelectronic packages, the three most common forms of corrosion mechanisms are uniform, galvanic and pitting corrosion.

## H1.2.1 Uniform Corrosion

Uniform corrosion is defined as a heterogeneous chemical reaction which occurs at a metal-electrolyte interface and involves the metal itself as one of the reactants. It occurs uniformly over the surface of a material. The process can either be time dependent or self limiting. If the reaction products are
 linearly with time until all the materials are being corroded. If these products do not dissolve readily in the corrodant, the process becomes a self limiting phenomenon. Since the corrosion rate is proportional to the current which flows from anode to cathode via the electrolyte and if the corrosion products are electrically resistive and eventually the current magnitude decrease as the corrosion product film thickness increases. The corroded material is typically in the form of an oxide which adheres to the corrosion surface and acts as a protective layer to retard further corrosion from occurring. The rate of corrosion will depend upon the stabllity of this corroded layer. For example, aluminum oxide will protect aluminum from corrosion.

Most commonly, uniform attack occurs on metal surfaces which are homogeneous in chemical composition or which have homogeneous microstructure. The access of the corrosive environment to the metal surface must also be present.

H1.2.2 Galvanic Corrosion

Electronic component design is unique in the wide variety of metals used
because of particular physical and electrical properties. Some of the more common metals and their uses in an electronic system are given in Table H-1. [17] These metals are combined to form a myriad of dissimilar metal couples in electronic equipment. In the presence of moisture, destructive galvanic corrosion can take place.

Galvanic corrosion can occur in metallization when dissimilar metals, such as, the molybdenum-gold system, or in aluminum metallizations with gold bond wire, are used. Corrosion occurs at exposed regions such as bonding pads and can proceed along the passivation-metal interface. An electrical potential difference will usually exist between two dissimilar metals exposed to a corrosive solution. When these two metals are electrically connected the more active metal will become the anode in the resulting corrosion cell, and its corrosion rate will be increased. The extent of this increase in corrosion will depend upon several factors. A high resistance in the electrical connection between the dissimilar metals will tend to decrease the rate of attack. On the other hand if a large area of the more noble metal is connected to a smaller specimen of the more active metal, attack of the more active metal will be greatly accelerated.

The conductivity of the corrosion medium will also affect both the rate and the distribution of galvanic attack. In solutions of high conductivity the corrosion of the more active alloy will be dispersed over a relatively large area. In solutions having a low conductivity, on the other hand, most of the galvanic attack will occur near the point of electrical contact between the dissimilar metals. This latter situation is usually the case, for example, under atmospheric corrosion conditions. [3]

## H1.2.3 Pitting Corrosion

In pitting corrosion, attack is highly localized to specific areas which develop into pits. Active metals such as aluminum, as well as alloys which depend on Al-rich passive oxide films for resistance to corrosion are prone to this form of attack. These pits usually show well defined boundaries at the
surface, but pit growth can of ten change direction as penetration progresses. When solid corrosion products are produced, the actual corrosion cavity may be obscured but the phenomenon can still be recognized from the well defined nature of the corrosion product accumulations. Pitting corrosion is usually the result of localized, autocatalytic corrosion cell action. Thus, the corrosion conditions produced within the pit tend to accelerate the corrosion process. As an example of how such autocatalysis works, consider the pitting attack of aluminum in an oxygenated solution of sodium chloride. Assume that there exists a weak spot in the oxide film covering the aluminum surface so that the corrosion process initiates at this point. The local accumulation of $\mathrm{Al}^{3+}$ ions will lead to a local increase in acidity due to the hydrolysis of these ions. That is, the hydrolysis of aluminum ions gives as the overall anodic reaction:

$$
\left.\mathrm{Al}+3 \mathrm{H}_{2} \mathrm{O} \Rightarrow 3 \mathrm{H}^{+}+\mathrm{Al(OH}\right)_{3}+3 \mathrm{e}^{+}
$$

If the cathodic oxygen reduction, which produces alkali, occurs at a region removed from this anodic reaction; the localized corrosion of the aluminum will produce an accumulation of acid. This acid destroys the protective oxide film and produces an increase in the rate of attack. In addition, the accumulation of a positive charge in solution will cause the migration of $\mathrm{Cl}^{-}$ions to achieve solution neutrality. This increased $\mathrm{Cl}^{-}$concentration can then further increase the rate of attack. This process is illustrated schematically in figure $H-2 .{ }^{[37]}$ Since the oxygen concentration within the pit is low, the cathodic oxygen-reduction reaction occurs at the mouth of the pit, thus limiting its lateral growth. In most cases pits tend to be randomly distributed and of varying depth and size. [4]

## H1.3 Factors Affecting the Rate of Corrosion

There are several mechanisms by which a microelectronic package can be contaminated. Contaminants may be sealed within a microelectronic package depending on the properties of the structural materials and fabrication methodology. Contaminants can also permeate into a package according to the
permeability of the package. When corroding contaminants are coupled with the appropriate environmental conditions such as temperature and temperature cycling, moisture content, electrical bias (either applied or galvanic bias), and ionic contamination levels, corrosion occurs.

## H1.3.1 Properties of the structural materials

The materials used to fabricate an electronic package will determine the inherent resistance of the package against corrosion, and its capability to minimize the moisture ingress rate and the amount of impurities which enter the package.

To minimize moisture access to the metallization layer in a package, a passivation layer is often applied. The passivation layer is frequently a glass, silicon nitride, silicon dioxide or other dielectric layer deposited onto the device surface. Plasma-deposited silicon nitride is used as a passivating layer because it is an effective barrier for alkali ions which may be left on the device surface after the final wash. However, silicon nitride can give rise to a change in the surface potential, which can introduce charge trapping and storage effects, and give rise to interface conduction due to the activation of traps. These effects can contribute to corrosion as well as contribute to device electrical performance degradation. ${ }^{[3]}$

Failures due to corrosion of the metallization are frequently associated with defects in the passivation, such as cracks and pinholes. These defects act as sites for the entrapment of contaminants or moisture which are instrumental in corrosion. The chemical vapor deposition (CVD) process deposits films which are in tensile stress, resulting in localized lifting or cracking of the passivating layer in regions of poor adhesion. This mechanism creates sites at which contaminants can penetrate to protected metallization patterns and initiate corrosive attack.

Aluminum, which is the most common interconnect material, has a stable oxide and is therefore self-passivating in the absence of ionic surface
contamination. In the presence of water combined with ionic contaminants such as sodium and chlorine, the oxide can be broken down and the aluminum attacked when an electrical bias is applied. The phosphorous content of the silicon dioxide layers used in the passivation is an important factor in the reliability of the devices. The phosphorous is added both to provide mechanical stability of the glass coating and as a getter for mobile sodium ions. However, too little phosphorus causes cracks in the passivation layer due to tensile stress of the film while too much phosphorus results in aluminum corrosion. Cracking of the passivation increases the susceptibility of the underlying aluminum to corrosion by impurities.

Die attach materials can affect the contaminant level in a package. When epoxies are used as adhesive, they can act as a source of ionic contamination since the epoxide resin itself is a mixture of hydrolizable chlorine, bromine and sodium.

Moisture, which is required for corrosion to occur, is often trapped in the cavity of a hermetically sealed microelectronic during the assembly process. Additionally, certain materials that are used in the microelectronic fabrication and assembly process inherently contain adsorbed moisture --polymers used for the die attachments, gold plated surfaces, and even the plastic used for the package itself. Moisture can ingress a package by permeation through polymers used in the seals and the package material, or by leakage through cracks or small voids between the plastic material and lead frame in molded plastic packages. Furthermore moisture may induce crack growth in package materials, destroying the hermetic seal.

## H1.3.2 Fabrication Methodology

Fabrication methodologies affect the amount of contaminants inherent in the package, the potential for contaminant ingression, and the rate at which corrosive damage will lead to a failure.

Throughout the fabrication process, wafers are cleaned with various acids and
solvents. Like water, these chemicals contain other elements that function as contaminants to integrated circuits and thus impact wafer ecology. Wafers are also exposed to industrial and specialty gases at every process step. As dry processing becomes more prevalent, gases are now one of the major raw materials employed in the manufacture of microelectronic packages.

Another factor to consider during the fabrication process is the recontamination of baked out parts during handing. That is, properly baked out parts can be recontaminated by the re-exposure to moisture at ambient environment. Research ${ }^{[6]}$ indicates that a dry surface will absorb many monolayers of moisture during exposure in less than one second. Therefore, baked out parts should be handled cautiously.

Soldering is a frequently used method in bonding the lid to the package. For high reliability applications, gold is preferred for soldering surfaces since it is more resistive to corrosion. It is usual to deposit a thin layer of gold onto both the lid and package using a plating technique. At the melting temperature, the solder melts and wets both surfaces to form the joint. When wetting occurs, sufficient solder volume must be available to compensate for manufacturing variations in lid and package flatness. Corners of domed lids and sealing edges are typical sites for out-of-flat build up.

Lid sealing process also affects the final moisture content of the package through the silicon used in the chip bonding eutectic.

The amount of silicon available is dependent on the temperature and duration of the seding process. As the sealing time and, therefore, temperature increases, the amount of silicon diffused from the eutectic bond increases and the silicon produced will react with the water vapor to produce silicon oxide. Hence the level of moisture decreases.

## H1.3.3 Permeability

Microelectronic packages are the exterior portions of the device which provide
protection to the internal die and a mating surface to the external circuitry. The permeability of a package determines the ingress rate of contaminants from the ambient environment.

The oxide coating and the seal structure are important in corrosion of the die. In particular, the oxide coating on the lead frame conductor must be sufficiently thick to allow a good chemical bond to the sealing glass, and second, the design of the seal and the residual stress present in the seal must be able to withstand the rigors of thermal shock.

Package enclosures are referred to as hermetic or non-hermetic, which relates to the package's ability to resist moisture intrusion. Hermetic packages are enclosed with inorganic moisture resistant material such as metal, glass and ceramic. Non-hermetic packages are made of organic materials such as plastics which are permeable to moisture. Plastic packages are typically molded from silicone, phenolic or epoxy. Due to their cost, plastic packages are very popular in recent years. However, they offer reduced resistance to ingress of moisture and are not acceptable for military application, but efforts are being made to improve their moisture protection characteristics.

In general, for a non-hermetic package, moisture ingress is dominated by permeation through the package body. For a hermetic package, moisture ingress is by leakage through defect induced leak paths in the lead and lid seal with insignificant diffusion through the housing material. The quantity of the permeated or leaked contaminants is dependent on the construction processes and materials.

The leakage of contaminants into a package is dependent on the leak rate of the package, assuming the package processing was proper. All packages leak at some rate, but a package is defined to be hermetic if its leak rate is less than a specified value. For military microelectronic packages this value ranges from $\leq 1 \times 10^{-8} \mathrm{~atm} \mathrm{cc} / \mathrm{sec}$ for package volume < 0.01 CC to $\leq 5 \times$ $10^{-7} \mathrm{~atm} \mathrm{cc} / \mathrm{sec}$ for package volume $>0.4 \mathrm{cC}$ as defined in MIL-STD-883 method 1014. The leak rate is also dependent on the shape of the leak path.

In general, the leak rate decreases as the cross section decreases or as it becomes more elongated and the flow changes from viscous to molecular. Generally, leaks into packages arise due to stress cracks which have elongated rather than circular cross sections. The differential pressure of the leaking medium, and the properties of leaking medium, including viscosity, density, and molecular mean path will also affect the leak rate.

A fluid arrives at one side of a barrier material, such as a seal, and leaves at the other side by the following steps: (1) condensation on or adsorption oy the membrane, (2) solution in the membrane, (3) diffusion, (4) dissolution, (5) evaporation or desorption from the membrane. All of these processes together make up permeation. Gases must go through all five steps; liquid are already condensed so that they only go through step 2,3 and 4 . Usually, though not always, step 3 , diffusion, the process by which a fluid moves through a membrane, is rate controlling. ${ }^{[7]}$ When the flow rate is different from the prediction, an argument invariably arises that permeation is not occurring, but leakage.

Permeation is a direct function of the partial pressure differential of the permeating species and to a lesser extent temperature changes. In the following sections, the contribution of moisture ingress will be mathematically modeled and interpreted to provide the platform for developing the time to failure ( $\tau$ ).

## H.3.3.1 Permeation

The ingress rate of the contaminants into a package can be expressed as a function of the partial pressure of the permeating species, and can be mathematically written as follows:

$$
\begin{equation*}
P(L, t)=P_{1}+\left(P_{0}-P_{1}\right) e^{\left.-\frac{\left(\pi^{2} D_{p} t\right.}{}\right)} \frac{4 L^{2}}{} \tag{H1.1}
\end{equation*}
$$

where:

| $P(L, t)$ | is the inside partial pressure at time $=t$ |
| :--- | :--- |
| $P_{1}$ | is the outside partial pressure |
| $P_{0}$ | is the initial inside partial pressure |
| $D P$ | is the permeation rate |
| $L$ | is the wall thickness |
| $t$ | is the time |

The development of equation HI .1 from fundamental principles is given in Appendix $\mathrm{H}-1$.

## H1.3.3.2 Leakage

The sources of moisture in the hermetically sealed packages have been delineated in various papers [8],[9],[10] and may be categorized as follows: 1) adsorbed water due to poor bake-out procedures; 2) generated internally by decomposition, desorption, or devitrification of sealing glasses; and 3) penetration of cracks and/or faulty seals.

A review of the fundamental gas flow equations ${ }^{[12]}$ delineates three definable areas of flow regime for leakage flow; namely, viscous, transitional, and molecular. Each regime has its own equation (see Appendix $H-2)$ describing the effects of the geometric considerations of the leak path along with various gas parameters. Among the three mechanisms, molecular flow is the dominant phenomenon since leakage pin-holes or tortuous capillaries have such small dimensions that, except for quite high pressure differentials, the mass transport will be controlled by wall collision rather than viscous drag.

Assuming molecular flow, and an external partial pressure, $P_{1}$, of a gaseous species of molecular weight $M$, and a hermetic package possessing a leak rate $Q_{S}$ equal to the maximum value allowed by its performance specification, the rate of ingress of the gaseous species into the package is

$$
\begin{equation*}
\text { Rate of Ingress }=\frac{P_{1} Q_{S}}{P_{a}}\left({ }_{M}^{M a}\right) 0.5 \tag{HI.2}
\end{equation*}
$$

where:

```
Pa}\mathrm{ is the atmospheric pressure
Ma}\mathrm{ is the molecular weight of the gas inside the package
```

The gaseous species which enters the package through the leak is also able to escape via the leak. For a partial pressure, $P_{0}$, inside the package, the rate of loss is

$$
\begin{equation*}
\text { Rate of Loss }=\frac{P_{0} Q_{S}}{P_{a}}\left({ }_{M}^{M \partial}\right) 0.5 \tag{H1.3}
\end{equation*}
$$

By combining equation H 1.2 and H . 3 , the rate at which the gaseous species builds up inside the internal cavity is

$$
\begin{equation*}
V{ }_{d t}^{d P}=\frac{\left(P_{1}-P_{0}\right) Q_{S}}{P_{d}}\left({ }_{M}^{M 2}\right) 0.5 \tag{H1.4}
\end{equation*}
$$

where $V$ is the internal volume of the package. Solving the differential equation H1.4 for the internal partial pressure gives

$$
\begin{equation*}
P(t)=P_{1}\left(1-e^{-D_{L} t}\right) \tag{H1.5}
\end{equation*}
$$

where $t$ is the duration of the exposure to the gaseous species, and

$$
\begin{equation*}
D_{L}=\frac{Q_{S}}{V P_{\alpha}}\left(\frac{M \partial}{M}\right) 0.5 \tag{1}
\end{equation*}
$$

is a leakage coefficient. It should be noted that from the time of fabrication, contamination of the package occurs, even though the device is not in operation or powered. Thus, the shelf life of the device cannot be ignored.

H1.3.4 Environmental Conditions

H1.3.4.1 Temperature and Temperature Cycling

The permeation and the corrosion rates are affected by the surrounding environment, and in particular, temperature combined with moisture is the most deteriorating. Chemical reaction rates are greatly enhanced at elevated temperature. Thus the rate of galvanic corrosion, when a liquid phase electrolyte is present, will increase accordingly due to a more rapid rate of electron transfer.

The primary components of the microelectronic package are the mold epoxy, lead frame, die, and die attach material. Each of these components has its own coefficient of thermal expansion, which determines how great the expansion or contraction of the material will be in response to changes in temperature. Large differences or mismatches in expansion coefficient between components can increase susceptibility of a given device to cracking initiated at the region of maximum stress under thermal cycling.

A microelectronic package undergoes numerous duty cycles in its life and the application and removal of power will subject the package to thermal cycling. This temperature fluctuation will also influence the actual duration of the corrosion process. For example, when a non-operating sealed package is exposed to a temperature below the dew point, the moisture inside the package will condense and the liquid combines with any ionic contaminant present which will provide a conductive path for an electrical leakage path between adjacent metallic conductors. When the package is operating, the heat dissipated by the chip will elevate the temperature inside to above the dew point, consequently the electrolyte will evaporate to the vapor phase and will no longer permit leakage between conductors.

## HI.3.4.2 Humidity

Humidity, one of the necessary elements for corrosion to occur, is the largest single risk factor concerning reliability and expected life of the device. ${ }^{[13]}$ Moisture ingress occurs through leak paths in the lid and lead seal resulting from cracks or flaws and by permeation through organic
encapsulant. Flaws result from manufacturing process deviations as well as mechanical and thermally induced stresses.

## H1.3.4.3 Electrical bias

When sufficient moisture is present to act as an electrolyte and a bias is applied, ions are carried to the anode or cathode (depending on the electrical charge of the impurities involved). The bias may simply be the varying voltage levels on different conductors caused by normal operation of the integrated circuits, or a galvanic bias may be present.

Corrosion kinetics greatly depends on the applied bias as shown in figure H-3 which gives the corrosion rate versus the applied voltage for epoxy encapsulated chips. [42]

## H1.3.4.4 Ionic contamination

Studies ${ }^{[43]}$ have shown that parts per billion levels of selected pollutants are sufficient under proper conditions of temperature and humidity to accelerate corrosion reactions in electronic equipment. Corrosion can occur during manufacturing, storage, shipping and service. Moisture and corrosive agents such as chlorides, fluorides, hydrogen sulfide, sulfur dioxide, nitrogen compounds such as ammonia, and other airborne contaminants are the major culprits. ${ }^{[44]}$ Sources of chlorine ions in a package include the chlorine-based dry etches used for microcircuit metallization, or if epoxy is used in the package, the outgassing of the surrounding epoxy. Sodium ions can be produced from the epoxy or glass used in the package.

In decreasing order of importance, the three sources for the ionic contaminants that may reside on the chip of hermetically sealed devices are [33].

1) Die-handling operations post fabrication and pre-sealing. The chip has its highest vulnerability to uncontrolled environment during mechanical
and human handling.
2) Wafer fabrication. The environment is clean, but inadequate cleaning and rinsing of slices can leave contaminants.
3) Package hermeticity failure, allowing the ingress of ions from external sources along with moisture. During subsystem and system assembly, many parts receive detergent washes and/or conformal coatings at the board level. Many of these materials are notorious sources of both positive and negative ions.

One of the standard methods of cooling an electronic enclosure is the use of forced ventilation, with air generally drawn from the surrounding atmosphere. In sites with aggressive atmospheres, this type of cooling will greatly accelerate corrosion because the circulating contaminated air comes in intimate contact with sensitive electronics. Unless the outside environment is benign, the introduction of outside air into an electronic equipment cabinet should be controlled.
Ionic contamination accelerates the corrosion process. Figure $\mathrm{H}-4$ gives a comparison of the corrosion results of unencapsulated chips between chips doped with 10 ppm NaCl and cleaned test chips. The mean time between failure (MTBF) of 50 hours for the doped chips compares poorly to 850 hours for the undoped chips, indicating the strong effect of a small concentration of mobile impurities.
h2. DEVELOPMENT OF THE FAILURE RATE MODEL FOR CORROSION

## H2.1 General Model For Corrosion Failure

Three major failure sites in a microelectronic package are identified in 4.5.1, viz: the wire bond, the die and die attach, and the metallization. An accelerated test was performed at $85^{\circ} \mathrm{C} / 85 \%$ RH with encapsulated packages and the percentage failure was reported ${ }^{[15]}$ and is shown in figure $H-5$. The reliability of the package in a corrosive environment was then plotted and best fitted with a Weibull curve as shown in figure $H-6$. The failure rate was also calculated using the Weibull model (figure $H-7$ ) which indicated that the
fallure mechanism is an increasing function of time, thus is a wear out phenomenon.

The time to fallure ( $\tau$ ) of a component due to corrosion can be modeled as the sum of the induction time and the time for the corrosion process to deplete bond pad metallization or segments or conductor metallization. Induction time is an indication of time required for moisture to penetrate the package and for initiation of the corrosion process. Mathematically,

$$
\begin{equation*}
\tau=\tau_{1}+\tau_{2} \tag{2}
\end{equation*}
$$

where:
$\tau$ is the time to failure
$\tau_{1}$ is the induction time to reach the threshold moisture content
$\tau_{2}$ is the time for completion of the corrosion process

Figure $H-8$ delineates $\tau_{1}$ for a hermetic package as a function of the package volume and the allowable leak rate from MIL-STD-883, Method 1011 , Table II, which provides the following data:

$$
\begin{array}{ll}
\text { Volume }<0.01 \mathrm{~cm}^{3} & , \text { Allowable leak rate } \leq 1 \times 10^{-8} \text { atm } \mathrm{cc} / \mathrm{sec} \\
0.01 \mathrm{~cm}^{3} \leq \text { Volume } \leq 0.4 \mathrm{~cm}^{3}, & \text { Allowable leak rate } \leq 5 \times 10^{-8} \text { atm } \mathrm{cc} / \mathrm{sec} \\
\text { Volume }>0.4 \mathrm{~cm}^{3} & , \text { Allowable leak rate } \leq 5 \times 10^{-7} \text { atm cc/sec }
\end{array}
$$

From Figure $\mathrm{H}-8$ it is seen that as the leak rate increases, $\tau_{1}$ (hermetic) approaches zero. Hence, if a microcircuit is subjected to environmental or handling stresses before installation which cause a latent flaw to develop into a leak, such as failure of a lid seal, then $\tau_{1 \text { (hermetic) }}$ will decrease and

$$
\tau_{2} \gg \tau_{1}
$$

Under this circumstance

$$
\begin{equation*}
\tau_{2} \simeq \tau_{2} \tag{H2.1a}
\end{equation*}
$$

Typically, for any type of package, the time required for the corrosion process to culminate in a falure far exceeds the moisture induction time, and

$$
\tau_{2}>10 \tau_{1}
$$

Therefore, equation H2.la effectively approximates the total time to corrosion failure. Evaluation of $\tau_{2}$ is useful for comparison of competing packaging materials and package designs.

## H2.2 Moisture Induction Time Model

The time for the corrosion process varies between different mechanisms and sites while the time to reach the threshold moisture content depends only on the package type.

To determine the induction time for a hermetic package, the internal volume and maximum allowable leak rate of the package have to be defined. With these two package parameters defined, ${ }^{\tau}$, hermetic can be read directly from figure H-8.

For a nonhermetic package, the permeability rate, Table 4.5-18, and effective thickness, figure $H-9$, of the package have to be identified. The time for the internal partial pressure of a package to reach $95 \%$ of the external partial pressure is derived in Appendix $\mathrm{H}-1$ (equation H 4.35 ). The induction time for a nonhermetic package is governed by the following equation:

$$
\begin{equation*}
{ }^{\tau} 1_{\text {nonhermetic }}=\frac{12 \mathrm{~L}^{2}}{\pi^{2} \mathrm{D}} \tag{H2.2}
\end{equation*}
$$

where:
$L$ is the effective thickness of the package (cm)
$D$ is the permeability rate of the encapsulant material, $\mathrm{cm}^{3}$-cm/cm ${ }^{2}$-sec-bar

Ulhlig ${ }^{[16]}$ states that a critical relative humidity exists, below which corrosion is negligible. Koelmans ${ }^{[20]}$ presented data that shows a drastic reduction in surface conductivity, as a function of RH, takes place at about $5 \%$ RH. It appears that the condensed film must reach a critical thickness in order to dissolve contaminants and support ionic conduction. The absolute minimum of moisture has been described as three monolayers of condensed or adsorbed water molecules. ${ }^{[32]}$ Table H-2 summarizes the amount of internal water vapor that could result in three monolayer coverage. Figure H-10 ${ }^{\text {[33] }}$ shows the same information graphically with a comparison to the allowed leakage rate from MIL-STD-883. Note that the larger the internal volume, the less moisture is required to produce the three monolayers. This is because with the decreasing area-to-volume ratio, there is less package surface area competing for water molecules, and thus the more likely they are to reside on the chip.

After the critical moisture content is reached inside a package, corrosion will take place once the inside temperature is dropped below the saturation temperature for the moisture to condense to form a liquid electrolyte with other ionic contaminants. Therefore, the inside temperature functions as a "switch" to activate or deactivate the corrosion process. The temperature activation function, $f^{*}(T)$, has a value of 0 when the inside temperature is above saturation temperature or below the freezing point, and has a value of 1 when the inside temperature is below saturation temperature and above freezing. Hence, the function can be expressed as:
h3. APPLICATION OF THE CORROSION fAIlURE RATE MODEL

## H3.1 Metallization Corrosion

Corrosion is a potential failure mechanism in electronic modules because of inherent susceptibility of the metal conductor lines. To reduce the occurrence of corrosion in the metallization, a passivation layer is applied
to protect it from contact with the environment. The ideal protective coating serves to prevent formation of the moisture film. It should form high energy bonds with the substrate which cannot be broken by moisture adsorption within the coating or by thermomechanically induced shear stress at the coating-substrate interface. It should have a low solubility for water to suppress conductivity in the film itself and have a low sorption coefficient. The passivation should also be chemically stable. However, defects on the passivation layer will promote pitting corrosion and eventually lead to a corrosion failure as shown in figure $H-11$. For metallization without the passivation layer, a mathematical model can be developed by using Faraday's and Ohm's laws, following the work of Howard. [22]

## H3.1.1 Model for metallization failure due to corrosion

Given the conditions shown in figure $H-12$, corrosion at the anode will proceed until a length of the electrode, approximately equal to its width, is corroded to an open condition. Dendritic growth (electrochemical metal migration from the cathode to the anode), which can cause shorts between conductors, is often an accompanying effect of corrosion. Steppan, et. al. [48] reviewed numerous studies initiated to understand and model dendritic growth and described the numerous conditions that contribute to this phenomenon. Zamanzadeh, et.
al. ${ }^{[49]}$ compared theoretical predictions with experimental observations and found differences in dendritic growth rates of several orders of magnitude between the predictions and observations. Dendritic growth has not been considered in this model due to its relative infrequency as a cause of catastrophic failure in microelectronic devices and the difficulty in accurately modeling its mechanism. Initially, the leakage current is given by

$$
\begin{equation*}
i=\frac{V}{\bar{R}}=\frac{V}{\rho S / A} \tag{H3.1}
\end{equation*}
$$

where $A$ is the cross section of the current path through the electrolyte $S$ is the separation of conductors connected by the electrolyte

Therefore,

$$
\begin{aligned}
& A=L t \\
& \text { and } t \text { is the electrolyte thickness (centimeters) in the direction } \\
& \text { parallel to conductor length } \\
& L \text { is the length of the conductor edge exposed to the } \\
& \\
& \text { electrolyte and perpendicular to } S:
\end{aligned}
$$

$$
\begin{equation*}
\text { then } \quad i=\frac{V L}{(\rho / t) S} \tag{H3.3}
\end{equation*}
$$

The term $\rho / t$ is the sheet resistance of the electrolyte. The number of squares is given by $S / L$ and can be quite low. The current is thus summed over S/L parallel paths of which the unit current is given by

$$
\begin{equation*}
i_{j}=\frac{V}{(\rho / t)} \tag{H3.4}
\end{equation*}
$$

Thus if the surface resistivity is lowered due to a higher ionic concentration, or if the potential field is increased, a dominant local corrosion will occur. The quantity of material corroded is given by Faraday's Law:

$$
\begin{equation*}
\frac{w^{2} h n d F}{M}=\int_{\tau} i_{j} d \tau=\frac{V \tau}{\rho / t} \tag{H3.5}
\end{equation*}
$$

where $M$ is the atomic weight of the metal conductor and $d$ is its density in $\mathrm{gm} / \mathrm{cm}^{3}$, n is the chemical valence, F is Faraday's constant, 96500 coulombs/mol, and $w$ and $h$ are width and height of the conductor in cm respectively. The time to failure, in seconds, is therefore

$$
\begin{equation*}
\tau=\frac{w^{2} h n d F}{M V f^{\star}(T)}\left(\frac{\rho}{t}\right)=\text { constant } \times \frac{\rho}{\tau f^{\star}(T)} \tag{H3.6}
\end{equation*}
$$

The constant is dependent entirely upon the geometry and composition of the corroding electrode, and it can be calculated from design parameters. The time to failure $\tau$ is clearly dependent on the sheet resistivity and thickness of the electrolyte and the value of the function $f^{*}(T)$, as defined
in equation H 2.3 . Since this function is discontinuous, the evaluation of $\tau$ is facilitated by replacing this function with a continuous equipment operating time factor defined as follows:

$$
\begin{equation*}
k_{3}=\frac{24}{24-\tau^{*}} \tag{H3.7}
\end{equation*}
$$

where $\tau^{*}$ is the number of equipment operating hours per day. When the equipment is energized, the power dissipated in each microelectronic device is transformed to heat which will raise the package inside temperature aboe the saturation temperature. The liquid electrolyte which supports the ion transfer necessary for the corrosion process to continue will evaporate, and the corrosion process will become inactive.

As discussed in paragraph H2.3, it has been postulated that the minimum water film thickness required to provide the ion mobility necessary to support electrochemical corrosion is 3 monolayers of water molecules. A water molecule can be considered to be enclosed by a rectangular prism whth a base of $2.08 \times 1.32$ angstroms and a height of 1.53 angstroms. Hence a 3 monolayer film thickness can be considered to be approximately 6 angstroms thick ( 6 x $\left.10^{-8} \mathrm{~cm}\right)$. However, Der Marderosian ${ }^{[37]}$ has reported that a 3 monolayer film thickness is $1.2 \times 10^{-7} \mathrm{~cm}$. It is conservative to use this value for $\tau$ in equation H3.6.

From the above considerations, the following metallization corrosion model is derived:

$$
\begin{equation*}
\tau^{2} m=8 \times 10^{11} \frac{k_{1} k_{2} k_{3}}{k_{4}} \frac{w^{2} h n d \rho}{M V} \tag{H3.8}
\end{equation*}
$$

where:

```
\({ }^{\tau}{ }_{2 m}\) is the time to failure, seconds
\(k_{1}\) is the physical properties index of the material,
    Table 4.5-12
\(k_{2}\) is the coating integrity factor, Table 4.5-13
```

```
k}\mp@subsup{3}{3}{}\mathrm{ is the operating time factor, Table 4.5-14
k}4\mathrm{ is the temperature-humidity environment acceleration
    factor, figure 4.5-1
    is the width of the metal conductor (cm)
    is the height of the metal conductor (cm)
    is the chemical valence of the material, Table 4.5-12
    is the density of the material (g/cc), Table 4.5-12
M is the atomic weight of the metal conductor,
    Table 4.5-12
V is the voltage bias, volts (see Appendix H-4)
p is the resistivity of the electrolyte (ohm-cm),
        Table 4.5-15
```

The metallization corrosion model was developed based on gold bond pads without protection at $85^{\circ} \mathrm{C} / 85 \mathrm{RH}$ for a continuous corrosion process. To compensate for condition restraints, four correction factors are introduced. The physical properties index, $k_{1}$, is a corrosion resistance factor. Since aluminum corrodes ten times faster than gold, ${ }^{[13]} k_{1}$ is 0.1 for aluminum and 1 for gold.

The coating integrity factor $k_{2}$ accounts for the existence and integrity of a passivation layer covering the metallization on microcircuit die. Sbar ${ }^{[45]}$ has experimentally demonstrated that a void and pin hole free completely bonded passivation layer will reduce the metallization corrosion rate by 2 to 3 orders of magnitude. This suggests that a value of $k_{2}=1$ can be assigned to unpassivated metallization, indicating that under this condition, corrosion proceeds without inhibition. A conservative value of $k_{2}=100$ can be assigned to represent a defect free, completely bonded passivation layer. Between these two limits, $k_{2}$ can assume values varying from 10 to 50 to account for varying defect levels. For conservatism, a default value of 10 can be assigned when a passivation layer exists and the defect level is unknown. Further investigation should be conducted to develop definitions for passivation layer defect types and magnitudes and associated values for $k_{2}$ between the two limits.

The temperature-humidity environment acceleration factor, $k_{4}$, is required to determine the time to failure for conditions other than $85^{\circ} \mathrm{C} / 85 \mathrm{RH}$.

Many temperature-humidity correlation relationships have been proposed. [24 to 28] Peck ${ }^{[29]}$ evaluated these previous models and proposed a modified Arrhenius model based on analysis of published data from 61 tests conducted over the period from 1970 to 1985 . He subsequently discarded the less reliable data prior to 1979 and evaluated new data. ${ }^{[30, ~ 47] ~ H e ~}$ proposed the following acceleration model based on over 90 tests:

$$
\begin{equation*}
k_{4}=\frac{\left(R H_{1}\right)^{n} \exp \left(E a / k T_{1}\right)}{\left(R H_{2}\right)^{n} \exp \left(E a / k T_{2}\right)} \tag{H3.9}
\end{equation*}
$$

where RH is test chamber relative humidity, percent
Ea is activation energy, electron volts
$k$ is Boltzman's constant, eV/ ${ }^{\circ} \mathrm{K}$
$T$ is test chamber temperature, ${ }^{\circ} \mathrm{K}$

Peck found that $n=-3.0$ and $E a=0.90 \mathrm{eV}$ provided excellent correlation between the test data and the predicted acceleration factor over the range of $25 \%<\mathrm{RH}<100 \%$ and $T \leq 150 \mathrm{C}$. Prior to applying equation H 3.9 , it is necessary to assure that the glass transition temperature ( Tg ) of the encapsulant is not less than 150 C . By using $R H_{1}=85 \%$ and $T_{1}=85 \mathrm{C}$, the following relationship is obtained:

$$
\begin{equation*}
k_{4}=\frac{7.6 \times 10^{6}}{(R H)^{-3} \exp (10444 /(T+273)} \tag{H3.9a}
\end{equation*}
$$

where $T$ is in ${ }^{\circ} \mathrm{C}$.

This equation is plotted as figure 4.5-1.

The resistivity of the electrolyte, $\rho$, is calculated based on the amount of contaminants in average indoor environment across the country as discussed in Appendix $\mathrm{H}-3$.

## H3.2 Bond Pad Corrosion

Recent advances in device passivation technology have resulted in protective films of high integrity and moisture imperviance. The use of these films on integrated circuits has greatly reduced the corrosion of aluminum conductors when these devices are placed on temperature, humidity, and bias stress. However, for microelectronic devices which incorporate wire bonding, the aluminum bond pads remain unpassivated and consequently are exposed to the packaging environment.

Figure $\mathrm{H}-13$ is taken from reference ${ }^{[23]}$ and depicts a typical bond pad structure where the edges of the pad and the remainder of the chip are protected by a multi-layer passivation structure.

Bond pad corrosion can be considered to be principally due to three separate mechanisms:
(1) chemical corrosion due to phosphoric acid formation from $\mathrm{P}_{2} \mathrm{O}_{5}$ leached from phosphosilicate glass passivation by liquid phase moisture. ${ }^{[35, ~ 36]}$
(2) electrolytic corrosion due to current leakage across a wetted surface between adjacent bond pads having different applied electrical potential. ${ }^{[14, ~ 34]}$
(3) galvanic corrosion due to the galvanic potential difference between dissimilar bond wire and bond pad metals, as discussed in Appendix H-4.

Mechanism (1) results in open circuit failure and can be minimized by appropriate choice of passivation materials, and will not be considered further in this study. Mechanism (2) will most likely result in microcircuit performance degradation before significant corrosion can develop. However, to assure conservatism in the corrosion model, this mechanism is considered in Appendix $H-4$ when choosing the appropriate bias voltage magnitude. Mechanism (3) also results in open circuit failure and requires corrosion of a finite
volume of bond wire or bond pad material as discussed in Appendix $\mathrm{H}-5$.

The process whereby contaminants can enter along the plastic/lead frame interface is discussed in reference ${ }^{[23]}$ and is depicted in figure $\mathrm{H}-14$. The interface gap is shown enlarged for clarity. The effects of temperature, humidity, bias and perhaps capillary action can cause the migration of these contaminants along the interface to the bond wire. As this occurs, the chloride ions and moisture can corrode the bare metal, with iron and nickel ions being dissolved. These ions can then travel along with the water/chloride contamination to the bond wire, up the wire and eventually reach the aluminum bond pad, whereby corrosion of the pad can proceed.

The corrosion chemistry of aluminum is basically a four step process that can be summarized as follows ${ }^{[41]}$ :

1) Adsorption of an aggressive anion ( $\mathrm{Cl}^{-}$) on to the protective anodic aluminum oxide film
2) Chemical reaction of $\mathrm{Cl}^{-}$with $\mathrm{Al}^{3+}$ in the oxide lattice $\mathrm{Al}^{3+}+2 \mathrm{OH}^{-}+\mathrm{Cl}^{-} \Rightarrow \mathrm{Al}(\mathrm{OH})_{2} \mathrm{Cl}$
3) Thinning of the oxide by electro-chemical dissolution
4) Direct attack of exposed Al by $\mathrm{Cl}^{-}$ions:

$$
\begin{aligned}
& \mathrm{Al}^{3+}+4 \mathrm{Cl}^{-} \Rightarrow \mathrm{AlCl}_{4}^{-} \\
& \mathrm{AlCl}_{4}^{-}+2 \mathrm{H}_{2} \mathrm{O} \Rightarrow \mathrm{Al}(\mathrm{OH})_{2} \mathrm{Cl}+2 \mathrm{H}^{+}+3 \mathrm{Cl}^{-}
\end{aligned}
$$

As can be seen from the last equation, chloride ions are both a reactant and a product during this process. As such, once the chlorine ions participate in the corrosion of aluminum, they are "re-cycled" and can start the process all over again. The implication is that a small amount of chloride ions can consume a much larger amount of aluminum.

## H3.2.1 Model for Bond Pad Failure Due to Corrosion

Equation H 3.8 for metallization corrosion can be applied to bond pad corrosion by replacing the metallization corrosion volume by the bond pad corrosion
volume. Appendix $H-5$ discusses the evaluation of the bond pad corrosion volume and provides the following conclusions:
(1) When the bond pad is anodic to the bond wire in a dissimilar metal coupling:

$$
\begin{equation*}
v_{c}=0.3 \mathrm{~s}^{2} \mathrm{t}_{\mathrm{b}} \tag{H-8a}
\end{equation*}
$$

```
where s = bond pad size, cm (for a square pad)
    t
```

(2) When the bond wire is anodic to the bond pad in a dissimilar metal coupling:
a) for a wedge or crescent bond:

$$
\begin{equation*}
V_{C}=0.236 \mathrm{D}^{3} \tag{H-8b}
\end{equation*}
$$

where $D=$ bond wire diameter, cm
b) for a ball bond:

$$
\begin{equation*}
V_{c}=3.77 \mathrm{D}^{3} \tag{H-8C}
\end{equation*}
$$

c) for unknown bond type use equation $\mathrm{H}-8 \mathrm{~b}$.
3) When the bond wire and bond pad are made from similar materials, use the smaller of equations $\mathrm{H}-8 \mathrm{a}$ and $\mathrm{H}-8 \mathrm{~b}$.

Then equation $H 3.8$ can be rewritten for bond pad corrosion by replacing the terms $w^{2} h$ with $V_{C}$, as follows:

$$
\begin{equation*}
\tau^{2} w=8 \times 10^{11} \frac{k_{1} k_{2} k_{3}}{k_{4}} \frac{V_{C} n d \rho}{M V} \tag{H3.10}
\end{equation*}
$$

where:


Note: When the bond pad and bond wire are made from similar materials, the choice of values for $k_{1}, n$, $d$ and $M$ is obvious and $V_{c}$ is chosen as discussed in (3) above.

H4. SUMMARY

Performance over time is key to the reliability of the package and must be predictable to aid in design and trade off studies. The time to failure of different sites in a package due to corrosion was mathematically modeled. The result can be used either to determine the reliability of the package, improve proposed designs or to function as a guide line for maintenance.

The models were developed based on fundamental concepts and validated with existing experimental data. However, more extent experiments are required to further improve the accuracy of the models by reducing the assumptions taken during the model development.

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```



FIGURE H-1
DIFFUSION PRESSURE GRADIENTS ACROSS A BARRIER

$$
\begin{aligned}
& \text { OXYGENATED } \\
& \mathrm{NaCI} \text { SOLUTION }
\end{aligned}
$$

Ci


FIGURE H-2
Schematic drawing illustrating the autocatalytic nature of pitting attack on aluminum in oxygenated sodium chloride solution


FIGURE H-3
Corrosion Rate Versus Voltage For Epoxy Encapsulated Devices


FIGURE H-4
Influence of Ionic Contamination on the Corrosion Result


## -■- unencapsulated $\ldots$ encapsulated

FIGURE H-5
Percentage Failure of Encapsulated and Unencapsulated Packages Under Corrosion


FIGURE H-6
Reliability of Encapsulated Package in a Corrosive Environment


FIGURE H-7
Failure Rate of Encapsulated Package in a Corrosive Environment


FIGURE H-8
Time to Reach 3 Monolayers of $\mathrm{H}_{2} \mathrm{O}$ as a Function of Package Internal Volume and Air Leak Rate


FIGURE H-9
Typical Plastic Encapsulated Package


FIGURE H-10
Maximum Allowable Moisture Content as a
Function of Internal Package Volume


Pitting in Passivated Metallization Layer


FIGURE H-12
Schematic Diagram for Metallization Corrosion


FIGURE H-13<br>Typical Bond Pad Structure



> Path for Contaminants $H-14$
> Entering the Package to the Pad


BALL BOND


ULTRASONIC WEDGE BOND

crescent
BOND

| BOND TYPE | $D^{\prime}$ OR L |  |  | W |  |  |
| :--- | :--- | :--- | :--- | :--- | :--- | :--- |
|  | MIN | NOM | MAX | MIN | NOM | MAX |
| BALL | 2D | 4D | 6D | - | - | - |
| U/S WEDGE | $1.5 D$ | $3.25 D$ | 5D | $1.2 D$ | $2.1 D$ | 3D |
| T/C WEDGE | $1.5 D$ | $3.25 D$ | 5D | $1.5 D$ | $2.25 D$ | 3D |
| CRESEENT | O.5D | $1.75 D$ | 3D | $1.2 D$ | $3.1 D$ | 5D |

FIGURE H-15
FORMED BOND GEOMETRY LIMITS


BALL BOND


WEDGE BOND

FIGURE $H-16$
CORROSION VOLUME GEOMETRY BOND PAD ANODIC TO WIRE


BALL BOND


WEDGE BOND

FIGURE $\mathrm{H}-17$
CORROSION VOLUME GEOMETRY WIRE ANODIC TO BOND PAD

## Table H-1

METAL

Magnesium Alloys

Iron, Steel
and Ferrous
Alloys

Alumi num
Alloys Copper

Alloys

Cadmium
Plating

Nickel
Plating

Gold Electrical connector contacts, printed circuit board edge connectors, leaf-type relays, miniature coaxial connectors, semiconductor leads, and microminiature and hybrid circuits

Silver Protective coating on relay contacts, wave guide interiors, wire, high frequency cavities, EMI/EMP shields, and EMI gaskets

Copper and Wire, PCB circuitry and heat sinks, component leads,
USES

Radar antenna dishes and light weight structure, such as chassis, support and frames

Component leads, magnetic shields, magnetic coatings on memory disks, transformers, brackets, racks, hermetic electrical connector shells and fastener hardware

Equipment housing, chassis, mounting racks, support, frames, electrical connector shell, and printed circuit board heat sinks terminals, bus bars, nuts and bolts, and radio frequency gaskets.

Sacrificial protective coating on ferrous fastener hardware and on electrical connectors

Barrier-type layer between copper and gold in electrical contacts, for corrosion protection on electrical connectors, PCB heat sinks, electrical bonds in EMI applications and for compatibility in dissimilar-metal junctions
Table $\mathrm{H}-1$ (CONTD)
METALSUSES
Tin Plating For corrosion protection, solderability, and compatibilitybetween dissimilar metals, on electrical connectors, radiofrequency shields, filters, small enclosures, component leadsand automatic switching devices
Solder and For joining, solderability and corrosion protectionSolder Plating
Beryllium Inertial guidance instruments

## Table H-2 <br> Moisture Content vs. Volume (PPM)

| \| Volume | Surface Area | Ratio of Area | Water | Number of | Moisture\| |
| :---: | :---: | :---: | :---: | :---: | :---: |
| (cc) | (cm) | to Volume | Thickness (cm) | Monolayers | Content |
| 0.001 | 0.08 | 80 |  |  | 13000 |
| 0.01 | 0.38 | 38 |  |  | 6200 |
| 0.1 | 1.7 | 17 | $1.2 \times 10^{-7}$ | 3 | 2700 |
| 1 | 8.2 | 8.2 |  |  | 1300 |
| 110 | 38 | 3.8 |  |  | 600 |
| 1100 | 175 | 1.75 |  |  | 280 |

APPENDIX H-1
DEVELOPMENT OF A PERMEATION MODEL

In order to develop a mathematical model, the validity of Fick's Laws have to be assumed as a beginning. This development assumes constant temperature conditions unless specifically noted otherwise. Recall that Fick's Laws are:

$$
\begin{align*}
& F=-D\left(\frac{\partial C}{\partial x}+\frac{\partial C}{\partial y}+\frac{\partial C}{\partial z}\right)  \tag{H4.1}\\
& \frac{d C}{}=D\left(\frac{\partial^{2} C}{d t}+\frac{\partial^{2} C}{\partial x^{2}}+\frac{\partial^{2} C}{\partial y^{2}}\right)  \tag{H4.2}\\
& \partial z^{2}
\end{align*}
$$

Assuming the permeation is one dimensional and occurs along the $x$ axis, as shown in figure $H-1$ based on a semi-infinite mathematical model, in uni-dimensional terms; i.e.,

$$
\begin{align*}
& F=-D \frac{d C}{d x}=D \frac{\left(C_{1}-C_{2}\right)}{L}  \tag{H4.3}\\
& \text { and } \frac{\partial^{2} C}{\partial x^{2}}=\frac{1}{D} \frac{\partial C}{\partial t} \tag{H4.4}
\end{align*}
$$

where:
$C$ is the concentration
$x$ is the membrane thickness
D is the diffusion constant
$t$ is the time

In some practical systems, the surface concentration may not be known but only the gas or vapor pressure $\mathrm{P}_{1}, \mathrm{P}_{2}$ on the two sides of the membrane is known. The rate of transfer in the steady state is then sometimes written

$$
\begin{equation*}
F=D_{p} \frac{\left(P_{1}-P_{2}\right)}{L} \tag{H4.5}
\end{equation*}
$$

and the constant $D_{p}$ is referred to as the permeability constant. Assuming the diffusion coefficient, $D$, is constant, and there is a linear relationship
between the external vapor pressure and the corresponding equilibrium concentration within the membrane, then equation $H 4.3$ and $H 4.5$ are equivalent, but not otherwise.

$$
\begin{equation*}
\text { Then } F=-D_{p} \frac{d P}{d x} \tag{H4.6}
\end{equation*}
$$

$$
\text { and } \frac{\partial^{2} p}{\partial x^{2}}=\frac{1}{D_{p}} \frac{\partial P}{\partial t}
$$

Consider the following conditions as in figure $\mathrm{H}-\mathrm{l}$ :

$$
\begin{array}{ll}
\frac{\partial^{2} P}{\partial x^{2}}=\frac{1}{D_{P}} \frac{\partial P}{\partial t}, & 0<x<L, t>0 \\
P(x, 0)=f(x), & 0<x<L \\
P(0, t)=P 1, & t>0 \\
\frac{\partial P}{\partial x}(L, t)=0 & t>0 \tag{H4.11}
\end{array}
$$

It is easy to verify that the steady-state solution of this problem is $P(x)=$ $P_{1}$. Using this information, this boundary value-initial value problem can be solved by the transient concentration $w(x, t)=P(x, t)-P$,

$$
\begin{array}{lc}
\frac{\partial^{2} w}{\partial x^{2}}=\frac{1}{D p} \frac{\partial w}{\partial t}, & 0<x<L, \\
w(x, 0)=f(x)-p_{1}=g(x), & 0<x<L \\
w(0, t)=0, & t>0 \\
\frac{\partial w}{\partial x}(L, t)=0 & t>0 \tag{H4.15}
\end{array}
$$

Since this problem is homogeneous, it can be solved by the method of separation of variables. The assumption that $w(x, t)$ has the form of a product, $\phi(x) T(t)$, and insertion of $w$ in that form into the partial differential equation H 4.12 leads to the separated equations

$$
\begin{equation*}
\phi^{\prime \prime}(x)+\lambda^{2} \phi=0, \quad 0<x<L \tag{H4.16}
\end{equation*}
$$

$$
\begin{equation*}
T^{1}+\lambda^{2} k T=0, \quad t>0 \tag{H4.17}
\end{equation*}
$$

Moreover, the boundary conditions take the form

$$
\begin{array}{ll}
\phi(0) T(t)=0, & t>0 \\
\phi^{\prime}(L) T(t)=0, & t>0 \tag{H4.19}
\end{array}
$$

It has been shown that $\phi(0)$ and $\phi^{\prime}(L)$ should both be zero:

$$
\begin{equation*}
\phi(0)=0, \quad \phi^{\prime}(L)=0 \tag{H4.20}
\end{equation*}
$$

Now, the general solution of the differential equation H 4.16 is

$$
\begin{equation*}
\phi(x)=a^{\prime} \cos \lambda x+b^{\prime} \sin \lambda x \tag{H4.21}
\end{equation*}
$$

The boundary condition, $\phi(0)=0$, requires that $a^{\prime}=0$, leaving

$$
\begin{equation*}
\phi(x)=b^{\prime} \sin \lambda x \tag{H4.22}
\end{equation*}
$$

The boundary condition at $x=L$ now takes the form

$$
\begin{equation*}
\phi^{\prime}(L)=b^{\prime} \lambda \cos \lambda L=0 \tag{H4.23}
\end{equation*}
$$

The three choices are $b^{\prime}=0$, which gives the trivial solution; $\lambda=0$, and $\cos \lambda L=0$. The third alternative requires that $\lambda L$ be an odd multiple of $\pi / 2$, which can be expressed as

$$
\begin{equation*}
\lambda_{n}=(2 n-1) \pi / 2 L, \quad n=1,2, \ldots \tag{H4.24}
\end{equation*}
$$

The eigenfunctions are given by the formula

$$
\begin{equation*}
\phi_{n}(x)=\sin \lambda_{n} x \tag{H4.25}
\end{equation*}
$$

With the eigenfunctions and eigenvalues determined, the solution to equation

H4. 17 becomes

$$
\begin{equation*}
T_{n}(t)=\exp \left(-\lambda_{n}^{2} D_{p} t\right) \tag{H4.26}
\end{equation*}
$$

By adopting the Fourier sine series, the solution to the problem is

$$
\begin{equation*}
P(x, t)=P_{1}+\varepsilon b_{n} \sin \lambda_{n} \times \exp \left(-\lambda_{n}^{2} D_{p} t\right) \tag{H4.27}
\end{equation*}
$$

Suppose that the initial condition H 4.9 is

$$
\begin{equation*}
P(x, 0)=P_{0}, \quad 0<x<L \tag{H4.28}
\end{equation*}
$$

Then equation H 4.13 becomes

$$
\begin{equation*}
g(x)=P_{0}-P_{1} \quad 0<x<L \tag{H4.29}
\end{equation*}
$$

and

$$
\begin{equation*}
b_{n}=\left(P_{0}-P_{1}\right) \frac{4}{\pi(2 n-1)} \tag{H4.30}
\end{equation*}
$$

The complete solution of the boundary value-initial value problem with initial condition $P(x, 0)=P_{0}$ would be

$$
\begin{aligned}
& P(x, t)=P_{1}+\left(P_{0}-P_{1}\right) \frac{4}{\pi} \Sigma \frac{1}{2 n-1} \sin \lambda_{n} x \exp \left(-\lambda D_{p} t\right) \\
& \text { For } x=L, t=\text { infinity, } p(L, \infty)=P_{1} \\
& \text { For } x=L, t=0 \\
& P(L, O)=P_{1}+\left(P_{0}-P_{1}\right) \frac{4}{\pi} \Sigma \frac{1}{2 n-1} \sin \lambda_{n} L \\
&=P_{1}+\left(P_{0}-P_{1}\right) \frac{4}{\pi} \Sigma \frac{1}{2 n-1} \sin \frac{(2 n-1) \pi}{2 L} L
\end{aligned}
$$

$$
\begin{align*}
& =P_{1}+\left(P_{0}-P_{1}\right) \frac{4}{\pi}\left(1-\frac{1}{3}+\frac{1}{5}-\frac{1}{7}+\ldots\right) \\
& =P_{1}+\left(P_{0}-P_{1}\right) \frac{4}{\pi} \frac{\pi}{4} \\
& =P_{0} \tag{H4.32}
\end{align*}
$$

Now, for any time $t$ at the boundary $x=L$, the partial pressure is

$$
\begin{align*}
& P(L, t)=P_{1}+\left(P_{0}-P_{1}\right)_{\frac{\pi}{\pi}}^{\sum}{ }_{\frac{1}{N}}^{1} \sin N \pi \exp \left[-\frac{(N \pi)^{2}}{\left.D_{p} t\right]}\right. \\
& =P 1+\left(\rho_{0}-\rho_{1}\right)^{4} \frac{\pi}{\pi} \sum \frac{1}{N} \sin \frac{N \pi}{2} e-\left[\frac{N^{2} \pi^{2}}{4 L^{2}} \quad D_{p} t\right] \\
& P(L, t)=P_{1}+\left(P_{0}-P_{1}\right)_{\frac{\pi}{4}}^{4}\left[e^{-\left[\frac{\pi^{2} D_{p} t}{4 L}\right]_{2}}-\frac{1}{3} e^{-\left[\frac{9 \pi^{2} D_{p} t}{2}\right]}+\right. \\
& \frac{1}{5} e^{-\frac{\left[25 \pi^{2} D_{p} t\right.}{4 L^{2}}-\frac{1}{7} e}-\frac{\left[49 \pi^{2} D_{p} t\right]}{\left.4 L^{2}+\ldots . .\right]} \\
& \simeq P_{1}+\left(P_{0}-P_{1}\right) e^{-\frac{\mathbb{T}^{2} D_{P} t}{4 L^{2}}} \tag{H4.33}
\end{align*}
$$

Let $P_{0}=0$

$$
\begin{align*}
& \text { Then } \left.\frac{P(L, t)}{P 1} \simeq 1-e-\frac{\pi^{2} D_{p} t}{4 L^{2}}\right)  \tag{H4.34}\\
& \text { as } t \rightarrow \infty, P(L, t) / P \simeq 1 \\
& \text { Let } \frac{P(L, t)}{P 1}=0.95 \\
& \text { Then } 1-e^{-\left(\frac{\pi^{2} D_{p} t}{4 L^{2}}\right)}=0.95
\end{align*}
$$

$$
\text { and } e^{-\left(\frac{\pi^{2} D_{p} t}{4 L^{2}}\right.}=0.05
$$

## Taking logarithms

$$
\begin{align*}
& \frac{-\left(\frac{\pi^{2} D_{p} t}{4 L^{2}}\right)=-3}{t} \\
t & \frac{12 L^{2}}{\pi^{2} D_{p}} \tag{H4.35}
\end{align*}
$$

## APPENDIX H-2 <br> DEFINING EQUATIONS FOR LEAKAGE FLOW REGIMES

Viscous flow occurs when the mean free path of the gas is smaller than the cross-section dimension of the physical leak. Poiseuille's Law for viscous flow through a cylindrical tube is shown.

$$
\begin{equation*}
Q=\frac{\pi r^{4}}{8 n 1} \times 10^{-3} P\left(P_{1}-P_{0}\right) \tag{H5.1}
\end{equation*}
$$

where
$Q$ is the flow rate, in micrometer liters per second
$r$ is the radius of tube, in centimeters
$n$ is the viscosity of gas in poise
1 is the length of tube, in centimeters
$P$ is the average pressure, $\left(P_{1}+P_{0}\right) / 2$, in micrometers Hg
$P_{1}$ is the outside partial pressure, in micrometers Hg
$P_{0}$ is the inside partial pressure, in micrometers Hg

Transition flow occurs when the mean free path of the gas is approximately equal to the cross-section dimension of the leak and it occurs under conditions intermediate between viscous flow and molecular flow. Again for a long tube, the flow may be expressed as shown below ${ }^{[39]}$ :

$$
\begin{equation*}
Q=\frac{30.48 r^{3}}{1} \sqrt{M}\left(P \quad T_{O}\right)_{O}^{[ } \frac{0.1472 r P}{L a}+\frac{1+2.507 r P / L a}{1+3.095 r \bar{P} / L a} \tag{H5.2}
\end{equation*}
$$

where:
$Q$ is the flow rate, in micrometer liters per second
$r$ is the radius of the tube, in centimeters
1 is the length of the tube, in centimeters
$M$ is the molecular weight of gas, in amu
$P_{1}$ is the outside partial pressure, in micrometers Hg
$P_{0}$ is the inside partial pressure, in micrometers Hg
$T$ is the temperature, in degrees kelvin
La is the mean free path, in centimeters, at the average pressure $\left(P_{1}+P_{0}\right) / 2$

Molecular flow occurs when the mean free path of the gas is greater than the longest cross-section dimension of the physical leak. Knudsen's Law for molecular flow neglecting the end effect is shown ${ }^{[40]}$ :

$$
\begin{equation*}
Q=\frac{30.48 r^{3}}{1} \sqrt{M} \tag{H5.3}
\end{equation*}
$$

where:
$Q$ is the flow rate, in micrometer liters per second
$r$ is the radius of the tube, in centimeters
1 is the length of the tube, in centimeters
$M$ is the molecular weight of gas, in amu
$T$ is the temperature, in degrees kelvin

## APPENDIX H-3 <br> development of electrolyte resistivity values

From Rice's data, ${ }^{[19]}$ the arithmetic mean of chlorine gas concentration within electronic equipment locations is $0.51 \times 10^{-6} \mathrm{gm} / \mathrm{m}^{3}$.

$$
\begin{aligned}
0.51 & \times 10^{-6} \mathrm{gm} \mathrm{Cl} \\
& \times \frac{1 \mathrm{~mole} \mathrm{Cl}_{2}}{71 \mathrm{gm}} \times \frac{0.0224 \mathrm{~m}^{3}}{1 \text { mole Cl}} 2 \\
& =1.6 \times 10^{-10} \mathrm{~m}^{3} \mathrm{Cl}_{2}
\end{aligned}
$$

Therefore, the concentration of chlorine gas is $1.6 \times 10^{-4} \mathrm{ppm}_{v}$. Consider the reaction of $\mathrm{Cl}_{2}$ with water.

$$
\begin{equation*}
\mathrm{Cl}_{2}(\mathrm{~g})+\mathrm{H}_{2} \mathrm{O} \leftrightarrow \mathrm{H}^{+}+\mathrm{Cl}^{-}+\mathrm{HOCl} \tag{H6.1}
\end{equation*}
$$

This equation can be derived by adding the standard electrode reactions:

$$
\begin{array}{ll}
\mathrm{Cl}_{2}(\mathrm{~g})+2 e^{-}=2 \mathrm{Cl}^{-} & E^{\circ}=+1.3583 \\
\mathrm{H}_{2} \mathrm{O}+\mathrm{Cl}^{-}=\mathrm{H}^{+}+\mathrm{HOCl}+2 e^{-} \quad E^{\circ}=-1.49 \tag{H6.3}
\end{array}
$$

Applying the Nernst equations,

$$
\begin{equation*}
E_{12}=E_{12^{\circ}}-\frac{R T}{2 F} \ln \frac{\left[\mathrm{Cl}^{-}\right]^{2}}{\left[\mathrm{Cl}_{2}\right]} \tag{H6.4}
\end{equation*}
$$

and

$$
\begin{equation*}
E_{13}=E_{13^{\circ}}-\frac{R T}{2 F} \ln \frac{\left[\mathrm{H}^{+}\right][\mathrm{HOCl}]}{\left[\mathrm{H}_{2} \mathrm{O}\right][\mathrm{Cl}-]} \tag{H6.5}
\end{equation*}
$$

Adding equations H6.4 and H6.5:

$$
\begin{equation*}
\mathrm{E}_{11}=\mathrm{E}_{12^{\circ}}+\mathrm{E}_{13^{\circ}}-\frac{\mathrm{RT}}{2 \mathrm{~F}} \ln \frac{[\mathrm{Cl}-]\left[\mathrm{H}^{+}\right][\mathrm{HOCl}]}{\left[\mathrm{Cl}_{2}\right]\left[\mathrm{H}_{2}\right]} \tag{H6.6}
\end{equation*}
$$

The activities of the $\mathrm{H}^{+}$and $\mathrm{Cl}^{-}$ions are close to their concentration in dilute solution and the activities of $\mathrm{Cl}_{2}$ is its partial pressure in atmospheres $\left(1.6 \times 10^{-10}\right)$. The activities of water and HOCl are unity. Therefore equation $H 6.6$ becomes

$$
\begin{aligned}
& E_{11}=1.3583-1.49-\frac{(8.314)(358)}{(2)(96500)} \ln \frac{\left[\mathrm{H}^{+}\right][\mathrm{Cl}-]}{1.6 \times 10^{-10}} \\
&=0 \\
& \Rightarrow \quad 0.1317=-0.01542 \ln \frac{\left[\mathrm{H}^{+}\right][\mathrm{Cl}-]}{1.6 \times 10^{-10}}
\end{aligned}
$$

from which

$$
\begin{aligned}
& {\left[\mathrm{H}^{+}\right]\left[\mathrm{Cl}^{-}\right]=3.125 \times 10^{-14}} \\
& {\left[\mathrm{H}^{+}\right] \text {or }\left[\mathrm{Cl}^{-}\right]=1.77 \times 10^{-7}}
\end{aligned}
$$

Equivalent conductivity is defined as

$$
\Lambda=\frac{1000}{C_{p}}
$$

where $C$ is the ionic concentration.

From the CRC Handbook of Chemistry and Physics, ${ }^{[21]}$ combined equivalent conductivity of $\mathrm{H}^{+}$and $\mathrm{Cl}^{-}$is 775 at $85^{\circ} \mathrm{C}$, hence

$$
\rho=\frac{1000}{1.77 \times 10^{-7} \times 775}
$$

For a corrosive environment, the amount of $\mathrm{Cl}_{2}$ existing is assumed to be ten times the normal environment, or $5.1 \times 10^{-6} \mathrm{gm} / \mathrm{m}^{3}$. By going through the same calculations as above, the resistivity of the electrolyte for this condition at $85^{\circ} \mathrm{C} / 85 \mathrm{RH}$ is found to be $2.3 \times 10^{6} \mathrm{ohm}-\mathrm{cm}$.

APPENDIX H-4
SELECTION OF BIAS VOLTAGE FOR EQUATIONS H3.7 \& H3. 10

Corrosion of metals is an electrochemical phenomenon and its rate is proportional to the electrical potential difference between the anodic and cathodic regions of the corrosion site. Hence the time to failure of conductor and bond pad metallization due to corrosive attack, as modeled in equations H3.7 and H3.10, is directly proportional to a voltage bias. The applied voltage difference between adjacent signal or ground metallizations on a microcircuit is the usual driving force in electrochemical corrosion. However, when two dissimilar metals are in contact, such as gold wire bonded to an aluminum pad, corrosion will proceed without an applied electrical bias when an electrolyte is present. The corrosion process is then driven by the galvanic potential difference existing between the two metals. The magnitude of the galvanic potential depends upon the electrolyte concentration, pH , flow, aeration and temperature. ${ }^{[31]}$ The anodic member of the dissimilar metal pair is usually corrosively attacked, but secondary effects such as varying ion concentration, relative anode/cathode area, electrolyte resistivity, polarization of the wetted metal surfaces by oxide films or gas evolution and the formation of insoluble corrosion products on the metal surfaces can change the corrosion rate or reverse the process to corrosive attack of the cathodic member. Since exact knowledge of the conditions actually present in a microelectronic device during corrosive attack is not feasible, a first approximation to the differing corrosion rates of various dissimilar metal couples can be achieved by assuming the corrosion rate is proportional to the electrochemical galvanic potential difference between the two metals, and by assuming that the anodic member receives the corrosive attack.

Table 4.5-16 has been abstracted from reference [46] and lists the electrochemical galvanic potential for materials commonly used in proximity to each other in microelectronic devices. The galvanic potential difference for any two metals is defined as the algebraic difference between their electrode potentials listed in the table. However, the galvanic potential difference for use in equations H3.7 and H3.10 is defined as follows:

$$
\begin{equation*}
V_{\text {galvanic }}=1+\left(V_{\text {cathode }}-V_{\text {anode }}\right) \tag{H7.1}
\end{equation*}
$$

For example, the galvanic potential difference for a gold wire bonded to an aluminum pad is:

$$
V_{\text {galvanic }}=1+(1.5-(-1.66))=4.16 \mathrm{~V}
$$

The value for the bias voltage $V$ for use in equations $H 3.7$ and $H 3.10$ shall be chosen as follows:
(1) for dissimilar bond wire and bond pad metals - use the larger of the applied signal or power supply voltage as compared to the galvanic voltage from Table 4.5-16
(2) for similar metals - use the applied signal or power supply voltage.

## APPENDIX H-5

BOND PAD/BOND WIRE CORROSION VOLUME

The time to failure of microcircuit metallization due to corrosive attack is directly proportional to the quantity of material that must be corroded before the electrical continuity of the circuit is disrupted. As discussed in paragraph H3.l.l, Faraday's Law relates time to the volume of material consumed in an electrochemical reaction. For a metallization conductor, the minimum volume, and consequently the minimum time to failure, is obtained by assuming active corrosion occurs along a conductor length equal to its width, which leads to the simple geometry contribution shown in equation H3.6. However, for corrosion occurring at a bond pad-bond wire interface, the corrosion volume geometry is more complex.

The corrosion volume considered in this study is a function of the bond pad geometry (length, width, thickness), the bond-wire size, the bond type (ball, wedge, crescent), the bond process (ultrasonic, thermocompression), and the position of the bond pad material and the bond wire material in the galvanic electrode potential series (Table 4.5-16). As discussed in Appendix H-4, it is assumed that the anodic member of a dissimilar metal couple will be corroded. Hence, determination of the corrosion volume to be used in equation H3. 10 begins with identification of the anodic member of the couple from Table 4.5-16.

MIL-STD-883, Method 2010, paragraphs 3.2.4.1 through 3.2.4.3 delineates acceptable geometry variation limits for four bond types. These data are shown in figure $H-15$. Typical corrosion volume geometry is shown in figures H-16 and H-17. The following observations are applicable to the relationship between the completed bond geometry and bond pad geometry:
(1) Microcircuit bond pads are typically of equal width and length, with the pad size bearing a restricted relationship to bond wire diameter that is dictated by bond process positioning tolerance limitations and MIL-STD-883 position acceptance criteria.
(2) For a square bond pad of side $S$, the relationship of $S$ to bond wire diameter $D$ may vary between $3 D \leq S \leq 60$, with a predominant value of $S=$ 40. ${ }^{\text {[38] }}$
(3) Review of figure H-15 indicates that acceptable geometry for formed ultrasonic and thermocompression wedge bonds are nearly identical. Also, the width of a crescent bond is nearly identical to the length of a wedge bond.
(4) From (2) and (3), it follows that maximum acceptable wedge and crescent bond geometry is greater than the typical bond pad size.
(5) Acceptable ball bond geometry is greater than acceptable wedge/crescent bond geometry. Hence, a larger pad size is required for ball bonds to permit reasonable bond process positioning tolerances, and the relationship $S=5 D$ is required.
(6) From (3) and (4), the complexity of bond pad geometry requirements can be reduced by concluding that all wedge and crescent bonds can be considered as approximately equal with respect to the effective corrosion volume associated with each type.
(7) MIL-STD-883, Method 2023, delineates bond strength acceptance criteria for bond wire diameters from $1.8 \times 10^{-3} \mathrm{~cm}(0.0007 \mathrm{in})$ to $7.6 \times 10^{-2}$ $\mathrm{cm}(0.030 \mathrm{in})$. Low power digital microcircuits typically utilize bond wire diameters from $1.8 \times 10^{-3} \mathrm{~cm}(0.0007 \mathrm{in})$ to $3.8 \times 10^{-3} \mathrm{~cm}$ (0.0015 in).
(8) Bond pad thickness for microcircuits typically range from 5000 angstroms to 10000 angstroms $\left(5 \times 10^{-5} \mathrm{~cm}\right.$ to $\left.1 \times 10^{-4} \mathrm{~cm}\right)\left(2 \times 10^{-5} \mathrm{in}\right.$ to $4 \times 10^{-5 \mathrm{in})}$.
(9) From (7) and (8) the relationship between bond wire diameter $D$ and bond pad thickness $t$ is $13 \mathrm{D} \leq \mathrm{t} \leq 57 \mathrm{D}$.

From the above, it is clear that for any bond type, when the bond pad material is anodic to the bond wire material, the entire bond pad volume must be consumed before the corrosion process results in an open circuit failure. Since corrosion time is proportional to corrosion volume, a subsidiary conclusion is that a ball bond will have approximately $50 \%$ longer corrosion life than other bond types, due to the larger bond pad required, when the pad is anodic to the wire material.

Kiely ${ }^{[18]}$ has suggested that depletion of $30 \%$ of the bond pad volume be considered as corrosion failure. This is not only conservative but also realistic, considering the mechanical and thermomechanical stresses present during military equipment operation. Such stresses could cause premature failure of a corrosion weakened bond pad. Hence, when the bond pad is the anode of a dissimilar metal couple, the corrosion volume is:

$$
\begin{equation*}
v_{c}=0.3 \mathrm{~s}^{2} \mathrm{t}_{\mathrm{b}} \tag{H.8a}
\end{equation*}
$$

```
where }\mp@subsup{v}{c}{}=\mathrm{ corrosion volume, cm
    S = bond pad size, cm (for a square pad)
    t
```

When the bond wire is anodic to the bond pad material, the corrosion volume geometry is shown in figure $\mathrm{H}-17$. For a wedge or crescent bond, the minimum corrosion volume is at the heel of the bond, and can be approximated as:

$$
\begin{equation*}
v_{c}=0.3 \pi D^{3} / 4=0.236 D^{3} \tag{H.8b}
\end{equation*}
$$

where $D=$ bond wire diameter, cm

For a bond bond, assuming that the formed ball height is approximately equal to the wire diameter and using the nominal formed ball diameter from figure H-15, the corrosion volume can be approximated as:

$$
\begin{equation*}
v_{c}=0.3 \pi(4 D)^{2} D / 4=3.77 D^{3} \tag{H.8c}
\end{equation*}
$$

Comparison of equations $H .8 \mathrm{~b}$ and H .8 C suggests that a ball bond will have approximately 16 times longer corrosion life than other bond types, when the wire is anodic to the pad material.

## APPENDIX I

OPERATIONAL $\triangle T$ VALUES FOR APPLICATION ENVIRONMENT CATEGORIES

The microelectronic device reliability prediction models developed in this report for die fracture, die attach fatigue, bond pad shear fatigue, bond wire flexure fatigue and bond wire axial fatigue evaluate the number of cycles to failure for each failure mechanism. Each of these mechanisms is induced by differential thermal expansion during exposure of the device to thermal cycling. The models developed can be described in generic terms as power law relationships between the mean number of cycles to failure and the local state of stress or strain in the device. In all cases, the temperature difference ( $\Delta T$ ) between the maximum and minimum temperatures of the thermal cycle is raised to a power. Hence, the choice of $\Delta T$ for use in the model equations has a significant effect on the predicted cycle life magnitude.

The environmental temperature extremes delineated in Military Specifications for various classes of electronic equipment forms an upper boundary for $\Delta T$. A list of these specifications and the extreme operating temperature for each equipment type is given in Table 4.6-9. From this data it can be seen that the $\Delta T$ upper boundary limit varies from $30^{\circ} \mathrm{C}$ to $179^{\circ} \mathrm{C}$ for different types of electronic equipment used in various application environments.

For electronic equipment used in any application environment, the temperature at the device is principally determined by factors other than the ambient temperature, e.g. power dissipated in the device, thermal resistance of the heat transfer path to the ambient, availability of supplementary cooling, etc. The heat transfer thermal resistance path includes the thermal effects of boundary layer air flow for avionic equipment, and for all equipment the path includes the thermal effects of second and third level packaging materials and structures, shelters, protective cases, vibration/shock isolators and vehicle structures. The thermal capacitance of metallic
structural elements contributes massively to attenuation and time lag of ambient temperature effects on individual microelectronic device cyclic operating temperature. Hence, it is unrealistic to assume that the specified environmental temperature extremes bear any defineable relationship to cyclic device operating temperature.

Very little published test data exists that provides a basis for determining the cyclic $\Delta T$ at device locations in equipment. Most test programs usually monitor temperatures on equipment surfaces or at selected internal locations. Such data, if available, would provide a realistic first order estimate of $\Delta T$ at device locations. Reference [1] reported temperatures recorded in the equipment bay of an $A-7 C$ aircraft during a 5 hour mission. Most likely the recorded temperature was the bay ambient and not the equipment surface. This data is summarized in Table I-l.

Early in 1989, the Institute for Interconnecting and Packaging of Electronic Circuits (IPC) formed a task group to establish criteria for, among other things, accelerated testing of surface mount technology solder joints. During its deliberations the task group defined 12 electronic product use categories, and for each category defined the extreme operating temperature range, the probable cyclic $\Delta T$ experienced under normal operating conditions, and the number of cycles per year that could be expected for each $\Delta T$. Table I-2 summarizes the data from reference [2].

The IPC data was generated by a task group with representation from companies with experience in military avionic, military ground, commercial aviation, computer, telecommunication, industrial and consumer electronic components and equipment. The task group proposal was then circulated to the IPC member companies for concurrence. Hence the data in Table I-2 represents the most realistic evaluation of probable $\Delta T$ magnitudes available at this time.

Adaptation of the IPC data to the reliability prediction models developed in this report requires two steps, viz:
(1) Determination of a single equivalent $\Delta T$ for the IPC use categories for which more than one combination of $\Delta T / n o$. of cycles/cycle duration groupings exist.
(2) Matching of the IPC use categories with the new MIL-HDBK-217 application environments proposed in 4.6.4 and listed in Table 4.6-10.

The materials to which the prediction models will be applied range in mechanical characteristics from nearly plastic (60-40 solder) through elastic to nearly brittle (ceramics). For near-plastic materials, the temperature cycle duration is unimportant, since plastic creep quickly reduces the level of applied thermomechanical stress. The creep-induced damage in the internal structure of the bulk material occurs during the temperature change portion of the cycle, and the cyclic accumulation of damage is the mechanism of failure. At low temperature and high strain rates the mechanism is drastically accelerated. On the other hand, the failure mechanisms for elastic and near-brittle materials involve intensification of stress fields around local flaws above the average thermomechanical stresses induced in the bulk material. Stress intensification above the yield point of elastic materials and above a critical value for near-brittle materials causes crack initiation at the flaw sites and propagation throughout the bulk material. For these material types, practical thermal cycle durations, i.e. > 3 seconds, are sufficient for activation of the mechanism. Hence the variation of cycle duration for various IPC use categories in Table I-2 need not be considered for the step (1) development noted above.

It is reasonable to assume that stress/strain magnitude (and hence $\Delta T$ ) has a significantly greater influence on the failure mechanisms modeled in this report than does number of cycles. As an appoximation to determining an equivalent $\Delta T$, let a weighting function be derived as follows:

$$
\begin{equation*}
\Delta T_{e q}^{m} \sum_{i=1}^{n}\left(N_{i}\right)=\sum_{i=1}^{n}\left(\Delta T_{i}^{m} N_{i}\right), m>1 \tag{I-1}
\end{equation*}
$$

```
where m = arbitrary constant
    N
    \DeltaT
    \DeltaTeq = equivalent }\Delta
```

The data given in Table $I-3$ is derived from Table I-2 using equation I-1 with $m=3$ to determine an equivalent $\Delta T$ and the data in Table I-4 is derived from Tables I-2 and I-3 with the following considerations in matching the IPC use categories to the proposed MIL-HDBK-217 application elements:
(1) $A_{I}$ : This environment is for aircrew inhabited compartments of air vehicles in which temperature and pressure is controlled. Comparable IPC use categories are commercial aircraft and military aircraft-I. For conservatism the higher value is recommended.
(2) $A_{U}$ : This environment is for uninhabited air vehicles or compartments of air vehicles with uncontrolled temperature and pressure. Comparable IPC use categories are military aircraft-II and military aircraft-III. For conservatism the higher value is recommended.
(3) $C_{L}$ : This environment is for the severe inertial conditions associated with electronically actuated cannon launched projectiles. The duration of this environment is extremely short and will have negligible effect on the failure mechanisms modeled in this report, assuming that the components chosen have been qualified for the inertial conditions. The storage environment prior to launch will have the greatest influence on the modeled failure mechanisms. The existing instructions in MIL-HDBK-217E, paragraph 5.1.1.3 for segmented reliability analysis when multiple application environments are applicable. See Note 2 of table I-4 and the discussion under ( 7 ) following for the $M_{F}$ application environment.
(4) $G_{B}$ : This environment is for instruments, computers and test, business,
medical and laboratory electronic equipment housed in temperature controlled buildings or shelters. Comparable IPC use categories are computers and telecommunication. The recommended value of $\Delta T$ lies between the IPC values and is chosen for similarity to the $A_{I}$ application environment.
(5) $G_{F}$ : This environment is for equipment housed in buildings or shelters without temperature control. Comparable IPC use category is military (ground/ship).
(6) $G_{M}$ :

This environment is for equipment mounted on powered or unpowered vehicles or for manually transported portable equipment. Comparable IPC use categories are military (ground/ship) for equipment mounted in compartments without temperature control and transportation (passenger compartment for temperature controlled vehicles or trailers.
(7) $M_{F}$ :

This environment is for missile powered or unpowered flight and the severe inertial conditions associated with missile launch, space vehicle boost and re-entry, rocket powered flight and parachute landing. There are no comparable IPC use categories. The contribution of this environment to the package (non-electrical) failure mechanism is negligible because the environment is of short duration e.g. missile launch, missile flight, manned space vehicled boost to orbit and re-entry, etc. For this reason, the storage environment prior to launch or flight has the dominant influence on the package related failure mechanisms. The principal source of thermally related stress during storage is the diurnal temperature cycle. Table I-5 summarizes the diurnal cycle temperature range data given in reference [3], which suggests that $\Delta T=20^{\circ} \mathrm{C}$ is a conservative choice for use in the failure mechanism model equations to represent storage under uncontrolled temperature conditions.
Ambient climatic temperature changes have a neglibible effect on
temperature cycle range experienced by equipment stored undertemperature controlled conditions. The temperature control systemsensitivity of approximately $\pm 3^{\circ} \mathrm{C}$ is the major contributor tocontrolled storage temperature cycle variation. For equipmentconstantly stored under controlled conditions it may be concludedthat package related failure mechanisms can be considered asinactive. Assessment of combined controlled and uncontrolledconditions can use $\Delta T=5^{\circ} \mathrm{C}$ for the controlled segments. SeeMIL-HDBK-217E, paragraph 5.l.1.3 for segmented multiple applicationenvironment reliability analysis instructions.
(8) $N_{I}$ : This environment is for equipment sheltered from weather exposure and accessible by naval vehicle or shore crew members. In some instances the sheltered volume may be temperature controlled e.g. submarine installations, surface vessel combat information center, etc. When actual installation conditions are known, the reliability analyst may utilze such data in lieu of the table I-4 value. Comparable IPC use category is military (ground/ship). The recommended value of $\Delta T$ is chosen to reflect the modifying effect of $N_{I}$ usage as compared to $N_{U}$ usage.
(9) $N_{U}: \quad$ This environment is for unsheltered ship and shore equipment exposed to weather conditions. Comparable IPC use category is military (ground/ship.). The recommended value of $\Delta T$ is chosen at the conservative higher level.
This environment is for undersea missile launch and torpedo mission equipment. The short duration of this environment will have negligible effect on package related (non-electrical) failure mechanisms. The pre-launch and pre-mission storage conditions determine the thermal stresses driving these mechanisms. There is no comparable IPC use category for this environment. From the discussion under (7) for the $M_{F}$ application environment,
uncontrolled storage temperature conditions should use $\Delta T=20^{\circ} \mathrm{C}$ and the effect of controlled storage conditions on component reliability can be ignored or a value of $\Delta T=5^{\circ} \mathrm{C}$ may be used.
(11) NUU:

This environment is for equipment immersed in sea water. There is no comparable IPC use category. The ambient temperature is relatively benign and constant. The recommended value of $\Delta T$ is chosed for compatibility with $N_{U}$ conditions, taking into account the ambient temperature stability of the $N_{U U}$ environment and the excellent heat transfer to the ambient.
$\begin{array}{ll}\text { (12) } S_{F}: \quad \text { This environment is for equipment in earth orbiting space } \\ & \text { vehicles. The comparable IPC use category is space. }\end{array}$

TABLE I-1
THERMAL CYCLE DATA FROM REFERENCE [1]

| Cycle <br> Temperature |  | Cycle <br> Duration <br> Minutes | Number <br> Cycles | ${ }^{\circ} \mathrm{C}$ <br> Min |
| :---: | :---: | :---: | :---: | :---: |
| 17 | 60 | 64 | 3 | 43 |
| 38 | 58 | 6 | 6 | 20 |

Table I-2
Thermal Cycle Data from Reference [2]

| IPC | OPERATING TEMP. RANGE, ${ }^{\circ} \mathrm{C}$ |  | CYCLIC $\Delta T$ | NUMBER CYCLES/ | CYCLE DURATION |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  | MIN. | MAX | ${ }^{\circ} \mathrm{C}$ | YEAR | HOURS |
| CONSUMER | 0 | 60 | 35 | 365 | 12 |
| COMPUTERS | 15 | 60 | 20 | 1460 | 2 |
| TELECOMMUNICATIONS | -40 | 85 | 35 | 365 | 12 |
| COMML. AIRCRAFT | -55 | 95 | 20 | 3000 | 2 |
| INDUSTRIAL | -55 | 65 | 20 | 185 | 12 |
|  |  |  | 40 | 100 | 12 |
|  |  |  | 60 | 60 | 12 |
|  |  |  | 80 | 20 | 12 |
| TRANSPORTATION <br> (Passenger Compt) | Same as Industrial |  |  |  |  |
| TRANSPORTAION | -55 | 125 | 60 | 1000 | , |
| (Engine Compt) |  |  | 100 | 300 | 1 |
|  |  |  | 140 | 40 | 2 |
| MILITARY | -55 | 95 | 40 | 100 | 12 |
| (Ground/Ship) |  |  | 60 | 265 | 12 |
| MILITARY | -55 | 95 | 20 | 1000 | 1 |
| (Aircraft - I) |  |  | 40 | 500 | 2 |
| MILITARY | -55 | 95 | 20 | 1000 | 1 |
| (Aircraft - II) |  |  | 60 | 500 | 2 |
| MILITARY | -55 | 95 | 20 | 1000 | I |
| (Aircraft - III) |  |  | 80 | 500 | 2 |
| SPACE | -40 | 85 | 35 | 3650 | 2 |

Table I-3
Equivalent $\Delta T$

| $\begin{aligned} & \text { IPC } \\ & \text { USE CATEGORY } \end{aligned}$ | ${ }^{\Delta T} \mathrm{C}^{\text {eq }}$ |
| :---: | :---: |
| CONSUMER | 35 |
| COMPUTERS | 20 |
| TELECOMMUNICATION | 35 |
| COMMERCIAL AIRCRAFT | 20 |
| INDUSTRIAL/TRANSPORTATION |  |
| (PASSENGER COMPARTMENT) | 44 |
| TRANSPORTATION (ENGINE COMPARTMENT) | 78 |
| MILITARY (GROUND/SHIP) | 56 |
| MILITARY (AIRCRAFT - I) | 30 |
| MILITARY (AIRCRAFT - II) | 43 |
| MILITARY (AIRCRAFT - III) | 56 |
| SPACE | 35 |

Table I-4
Recommended Value for Component Operating $\Delta T$ (see note 1)

| $\begin{array}{c}\text { MIL-HDBK-217 } \\ \text { APPLICATION ENVIRONMENT }\end{array}$ |  | ${ }^{\circ}{ }^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: |
|  | PRESENT | PROPOSED |$]$

Note 1. Table I-4 $\Delta T$ values are for use when thermal analysis or test data are not available.

Note 2. Application environments referring to this note are of short duration and have negligible effects on the package (non-electrical) related failure mechanisms, for which the pre-launch storage conditions will have the dominant effect. Use $\Delta T=5^{\circ} \mathrm{C}$ for storage under controlled temperature conditions and $\Delta T=20^{\circ} \mathrm{C}$ for uncontrolled storage conditions.

Note 3. Use $G_{B}$ application environment for equipment mounted in temperature controlled compartments and $G_{F}$ for uncontrolled compartments.

Table I-5
Diurnal Cycle Temperature Range

| REGIONAL SURFACE CLIMATIC TYPE |  |  | DIURNAL $\Delta T,{ }^{\circ} \mathrm{C}$ |
| :---: | :---: | :---: | :---: |
| Basic | Hot |  | 13 |
|  | Cold |  | 11 |
|  | Constant High | Humidity | 0 |
|  | Variable High | Humidity | 9 |
|  | Cold-Wet |  | 10 |
| Hot | Dry |  | 17 |
|  | Humid |  | 10 |
| Cold |  |  | 9 |
| Severe Cold |  |  | 0 |
| World Wide Long Term High Temperature <br> Extremes |  | 10 yr | 20 |
|  |  | 20 yr . | 21 |
|  |  | 30 yr . | 22 |

## REFERENCES

[l] E. Edwards, J. Steinkirchner, S. Flint, "Avionic Environmental Factors for MIL-HDBK-217", Rome Air Development Center, U.S. Air Force, RADC-TR-81-374, Figure 3-5.
[2] "Minutes of the Surface Mount Solder Joint Reliability Task Group Meeting" dated 31 July/l August 1989; Institute for Interconnecting and Packaging Electronic Circuits (IPC).
[3] "Climatic Information to Determine Design and Test Requirements for Military Systems and Equipment", MIL-STD-210C, 9 January 1987.

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[^0]:    * Attendees included representatives from the following companies: Anadigics; LSI Logic; Intel Corp.; Teledyne Microelectronics; SEEQ Technology; D. Steward Peck Consulting; and Westinghouse.

[^1]:    * Source References MIL-STD-883C and RAC MDR-22

[^2]:    W.F. = Weighting Factor

[^3]:    $\lambda_{0}=\lambda$ Observed $\quad \lambda_{p}=\lambda$ Predicted, New Model $\lambda_{2} 17 E=\lambda$ Predicted Per MIL-HDBK-217E

[^4]:    $\lambda$ Predicted Per MIL－HDBK－217E
    （Extrapolated As Necessary）

    | 11 |
    | :--- | :--- |
    | $\sim$ |
    | $\sim$ |
    | $\sim$ |
    | $\sim$ |

[^5]:    partinem
    
    
    

[^6]:    Figure F-10 SCHEMATIC REPRESENTATION OF WIRE BOND FLEXURE DUE TO
    DEVICE TEMPERATURE / POWER CYCLING

