



National Aeronautics and
Space Administration

**NOT
MEASUREMENT
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MSFC-STD-3663

REVISION A

EFFECTIVE DATE: February 24, 2014

George C. Marshall Space Flight Center
Marshall Space Flight Center, Alabama 35812

ES30

MSFC TECHNICAL STANDARD

**MSFC STANDARD FOR
CONFIGURABLE LOGIC DEVICE
DEVELOPMENTS**

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DOCUMENT HISTORY LOG

Status (Baseline/ Revision/ Canceled)	Document Revision	Effective Date	Description
Baseline		4/11/2012	Baseline release; document authorized through MPDMS.
Revision	A	2/24/2014	Revision A release was authorized by the MSFC Technical Standards Document Control Board (DCB) through the Multiprogram Document Management System (MPDMS). Revision includes references to NASA-HDBK-4008 in sections 2.5, 4.2.7, 5.1.3, 5.3, 5.5.1, 5.6.1, 5.7.1, and Appendix D. Provided minor format edits throughout the document (correct document titles, adjusted margins, section numbering). Sec 2.5, Added Relationship to NASA-HDBK-4008 content. Sec 3.1, Added to and corrected Acronyms. Sec 3.2, Updated to add definition and clarify content on some. Sec 3.3, Updated to add note and wording to clarify convention used in document content. Sec 4.0, Added new Configuration Logic Device (CLD) requirements. Sec 4.2.1-Removed content. Sec 4.2.4, Updated to clarify what appropriate CM should be included for CLDs. Sec 4.2.5, Updated to clarify origination of corrective action results. Sec 4.2.7, Updated section to add Execution content to Acquisition and Planning. Sec 4.2.8, Added Training and Experience content. Sec 4.3, 4.3.1-4.3.8 and 4.4, Added System Safety and Quality Assurance content. Sec 4.5, 4.5.1-4.5.2, Added CDL Requirements Tailoring content. Sec 5.1, Updated content to clarify specific CLD Development Plan Requirements. Sec 5.1.2, Updated content to clarify Documentation Lifecycle. Sec 5.1.5 and 5.1.7, Updated to remove unnecessary content. Sec 5.3, Updated Preliminary and Detailed Design to add additional information on CLD design content. Sec 5.3.3, Updated section to remove reference to off the shelf items and clarify heritage non-development items. Sec 5.6, Updated to add Hardware Description Language (HDL) design guideline note. Sec 5.5.1, Updated Analysis content to add personnel involved with developing simulations note. Sec 5.5.6, Added Regression Testing content. Sec 5.7.1, Updated to add issues with integration clarification content to Board/Sys Integration. Sec 5.7.2, Added In-Flight Reconfiguration content. Sec 5.8, Added Maintenance of The Design content. Appendix B, Added Requirements Adequacy content to Design Review Checklist. Appendix F and G, Complete rewrite of Suggested CLD Documentation content and Compliance Matrix. Deleted Figure I, Table I and Table II.

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FOREWORD

This Marshall technical standard defines the technical and managerial processes necessary to manage and develop electronic designs containing complex programmable logic devices, such as Field Programmable Gate Arrays (FPGAs), Application Specific Integrated Circuits (ASICs), and similar devices (sometimes referred to as “complex electronics”). Throughout this document, a component from this family of devices is referred to as a Configurable Logic Device (CLD.)

This Standard is recommended for all Marshall Space Flight Center (MSFC) projects but is not mandatory unless specifically imposed.

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1.0 SCOPE

1.1 Scope

This standard applies to Configurable Logic Devices (CLDs) to the extent identified in applicable requirements or contractual documentation.

The intent of this standard is to define requirements to ensure CLD development is managed appropriately, in order to ensure delivery and fielding of robust CLD hardware. A robust device does not contain systematic undesirable features and will respond predictably to various conditions and environments. A reliable device is robust and can demonstrate performance over a period of time based on lifetime (random) failure statistical data.

Planning requires establishing standards and methodologies that are used, researching and analyzing tools, and then procuring those necessary to manage and execute the project.

Compliance with these process requirements is accomplished through technical insight, participation in requirements, design, and status reviews, participation in test readiness reviews, and review of documentation, including the development plans. Specific responsibilities are defined in section 4.1.

Although various aspects of the design of FPGA and ASIC devices are sometimes referred to as “firmware,” the usage of that terminology does not establish an equivalence to the term “firmware” as used in NASA Procedural Requirement (NPR) 7150.2, NASA Software Engineering Requirements. Therefore, the requirements of NPR 7150.2 are not applicable to CLD designs, although some developing organizations may apply those methodologies and processes successfully in CLD designs. Current NASA approaches to CLD development are addressed in the NASA Engineering and Safety Center Technical Assessment Report, NESC-RP-09-00546 “Development, Design, Test, and Evaluation Process for Robustness of Space Flight Programmable Logic Devices.” This standard is developed consistent with that approach.

Note: When a processor is embedded within a CLD, from a software perspective, the processor is no different from a processor that is a discrete “chip.” As such, while the design and implementation of that processor into the CLD is covered by this standard, the software that will execute on that processor is covered by the NPR 7150.2 definition and requirements.

1.2 Change Authority & Tailoring

Proposed changes to this standard are governed by Marshall Procedural Requirements (MPR) 8070.1.

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Exceptions, tailoring, or other modifications to the requirements of this document specific to a given program, project, or activity are within the authority of the responsible program, project, or activity technical authority having invoked this Standard.

2.0 APPLICABLE DOCUMENTS

2.1 Applicable Documents

MPR 8070.1	Administration of MSFC Technical Standards and MSFC Standard Data Requirement Descriptions
MSFC-STD-3012	EEE Parts Management and Control Requirements for MSFC Space Flight Hardware

2.2 Referenced Documents

The following documents contain supplemental information to guide the user in the application of this document.

NESC-RP- 09-00546	Development, Design, Test, and Evaluation Process for Robustness of Space Flight Programmable Logic Devices
MPR 7123.1	MSFC Systems Engineering Processes and Requirements
NASA-HDBK-4008	Programmable Logic Devices (PLD) Handbook
NASA-HDBK-8739.23	NASA Complex Electronics Handbook for Assurance Professionals
NPR 7150.2	NASA Software Engineering Requirements
RTCA/DO-254	Design Assurance Guidance for Airborne Electronic Hardware
ECSS-Q-60-02A	Space Product Assurance Application Specific Integrated Circuits (ASIC) and Field Programmable Gate Arrays (FPGA) Development

The following websites may be used as a reference for users of this document.

http://klabs.org/	NASA Office of Logic Design (OLD)
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<https://nen.nasa.gov/web/avionics/pld>

NASA Engineering Safety Center
Community of Practice for
Programmable Logic Devices

<http://www.hq.nasa.gov/office/codeq/software/ComplexElectronics/index.htm>

NASA Assurance Process for
Complex Electronics

2.3 Order of Precedence

In the event of any conflict between the text of this standard and the references cited herein, the text of this standard shall take precedence. However, nothing in this text shall supersede applicable laws and regulations unless a specific exemption has been obtained.

2.4 Acknowledgements

The requirements and recommendation contained in this specification are the result of MSFC studies of processes and best practices from a variety of sources, including published studies, center-level documentation at other NASA centers, and program documentation and discussions conducted as part of the Ares Project for the Constellation Program. The safety critical checklist in Appendix A is based upon computing system requirements from the Constellation program. The Design Review Checklist (Appendix B) and Designers Checklist of Best Practices (Appendix C) are both based closely upon documentation from the Goddard Space Flight Center. Other materials reviewed include the Naval Research Laboratory guidelines for the Microwave Imager/Sounder program, and a report by the Aerospace Corporation for the Air Force Space Command.

2.5 Relationship to NASA-HDBK-4008

NASA-HDBK-4008 is a handbook, which provides guidance such as engineering information, lessons learned, and possible options to address technical issues.

The intended relationship between this standard and NASA-HDBK-4008 is as follows: Where selected (in part or in whole) as a requirement for an MSFC project by the appropriate project and technical authorities, MSFC-STD-3663 becomes a mandatory requirement (to the extent specified), whereas NASA-HDBK-4008 is available as a guidance document in all cases, whether or not MSFC-STD-3663 is applicable. Where both are in use, while there is overlap between the two documents, MSFC-STD-3663 provides more extensive details into technical management aspects of CLD developments, whereas NASA-HDBK-4008 provides more information for the detailed designers and implementers of the CLD devices and the circuit boards in which the devices are incorporated.

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Note: In all cases, information contained within NASA-HDBK-4008 should be evaluated for applicability and correctness in a given project, and should not be considered as the best solution in every application.

3.0 DEFINITIONS

3.1 Acronyms

The acronyms used in this standard are defined as follows:

ASIC	Application-Specific Integrated Circuit
BOL	Beginning Of Life
CDR	Critical Design Review
CLD	Configuration Logic Device
CLDP	Configurable Logic Devices Development Plan
CM	Configuration Management
CMMI	Capability Maturity Model Integration
CMOS	Complementary Metal Oxide Semiconductor
DDT&E	Design, Development, Test and Evaluation
EEE	Electrical, Electronic, and Electromechanical
ESD	Electrostatic Discharge
FPGA	Field Programmable Gate Array
HDL	Hardware Descriptor Language
I/O	Input/Output
IP	Intellectual Property
ITIV&V	Information Technology Independent Verification and Validation
JTAG	Joint Test Action Group
MPR	Marshall Procedural Requirements
MSFC	Marshall Space Flight Center
NPR	NASA Procedural Requirements
OLD	Office of Logic Design
OPR	Office of Prime Responsibility
PDR	Preliminary Design Review
PLD	Programmable Logic Devices
PDDD	Programmable Devices Design Documentation
PWB	Printed Wiring Board
RCLD	Risks (for) Configuration Logic Device
RTCA	Radio Technology Commission for Aeronautics
SDF	Standard Delay Format
SEMP	Systems Engineering Management Plan
SMA	Safety and Mission Assurance

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SRR	System Requirements Review
STA	Static Timing Analysis
TPM	Technical Performance Measure
TTL	Transistor-Transistor Logic
UDF	Unit Development Folder
V&V	Verification & Validation

3.2 Definitions

Term	Description
Acquiring Organization	The organization responsible programmatically and technically for the development of a CLD design, a CLD device, or a component or subsystem containing one or more CLDs. With respect to this Standard, NASA is senior Acquiring Organization, but in a structured or tiered acquisition, the role of Acquiring Organization is found whenever a development is given to a vendor, subcontract, or other provider.
Best Practice	A recommended approach that is intended to achieve high product quality.
Critical Function	As used within this document, those functions that are either safety critical or designated mission critical, thus requiring the stricter control specified herein.
Developer	With respect to this Standard, the Developer is the organization or individual performing any function in CLD development other than those specified for the Acquiring Organization.
Firmware	Terminology used to describe either software that resides in a read-only device, or the combination of that read-only software and the device itself. This terminology is sometimes applied to data or other information stored in a read-only device, and as such is used informally—and often incorrectly—to describe CLD designs. Due to the imprecision of the term, as well as common misuse, it is recommended that the term firmware be avoided whenever possible.
Hazardous Command	A command that, if executed in certain states or under certain conditions, could result or lead to one or more hazardous conditions, but when executed at the appropriate time is part of nominal performance.

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Term	Description
Intellectual Property	In the context of this Standard, Intellectual Property (IP) refers to CLD design elements provided from another organization, not necessarily custom-developed for the application to which another user intends. The delivered IP may not include full visibility into its content and structure.
Lint Tool	A tool used to analyze software or Hardware Descriptor Language (HDL) for suspicious usage.
Mission Critical	Any condition, event, operation, process, equipment, or system that possesses the potential to prevent the accomplishment of one or more delineated mission objectives.
Operator	A human being interacting with a computing system.
Printed Wiring Board	A bare circuit card, without any components installed.
Safety Critical	Any condition, event, operation, process, equipment, or system that possesses the potential of directly or indirectly causing harm to humans, destruction of the system, damage to property external to the system, or damage to the environment.
Unit Development Folder	An electronic or paper system to keep up with the design outputs as part of the developer's internal processes.

3.3 Convention and Notation

This standard applies the following convention: all mandatory actions (i.e., requirements) are denoted by statements containing the term “shall.” The following terms also apply: “may” or “can” denote discretionary privilege or permission, “should” denotes a good practice and is recommended, but not required; “will” denotes expected outcome, and “are/is” denotes descriptive material.

The term critical conveys a characteristic that is either safety critical or designated mission critical.

Each mandatory requirement (i.e. ‘shall’ statement) is numbered for easy reference. The numbering system utilizes the acronym “CLD” followed by a numerical value, i.e. CLD-xxx. These numbers are not necessarily in sequential order with the document but are maintained consistent across previous revisions.

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Note: As used in this document, the mandatory requirements (a.k.a. 'shall statements') are not intended to convey an individual formal verification of the type routinely performed for functional requirements and safety/hazard controls. See also section 1.1.

4.0 GENERAL REQUIREMENTS

4.1 Responsibilities

Note: Authorities or responsibilities not explicitly assigned are reserved to the Developer.

4.1.1 Acquiring Organization Responsibilities

The Acquiring Organization, i.e. the organization requiring or procuring a CLD design, a CLD implementation, or component, subsystem, or system containing one or more CLDs, shall (CLD-001):

- a. Determine whether this standard, another standard, or no standard is to be applied to a development, and at what level.
- b. Assure appropriate flow down of applicable CLD standards to contracts, subcontracts, and vendors, including non-development items.
- c. Approve variances or disposition of noncompliances against applicable CLD standards.

4.1.2 MSFC Engineering Directorate Responsibilities

The MSFC Engineering Directorate, or designee, shall (CLD-002):

- a. Provide the Acquiring Organization with technical insight into the CLD development and CLD work products, in accordance with established work commitments.
- b. Support audits of CLD developments conducted by the MSFC Safety, Reliability, and Mission Assurance Directorate to the extent specified in the Project Plan or other workforce agreements.
- c. Provide technical authority for interpretation of and compliance with this MSFC Standard.
- d. Maintain and update this MSFC Standard, as needed.

4.1.3 MSFC Safety and Mission Assurance (SMA) Directorate Responsibilities

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The MSFC SR&MA, or designee, shall (CLD-003) to the extent specified in the Project Plan or other workforce agreements:

- a. Include CLD developments within the scope of activities documented in the Safety, Reliability, and Quality Assurance Plan(s).
- b. Perform audits on the CLD development organizations.
- c. Support peer reviews that include MSFC participation.

4.1.4 Developing Organization Responsibilities

Organizations developing CLDs (hereafter known as the “Developer”) shall (CLD-004) be responsible for:

- a. Complying with the requirements specified in this standard to the extent specified in the contract and applicable requirements specifications.
- b. Ensuring that applicable requirements are flowed down to all organizations and subcontracts producing hardware or products which are within the Developer’s scope of responsibility.
- c. Providing the Acquiring Organization and its authorized representatives access to development and test activities, including monitoring integration and verification adequacy, trade study data, auditing of the development process, and participation in reviews and technical interchange meetings, to the extent allowed in any applicable contracts.
- d. Establish and provide the roles and responsibilities equivalent to MSFC Engineering Directorate and MSFC Safety and Mission Assurance (SMA), for oversight or insight into subordinate developing organizations.
- e. Perform appropriate functions of the Acquiring Organization for procured or contracted items.

4.2 CLD Relationship to Overall Programmatic Approach

CLDs are normally developed as part of the overall development structure of a project. As such, it is not necessary to identify or reiterate all requirements that are necessary for a well-structured design, development, test, and evaluation (DDT&E) program in accordance with applicable NASA and project requirements. Instead, this MSFC Standard addresses specifically those aspects of CLD DDT&E that are unique, or driven by unique parent requirements. However, CLD developments are factors in each of the following programmatic areas:

- a. Schedule

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- b. Budget
- c. Data management
- d. Management of Safety, Security and Privacy of Information Technology (IT) Products/Services
- e. Risk Management
- f. Systems engineering (see MPR 7123.1)
- g. Verification and Validation (See MPR 7123.1)
- h. Safety and Mission Assurance, including
 - 1. System Safety
 - 2. Reliability & Maintainability
 - 3. Quality Engineering & Quality Assurance

The NASA Acquiring Organization shall (CLD-005) determine whether or not to track CLD development budgets separately to support future cost estimating. The Developer may choose to separately track CDL development budgets internally and with their suppliers, even if NASA does not require it of the Developer.

4.2.1 Verification and Validation, of Models and Simulations

The Developer shall (CLD-008) verify and validate, in accordance with project requirements, any models or simulations used for final verifications that are not testable by the Developer (including testing at higher levels of assembly.)

4.2.2 Peer Reviews

Peer reviews and inspections are the in-process technical examination of work products (including test benches) by the designer's peers for the purpose of finding and eliminating defects early in the life cycle. Peer reviews are performed following defined procedures covering the preparation for the review, conducting the review itself, documenting results, reporting the results, and certifying the completion criteria. Each Developer shall (CLD-009) define, within its approach for CLD developments, the use of peer reviews, the peer review process, and the interrelationship between peer reviews and

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project-level formal reviews, including reporting requirements. The Developer shall (CLD-010) perform peer reviews, at a minimum, for the design and design products.

For effective peer reviews, the Developer selects peer reviewers with both expert-level experience and knowledge of CLD designs. Training is important for consistency in the review process and should be considered with selecting peer reviewers.

Recommendations for conducting peer reviews are provided in Appendix D and may be used as a guideline.

4.2.3 Configuration Management

Configuration management (CM) establishes and maintains the integrity of the product development throughout the life cycle. CM involves identifying the configuration of products that are delivered to the customer and used in development, systematically controlling changes to the configuration, and maintaining the integrity and traceability of the configuration. Developers shall (CLD-011) implement CM for both the electronic configuration files (i.e., “1s and 0s”) used to configure CLD chips (including memory devices that hold the design externally to the FPGA) as well as the design files, configurations, and environments used to generate them. CM for these files may be included in project or software CM documentation and do not necessarily require separate procedures and plans to be written.

The Developer shall (CLD-012) include CLDs in appropriate CM plans that describe the functions, responsibilities, and authority for the implementation of CM for the project.

Appropriate CM for CLDs should include:

- a. Track and evaluate changes to products.
- b. Identify the configuration items (e.g., hardware, documents, code, data, scripts) and their versions to be controlled.
- c. Establish and implement procedures designating the levels of control that each identified configuration item must pass through; the persons or groups with authority to authorize changes and to make changes at each level; and the steps to be followed to request authorization for changes, identify impacts to other products, tests, or documents, process Change Requests, track changes, distribute changes, and maintain past versions.
- d. Prepare and maintain records of the configuration status of configuration items.
- e. Ensure that configuration audits are performed to determine the correct version of the configuration items and verify that they conform to the documents that define them.

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- f. Establish and implement procedures for the storage, handling, delivery, release, and maintenance of deliverable products.
- g. Provide and maintain traceability from design to hardware or CLD code.
- h. Track changes, including but not limited to both design and requirements, and provide data for review.
- i. Track defects (a.k.a. “bugs”) and the resulting changes.

The Acquiring Organization or lower-tier configuration control boards, as delegated, shall (CLD-013) control delivered products, including documentation, Hardware Descriptor Language (HDL) source, programming files, data tables, and products used to generate CLDs.

4.2.4 Corrective Action

The Developer shall (CLD-014) identify inconsistencies between requirements and design products and initiate corrective actions. Examples include the results of peer reviews, design reviews, audits, etc.

The Acquiring Organization shall (CLD-015) ensure that corrective actions are taken and managed to closure when actual results and performance deviate from the plans.

4.2.5 CLD Design Reviews

Development process includes both joint management reviews and technical reviews defined in the appropriate Systems Engineering Management Plan (SEMP). Multiple requirements and design reviews may be planned and performed by both the Acquiring Organization and the Developer(s).

Each Developer shall (CLD-016) regularly hold reviews of CLD requirements, design and development activities, test procedures, status, and results with the project stakeholders and track issues to resolution. This includes formal external reviews as well as peer reviews internal to the Developer. Specific requirements are established by systems engineering planning and, where applicable, by contracts.

See Appendix B, for recommended items to review and consider at a Design Review.

Omitting any of the detailed design phase steps increases the likelihood of having design problems and anomalies, increasing technical and programmatic risks.

Development risk increases if a robust preliminary design is not developed, documented, and reviewed. Lack of a preliminary design increases the probability that requirements may be missed in the design, causing development schedule and cost impacts.

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4.2.6 Acquisition Planning and Execution

The Acquiring Organization shall (CLD-017) evaluate potential suppliers using the following criteria:

- a. Assessment of the CLD processes of the potential supplier, measured against the mandatory requirements of this standard and any additional requirements imposed.
- b. Assessment of the CLD processes used by the potential supplier, measured against the best practices identified within this standard.
- c. The use of Capability Maturity Model Integration (CMMI) or equivalent process maturity certification for development organizations.

Note: This standard does not impose a requirement for CMMI but does recognize that CMMI may be used by a Developer to lend strength to their processes.

Standard data requirements documents, including two that are directly applicable to CLD developments, are available thru the MSFC Integrated Document Library. <https://masterlist.msfc.nasa.gov/drm/>

<u>STD/DE-PDDD</u>	<u>Programmable Devices Design Documentation</u>
<u>STD/DE-CLDP</u>	<u>Configurable Logic Devices Development Plan</u>

See also NASA-HDBK-4008, section 13, "Out-of-House Considerations".

Following selection of a supplier the Acquirer performs a management and insight role with that supplier, as part of the project management and systems engineering process. The Acquirer shall (CLD-071) assess the supplier's performance. In assessing performance, the Acquirer should evaluate the supplier's performance with respect to the following criteria:

- a. Handling of project requirements changes.
- b. Accurate transformation of high-level project requirements into detailed requirements and designs.
- c. Specification of interfaces between the supplier's product and systems external to it.
- d. Risk management planning and implementation.
- e. Integration and test plan and its implementation in accordance with the required activities in the projects integration and test plans.

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f. The supplier's CM plan and its implementation in accordance with the required activities of the project's CM plan.

g. The content and frequency of progress reports, product metrics, and process metrics submitted in response to measurement plans.

h. The supplier's delivery, integration, verification, and validation processes.

Each Developer shall (CLD-072) require suppliers (including subcontractors) to provide electronic access by authorized NASA project personnel for in-process and supplementary CLD technical documents and files that are developed for NASA projects, in accordance with the contract and NASA insight planning.

4.2.7 Training and Experience

The Developer shall (CLD-101) define the training and experience criteria for selection of design, review, and assurance personnel for CLD developments. For effective peer reviews, the Developer should include peer reviewers with both expert-level experience and knowledge of CLD designs.

4.3 System Safety

4.3.1 Safety and Hazard Control

The Developer shall (CLD-062) ensure that CLDs are included in documented assurance planning and that appropriate analysis is performed to determine critical functions and hazards.

4.3.2 NASA Independent Verification and Validation Reporting

The Developer shall (CLD-063) provide access to IV&V facility personnel for CLD products and data produced in accordance with the requirements of this plan, for any CLD developments identified by the Acquiring Organization for project NASA Independent Verification and Validation (IV&V).

4.3.3 Safety Criticality Determination

During the concept or formulation phase of each CLD development, the Developer shall (CLD-064) determine whether the CLD implements safety critical functions. Note: The system criticality determines the overall criticality of hardware, but the Developer identifies specific CLDs implementing safety critical functions in support of that higher-order determination.

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Each Developer shall (CLD-006), with the concurrence of the Acquiring Organization, classify and document the classification of the CLDs as one of the following:

- a. Safety critical—a characteristic in which loss of function or erroneous function could lead to loss or injury of crew or ground personnel, destruction of the system, damage to property external to the system, or damage to the environment.
- b. Mission critical—a characteristic in which loss of function or erroneous function could lead to the inability to accomplish one or more delineated mission objectives.
- c. Noncritical—all others.

If changes in the application or analysis determine that a previously noncritical system is now safety or mission critical, the Developer shall (CLD-007) update the development methodology and documentation to the requirements for a safety critical application. See also Radio Technology Commission for Aeronautics (RTCA)/DO-254, Design Assurance Guidance for Airborne Electronic Hardware, for guidance.

4.3.4 Safety Critical Function Specifications

For all safety critical CLD specifications, the Developer shall (CLD-065):

- a. Perform the specification completeness checklist of Appendix A.
- b. Document and implement an approach used to demonstrate correctness, consistency, and completeness of CLD requirements specifications.
- c. Identify within the specification all safety-related requirements.

4.3.5 Safety Verification

Using the system specification and associated design and implementation, the Acquiring Organization shall (CLD-066) ensure that all safety-related requirements for safety critical CLD designs have been implemented correctly and verified by testing and any other appropriate verification methods.

4.3.6 Safety Impact Evaluation

Each Developer shall (CLD-067) evaluate any changes to safety critical CLDs, including those that result from problem or discrepancy resolution, for potential safety impacts, including the creation of new hazard contributions and impacts, modification of existing hazard controls or mitigations, and detrimental effect on safety critical software or hardware. See also section 5.5.6.

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4.3.7 Computing System Boundary

Developers and the Acquiring Organization (for CLDs implemented into higher order systems) shall (CLD-068) define in hazard reports the boundaries of the computing system element within a safety critical control system. For example, if a non-critical CLD failure within a critical circuit were to fail, the boundary of fault propagation would need to be addressed (e.g. at the circuit, card, box, or system level.)

4.3.8 Trend Analysis

The Acquiring Organization shall (CLD-069) ensure the analysis and measurement of performance trend data for safety critical computing hardware, including the development and execution of plans to improve performance measures that do not meet defined expectations. This function may be delegated to the Developer.

4.4 CLD Quality Assurance

A successful CLD development requires a coordinated effort between engineering and SMA throughout the entire life-cycle. During the phase in which HDL is being designed, the focus is more upon process assurance, transitioning to quality engineering for the hardware implementation of the devices. SMA provides assessment of the trade studies, evaluation of the high level design, and an analysis of the top-level architecture. SMA reviews all simulation and analysis results.

The Developer shall (CLD-070) establish quality assurance processes and guidelines to address both process assurance during the design and quality assurance during the manufacturing phase of CLDs. The Acquiring Organization may establish quality assurance requirements that flow to the Developer.

See also NASA-HDBK-8739.23 "NASA Complex Electronics Handbook for Assurance Professionals."

4.5 CLD Requirements Tailoring

This standard is developed to encompass a broad range of CLD development. Each program, project, or activity is unique and varies in complexity. Therefore, it is essential that the Acquirer and the Developer work together to identify an appropriate development approach, consistent with the risk posture of the overall activity. Exceptions, tailoring, or other modifications to the requirements of this document specific to a given program, project, or activity are within the authority of the responsible program, project, or activity technical authority having invoked this Standard.

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4.5.1 Tailoring Risks

The Acquirer shall (CLD-102) assess a specific development approach as measured by the requirements of this standard and identify candidate risks for formal risk management through established processes. The generic development risks for CLD (RCLD) underlying the requirements in this standard are defined below and mapped to specific requirements in Appendix G.

- RCLD-1 Latent defect that is not found until a failure occurs in the fielded product.
- RCLD-2 Inadequate artifacts to certify the suitability of the CLD to meet the expectations of the Acquirer, Stakeholder, or Regulatory Authorities.
- RCLD-3 Uncorrectable defects, within cost or schedule constraints that impact the performance needed by the Acquirer.
- RCLD-4 Defects that will manifest during later phases of the development (but before acceptance by the Acquirer) and that cause non-trivial cost or schedule impacts to correct are not found.
- RCLD-5 Resulting design meets requirements but is a sub-optimal implementation (e.g. margin, power, cycle time, cost, etc.)
- RCLD-6 Inability of Acquirer to maintain or update the CLD in the absence of the Developer.
- RCLD-7 Risk of cost or schedule growth or inefficiency
- RCLD-8 Decreased Acquirer insight into Developer's technical or programmatic processes.
- RCLD-9 Inability of acquirer to integrate safety hazards, risks, cost, schedule or technical performance

4.5.2 Tailoring Guidance

It is highly recommended that all of the requirements in this specification be considered when formulating a development that will include CLDs. However, not every requirement will add value in every case. For example, where heritage or legacy designs are used, or where these requirements are applied mid-way through the development, many of the early phase requirements (for example, acquisition planning) may no longer be relevant. Many of these requirements are also written assuming complex designs or design aspects that may not be fully testable, whereas

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simple designs can be fully tested. It is therefore important for the Acquirer for a given development to work with the Developer to determine what is most appropriate for the requirements and design approach—and use that to develop tailoring of the requirements for this standard. It is impossible to anticipate every permutation in the abstract. However, the following general guidance is given:

Requirements CLD-001, 002, 003, and 004 are considered ‘de facto’ requirements that are taking place (to some extent) by virtue of the development of this standard and consideration of applicability.

Requirements CLD-018 and CLD-102 are the most important requirements in this standard, because the Development Plan (CLD-018) defines explicitly the Developer’s approach and enables the evaluation (CLD-102) which allows the Acquirer to explicitly evaluate that approach against this Standard and identify residual risks.

Further guidance on tailoring is determined by the complexity, criticality, and risk tolerance of a given development, as shown below. In all cases where a requirement from this standard is tailored (especially by exclusion) this should be taken into account for risk determination. (See CLD-102).

CLD Project Type	CLD Requirements To Be Applied	Notes
Low complexity or high risk tolerance	CLD- 018, 019, 028, 050, 055, 056, 102, 103	
Moderately complex or moderate risk tolerance developments	CLD- 018, 019, 028, 050, 055, 056, 102, 103 PLUS CLD-005, 006, 007, 009, 010, 011, 012, 013, 014, 015, 016, 017, 020, 022, 023, 024, 025, 026, 027, 032, 033, 038, 039, 040, 041, 047, 048, 051, 053, 059, 060, 061, 062, 064, 070, 071, 072, 073, 101, 104	May also need to include requirements for Critical or Safety Critical Applications
Highly complex, low-risk tolerance, high visibility, or large cost (including most manned systems)	CLD- 018, 019, 028, 050, 055, 056, 102, 103 PLUS CLD-005, 006, 007, 009, 010, 011, 012, 013, 014, 015, 016, 017, 020, 022, 023, 024, 025, 026, 027, 032, 033, 038, 039, 040, 041, 047, 048, 051, 053, 059, 060, 061, 062, 064, 070, 071, 072, 073, 101, 104 PLUS CLD-008, 031, 035, 036, 044, 045, 046, 049, 057, 063	May also need to include requirements for Critical or Safety Critical Applications
Additional Requirements for	CLD-029, 030, 042, 054	

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CLD Project Type	CLD Requirements To Be Applied	Notes
Mission Critical Application		
Additional Requirements for Safety Critical Applications	CLD-029, 030, 042, 054 PLUS CLD-037, 043, 052, 058, 065, 066, 067, 068, 069	

5.0 DETAILED REQUIREMENTS

The Acquiring Organization and/or the Developer may apply additional process-based approaches to their individual developments. Of particular value is the capability maturity model/integration (CMMI) approach and certification. CMMI process certification, although not a requirement for CLD developments is a best practice and may yield value.

5.1 Definition/Planning

Each Acquiring Organization shall (CLD-018) document or record the acceptance criteria and conditions for the CLD deliverables, or the CLD portion of higher-level assemblies.

The Developer shall (CLD-019) produce a development plan that documents the organization's approach to design, development, test, and evaluation (DDT&E) of and assurance for CLDs and tailors their organizational specific processes and procedures as necessary. This plan is subject to approval by the Acquiring Organization. The plan should include a compliance assessment per Appendix G.

Specific requirements from this standard that are normally addressed by the CLD Development Plan include: CLD-009, 016, 019, 020, 022, 023, 042, and 046. The Developer may also use the Development Plan for CLD-012, 101, 006, 070, 024, 029, and 045. However, the Development Plan may include additional information or may point to other documentation to address any of the requirements of this standard.

Note: Development risk increases if any of the planning steps are omitted. Lack of planning increases the likelihood of cost and schedule impacts.

5.1.1 Unique Life Cycle

Each Developer shall (CLD-020) define the development life cycle being used for development of CLDs. A typical generic life cycle is shown in Appendix E. This life cycle is an example and is not intended to constrain the process used by an individual Developer, but it may be used in the absence of specific policies. The Acquirer should address any significant departures from this generic template.

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5.1.2 Documentation Lifecycle

CLD developments require unique documentation above the traditional drawings and analysis produced for a circuit card design. Each Developer shall (CLD-022) document in their Development Plan an approved list of deliverables based on implementation of this MSFC Standard and any additional requirements imposed by the Acquiring Organization or by contract. One suggested set of documentation is shown in Appendix F. For CLDs that are noncritical, critical with low complexity, prototype, development units, or non-flight products, the Acquiring Organization should agree to a reduced documentation set.

5.1.3 Organizational Approach

For each developing organization the Developer shall (CLD-023) define the organizational approach utilized for CLD developments, to include:

- a. Management, assurance, and control functions.
- b. Data management and CM.
- c. Plans for process improvement and process institutionalization.
- d. Roles and responsibilities for SMA.
- e. Version control for electronic design files (prior to entry into formal CM processes).
- f. The use of peer reviews and the peer review process.
- g. Processes for identification and management of risks internal to the development organization.

This documentation may be one or more stand-alone documents or may be included in overall planning documents that have greater scope than CLDs.

See also NASA-HDBK-4008, section 5.1 “Roles and Responsibilities” for one possible approach to development team organization.

5.1.4 Margins and Technical Performance Measures

The Developer shall (CLD-024) define CLD margins specific to the device type utilized and in relation to the avionics architecture level technical performance measure (TPM) in order to maintain performance for both input/output (I/O) pins and logic modules (gates, flip-flops, etc.).

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These margins shall (CLD-025) be phased to reflect decreasing margin requirements progressively at Preliminary Design Review (PDR), Critical Design Review (CDR), fabrication, programming, and delivery.

The Developer shall (CLD-026) track CLD resource utilization as TPMs and report in accordance with the requirements of the Acquiring Organization.

5.1.5 Verification and Validation Planning

Verification and validation activities can span multiple iterations of the design cycle that leads ultimately to the final product. V&V can take place during any or all of the following:

- a. Simulations.
- b. Developmental tests (e.g. ‘breadboard,’ ‘engineering model,’ etc.).
- c. Temperature range testing.
- d. Integration tests with software or higher level systems.

The Developer shall (CLD-027) perform requirements validation to ensure that the CLD performs as intended in the customer environment.

Each Developer shall (CLD-028) plan both verification and validation activities to include methods, environments, and criteria, subject to the approval of the Acquiring Organization.

The Developer shall (CLD-029) define and implement an approach utilizing independent personnel (i.e., separate from the designer(s)) for verification and validation of critical CLDs.

For CLDs that implement one or more critical functions, the Developer’s design team shall (CLD-030) document, for the V&V activity, the CLD design characteristics, including the results from the analysis of customer and other stakeholder requirements, design features, and the operational concepts. References to higher level documents can be used. This document provides traceability for the implementation and establishes the guidelines for the test and verification steps.

Note: The CLD functional requirements are derived from the board-level and system-level requirements

5.1.6 Independent Verification

The Acquiring Organization shall (CLD-031) specify any external verification activities to be performed in-line with the Developer and whether they are milestones that are mandatory sequential steps in the Developer’s progress.

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5.1.7 Design Maintenance, Operations, and Retirement

Planning for operations, maintenance, and retirement begins early in the life cycle. Operational concepts and scenarios are derived from customer requirements and validated in the operational or simulated environment. Design maintenance activities sustain the product from delivery to the customer until retirement.

5.2 Requirements Definition

The Developers shall (CLD-035) maintain bidirectional traceability of requirements to the project plans and work products throughout the life cycle, including traceability reports submitted at identified points in the lifecycle.

Traceability reports shall (CLD-036) be available electronically.

For each CLD that implements one or more safety critical functions, the Developer shall (CLD-037) either:

- a. Develop a requirements specification (Index 2 from Table I) for the device or devices; or
- b. Include specific requirements for the CLD device in subsections of specifications at either the board level or higher assembly.

The Developer or the Acquiring Organization may, as a best-practice, implement this requirement for noncritical CLDs that are highly complex.

5.3 Preliminary and Detailed Design

A typical design process is divided into a Preliminary Design Phase and a Detailed Design Phase (often called the Critical Design Phase.) During the Preliminary Design, requirements are translated into an architecture, block diagrams, data flows, and preliminary resource estimates (e.g. gate counts, pin counts, etc.). Critical modules of the design may be prototyped or developed in detail to prove feasibility, refine resource estimates, or as risk mitigation. This phase normally culminates with a Preliminary Design Review (PDR). During the Detailed Design Phase, the preliminary design is updated and expanded to fully address all requirements. Simulation test benches will also be developed and used to confirm the functionality of the design. Prior to entering the Implementation phase, a peer review is normally held.

A CLD design consists of more than just the HDL logic design. Improper planning of electrical board level electrical integration can result in a flawed design. This includes cases where external components are not modeled sufficiently in simulations and analysis. The Developer

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shall (CLD-103) include board-level electrical considerations in the design, analysis, and review of CDL developments. See Appendix B of this standard for guidance. See also NASA-HDBK-4008, Appendix F.

Note: Lack of a good top level design can cause requirements to be missed and schedule and cost impacts in the detailed design phase. Tailoring out of preliminary design products and reviews increases risk, even in noncritical designs.

See Appendix C for a list of best practices to consider during design.

See also NASA-HDBK-4008, Section 7.3 “Design Standard/Best Practices”.

5.3.1 Configurable Logic Device Identification

The developing organization shall (CLD-038) generate a list of CLDs to be developed and identify whether each device implements critical functions.

5.3.2 Parts Selection

The parts to be used for the fielded implementation CLDs shall (CLD-039) be selected and documented along with the criteria used for making the selection. The parts used for the flight FPGA implementations should be selected as early in the development cycle as feasible. This will allow for the long procurement cycles normally associated with flight FPGA devices. In addition to the mandatory requirements of the program Electrical, Electronic, and Electromechanical (EEE) Parts Management and Control Requirements and MSFC-STD-3012, the following factors should be taken into consideration in selecting a device family and specific part number:

- a. Package style.
- b. Reliability, flight qualification status, and heritage.
- c. Radiation specs (total dose and single event effects).
- d. Estimate of utilization:
 1. Use prior experience.
 2. Find similar design and get gate count for target technology.
 3. Overestimate if a guess is necessary.
 4. Quantity needed.

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- e. Speed rating.
- f. The long procurement cycles normally associated with flight grade devices.
- g. The availability of equivalent commercial grade devices that may be desirable in the development of breadboards and test boards. For cost reasons, equivalent commercial devices may be considered for the development of breadboards and test beds.

5.3.3 Incorporation of Non-Development Items

The Developer may include non-development items such as ‘heritage’ (e.g. created previously by the Developer for a different purpose) or ‘off-the-shelf’ (procured or reused from an organization other than the Developer) design elements.

The Developer shall (CLD-040) ensure that any utilized non-development items have identifiable and bounded impacts upon the overall function and reliability of both the CLD and the overall circuit design.

The Developer shall (CLD-041) ensure that when a non-developmental product is to be acquired by the Developer, the following conditions are satisfied:

- a. The requirements that are to be met by the non-developmental item are identified.
- b. The non-developmental item includes documentation to fulfill its intended purpose (e.g., usage instructions).
- c. Proprietary, usage, ownership, warranty, licensing rights, and transfer are addressed.
- d. Future support for the non-developmental product is planned.
- e. The non-developmental item is validated to the same level of confidence as would be required of the developed items, although this validation may take place as part of the validation of a higher assembly.
- f. Any risks assumed by the use of non-developmental items are evaluated for potential formal risk management tracking.

A special case of non-developmental items, very common in the development of CLDs with industry standard functions or interfaces, is Intellectual Property (IP). IP is a design element that is electronic or documentation based rather than a physical functional device (although physical devices may also include or be accompanied with IP.).

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When selecting IP for use, the design and assurance teams should consider:

- a. The format of the IP provided (e.g. HDL code, encrypted netlist, etc.)
- b. The availability of documentation (test procedures, instructions, scripts, netlists, test benches, etc.),
- c. Heritage of the IP (i.e. where has it been fielded before and what was the result of that application)
- d. Cost (one time licensing fees, verses per use fees)
- e. Technical support provided

5.3.4 Safety Critical Design Identification

Each CLD design, including but not limited to HDL designs and schematic gates designs, shall (CLD-042) define and utilize a method of notating critical design elements in design documentation.

5.3.5 Mixed-Classification Platforms

When safety critical and non-safety critical design elements are both included within a single physical CLD device, the Developer shall (CLD-043) ensure that the level of potential interaction or interference between the safety critical and non-safety critical elements is bounded so as to ensure safe operation.

As a best practice, avoid mixing safety critical and non-safety critical elements in a single physical CLD, when feasible and practical.

5.3.6 Diagram Semantics

Developers shall (CLD-044) include definition of the semantics used in all diagrams provided as artifacts of compliance or certifications.

5.3.7 Hardware Descriptor Language Design Guidelines

Each Developer utilizing HDL shall (CLD-045) define and utilize HDL design guidelines for each design classification (e.g., critical, noncritical, etc.) for the HDL development performed. Parent organizations should consider the use of common HDL design guidelines across multiple design organizations in order to facilitate effective reviews and design insight.

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Examples of the types of HDL design guidelines that may be defined include, but are not limited to:

- a. Naming conventions to allow recognition of the function of signals by their name.
- b. Use of the comment header of the HDL design to capture nomenclature.
- c. Use modular design to ease testability, readability, and simulation.

Note: The existence of HDL design guidelines does not ensure a good design, nor does the absence of such guidelines necessarily result in a bad design. However, HDL design guidelines will help with reviews and integration.

5.3.8 Secure Design Practices

Developers shall (CLD-046) produce and follow secure design practices to ensure the delivered products are not vulnerable to:

- a. Unauthorized access to the internal design, and
- b. Unauthorized control of the functions of the hardware.

5.3.9 Version Control

The Developer shall (CLD-047) implement version control, at the point pre-determined by the Developer, for all files in accordance with the program's CM plan, providing the following features:

- a. Ease of tracking changes.
- b. Reverting to an earlier version of the code.
- c. Archiving.
- d. Identification of the author of the change.

5.3.10 Design Analysis Tool Selection

The Developer shall (CLD-048) evaluate and select appropriate design analysis tools, with consideration given to each of the following.

5.3.10.1 Use of Lint Tools

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A “lint tool” is a product that analyzes the HDL design for various syntax and construct errors that may not be found during synthesis, such as non-portable constructs. The designers should make frequent use of lint tool checks prior to both simulation and synthesis.

5.3.10.2 HDL Rule Checkers

Other HDL Rule Checkers can be used to provide configurable rules checking specific to the developer’s specific design requirements. When available, these tools should be used, and the results should be incorporated into the HDL design during both the pre-simulation and pre-synthesis phases of design.

5.3.10.3 Code Coverage

A code coverage tool is used to assess what percentage of an HDL design has been exercised during simulations. Code coverage tools should be used to help assess the confidence in the quality of the design.

5.4 Implementation

During the implementation phase, the functional design is targeted to the physical device and the configuration documentation and files created. Typically, this includes steps such as:

- a. Performing Vendor Specific Place and Route.
 - b. Selecting and/or documenting constraints and settings (e.g. fixed pins, minimal clock skew paths, etc.).
 - c. Verify post-route.
 - d. Developing the procedures and altered item drawings for configuration of FPGA targets.
- As a best practice, consider the use of a script to perform place and route functions, because this will ensure repeatability between runs by reducing the chance of human error.

As part of the post-route verification, the design and assurance teams shall (CLD-049) review the timing report as well as logs from vendor and analysis tools for errors, warnings and notes. Any errors or warnings that are not corrected should be thoroughly understood, and rationale should be developed for not making further design changes. It is very important to understand what the synthesis tool is actually doing, in order to understand the log reports.

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5.5 Verification & Validation

Verification activities include design reviews, engineering peer reviews, simulations, post place-and-route analysis, and post-programming verifications, and the physical lab environment. Validation (i.e., to demonstrate that a verified device will satisfy its intended use in its intended environment) is typically performed at a higher systems level.

The Developer shall (CLD-050) perform the planned verification and validations of CLD development products.

Each Developer shall (CLD-051) record, address, and track to closure the results of verification and validation activities.

For each safety critical verification, the Developer shall (CLD-052) include test in the actual hardware (prototype or final) intended for fielding.

5.5.1 Analysis

The Developer shall (CLD-053) verify the synchronous design of an FPGA by static timing analysis or alternatively by post-route timing analyses using a place and route tool and test vector simulation with timing checkers performed at the primitive level.

As a design goal, CLD code coverage thru analysis should be at least 100% for all CLD designs.

If 100 percent code coverage is not achieved, the Developer shall (CLD-054) either increase the number of simulation cases or document the rationale for retaining each uncovered statement.

Note: It is important that personnel involved with developing simulations or reviewing the results understand the simulation tool capabilities, review the simulation results for adequate coverage, and perform sufficient simulations to cover situations when multiple parameters are simultaneously at specified limits (often called “corner cases.”)

See also NASA-HDBK-4008, Section 8.4.2 and subsections, for additional discussion of timing analysis.

5.5.2 Test Plans & Procedures

The Developer shall (CLD-055) develop and maintain Test Plan(s) and Test Procedure(s). Suggested content to address includes a description of test preparations, including hardware and software, including:

- a. Test descriptions, including:

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1. Test identifier.
 2. Requirements addressed by the test case.
 3. Prerequisite conditions.
 4. Test input.
- b. Instructions for conducting procedure.
 - c. Expected test results, including criteria for evaluating results and assumptions and constraints.
 - d. Criteria for evaluating results.
 - e. Requirements traceability.
 - f. Identification of test configuration.
 - g. Sufficient information to ensure that tests are repeatable, including the seeds used with pseudorandom number generators.

5.5.3 Test Execution

During CLD testing, the Developer shall (CLD-056):

- a. Perform tests as defined in documented test plans.
- b. Ensure that the implementation of each requirement is verified to the requirement.
- c. Include evaluation test results and document the evaluation.
- d. Document defects identified during testing, and track to closure.
- e. Maintain traceability from the test procedures to the requirements.
- f. Ensure that CLD hardware is tested on the target circuit board or a high-fidelity simulation.

5.5.4 Defect Reporting Requirements

The Developer shall (CLD-057) implement problem reporting and resolution for CLD defects in accordance with program requirements.

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5.5.5 Defect Elimination

The Developer of safety critical CLD designs shall (CLD-058) identify the approaches and tools to be used to demonstrate the absence of design defects in HDL or post-synthesis products. The checklists in Appendix A may be used as is or used as guidelines in developing specific criteria.

5.5.6 Regression Testing

The Developer shall (CLD-104) identify and perform regression testing when a design is modified. Regression testing may be partial or complete repetition of previous tests, and may require modified procedures in order to adequately test the change. If regression testing is not performed after a change is made, the design may not function properly in higher level assemblies.

5.6 Manufacturing/Production

The Altered-Item Drawing defines the process and tools necessary to program the correct FPGA device as called out in the assembly parts list. The Developer shall (CLD-059) develop CLD altered-item drawings containing, at a minimum, the following information:

- a. Identification of altered item marking.
- b. Identification of altered item configuration (i.e. programming) files including traceability back to the source HDL, scripts, tool versions, and test benches.
- c. Identification of the original unaltered part.
- d. Processing instructions
 1. Handling
 2. Marking
 3. Programming
 4. Inspections.

5.6.1 Configuration of Delivered Devices

The Developer shall (CLD-060) perform configuration or reconfiguration of deliverable CLD components (including those included in higher-level assemblies) in accordance with approved work authorization documentation (e.g., drawings, procedures, etc.), utilizing the current approved CM controlled baseline of the design, unless another version is explicitly authorized, and monitored by the Developer's quality assurance organization.

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The Developer shall (CLD-061) reflect the results of the configuration process (including traceability, resolution of anomalies, serial numbers, etc.) in the as-built documentation of the hardware.

See also NASA-HDBK-4008, section 8.6.1, "Programming File(s) Build Considerations" for additional recommendations.

5.7 Fielding The Device

5.7.1 Board/System Integration

A configured CLD chip is fielded by assembly onto a circuit card. At this stage, traditional and existing electronic engineering, manufacturing, and quality assurance techniques dominate. However, the design of the CLD is not validated until the card or higher assembly are shown to meet the requirements that are traceable to the CLD.

At this phase, issues with the integration of the CLD device into the electrical design of the board may appear. See Appendix B and NASA-HDBK-4008 for guidance on how to avoid board-level design issue at this stage.

5.7.2 In-Flight Reconfiguration

The ability to reconfigure a CLD device after it has been delivered to a customer is enabled by many current FPGA technologies, although the ability to do so with minimal access to the component is a function of the design of the system, box, and board on which the FPGA is installed. Care is required when reconfiguring FPGA devices, or more specifically the memory devices containing the FPGA configuration definition, especially for FPGAs performing critical functions, once a device is fielded. In-flight reconfigurations, where access is entirely remote with no direct access from personnel and where the operation of the device may be required to support system operation, require especial caution. An improperly configured FPGA can cause the device to stop functioning in-flight. Systems designed to support in-flight reconfigurations should have a fail-safe mode to restore the system to the last working state in the event of a reconfiguration error. The fail-safe mode allows the FPGA to be reconfigured using the last known reliable configuration file stored locally in the system from an external location on the spacecraft, or even from ground.

In-flight reconfigurations should be included in the maintenance planning when planned by the mission and possible.

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5.8 Maintenance Of The Design

The Developer shall (CLD-032), consistent with the requirements of the Acquiring Organization, provide for the operations and maintenance of delivered CLD design products and maintain the design from the time of delivery until design retirement.

The Developer shall (CLD-033) complete and deliver CLDs or other end-products containing CLD design elements to the Acquiring Organization (or designee) with appropriate documentation to support the operations and maintenance phase of the life cycle.

The Developer shall (CLD-034):

- a. Document the maintenance plans through operations, maintenance, and retirement activities.
- b. Implement operations, maintenance, and retirement activities as defined in the respective plans.
- c. Complete and deliver the product to the customer with appropriate documentation to support the operations and maintenance phase of the life cycle.

5.9 Potential – Design Requirement Evaluation

The Acquiring Organization and the Developer shall (CLD-073) evaluate the following design requirements for applicability and potential incorporation into appropriate requirements specifications for CLDs or systems containing CLDs. Where both hardware and software elements are present in a computing system, the implementation of these requirements should be applied at the computing system level (i.e., the combination of hardware and software). This approach, rather than allocating requirements separately to hardware and software, enables a holistic consideration of the potential contributors and combinations of contributors to hazards and hazard controls.

Note: As used in the following list, the word ‘shall’ is not a mandatory requirement of this standard, but is draft language for possible incorporation into design specifications.

- a. Hazardous function control. Computing systems shall provide hazardous function control where the inadvertent activation or deactivation of the function or capability could result in an identified critical or catastrophic hazard.
- b. Safe initialization. Computing systems shall initialize to a known, safe state. Circuitry interfaced to the CLD shall take into consideration the transient nature of inputs/outputs of the CLD during power-up and power-down conditions.

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- c. State transition. Computing systems shall safely transition between all predefined known states.
- d. Orderly shutdown. Computing systems that implement termination of safety critical functions shall perform orderly, controlled shutdowns of those functions to known, safe states.
- e. Off-nominal power. Safety critical computing systems shall establish a safe or powered-down state when self-monitoring functions detect off-nominal power conditions.
- f. Operator overrides. Computing system overrides shall require at least two independent actions by the operator.
- g. Command sequence. Where execution of commands out of sequence can cause a hazard, the computing system shall reject commands received out of sequence.
- h. Inadvertent memory modification. Computing systems shall detect inadvertent memory modification and recover to a known, safe state.
- i. Anomaly recovery. Computing systems shall establish a predefined safe state prior to the operational time predicted to cause a critical failure, following detection of predetermined indications of incorrect or incomplete processing.
- j. External input. Computing systems shall discriminate between valid and invalid input from external sources and reject the invalid input while remaining in safe operations.
- k. Integrity checks. Computing systems shall perform integrity checks on input and output across the computing system boundary.
- l. Command rejection. Computing systems shall reject hazardous commands that do not meet prerequisite checks for execution.
- m. Prerequisite checks. Computing systems shall perform prerequisite checks prior to the execution of hazardous commands.
- n. Inhibit display. Computing systems shall make available, for display to the operators and to other circuitry, the status of inhibits used to control hazards.
- o. Inhibit state change. For commands that change the state of an inhibit, the computing system shall require a unique command for each state transition for each inhibit.

6.0 NOTES

None.

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APPENDIX A. SAFETY CRITICAL SYSTEM SPECIFICATION CHECKLIST

The following checklist items apply to the development and documentation of safety critical computing system specifications, including CLDs. These items are provided to ensure the comprehensiveness of these specifications. Not all items are appropriate to all designs.

- a. Demonstrate completeness of human-computer interface requirements criteria including:
 1. Specification of the events to be queued.
 2. Specification of the type (such as alert and routine) and number of event queues to be provided
 3. Ordering scheme within the queue (priority versus time of arrival).
 4. Operator notification mechanism for items inserted in the queue.
 5. Operator review and disposal commands for queue entries.
 6. Queue entry deletion and rejection.
 7. Observability of the system state.
 8. For every data item displayable to a human (values and labels):
 - (a) What events cause this item to be displayed?
 - (b) Can and should the display of this item ever be updated once it is displayed? If so, what events should cause the update? Events that trigger updates may be: external observables; the passage of time; actions taken by the viewing operator; actions taken by other operators.
 - (c) What events should cause this data display to disappear?

- b. Demonstrate completeness of system state requirements, including:
 1. The system and software starting in a safe state. Interlocks are initialized or checked to be operational at system startup, including startup after temporarily overriding interlocks.
 2. The internal software model of the process is updated to reflect the actual process state at initial startup and after temporary shutdown.
 3. All system and local variables, including clocks, are properly initialized upon startup.
 4. The behavior of the software with respect to inputs received before startup, after shutdown, or when the computer is temporarily disconnected from the process (off-line) is specified.
 5. The maximum time the computer waits before the first input is specified.
 6. Paths from fail-safe (partial or total shutdown) states are specified.
 7. The time in a safe but reduced-function state is specified.
 8. Interlock failures should result in the halting of hazardous functions.

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9. There is a response specified for the arrival of an input in any state, including indeterminate states.
 10. Systems using redundancy should specify how the system establishes state consistency across all redundant units.
 11. Systems using redundancy should specify how failed units are identified and removed from the system. Note: this requirement is meant to address Byzantine agreement issues.
- c. Demonstrate completeness of input and output variable requirements including:
1. The specification should address all information available from each sensor. Note: if information available from a sensor is to be ignored, the specification should say so.
 2. Legal output values that are never produced are checked for potential specification incompleteness.
 3. The specification should identify any groupings of input values that must be received and processed in a time-homogenous manner.
- d. Demonstrate completeness of requirements for events that trigger state changes including:
1. Robustness criteria:
 - (a) Every state should have a behavior (transition) defined for every possible input.
 - (b) The logical OR of the conditions on every transition out of any state should form a tautology. Note: A tautology is a statement that contains more than one sub-statement and that is true regardless of the truth values of its parts (e.g., “either the valve is open OR the valve is not open”).
 - (c) Every state should have a behavior (transition) defined in case there is no input for a given period of time (a timeout).
 - (d) Every state should have defined state transitions for exceptional conditions or document that the exceptional conditions have no safety impact. Exceptional conditions include debug exceptions, nonmaskable interrupts, breakpoints, overflow, bounds check, invalid op codes, coprocessor not available, co-processor error, floating point exception (e.g., division error), segment or gate not present, stack fault, general protection failure, page fault, or other exceptional conditions or interrupts unique to the implementation.
 2. Nondeterminism criterion:
 - (a) The behavior of the state machine is deterministic.
 3. Value and timing assumptions:
 - (a) All incoming values are checked and a response specified in the event of an out-of-range or unexpected value.
 - (b) All inputs are fully bound in time, and the proper behavior specified in case the limits are violated or an expected input does not arrive.

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- (c) A trigger involving the nonexistence of an input is fully bounded in time.
 - (d) A minimum and maximum load assumption is specified for every interrupt signaled event whose arrival rate is not dominated (limited) by another type of event.
 - (e) The computing system should check the minimum-arrival-rate for each physically distinct communication path.
 - (f) The computing system should query its environment with respect to inactivity over each communication path.
 - (g) The response to excessive inputs (violations of load assumptions) is specified.
 - (h) When the desired response to an overload condition is performance degradation, the specified degradation is smooth.
 - (i) When the desired response to an overload condition is performance degradation, the operators are informed of the degradation.
- e. Demonstrate output specification completeness including:
1. Safety critical outputs are checked for reasonableness and for hazardous values and timing.
 2. For the largest interval in which both input and output loads are assumed and specified, the absorption rate of the output environment should equal or exceed the input arrival rate. The absorption rate here is the rate at which the output environment is consuming the load.
 3. Contingency action is specified when the output absorption rate limit is to be exceeded.
 4. Update timing requirements or other solutions to potential overload problems, such as operator event queues, are specified.
 5. Automatic update and deletion requirements for information in the human-computer interface are specified.
 6. The required disposition for obsolete queue events should include specification of what to do when the event is currently being displayed and when it is not.
 7. All inputs used in specifying output events are properly limited in the time they can be used (data age).
 8. Output commands that may not be able to be executed immediately are limited in the time they are valid.
 9. Incomplete hazardous action sequences (transactions) should have a finite duration specified.
 10. Upon exceeding the duration limit of a hazardous action sequence the software should cancel the sequence automatically, return to a safe state, and inform the operator.
 11. Revocation of a partially completed action sequence should address the specification of multiple times and conditions under which varying automatic cancellation or postponement actions are taken.

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12. Operator warnings are issued in the event of revocation of a partially completed action sequence.
 13. A latency factor is included when an output is triggered by an interval of time without a specified input and the upper bound on the interval is not a simple, observable event. The latency factor represents the interval of time during which the receipt of new information cannot change an output O even though it arrives prior to the actual output of O .
 14. Contingency action is specified to handle events that occur within the latency period.
 15. A latency factor is specified for changeable human-computer interface data displays.
 16. Appropriate contingency action is specified for data affecting the human-computer interface display that arrives within the latency period.
 17. A hysteresis delay action is specified for human-computer interface data to allow time for human interpretation.
 18. The specification should state what to do if data should have been changed during the hysteresis period.
- f. Demonstrate completeness of output to trigger event relationship requirements including:
1. Basic feedback loops, as defined by the process control function, are included in the software requirements. Note: In a basic feedback loop there must be one or more inputs that the software can use to detect the effect of any output on the process: the requirements must include appropriate checks on these inputs in order to detect internal or external failures or errors.
 2. Every output to which a detectable input is expected should have associated with it a requirement to handle the normal response.
 3. Every output to which a detectable input is expected should have requirements to handle a response that is missing, too late, too early, or has an unexpected value.
 4. Every output to which a detectable input is expected should have requirements to handle anomalous conditions that could be checked. An example of such an anomalous condition is an open circuit for a sensor.
 5. Spontaneous receipt of a non-spontaneous input is detected and responded to as an abnormal condition.
 6. Stability requirements are specified when the process is potentially unstable.
- g. Demonstrate completeness of the specification of transitions between states:
1. All specified states are reachable from the initial state. A state q_m is said to be reachable from state q_n if there exists a path from q_n to q_m and the logical AND of the predicates in the instantiated predicate sequence s_i corresponding to that path does not result in a contradiction.
 2. Desired recurrent behavior is part of at least one cycle.

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3. Required sequences of events are implemented in and limited by the specified transitions.
 4. States should not inhibit the production of later required outputs.
 5. Output commands that are physically reversible are reversible.
 6. If x is to be reversible by y , there is a path between the state where x is issued and a state where y is issued.
 7. Preemption requirements are specified for any multi-step transactions in conjunction with all other possible control activations.
 8. Soft and hard failure modes are eliminated for all hazard-reducing outputs. A *soft failure* mode is one in which the loss of the ability to receive a particular input *could* inhibit the software from providing an output with a particular value, while a *hard failure mode* involves the loss of the ability to receive an input that prevents the software from producing that output value. An output is *hazard reducing* if it leads to a state having a lower risk level; likewise, an output is *hazard-increasing* if it leads to a state having a higher risk level.
 9. Hazard-increasing outputs should have both soft and hard failure modes.
 10. Multiple paths are provided for state changes that maintain or enhance safety.
 11. Multiple inputs or triggers are provided for paths from safe to hazardous states.
 12. States should correctly handle the processing of items placed into a queue when in a prior state.
- h. Demonstrate constraint satisfaction by showing that the requirements include the identified project-specific safety requirements and are consistent with the identified software system safety constraints, including:
1. Transitions should satisfy software system safety requirements and constraints.
 2. Reachable hazardous states are eliminated or, if that is not possible, their frequency and duration reduced to only those states needed to achieve the goals of the system.
- i. Demonstrate that the requirements are consistent with the following general safety policy:
1. There are no paths to undesired hazardous states.
 2. All paths from a hazardous state should lead to safe states. Note that time in the hazardous state should be minimized, and that contingency action may be necessary to reduce risk while in the hazardous state. Note also that it may not be possible to build a completely safe system, i.e., it may not be possible to get from every hazardous state to a safe state. In that event, the system must be redesigned or some risk accepted.
 3. If a safe state cannot be reached from a hazardous state within an acceptable amount of time, all remaining paths from that hazardous state should lead to the least risk state available given the hazard and the environmental conditions, and at least one such path should exist.

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APPENDIX B. DESIGN REVIEW CHECKLIST

- a. Part Parameters and Deratings
 1. Data book part parameters may not match the part's operating environment.
 2. Derate (see MSFC-STD-3012 for specific criteria) for
 - (a) Temperature
 - (b) Age
 - (c) Voltage
 - (d) Radiation
 - (e) Excess load capacitance

- b. Timing analysis
 1. Analyze, for each clocked device:
 - (a) T_{su} (setup time) and T_h (hold time) for all clocked inputs
 - (b) T_{pw} (pulse width time) of clocks, asynchronous set, clear, and load inputs
 - (c) Set and clear recovery time
 - (d) Show all clock inputs and asynchronous inputs are free from both static (010 or 101) and dynamic (001011 or 110100) hazards.
 2. Parallel clocking
 3. Clock skew
 4. Timing of analog circuitry
 5. Minimum propagation delays
 6. Calculation of pulse shortening
 7. Transition times in delay calculations
 8. Clocking handled properly
 9. All clock-domain crossings are handled properly
 10. Asynchronous inputs filtering for meta-stability issues
 11. Time critical paths of each device and their timing margins
 12. Worst case timing analysis at the device and board levels

- c. Completeness of simulations performed:
 1. Best Case (Lowest Temperature, Highest Operating Voltage, Zero Radiation, Best Process)
 2. Worst Case (Highest Temperature, Lowest Operating Voltage, Maximum Radiation, Slowest Process)

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3. Simulation code/circuitry coverage (i.e. simulations adequately tests all sections of code and circuitry)
 4. Percent of nets in each device covered by the fault simulation (i.e., percent of nets exercised by the test vectors and their effect of faults are observable at the device's primary output)
- d. Gate Output Loading
1. Show that no gate output drive capacities have been exceeded
 2. High output drive currents may:
 - (a) Affect output voltage levels and propagation delays
 - (b) Cause thermal problems resulting in part damage
- e. Interface Margins
1. All gates must have their input logic level thresholds met.
 - (a) Different part families
 - (b) Digital and analog part interfaces
 2. Decreased interface margins
 - (a) Increase noise susceptibility
 - (b) Can affect the operation of some parts
 - (c) Increase Icc of Complementary Metal Oxide Semiconductor (CMOS) parts
 3. Many parts have maximum input transition times
 4. Slew rates
 5. Analyze input requirements of analog circuits
 6. Driving mixtures of Transistor-Transistor Logic (TTL) and CMOS
- f. State Machines
1. Analyze state machines for
 - (a) Unused states and lock-up
 - (b) Simultaneous assertion of flip-flop sets and clears
 - (c) Reset conditions and homing sequences
 2. Be careful with asynchronous state machines
- g. Asynchronous Interfaces
1. i.e., where the setup and hold times of incoming signals at receiving flip-flops cannot be guaranteed.

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2. Synchronize asynchronous inputs
 3. Don't use synchronizers to solve timing problems
- h. Resets
1. POR assertion and release voltages
 2. Reset T_{pw} must consider
 - (a) Longest reset T_{pw} specified for parts
 - (b) Power supply ramp rate
 - (c) Oscillator start-up time
 3. Reset should be synchronized
 4. No unintended execution of external Commands on power-up
- i. Part Safety Conditions
1. Protection of Electrostatic Discharge (ESD) sensitive parts
 2. Input voltage levels
 3. Tri-state output overlap
 4. Floating inputs
 5. Use of internal IC protection diodes
 6. Internal fan-out of signals
 7. External source/sink current and voltage level compatibility, and the use of shorted output pins to increase drive current
 8. Absolute maximum ratings!
- j. Cross-Strap Signals
1. Must provide fault isolation
 - (a) No powering of modules via cross-strap circuitry
 - (b) Failure of one box does not cause failure of another
 - (c) Sharing of cross-strap gates
- k. Circuit Interconnections
1. Signal integrity
 - (a) Termination of high edge-rate signals
 - (b) Drivers and receivers for off-board signals
 2. Noise considerations
 - (a) Off-board connections of edge-sensitive inputs

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- (b) Edge rates of harness signals
 - (c) Harness noise threat model
 - (d) Noise susceptibility analysis of input circuitry
- l. Bypass Capacitance Analysis
- 1. On-board bulk and bypass capacitance
 - (a) Power supply line inductance
 - (b) Circuit operating frequency
 - (c) Component current requirements
 - (d) Vendor recommendations
 - 2. Capacitor frequency response
 - 3. Capacitor placement
- m. Special Pins
- 1. Know what each pin on every device does and make sure it is properly used
 - (a) Mode pin on FPGAs
 - (b) Joint Test Action Group (JTAG) pins
 - 2. No-connect pins
- n. Testability
- a. Design with testing in mind and incorporate the resources needed to facilitate it. Consider observability during implementation and how to debug the circuit while the part is on the (test or flight) board.
- o. Requirements Adequacy
- Have requirements been defined to an adequate level, including both system-level and board-level allocated requirements, as well as internally derived design requirements? Examples include:
- 1. Functions to be implemented.
 - 2. Performance (speed, critical timing, throughput).
 - 3. Interface description (signal levels, timing, software, data formats).
 - 4. Environmental constraints (thermal, radiation level at part, mission duration).

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5. Testability requirements (Joint Test Action Group (JTAG)), board scan, software, observable internal points).
6. Responses to off-nominal inputs and conditions, including handling of detected errors.

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APPENDIX C. DESIGNER'S CHECKLIST OF BEST PRACTICES

The following recommendations are provided to assist designers in following sound development practices.

Developing HDL Designs

- a. Follow Guidelines, checklists, Style Guides, and Coding Standards.
- b. Document your code properly. Inline documentation helps both the original designer at a later date and future engineering personnel who may assume responsibility for the design.
- c. Document the purpose of each procedure or function.
- d. Use inline comments to explain why and how any tricks to achieve the design are necessary.
- e. Consider the electrical implications of the code. A CLD design is a hardware implementation, not software. Some of the points below require action at the board level, outside the part. Communicate issues with the board designer:
 1. Reset Practices
 - (a) Typically asynchronously applied and synchronously removed
 2. Timing Practices
 - (a) Synchronous design
 - (b) Asynchronous inputs
 - (c) Signals which cross different clock boundaries
 3. Logic Practices
 4. Error Handling
 - (a) Design for return to safe state if the unexpected occurs in inputs
 - (b) Consider Error-handling in every circuit ... "what happens if..." and design the circuit to get to a safe state and continue.
 5. Power Related
 - (a) Proper power supply decoupling.
 - (b) Power supply sequencing.
 - (c) Distribute simultaneously switching output pins around periphery to avoid overloading supplies and causing ground-bounce.

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6. Interfacing

- (a) Verify correct I/O levels are being used. Choose best I/O drivers.
 - (i) Use the slowest edge rates possible given the design constraints.
 - (ii) Handle power-up/power-down where I/O may not be valid, to prevent an invalid state.
 - (iii) Don't allow bus contention.
 - (iv) Don't allow tri-state buses to float in the center region.
 - (v) Input slew rate specification must be met.
 - (vi) Perform signal integrity analysis of all the interfaces to determine the need for external impedance matching termination.
 - (vii) De-bounce and de-glitch interfaces from mechanical devices. Use minimum bandwidth necessary to observe the signal.

7. Testability

- (a) Plan your design with testing in mind and incorporate the resources needed to facilitate it. Consider observability as you implement your design. Think about how you will debug the circuit while the part is on the breadboard, engineering development, and flight boards.
- (b) Reserve test pins as test-only pins. Buffer the signals provided to the test pins from the internal circuitry.

Develop Test Code –The following guidelines should be observed:

- a. Follow the test sequence identified in the test procedure. Refer to the assigned test number for each test.
- b. Use self-checking and self-documenting test-benches.
- c. Analyze code coverage of simulation and test vectors.
- d. Automate tests using scripts for repeatability and unattended runs.

Simulate Functional code using test-benches

- a. Review tests.
- b. Review waveforms for sanity check.
- c. Capture I/O to other chips and systems
- d. Share with interfacing design engineers.
- e. Take the time to discuss results at this point; it can save lots of hassles later.

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- f. Chase down all warnings and errors reported by simulator.
 1. Understand why they are there.
 2. Document any decision to ignore them.

External components interfacing to the CLD need to be modeled correctly, and to an appropriate fidelity, in order to achieve meaningful simulation results.

Synthesize the design

- a. Use equivalent to flight part from the beginning.
- b. Set timing constraints in synthesis using constraint files.
- c. Use loading for each pin by reviewing schematics and specs for each interfacing part.
- d. Set critical paths if pushing part speed in any particular path.
- e. Begins familiarity with critical paths.
- f. Using constraint files assists with self-documenting design.
- g. Review output files and logs for synthesis.
- h. Understand all warnings, and if you decide to ignore any, document the reason why.
- i. Search through the netlist for issues. For example, search for flip-flops with both asynchronous preset and clear. These should not be used, and point to interpretation issues in the code. Search for latches; may be unintended result of coding style.

Transfer netlist to vendor-specific place & route tool

- a. Set timing constraints. Document and archive constraints files for reproducibility and review.
- b. Double-check false paths and multi-clock paths.
- c. Set proper flight part
 1. Package
 2. Temperature range (MIL range suggested to ensure sufficient timing margin)
 3. Voltages (Core, I/O)
 4. Radiation level
- d. Fix pin locations
- e. Run Place and Route.
- f. Export Min-Typ-Max Standard Delay Format (SDF) files for simulation
 1. Min/Max delays will be contained within this file, ranging from the best case to the worst case.

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Post-Route Verification

- a. Review all logs from vendor tools for errors, warnings, and notes.
- b. Review timing report to verify that the longest routes make sense.
- c. Timing Analysis
 1. Use the vendor's Static Timing Analysis (STA) Tool
 2. Include delays to/from pads on board
 3. Consider clock source and delays
 4. Include loading on outputs
 5. Get min/max data for any device interfacing with CLD
 6. Enter all constraints into the STA tool
- d. Back-Annotated Simulations
- e. Re-run simulations that were run on Register Transfer Language
- f. Run at least these two conditions:
 1. Best Case beginning of life (BOL) simulation: (Max Voltage, Min Temp), Zero Radiation, Highest Speed.
 2. Worst Case BOL simulation: (Min Voltage, Max Temp), Zero Radiation.
- g. Read every warning and error the tools generate. If you decide to ignore a warning, document the reason.
- h. Verify that timing and functionality are both met.

Test Plan

- a. Simulation environment testing
- b. Breadboard testing
 1. Flight Software. Typically tests only normal modes, positive testing
 2. Special Test Code. Plan early for in-situ debugging using special software
- c. Engineering Unit testing
 1. Temperature testing
 2. Verification Suite and Flight Software
- d. Flight Unit testing
 1. Plan for observability of functions while in a chamber

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Test Procedure

- a. Functional and Timing Tests
 1. Detailed instructions on how to test each function in the FPGA.
 2. How to test the mitigation or error correction techniques.
 3. Link the tests to each item in the specification (which follows requirements).
 4. Positive and Negative tests. Make sure it works how it is intended and reacts safely to unintended inputs.
 5. Number the tests in the document. These numbers are referred to in the test bench code.

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APPENDIX D. RECOMMENDATIONS FOR CONDUCTING CLD PEER REVIEWS

Peer reviews are used within all engineering disciplines, but are of particular importance to CLD designs. Typically the peer review is the most important review of the design process. The goal for the peer review is for the design engineer to demonstrate to the review panel that the design meets all its requirements has been designed properly, and all analyses and simulations have been performed to verify the design in the intended application, over the temperature range and for the life of the mission. See also NASA-HDBK-4008, Appendix B “Sample Peer Review Checklists” for additional considerations and a sample peer review checklist.

The review panel should include at least:

- a. One CLD designer from outside the project, to serve as the chairperson for the review team, with experience using the same part type.
- b. One CLD designer from the project, preferably one who designs a chip interfacing with the one being reviewed.
- c. Include representatives of the software designer, for any hardware that has a software interface.
- d. Process or Quality Assurance.
- e. Other reviewers as needed, as described below.
 1. All owners of requirements that are flowed down (review the CLD requirements).
 2. The board-level designer and box lead (review all interfaces).
 3. Software engineers must review the functional interfaces and test requirements.
 4. Printed Wiring Board (PWB) designers (review requirements relevant to layout).
 5. Thermal engineers (to be advised as to expected power dissipation).

The peer review of a CLD design is normally conducted in several stages. The following list provides a guideline for the topics that should be addresses as part of the peer review process, as well as a recommendation for how the process can be implemented:

- a. Initial Meeting
 1. Requirements Review

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2. Design Overview – Include context drawings or schematics
3. Interface Descriptions. Discuss timing/ functionality of external interfaces
4. Design (HDL) Structure – include block diagrams
5. Design (HDL) Walkthrough – Discuss:
 - (a) Reset handling
 - (b) How illegal states are handled
 - (c) Use of global vs. routed clock signals
 - (d) Clock boundary signal resynchronization
6. Implementation discussion:
 - (a) Pinouts
 - (b) I/O Selection
 - (c) External clocks (draw clock tree for each oscillator)
 - (d) Clocking(rates, routing resources, distribution)
 - (e) Reset (source, location, duration)
 - (f) Combinatorial and sequential modules utilization percentages
7. Test Plan – Walk through test procedure document and test sequence flowchart.
8. Present results:
 - (a) Simulation results
 - (b) Timing Analysis. Show how margins are met (20% margin)
 - (c) Interface Analysis (drive strengths, I/O levels, power supply levels, sampling of input signals, no bus left floating)
 - (d) Board Implementation (power supply decoupling, signal integrity analysis, routing)
9. Hand off CD with design package to the peer review team:
 - (a) Code
 - (b) Test Code
 - (c) Documents – board-level review charts
 - (d) List of design tools and version numbers
 - (e) Constraint files
 - (f) Vendor tool output files
 - (g) Manufacturers datasheets
 - (h) Anything else needed to understand and test the design

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b. Independent Analysis

Individual reviewers independently review design aspects assigned to them by the chairman of the peer review team. The purpose of this step is to accomplish:

1. Review of the schematics and code
2. Review board implementation, including results of signal integrity analysis
3. Verify critical interfaces and implementation details
4. As needed, run simulations of critical sections of the design
5. Develop questions and comments and communicate them to the other review team members for their consideration. The communication at this point can be via email or alternate agreed-upon method.
6. Each reviewer submits to the chairman his assessment of the review using the CLD Review Checklist Form provided in Appendix D
7. The chairperson ensures that all reviewers are satisfied that the flight implementation meets requirements.

c. Final Peer Review Meeting

At this meeting, held between the design team and the peer review panel members, the review chairperson communicates the following:

1. A summary of the issues that arose during review process and their resolutions
2. The results of the peer review
3. Any formally documented actions generated during the review
4. Proposed plan for the resolution of open actions

d. End of Peer Review

Once all open issues are resolved, the chairperson provides:

1. A memorandum indicating that the design has been successfully reviewed and is acceptable for flight
2. A signed copy of the CLD Review Checklist Form provided in Appendix D

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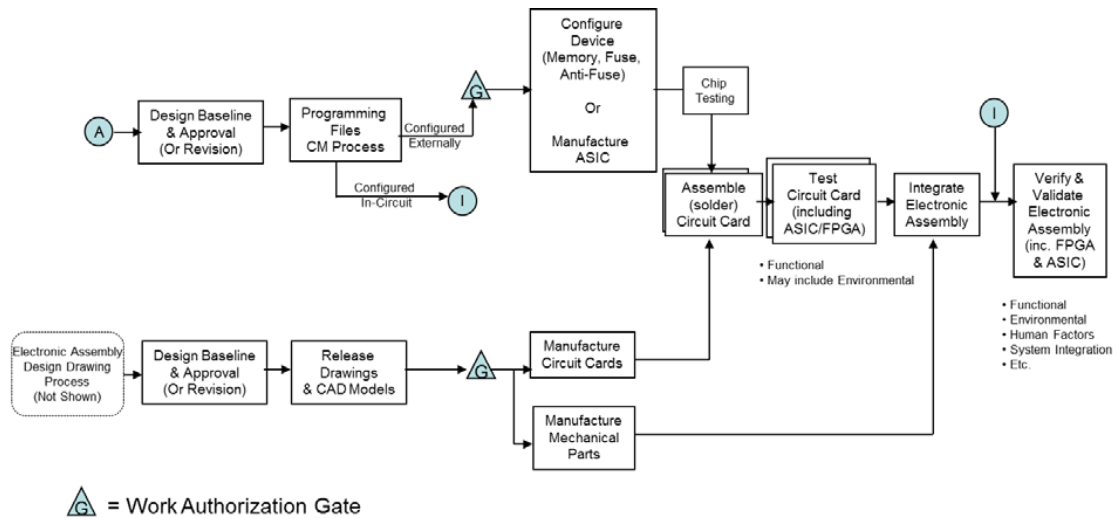
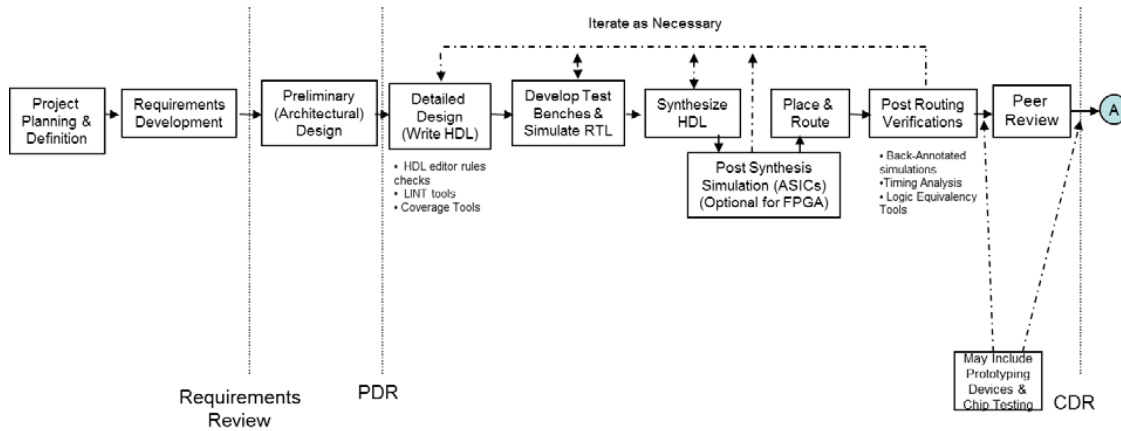
e. Presentation of Peer Review Results at formal Project Reviews

While each individual CLD design is typically not covered at project-level formal reviews, these reviews should present the results of the peer review process to so that questions can be answered regarding:

1. Demonstrate margins and how they are calculated
2. Results of Peer Review issue resolution
3. Any outstanding actions
4. Peer Review Checklist certifying successful completion

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APPENDIX E. NOTIONAL CLD LIFECYCLE



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The work authorization gates shown represent decision points between the design phase and the beginning of hardware implementation. Traditionally, proceeding to hardware implementation, except for development units, is constrained to follow CDR, unless the Acquiring Organization grants permission. The Acquiring Organization may choose to place requirements on the criteria for these gates, relative to Developer design milestones and element or project level design reviews.

Guidelines to entry and exit criteria for these phases may be found in ECSS-Q-60-02A, "Space product Assurance ASIC and FPGA development."

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APPENDIX F. SUGGESTED CLD DOCUMENTATION

Reference is made to ECSS-Q-60-02A, Space Product Assurance ASIC and FPGA Development, for recommendations about the content and preparation of documentation associated with CLD developments.

The following notes apply to lines as noted:

- a. May be combined into other project documentation.
- b. V&V of the device may be treated as part of the PWB or assembly in which it functions.
- c. Required for stand-alone developments deliverable to an organizationally separate customer; as part of the overall project planning for FPGA/ASIC designs conducted by the same responsible organization performing PWB (or higher) design activities.
- d. Results to be summarized at formal customer design review.
- e. If performed.
- f. Required if chips are delivered directly to a customer, unless all characteristics are included in the release report.

Where required by the customer:

- D = Document or Drawing: Either electronic or both electronic and hardcopy
- E = Electronic: Format of files and media must be mutually agreed upon
- F = Final
- P = Preliminary
- U = Update
- UDF = Unit Development Folder
- X = Required

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Documentation	Document Type	Definition Phase	Requirements Phase	Preliminary Design	Detailed Design	Implementation	V&V	Manufacturing & Production	Fielding	Maintenance
CLD Development Plan	DRD/STD-CDDP	X		U	U					
Feasibility and risk analysis(d) (e)	UDF	<input type="checkbox"/> X	<input type="checkbox"/>							
CLD Standards, Tailoring, & Risk Report	Acquirer	<input type="checkbox"/> X	<input type="checkbox"/>							
CM Plans (a)	Formal	P	F							
CLD Quality Assurance Plan (a)	Formal	P	F							
CLD Requirements Specification(s)	Formal		X	U						
Acquirer Acceptance Criteria	Acquirer	X	U							
CLD Part Selection & Criticality List	Deliverable	P	U	F						
CLD Hazard Reports (a)	Deliverable		P	U	F					
HDL Design Guidelines	UDF		P	F						
Preliminary Design Report (<i>Architecture definition report, Feasibility & Risk Analysis; Architecture Initial Validation and Optimization report</i>) (d)	UDF			X						
Design database containing: Preliminary Design Files (e.g. HDL); Simulation Models and Initial Simulation Results	UDF or DRD/STD-PDDD			X	U	U	U			

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Margins/TPM Reports (a) (d)	UDF			X	X	X	X	X	X	X
CLD Verification & Validation Plan (a) (b)	Formal			P	F		U			
Component data sheet (f)	Deliverable			P	U	U	F			
Detailed Design Report (<i>Design entry report; Netlist generation report</i>) (d)	UDF				X					U
Updated design database containing: Design Files; Post-layout netlist; static timing analysis; Corresponding parasitic information; Test vectors for production; scripts for automated design functions; error logs from CAD and analysis tools	UDF or DRD/STD-PDDD				X	U	U			U
Test Plans (a)	Formal				P	F				
Layout Reports (<i>layout generation report; layout results</i>) (d)	UDF					X				
Detailed Component Specification (procurement or fabrication)	Formal					P	F			
Model Verification & Validation Report (a) (d)	Formal					X				

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Documentation	Document Type	Definition Phase	Requirements Phase	Preliminary Design	Detailed Design	Implementation	V&V	Manufacturing & Production	Fielding	Maintenance
CLD Design Characteristics Description	Formal				X	U				
Test Procedures	Formal						X			
CLD Verification & Validation Reports (a)	Deliverable						X			
Radiation test report (e)	Formal						X			
Experience summary report	UDF						X	U	U	
Altered Item Drawings	Formal							X		
Production test results and reports (ASICs only) or burn-in, etc. including characterization, qualification, and screening results (e)	Formal							X		
As-Built Documentation (a)	Deliverable							X	U	U
Application note (a) (f)	Deliverable							X		U
Maintenance Manuals & Associated Documentation (a)	Deliverable								X	U
Minutes of Design Review (System Requirements Review (SRR), Preliminary Design Review (PDR), Critical Design Review (CDR), Peer Reviews, etc.)	UDF	X	X	X	X	X	X	X	X	X
Discrepancy/Problem Tracking Reports (d)	Formal	X	X	X	X	X	X	X	X	X

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APPENDIX G. COMPLIANCE MATRIX

Requirement	Developer Responsibility	Acquirer Responsibility	Criticality Applicability	RCLD-1	RCLD-2	RCLD-3	RCLD-4	RCLD-5	RCLD-6	RCLD-7	RCLD-8	RCLD-9	Notes
CLD-001		X	All	X	X	X	X	X	X	X	X	X	Acquiring Organization Responsibilities
CLD-002			All	X		X	X	X			X	X	MSFC Engineering Directorate Responsibilities
CLD-003			All	X	X	X	X	X			X	X	MSFC SMA Responsibilities
CLD-004	X		All	X	X	X	X	X	X	X	X	X	Developer Responsibilities
CLD-005		X	All							X	X		CLD Development Budget Tracking
CLD-006	X	C/A	All		X						X	X	Criticality Determination
CLD-007	X		All		X						X	X	Criticality Update
CLD-008	X		All	X		X	X		X			X	V&V of Models and Simulations
CLD-009	X		All	X		X	X	X		X			Define Use of Peer Reviews
CLD-010	X		All	X		X	X	X		X			Minimum Usage of Peer Reviews
CLD-011	X		All		X				X	X			CM for CLDs
CLD-012	X		All		X				X	X			CM Planning
CLD-013		X	All						X			X	Configuration Management (CM) Control of delivered products
CLD-014	X		All	X		X	X	X		X			Identify Inconsistencies (Requirements & Design products)

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Requirement	Developer Responsibility	Acquirer Responsibility	Criticality Applicability	RCLD-1	RCLD-2	RCLD-3	RCLD-4	RCLD-5	RCLD-6	RCLD-7	RCLD-8	RCLD-9	Notes
CLD-015		X	All			X	X	X		X	X		Ensure corrective actions taken
CLD-016	X		All				X	X			X	X	CLD design review
CLD-017		X	All	X	X	X	X	X	X	X	X	X	Acquisition Planning
CLD-018		X	All		X	-		-	X	X		X	Document CLD Acceptance Criteria
CLD-019	X	C/A	All		X					X	X	X	Development Plan
CLD-020	X		All							X	X		Define Unique Lifecycle
CLD-021	n/a	n/a	n/a										Deleted
CLD-022	X		All		X					X	X	X	Document Deliverables
CLD-023	X		All							X	X	X	Define Organizational Approach
CLD-024	X		All					X	X	X	X	X	Define Margins
CLD-025	X		All					X		X	X		Phase Margins
CLD-026	X		All					X	X		X	X	Define TPMs
CLD-027	X		All	X	X	X	X	-		X			Requirements Validation
CLD-028	X	A/C	All	-	X	-	-			X	X		Verification and Validation (V&V) Planning
CLD-029	X		Critical	X		X	X	X					Independent V&V Personnel Approach
CLD-030	X		Critical	X	X	X	X					X	CLD Design Description
CLD-031		X	All	X	X	X	X			X	X	X	Acquiring Organization independent Verification
CLD-032	X		All						X				Provide Operations & Maintenance Support Until Retirement
CLD-033	X		All						X				Deliver End Products and Documentation to Acquiring Org or Designee
CLD-034	X		All						X				Maintenance

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CLD-035	X		All	X	X	X	X					X	Bidirectional Traceability of Requirements
CLD-036	X		All								X	X	Traceability Reports Available Electronically
CLD-037	X		Safety Critical	X	X	X	X		X	X	X		Requirements Specification for CLDs
CLD-038	X		All		X						X	X	CLD Usage List
CLD-039	X		All		X			X			X		Parts Selection
CLD-040	X		All	X		X	X	X					Bounded Nondevelopment Items
CLD-041	X		All	X		X	X	X	X				Criteria for usage of heritage or non-developmental product
CLD-042	X		Critical								X	X	Notating critical design elements
CLD-043	X		Safety Critical	X	X		X	X					Mixed-Classification Platforms
CLD-044	X		All								X	X	Diagram Semantics
CLD-045	X		All							X	X		HDL Design Standards
CLD-046	X		All	X		X	X		X			X	Secure Design Practices
CLD-047	X		All							X			Version Control
CLD-048	X		All	X	X	X	X	X					Design Analysis Tool Selection
CLD-049	X		All	X	X		X	X		X			Post-Route Verification Assurance
CLD-050	X		All	X	X	X	X					X	Perform Planned V&V
CLD-051	X		All		X						X		Track V&V Activities
CLD-052	X		Safety Critical	X	X	X	X			X			Safety-Critical V&V In Actual Hardware

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CLD-053	X		All	X	X	X	X	X					Post Route Timing Analysis
CLD-054	X		Critical	X	X	X	X	X					Code Coverage
CLD-055	X		All	X		X	X				X		Test Plans and Procedures
CLD-056	X		All	X		X	X	X					Test Execution
CLD-057	X		All		X						X		Defect Reporting
CLD-058	X		Safety Critical	X		X	X	X			X		Defect Elimination
CLD-059	X		All				X		X	X			Altered Item Drawings
CLD-060	X		All				X						Configuration of Delivered Devices
CLD-061	X		All		X				X		X		CLD Configuration Reflected In As-Built Documentation
CLD-062	X		All	X	X						X	X	Safety and Hazard Controls
CLD-063	X	X	All	X	X	X	X			X	X		NASA IV&V
CLD-064	X		All								X	X	Safety Criticality Determination
CLD-065	X		Safety Critical	X	X	X	X					X	Safety Critical Function Specifications
CLD-066		X	Safety Critical	X		X	X					X	Safety Verification
CLD-067	X		Safety Critical	X		X	X			X		X	Safety Impact Evaluation
CLD-068	X	X	Safety Critical	X	X	X	X					X	Computing System Boundary
CLD-069		X	Safety Critical							X	X		Trend Analysis
CLD-070	X		All	X	X	X	X			X	X		Establish Quality Assurance Processes and guidelines
CLD-071		X	All		X					X		X	Supplier Performance Assessment
CLD-072	X		All								X	X	NASA Performance Insight

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Requirement	Developer Responsibility	Acquirer Responsibility	Criticality Applicability	RCLD-1	RCLD-2	RCLD-3	RCLD-4	RCLD-5	RCLD-6	RCLD-7	RCLD-8	RCLD-9	Notes
CLD-072	X	X	All	X		X	X						Design Requirements Evaluation
CLD-101	X		All									X	Training and Experience
CLD-102	X		All									X	Assess Development Risk Against This Standard
CLD-103	X		All	X		X	X	X					Include Board-Level Electrical Considerations
CLD-104	X		All	X			X						Regression Testing

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