GODDARD TECHNICAL STANDARD	GSFC-STD-1000G
Goddard Space Flight Center Greenbelt, MD 20771	Approved: 6/30/2016 Revalidation Date: 6/30/2021 Superseding GSFC-STD-1000F

Goddard Space Flight Center

Rules for the Design, Development, Verification, and Operation of Flight Systems

Requests for information, corrections, or additions to this standard should be submitted via "Feedback" in the GSFC Technical Standards System at http://standards.gsfc.nasa.gov.

Goddard Space Flight Center

Rules for the Design, Development, and Operation of Flight Systems

GSFC-STD-1000
Revision G

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INTRODUCTION

Purpose:
The Goddard Open Learning Design (GOLD) Rules specify sound engineering principles and practices, which have evolved in the Goddard community over its long and successful flight history. They are intended to describe foundational principles that "work," without being overly prescriptive of an implementation "philosophy." The GOLD Rules are a select list of requirements, which warrant special attention due either to their historical significance, or their new and rapidly evolving nature.

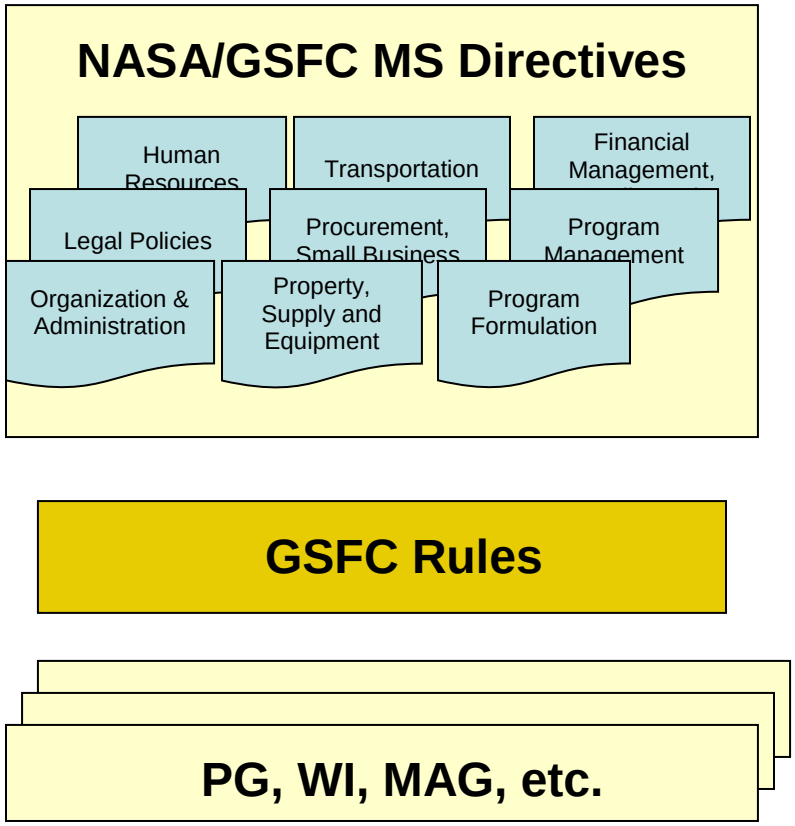
The formalization of key requirements helps establish the methodology necessary to consistently and efficiently achieve safety and mission success for all space flight products. The GOLD Rules share valuable experiences, and communicate expectations to developers. Where appropriate, the rules identify typical activities across lifecycle phases with corresponding evaluation criteria. The GOLD Rules also provide a framework for the many responsible Goddard institutions to assess and communicate progress in the project's execution. The GOLD Rules ensure that GSFC Senior Management will not be surprised by late notification of noncompliance to sound and proven engineering principles that have made GSFC missions consistently successful. Each GOLD Rule specifies requirements in the form of a Rule Statement, along with supporting rationale, and guidance in the form of typical lifecycle phase activities and verifications.

Scope:
The GOLD Rules focus on fundamental principles and practices, and therefore are intended to apply to all space flight projects (and where applicable, associated ground projects) regardless of implementation approach or mission classification (except where explicitly noted). Whenever necessary, rules clarify requirements and expectations consistent with different mission classifications. Although not required, an a priori Mission Exceptions List (MEL) may be proposed at the start of a Program and/or Project, to highlight rules which may not apply to that mission. If a MEL is submitted and approved, waivers will not be required for exceptions covered by the MEL unless changes occur to the underlying basis for exception. For rules that include multiple elements (e.g., "test as you fly"), waivers and exceptions are valid for the specific elements indicated in a MEL or waiver and do not constitute a global approval to waive all elements of that rule. Other exceptions that arise during execution of the mission still require waivers, as appropriate. A MEL approved at the program level for multi project programs will be reviewed at key points in the program lifecycle (e.g. at the release of a new Announcement of Opportunity) to validate its applicability for new Projects within that program.

The GOLD Rules is a living document, periodically assessed and updated to improve its clarity of purpose and effectiveness. While the engineering principles and practices are stable, the select set of requirements may evolve based on whether they continue to warrant increased visibility by their inclusion. The intent is to improve the GOLD Rules over time, not to grow it in size, complexity, and coverage so that it becomes more cumbersome and less helpful over time. Requirements temporarily included because of their new and rapidly evolving nature, must be accompanied by transition plan out of GOLD rules and into an appropriate lower level document.

GSFC Rules are governed by **GPR 8070.4**, configuration-controlled and accessible to all GSFC employees. A technical authority designated for each rule will be responsible for requirements validation, rationale verifications, related guidance and lessons learned, and participation in the evaluation of proposed changes and waivers. The process for submitting waivers is described in GPR 8070.4. Note, for any rule listing multiple owners, the project should work any waiver requests with the owner designated as "primary" and it will be the responsibility of the "primary owner" to get concurrence from the other owners.

NASA/GSFC Processes and Rules Hierarchy



NPDs, NPRs, GPDs, GPRs
Provide policy direction and High-level requirements
Owner: Center Director via Management System Council

Rules for the Design, Development, Verification and Operation of Flight Systems applicable to all GSFC Projects
Owner for Content: AETD
Owner for Configuration Management: SMA-D
Owner for Implementation: FPD

Procedures and Guidelines, applicable to specific line Organizations and engineering disciplines
Owner: Directorates

Figure 1

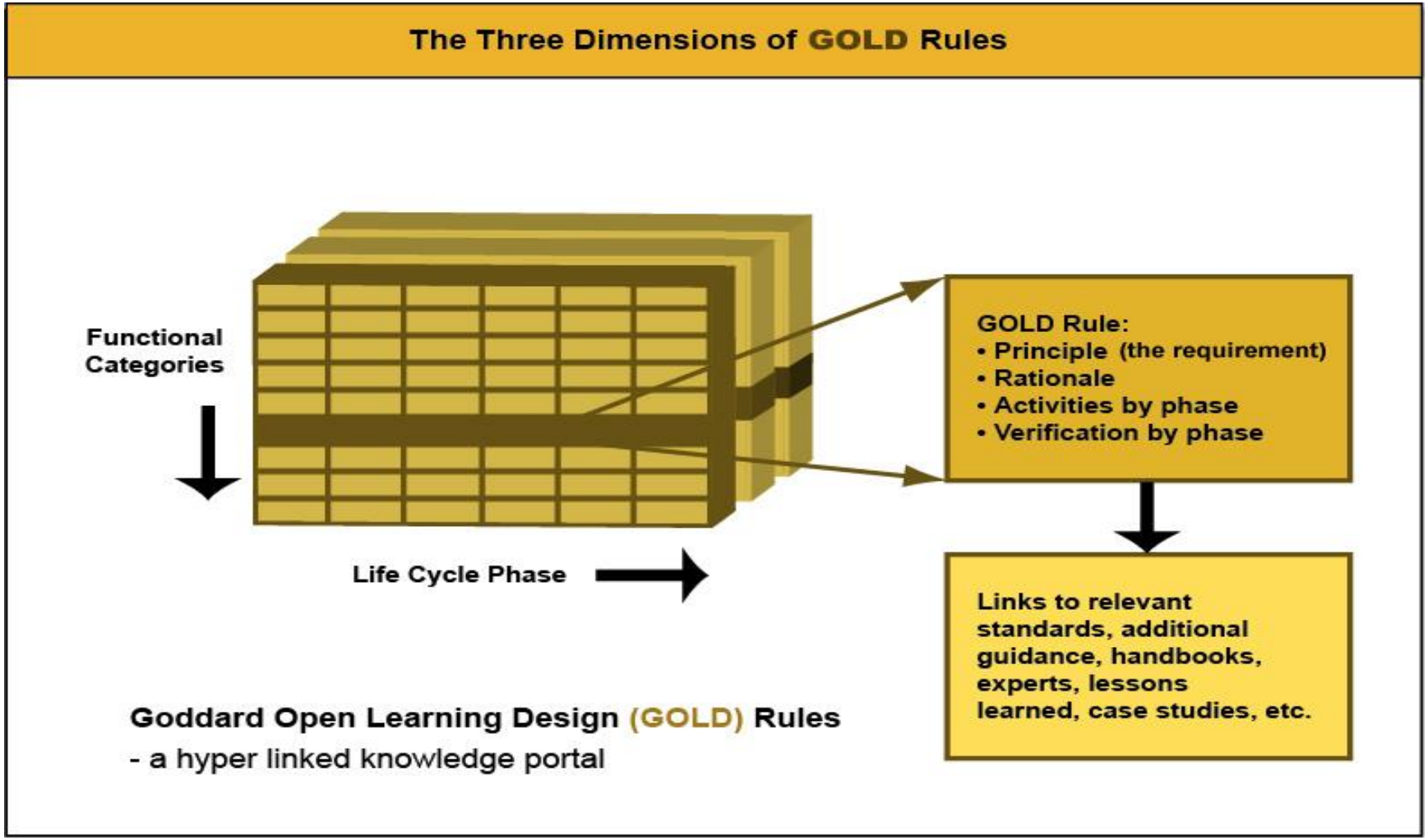
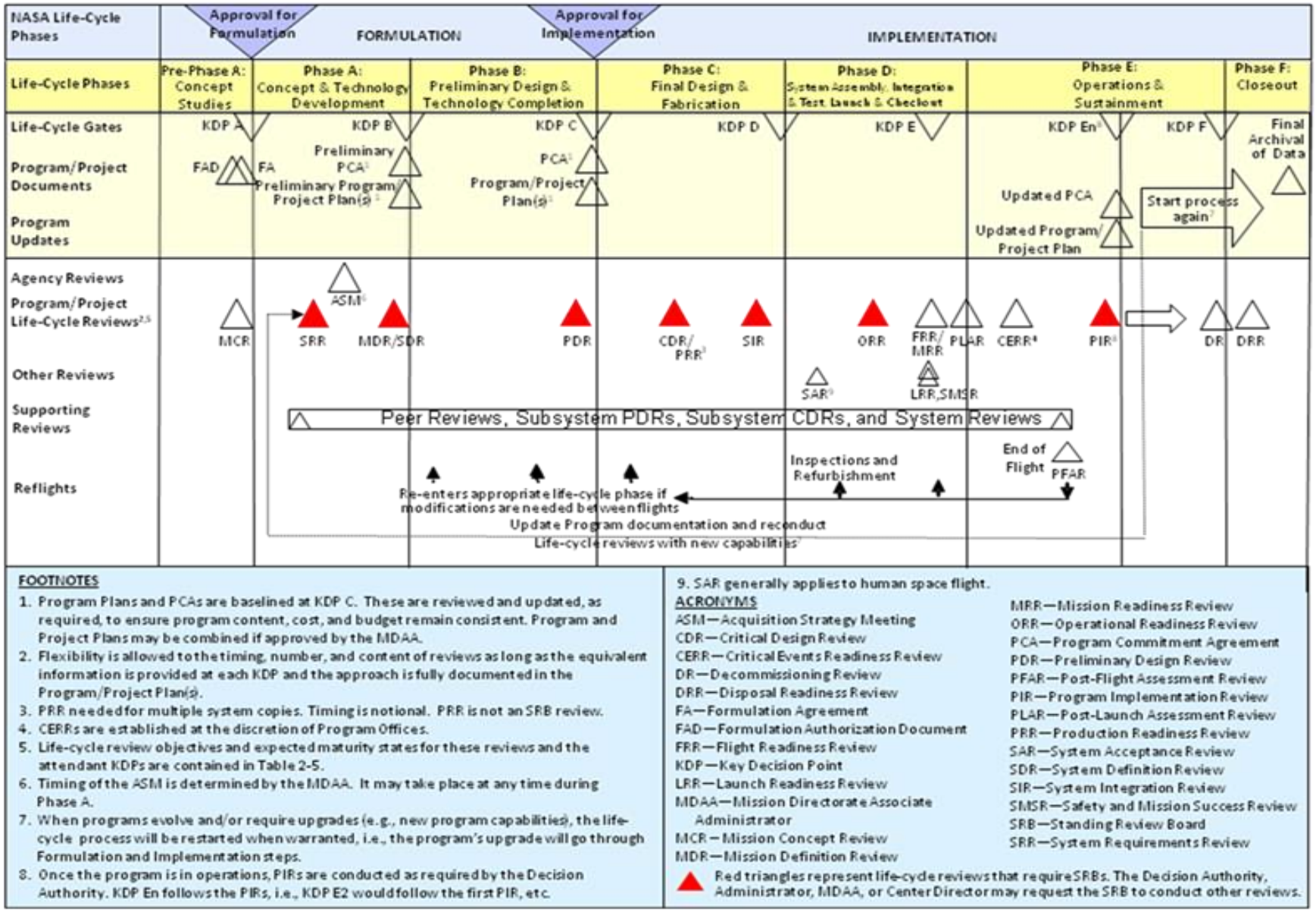


Figure 2



FOOTNOTES

1. Program Plans and PCAs are baselined at KDP C. These are reviewed and updated, as required, to ensure program content, cost, and budget remain consistent. Program and Project Plans may be combined if approved by the MDAA.
2. Flexibility is allowed to the timing, number, and content of reviews as long as the equivalent information is provided at each KDP and the approach is fully documented in the Program/Project Plan(s).
3. PRR needed for multiple system copies. Timing is notional. PRR is not an SRB review.
4. CERRs are established at the discretion of Program Offices.
5. Life-cycle review objectives and expected maturity states for these reviews and the attendant KDPs are contained in Table 2-5.
6. Timing of the ASM is determined by the MDAA. It may take place at any time during Phase A.
7. When programs evolve and/or require upgrades (e.g., new program capabilities), the life-cycle process will be restarted when warranted, i.e., the program's upgrade will go through Formulation and Implementation steps.
8. Once the program is in operations, PIRs are conducted as required by the Decision Authority. KDP En follows the PIRs, i.e., KDP E2 would follow the first PIR, etc.
9. SAR generally applies to human space flight.

ACRONYMS

ASM—Acquisition Strategy Meeting
CDR—Critical Design Review
CERR—Critical Events Readiness Review
DR—Decommissioning Review
DRR—Disposal Readiness Review
FA—Formulation Agreement
FAD—Formulation Authorization Document
FRR—Flight Readiness Review
KDP—Key Decision Point
LRR—Launch Readiness Review
MDAA—Mission Directorate Associate Administrator
MCR—Mission Concept Review
MDR—Mission Definition Review
MRR—Mission Readiness Review
ORR—Operational Readiness Review
PCA—Program Commitment Agreement
PDR—Preliminary Design Review
PFAR—Post-Flight Assessment Review
PIR—Program Implementation Review
PLAR—Post-Launch Assessment Review
PRR—Production Readiness Review
SAR—System Acceptance Review
SDR—System Definition Review
SIR—System Integration Review
SMSR—Safety and Mission Success Review
SRB—Standing Review Board
SRR—System Requirements Review

Red triangles represent life-cycle reviews that require SRBs. The Decision Authority, Administrator, MDAA, or Center Director may request the SRB to conduct other reviews.

Figure 3 (Reference: NPR 7120.5, The NASA Project Lifecycle)

User's Guide

<table>
<tr><td>Rule #</td><td colspan="5">Title</td><td colspan="2">Discipline</td></tr>
<tr><td>Rule</td><td colspan="7">Rule Statement – The requirement.</td></tr>
<tr><td>Rationale:</td><td colspan="7">Statement(s) providing justification, clarification and/or context.</td></tr>
<tr><td>Phase:</td><td><A</td><td>A</td><td>B</td><td>C</td><td>D</td><td>E</td><td>F</td></tr>
<tr><td>Activities:</td><td></td><td colspan="5">Rule-associated best practices, within each phase, to ensure compliance (guidance only)</td><td></td></tr>
<tr><td>Verification:</td><td></td><td colspan="5">Rule-associated best practices, within each phase, to ensure compliance (guidance only)</td><td></td></tr>
<tr><td colspan="2">Revision Status:
When implemented/modified</td><td colspan="4">Owner:
Subject Matter Expert / Technical Authority</td><td colspan="2">Reference:
Supporting Materials</td></tr>
</table>

Figure 4

1.05	Single Point Failures				Systems Engineering		
Rule:	Single point failures that prevent the ability to fully meet Mission success requirements shall be identified, and the risk associated with each shall be characterized, managed, and tracked and the system trades necessary to determine the need and effectiveness of mitigation efforts (e.g., redundancy, selection of robust parts, etc.) commensurate with mission class shall be conducted and documented. NOTE: Does not apply to missions explicitly architected as single-string.						
Rationale:	Robust design approaches make the elimination of single point failures desirable. From a risk management perspective, it is recognized that the acceptance of some single point failures may be prudent. In these cases, it is essential to understand the attendant risks and ensure that they are communicated to senior management.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify all requirements necessary for minimum Mission success. 2. Determine if a breach of any of these requirements will cause the minimum mission to fail.	1. Identify failures that would cause the minimum mission to fail and develop a design strategy to avoid single point failures.	1. Identify failures for all hardware and software that performs mission-critical functions. 2. Develop a design to avoid single point failures.	1. Design mission-critical elements to avoid single point failures. 2. Identify and communicate single point failures to stakeholders and review panels 3. Characterize the risk likelihood and consequences of any single point failures 4. Identify mitigation strategies for the single point failures identified	1. Communicate single point failures to stakeholders and review panels. 2. Provide mitigation status of any identified single point failures	N/A	N/A
Verification:	1. Verify or present management exceptions at MCR.	1. Verify or present management exceptions at MDR.	1. Verify or present management exceptions at PDR.	1. Verify or present management exceptions at CDR.	1. Verify or present management exceptions at PER and PSR.	N/A	N/A
Revision Status: Rev. E, Updated Rev G		**Owner:** Mission Engineering and Systems Analysis Division (590)			**Reference:**		

1.06	**Resource Margins**				**Systems Engineering**		
Rule:	Total (contingency plus reserve) resource margins shall be met in accordance with Table 1.06-1. The allocation of system margin between contingency and reserve shall be at the discretion of the project.						
Rationale:	Compliance with these margins improves performance on cost and schedule as well as overall mission performance. NOTE: Flight software margin guidelines are covered in Rule 3.07.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify resource margins. 2. Identify the percent of resource that was determined by estimation, calculation or measurement.	1. Update resource margins. 2. Identify the percent of resource that was determined by estimation, calculation or measurement.	1. Update resource margins. 2. Identify the percent of resource that was determined by estimation, calculation or measurement.	1. Update resource margins. 2. Identify the percent of resource that was determined by estimation, calculation or measurement.	1. Update resource margins.	N/A	N/A
Verification:	1. Verify at MCR.	1. Verify at ICR and MDR.	1. Verify at PDR and confirmation review.	1. Verify at CDR.	1. Verify at PER and PSR.	N/A	N/A
Revision Status: Baseline; Updated: Rev G		**Owner:** Mission Engineering and Systems Analysis Division (590)				**Reference:** AIAA Guidelines	

Table 1.06-1 Technical Resource Margins
All values are assumed to be at the end of the phase

Resource	Pre-Phase A	Phase A	Phase B	Phase C	Phase D	Phase E
Mass (dry)****	≥25%	≥20%	≥15%	≥10%	0	
Mass (wet)	< LV Capability	< LV Capability	< LV Capability	< LV Capability	< LV Capability	
Power (wrt EOL capacity)	≥25%	≥20%	≥15%	≥10%	≥5% *	
Propellant	3σ***				3σ	
Telemetry and Command hardware channels**	≥25%	≥20%	≥15%	≥10%	0	
RF Link NEN*****/SN	>3dB/>0dB	>3dB/>0dB	>3dB/>0dB	>0dB/>0dB	>0dB/>0dB	
Margin (in percent) = (Available Resource-Estimated Value of Resource)/Available Resource X 100						

*At launch there shall be 5% predicted power margin for mission critical, cruise and safing operating modes as well as to accommodate in-flight operational uncertainties.
** Telemetry and command hardware channels read data from hardware such as thermistors, heaters, switches, motors, etc.
*** The 3 sigma variation is due to the following: 1. Worst-case spacecraft mass properties 2. 3-sigma low launch vehicle performance 3. 3-sigma low propulsion subsystem performance (thruster performance/alignment, propellant residuals) 4. 3-sigma flight dynamics errors and constraints 5. Thruster failure (applies only to single-fault-tolerant systems)
**** Estimated value of resource includes contingency/reserve to cover mass uncertainty of immature items (e.g. low TRL).
***** Users of non-NEN ground stations should use the NEN guidelines listed here; assumes EOL properties

1.07	End-to-End GN&C Phasing				Systems Engineering		
Rule:	All GN&C sensors and actuators shall undergo end-to-end (i.e., from sensor stimulus to actuator response) phasing/polarity testing after spacecraft integration in the final flight configuration (hardware and software), and shall have flight software mitigations to efficiently correct phasing/polarity errors. The test methodology and results shall be independently reviewed.						
Rationale:	Inadequate verification of signal phasing or polarity can result in unexpected on-orbit performance and possible loss of mission. Component-level and end-to-end phasing tests and flight software mitigations can ensure correct operation.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Define interface requirements of sensors and actuators. 2. Design flight software to include capability to fix polarity problems via table upload.	1. Update ICDs to include polarity definition. 2. Review vendor unit-level phasing test plans. 3. Write flight S/W to include capability to fix polarity problems via table upload. 4. Create unit-level & end-to-end phasing test plan.	1. Perform unit-level phasing tests. 2. Test flight S/W for table upload functionality. 3. Perform end to-end phasing test for all sensor-to-actuator combinations. 4. Develop & test contingency flight ops procedures for fixing phasing problems. 5. Conduct an independent review of the methodology and results	N/A	N/A
Verification:	N/A	N/A	1. Verify through peer review and at PDR.	1. Verify through peer review and at CDR.	1. Verify phasing methodology/results at PSR and FSW/Ops mitigations at ORR.	N/A	N/A
Revision Status: Rev. E, Updated Rev G			**Owner:** Guidance, Navigation, and Control Systems Engineering Branch (591)			**Reference:** ACS Handbook sec. 7.3.3.1	

1.08	System End-to-End Testing				Systems Engineering		
Rule:	System end-to-end testing shall be performed in the final flight configuration, hardware and software. End-to-end testing shall be from instrument(s) sensor input, through the spacecraft, to a command and telemetry ground system.						
Rationale:	End-to-end testing is the best verification of the system's functionality..						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify end-to-end tests that represent system-level functions.	1. Review and update the list of end-to-end tests and analyses identified in Pre-phase A. 2. Define success criteria for verification and incorporate into verification plan. 3. Review and update verification plan and schedule. 4. Identify facilities required for end-to-end testing.	1. Review and update list of end-to end tests and analyses identified in Phase A. 2. Review and update verification plan and schedule. 3. Identify test plans and facilities that need to be in place for end-to-end testing.	1. Draft final verification plan. 2. Sign off on plan, put under CM test schedule. 3. Identify and schedule sequence of analyses and testing for verifying end-to-end flight performance. 4. Quantify the fidelity of each verification step.	1. Perform end-to-end testing per the plan developed in Phase C.	N/A	N/A
Verification:	1. Verify all elements of the operating observatory and ground system at MCR.	1. Verify at MDR.	1. Verify at SDR or SRR, PDR.	1. Verify at CDR.	1. Verify at PSR and LRR.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. F, Updated Rev G	Mission Systems Engineering Branch (599)	GEVS 2.8

1.09	Test as You Fly				Systems Engineering		
Rule:	All GSFC missions shall follow a, "Test as You Fly (TAYF) - Fly as You Test" approach, throughout all applicable life cycle phases. Each deviation to this approach, along with the rationale for the deviation, shall be documented and a waiver submitted. Note: A waiver or exception to this rule will be based only on the specific elements that appear and are approved in the request and is not a global approval to waive TAYF for all elements.						
Rationale:	Testing of all critical mission-operation elements as they will be flown greatly reduces the risk of encountering negative impacts upon Mission success, from partial to full loss of mission capability.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:		1. Develop the preliminary test plan employing a TAYF philosophy.	1. Develop final test plan, employing a TAYF philosophy. 2. Develop a preliminary list of TAYF exceptions and discuss with rule owners.	1. Develop test procedures employing a TAYF philosophy.	1. Perform testing per plan / procedures.	N/A	N/A
Verification:		1. Verify at MDR.	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. F, Updated Rev G			**Owner:** Mission Engineering and System Analysis Division (590, Primary) and Instrument Systems and Technology Division (550)			**Reference:**	

1.11	Qualification of Heritage Flight Hardware				Systems Engineering		
Rule:	All heritage flight hardware shall be fully qualified and verified for use in its new application. This qualification shall take into consideration necessary design modifications, changes to expected environments, and differences in operational use.						
Rationale:	All hardware, whether heritage or not, must be qualified for its expected environment and operational uses.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify/list heritage hardware to be used and make a cursory assessment of "use as is" or delta-qual. 2.Determine life expectancy of the residual spare flight hardware to be used from previous flight projects including implications of obsolete parts.	1. Update hardware list and identify the qualification requirements. 2. Assess through the peer review process the ultimate applicability of previously flown/heritage hardware designs.	1. Refine/finalize heritage hardware list and the required qualification requirements.	1. Qualify heritage hardware as part of overall qualification of mission hardware.	1. Develop, test, and integrate the flight articles.	N/A	N/A
Verification:	1. Review summary documentation at MCR.	1. Review summary documentation at MDR.	1. Review summary documentation at PDR.	1. Review summary documentation at CDR.	1. Review summary documentation at PER and PSR.	N/A	N/A
Revision Status: Rev. F, Updated Rev G			**Owner:** Mission Systems Engineering Branch (599)			**Reference:**	

1.14	Mission Critical Telemetry and Command Capability					Systems Engineering	
Rule:	Continuous telemetry coverage shall be maintained during all mission-critical events. Mission-critical events shall be defined to include separation from the launch vehicle; power-up of major components or subsystems; deployment of mechanisms and/or mission-critical appendages; initial thruster firings and all planned propulsive maneuvers required to establish mission orbit and/or achieve safe attitude. Following launch vehicle separation, critical deployments, and initial orbit attitude acquisition, continuous command coverage shall be maintained during all subsequent mission-critical events.						
Rationale:	With continuous telemetry and command capability, operators can prevent anomalous events from propagating to mission loss. Also, flight data will be available for anomaly investigations.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify and document potential mission-critical events in concept of operations. 2. Identify and document in concept of operations all potential needs for communications coverage, such as TDRSS or backup ground stations.	1. Update concept of operations. 2. Identify requirements for critical event coverage in ground system design.	1. Address and document coverage of mission critical events in draft of Mission Operations Concept. 2. Address critical event coverage in requirements for ground system design.	1. In Operation Plan, identify telemetry and command coverage for all mission-critical events.	1. Update Operations Plan. 2. Address telemetry and command coverage of critical events in Operations Procedures.	1. Perform critical events with telemetry and command capability.	N/A
Verification:	1. Verify or present exceptions at MCR.	1. Verify or present exceptions at MDR.	1. Verify or present exceptions at PDR.	1. Verify or present exceptions at CDR.	1. Verify or present exceptions at ORR.	1. Verify telemetry capability for events not excepted in Phase D during mission operations.	N/A
Revision Status: Rev. F, Updated Rev G		**Owner:** Mission Systems Engineering Branch (599)				**Reference:**	

1.17	Safe Hold Mode				Systems Engineering		
Rule:	All spacecraft shall have a power-positive, thermally safe, control mode (Safe Hold) to be entered in spacecraft emergencies. Safe Hold Mode shall have the following characteristics: (1) its safety shall not be compromised by the same credible fault that led to Safe Hold activation; (2) it shall be as simple as practical, employing the minimum hardware set required to maintain a safe attitude; and (3) it shall require minimal ground intervention for safe operation.						
Rationale:	Safe Hold Mode should behave very predictably while minimizing its demands on the rest of the spacecraft. This facilitates the survival, diagnosis, and recovery of the larger system. Complexity typically reduces the robustness of Safe Hold, since it increases the risk of failure due to existing spacecraft faults or unpredictable controller behavior.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Ensure that requirements document and operations concept include Safe Hold Mode.	1. Ensure that requirements document and operations concept include Safe Hold Mode.	1. Identify hardware & software configuration for Safe Hold Mode. 2. In preliminary assessment, demonstrate that no single credible fault can both trigger Safe Hold entry and cause Safe Hold failure. 3. Analyze performance of preliminary Safe Hold algorithms.	1. Establish detailed Safe Hold design including entry/exit criteria and FDAC requirements for flight software. 2. In final assessment, demonstrate that no single credible fault can both trigger Safe Hold entry and cause Safe Hold failure. 3. Analyze performance of Safe Hold algorithms. 4. Via a rigorous risk assessment, decide whether or not to test Safe Hold on-orbit.	1. Implement Safe Hold Mode. 2. Verify proper mode transitions, redundancy, and phasing in ground testing. 3. Execute recovery procedures during mission simulations. 4. Perform on-orbit testing if applicable.	N/A	N/A
Verification:	1. Verify through peer review and at MCR.	1. Verify through peer review and at MDR.	1. Verify through peer review and at PDR.	1. Verify through peer review and at CDR.	1. Verify at PER and FOR.	N/A	N/A
Revision Status: Rev. G		**Owner:** Attitude Control Systems Engineering Branch (591)			**Reference:**		

1.19	Initial Thruster Firing Limitations				Systems Engineering		
Rule:	If alternate actuators (e.g. reaction wheels) are present, the momentum induced by initial thruster firings shall be within the alternate actuators' capability to execute safe recovery of the spacecraft.						
Rationale:	Polarity issues and thruster underperformance typically occur early in the mission. Both conditions can result in a spacecraft emergency due to excessive spacecraft spin rates.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. The Attitude Control System (ACS) Concept shall ensure that thrusters will not be required during launch vehicle separation for a 3-sigma distribution of cases. The concept for operations shall ensure that, except in case of emergency, all thrusters can be test-fired on-orbit prior to the first delta-v maneuver.	1. The Attitude Control System shall design the thruster electronics, size and place the thrusters, and size other actuators (e.g. reaction wheels) such that a failed thruster can be shut down and the momentum absorbed before power or thermal constraints are violated. The activities specified in Pre-Phase A shall be maintained.	1. Hardware (processors, power interfaces, data interfaces, etc.) and software shall ensure that anomalous thruster firings will be shut down quickly enough to allow recovery of the spacecraft to a power-safe and thermal-safe condition. 2. Develop design and operations concept consistent with the activities established in Pre-Phase-A.	1. Establish detailed recovery procedures. Finalize design and operations concept consistent with the activities established in Pre-Phase-A.	1. Test failed thruster conditions with the greatest possible fidelity. Verify transitions and polarity. 2. Ensure that recovery procedures have been simulated with the flight operations team. 3. During on-orbit testing, thrusters shall be test fired to verify polarity and performance prior to being used in a closed loop control.	1. Ground contact shall be maintained during thruster firings.	1. Maintain activity per Phase E. 2. Document any lessons learned.
Verification:	1. GN&C and system engineering organizations shall verify at MCR.	1. GN&C and system engineering organizations shall verify at MDR.	1. GN&C and system engineering organizations shall verify at PDR.	1. GN&C and system engineering organizations shall verify at CDR.	1. GN&C and system engineering organizations shall verify at SAR. 2. Follow-up at Operational Readiness Review (ORR).	1. Document lessons learned.	1. GN&C and system engineering organizations shall verify at DR. 2. GN&C and system engineering organizations document lessons learned.
Revision Status: Rev. F, Updated Rev G		**Owner:** Attitude Control Systems Engineering Branch (591)				**Reference:**	

1.20	**Wetted Joints of Hazardous Propellants**				**Systems Engineering**		
Rule:	All joints in the propellant lines between the propellant supply tank and the first isolation valve shall be NDE-verified welds.						
Rationale:	Failure of wetted joint poses a catastrophic threat to personnel and/or facility.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Confirm system requirements for welded tubing joints between the propellant supply tank and the first isolation valve.	1. Present weld & technician certification plans and NDE plans.	1. Certify integrity of welds by NDE.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G			**Owner:** Propulsion Branch (597)			**Reference:**	

1.21	Overpressurization Protection in Liquid Propulsion Systems				Systems Engineering		
Rule:	The propulsion system design and operations shall preclude damage due to pressure surges ("water hammer"). (Note: See also rule 1.28 "Unintended Propellant Vapor Ignition.")						
Rationale:	Pressure surges could result in damage to components or manifolds, leading to failure of the propulsion system, damage to facilities, and/or safety risk to personnel.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Perform pressure surge analysis, based on worst-case operating conditions, to determine maximum surge pressure. 2. If maximum surge pressure is greater than system proof pressure, incorporate design features to reduce surge pressure below proof pressure.	1. Demonstrate by test that maximum surge pressure is less than proof pressure of the affected components and tubing manifolds. 2. Demonstrate by test that surge-suppression features (if applicable) do not lead to violation of flow-rate/pressure drop requirements. 3. Demonstrate by analysis that flight SW and/or on-orbit procedures will prevent operation of propulsion system beyond conditions assumed in pressure surge analyses and tests.	N/A	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	N/A	N/A	N/A
Revision Status: Rev. E		**Owner:** Propulsion Branch (597)			**Reference:**		

1.22	Purging of Residual Test Fluids				Systems Engineering		
Rule:	Propulsion system design and the assembly & test plans shall preclude entrapment of test fluids that are reactive with wetted material or propellant.						
Rationale:	Residual test fluids can be reactive with the propellant or corrosive to materials in the system leading to critical or catastrophic failure.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. If test fluids are used in the assembled system, present plans for purging & drying of system.	1. Demonstrate that the method for drying the wetted system has been validated by test on an equivalent or similar system.	1. Verify dryness of wetted system by test.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PSR.	N/A	N/A
Revision Status: Rev. E			**Owner:** Propulsion Branch (597)			**Reference:**	

1.23	Spacecraft “OFF” Command				Systems Engineering		
Rule:	No single command shall result in Spacecraft "OFF." This includes both the single string spacecraft case and the redundant spacecraft with one side failed case.						
Rationale:	Requiring multiple actions to power off the spacecraft will mitigate the possibility of an unintentional spacecraft power off.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Complete applicability assessment.	1. Reassess and update applicability. 2. Complete initial compliance assessment, based upon applicability.	1. Reassess compliance. 2. Ensure flow-down traceability to appropriate sub-system in draft technical requirements and Design-To specifications. 3. Define verification approach.	1. Reassess compliance. 2. Ensure flow-down traceability to appropriate sub-system in technical requirements and Design-To specification baselines. 3. Update verification approach.	1. Reassess compliance. 2. Perform verification activity.	N/A	N/A
Verification:	Verify at MCR.	Verify at SRR, MDR..	Verify at PDR.	Verify at CDR and SIR.	Verify at ORR, SMSR, and FRR.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G		**Owner:** Mission Systems Engineering Branch (599)			**Reference:**		

1.24	**Propulsion System Safety Electrical Disconnect**				**Systems Engineering**		
Rule:	An electrical disconnect "plug" and/or set of restrictive commands shall be provided to preclude inadvertent operation of propulsion system components.						
Rationale:	Unplanned operation of propulsion system components (e.g. 'dry' cycling of valve; heating of catalyst bed in air; firing of thrusters after loading propellant) can result in injury to personnel or damage to components.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Present design and/or operational plan that preclude unplanned operation of propulsion system components.	1. Present detailed design of electrical disconnect and/or set of restrictive commands to preclude unplanned operation of propulsion system components. 2. Present detailed plan for verification of operation after installation for flight (for electrical disconnect plugs). See rule 2.25, Electrical Interface Verification.	1. Demonstrate the effectiveness of the disconnect and/or set of restrictive commands by test.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G			**Owner:** Propulsion Branch (597)			**Reference:**	

1.25	**Redundant Systems**				**Systems Engineering**		
Rule:	When redundant systems or functions are implemented, the redundant components, or functional command paths, shall be independent, such that the failure of one component or command path does not affect the other component or command path. Critical single point failures due to electrical, thermal, mechanical and functional dependencies should be documented. The design shall avoid routing of redundant power/signals through a single connector, relay, integrated circuit or other common interface.						
Rationale:	For redundancy to have its desired effects to enhance system reliability, care must be taken to maintain independence between the redundant and primary systems.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Complete applicability assessment.	1. Reassess and update applicability. 2. Complete initial compliance assessment, based upon applicability.	1. Reassess compliance. 2. Ensure flow-down traceability to appropriate sub-system in draft technical requirements and Design-To specifications. 3. Define verification approach.	1. Reassess compliance. 2. Ensure flow-down traceability to appropriate sub-system in technical requirements and Design-To specification baselines. 3. Update verification approach.	1. Reassess compliance. 2. Perform verification activity.	N/A	N/A
Verification:	1. Verify at MCR.	1. Verify at SRR, MDR, and PNAR.	1. Verify at PDR and NAR.	1. Verify at CDR and SIR.	1. Verify at ORR, SMSR, and FRR.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G		**Owner:** Mission Systems Engineering Branch (599)			**Reference:**		

1.26	**Safety Inhibits & Fault Tolerance**				**Systems Engineering**		
Rule:	The external leakage of hazardous propellant is a Catastrophic Hazard, and requires three independent inhibits to prevent it. Dynamic seals (e.g. solenoid valves) shall be independently verified as close to propellant loading as possible. Static seals (i.e. crush gaskets, o-rings, etc.) are recognized as non-verifiable at the system level. The integrity of these seals shall be controlled by process or procedures consistent with industry standards. Secondary/tertiary seals and materials internal to the device that would be exposed in the event the primary seal fails shall be compatible with the working fluid. Components where fault tolerance is not credible or practical (e.g., tanks, lines, etc.) shall use design for minimum risk instead.						
Rationale:	Adequate control of safety hazards is necessary in order to develop safe hardware and operations. Verification of independence of inhibits is necessary to preclude propagation of failure in safety inhibits that can result in critical or catastrophic threats to personnel or facility. The internal volume between redundant inhibits (seals) shall be limited to the minimal practical volume and designed to limit the external leakage in the event of failures.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Identify proposed design inhibits that preclude hazardous condition and document in preliminary hazard analysis. 2. Present compliance with range safety requirements, including fault tolerance to hazardous events. Document in subsystem design and initial MSPSP.	1. Demonstrate by analysis or component test that A) failure in selected inhibit will not cause failure of the other inhibits, or B) that no single event or software command can open multiple inhibits. 2. Provide implementation details of the fault tolerance requirements of propulsion system. Document in subsystem design and Intermediate MSPSP.	1. Demonstrate by analysis or component test that A) failure in selected inhibit will not cause failure of the other inhibits, or B) that no single event or software command can open multiple inhibits. 2. Provide hazard control verification details addressing fault tolerance of propulsion system. Document in subsystem design and Final MSPSP.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR and in Preliminary MSPSP/Safety Data Package.	1. Verify at CDR and in Intermediate MSPSP/Safety Data Package.	1. Verify in Final MSPSP Safety Data Package.	N/A	N/A
Revision Status: Rev. F, updated Rev G			**Owner:** System Safety Branch (321) & Propulsion Branch (597)			**Reference:**	

1.27	**Propulsion System Overtemp Fuse**				**Systems Engineering**		
Rule:	Flight fuses (or other over-current protection devices) for wetted propulsion system components shall be selected such that overheating of propellant will not occur at the maximum current limit rating of the flight fuse. (Note: See also rule 2.06 "System Fusing Architecture.")						
Rationale:	Propulsion components such as pressure transducers normally draw very low current, and therefore their fuses are usually oversized. In such cases it may be possible for a malfunctioning component to overheat significantly without exceeding the rating of the fuse. Any wetted component (i.e., in addition to fuses) that could be continuously powered should also be considered. Exceeding the auto-ignition temperature of propellant can result in mission failure or critical/catastrophic hazard to personnel and facility.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Present fusing plan for wetted propulsion system components.	1. Present mitigation plan and/or over-current thermal analysis to show that wetted components will not exceed maximum allowable temperature of propellant at the maximum current limit rating for the flight fuse. 2. Verify that a single failure within the drive electronics of pulsed components will not result in the pulse components being continuously powered.	1. Verify by inspection of QA records that the correct flight fuse has been installed.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER or PSR.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G		**Owner:** Propulsion Branch (597, Primary), Component Hardware Systems Branch (596)			**Reference:** EEE-INST-002		

1.28	Unintended Propellant Vapor Ignition				Systems Engineering		
Rule:	Propulsion system design and operations shall preclude ignition of propellants in the feed system.						
Rationale:	Ignition of propellant vapor can occur due to a variety of conditions including (1) mixing of fuel and oxidizer in pressurant manifolds via diffusion and condensation; (2) pyrotechnic valve initiator products entering propellant manifolds; (3) adiabatic compression of gas due to pressure surges, i.e. "water hammer" effects. These conditions can cause hardware damage and/or mission failure.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Present design analysis, including pyro valve firing sequence and/or propellant line initial pressurization, supporting mitigation of conditions for ignition of propellant vapors. 2. For bipropellant systems, demonstrate by analysis that the design provides adequate margin against diffusion and condensation of propellant vapors in common manifolds.	1. Demonstrate by analysis or test that pyro valve firing sequence and/or propellant line initial pressurization plan will not promote conditions for ignition of propellant vapor. 2. For bipropellant systems, demonstrate by test that selected pressurant system components exhibit vapor diffusion resistance per the Phase B analysis.	N/A	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.		N/A	N/A
Revision Status: Rev. E		**Owner:** Propulsion Branch (597)			**Reference:**		

1.30	**Controller Stability Margins**				**Systems Engineering**		
Rule:	The Attitude Control System (ACS) shall have stability margins of at least 6db for rigid body stability with 30 degrees phase margin. The magnitude of the flexible modes in the open-loop transfer function shall be less than minus 12dB.						
Rationale:	Proper gain and phase margins are required to maintain stability for reasonable unforeseen changes and uncertainty in spacecraft configuration.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify in the Attitude Control System (ACS) Concept if the gain and phase margin requirements will be difficult to meet due to the spacecraft configuration.	1. Update the ACS concept and identify if the gain and phase margin requirements will be difficult to meet due to the spacecraft configuration.	1. Design all control modes so that the rigid body stability margins are at least 6 dB of gain margin and 30 degrees of phase margin. 2. Ensure that the magnitude of the flexible modes in the open-loop transfer function is less than minus 12dB.	1. Stability analyses should include all flexible mode effects, sample data and delay effects (and other nonlinear effects such as fuel slosh) incorporated with adequate evaluation of mode shape, damping and frequency uncertainties.	1. Verify that the stability analyses presented at CDR encompass the "as built" mass properties and flexible body models. 2. Update CDR analyses if necessary to verify that stability margin requirements are met.	N/A	N/A
Verification:	1. GN&C and system engineering organizations verify at MCR.	1. GN&C and system engineering organizations verify at MDR.	1. GN&C and system engineering organizations verify at PDR.	1. GN&C and system engineering organizations verify at CDR.	1. GN&C and system engineering organizations verify at PSR.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G		**Owner:** Attitude Control Systems Engineering Branch (591)				**Reference:** ACS Handbook	

1.31	**Actuator Sizing Margins**					**Systems Engineering**	
Rule:	The Attitude Control System (ACS) actuator sizing shall reflect specified allowances for mass properties growth.						
Rationale:	Knowledge of spacecraft mass and inertia can be very uncertain at early design stages, so actuator sizing should be done with the appropriate amount of margin to ensure a viable design.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. ACS actuators (including propulsion) shall be sized for the current best estimate of spacecraft mass properties with 100% design margin.	1. ACS actuators (including propulsion) shall be sized for the current best estimate of spacecraft mass properties with 50% design margin.	1. ACS actuators (including propulsion) shall be sized for the current best estimate of spacecraft mass properties with 25% design margin.	N/A	N/A	N/A
Verification:	N/A	1. GN&C and system engineering organizations shall verify at MDR.	1. GN&C and system engineering organizations shall verify at PDR.	1. GN&C and system engineering organizations shall verify at CDR.	N/A	N/A	N/A
Revision Status: Rev. F			**Owner:** Attitude Control Systems Engineering Branch (591)			**Reference:** ACS handbook	

1.32	Thruster and Venting Impingement				Systems Engineering		
Rule:	Thruster or external venting plume impingement shall be analyzed and demonstrated to meet mission requirements.						
Rationale:	Impingement is likely to contaminate critical surfaces and degrade material properties and can also create adverse and unpredictable S/C torques and unacceptable localized heating.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Develop analytical mass transport model. 2. Update as design evolves.	1. Refine analysis based on updated designs.	1. Refine analysis based on updated designs. 2. Measure venting rates during T/V tests and verify analysis.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PSR.	N/A	N/A
Revision Status: Rev. F		**Owner:** Mission Engineering and Systems Analysis Division (590)				**Reference:**	

1.33	Polarity Checks of Critical Components				Systems Engineering		
Rule:	All hardware shall be verified by test and inspection for the proper polarity, orientation, and position of all components (sensors, switches, and mechanisms) whose performance is affected by these parameters						
Rationale:	Each spacecraft and instrument contains many components that can be reversed easily during installation. Unless close inspections are performed, and proper installations are verified by test, on-orbit failures can occur when these components are activated.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Identify all polarity-dependent components in the spacecraft design concept. 2. Ensure that design concept provides capability for testing functionality of polarity-dependent components at end-to-end mission system level, in addition to subsystem level.	1. Identify all polarity-dependent components in the spacecraft preliminary design. 2. Ensure that preliminary design provides capability for testing functionality of polarity-dependent components at end-to-end mission system level, in addition to subsystem level. 3. Develop test plan for polarity-dependent components.	1. Identify all polarity-dependent components in the spacecraft detailed design. 2. Ensure that detailed design provides capability for testing functionality of polarity-dependent components at end-to-end mission system level, in addition to subsystem level. 3. Develop test procedures for polarity-dependent components.	1. Execute polarity tests at subsystem and end-to-end mission system levels.	N/A	N/A
Verification:	N/A	1. Verify through peer review and at MDR.	1. Verify through peer review and at PDR.	1. Verify through peer review and at CDR.	1. Verify through peer review, at PER, and at PSR.	N/A	N/A
Revision Status: Rev. E		**Owner:** Mission Systems Engineering Branch (599)				**Reference:**	

1.35	**Maturity of New Technologies**				**Systems Engineering**		
Rule:	All technologies shall achieve a TRL 6 by PDR. Not applicable to technology demonstration opportunities.						
Rationale:	The use of new and unproven technologies requires a thorough qualification program in order to reduce development risk to an acceptable level.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify relevant technologies, readiness levels, develop overall risk mitigation plan (including fall back to existing technologies), and conduct peer review(s).	1. Develop qualification plan for specific technologies, including risk mitigation. Peer review plan.	1. Implement qualification plan and demonstrate that TRL 6 has been achieved. Peer review qualification results.	N/A	N/A	N/A	N/A
Verification:	1. Review summary documentation at MCR.	1. Review summary documentation at MDR.	1. Review summary documentation at PDR.	N/A	N/A	N/A	N/A
Revision Status: Rev. E			**Owner:** Applied Engineering and Technology Directorate (500)			**Reference:**	

1.37	**Stowage Configuration**				**Systems Engineering**		
Rule:	When a spacecraft is in its stowed (launch) configuration, it shall not obscure visibility of any attitude sensors required for acquisition, and shall not block any antenna required for command and telemetry.						
Rationale:	Establishment of spacecraft communications and acquisition of safe attitude are the two highest-priority post-separation activities, and should not be dependent on completion of deployments.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Demonstrate by inspection that mechanical subsystem concept allows for full visibility of sensors and telemetry & command antennas.	1. Demonstrate by field-of-view analysis that mechanical subsystem preliminary design allows for full visibility of sensors and telemetry & command antennas.	1. Demonstrate by field-of-view analysis that mechanical subsystem detailed design allows for full visibility of sensors and telemetry & command antennas.	1. Ensure during I&T that mechanical subsystem detailed design allows for full visibility of sensors and telemetry & command antennas.	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. E			**Owner:** Mission Systems Engineering Branch (599)			**Reference:**	

1.39	**Propellant Sampling in Liquid Propulsion Systems**				**Systems Engineering**		
Rule:	Liquid propellant quality shall be verified by sampling at point of use prior to loading spacecraft propulsion system.						
Rationale:	Contaminated propellant could result in damage to components or manifolds, leading to failure of the propulsion system with a potential impact on mission success. If detected after loading propellant into the flight system, purging and cleansing the propulsion system of contaminants would incur significant cost and result in launch delay.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Ensure propellant sampling is included in project planning.	1. Include propellant sampling requirements in the propulsion system design process including the design of the GSE. 2. Include discussions of propellant sampling requirements in Ground Operations Working Group (GOWG).	1. Incorporate propellant sampling in development of fuel loading procedures. 2. Incorporate propellant sampling considerations into fuel loading equipment selection/design. 3. Include propellant sampling and analysis requirements in GOWG discussions.	1. Analyze samples to demonstrate the propellant meets quality standards 2. Ensure adequate propellant flow through the entire propellant loading system to detect contamination sources within the loading system. 3. Draw samples at "point of use" after the propellant flows through loading equipment and as close as possible to spacecraft. 4. Include propellant sampling and analysis rqts for purity and particulate count in launch processing timelines prior to introduction to on-board flight hardware 5. Wait for acceptable analysis results before loading propellants into the flight system.	N/A	N/A
Verification:	N/A	1. Review summary documentation at MDR.	1. Review summary documentation at peer reviews and PDR.	1. Review summary documentation at peer reviews and CDR.	1. Review summary documentation at PSR.	N/A	N/A
Revision Status: Rev. F		**Owner:** Propulsion Branch (597)				**Reference:**	

1.40	Maintaining Command Authority of a Passive Spacecraft				Systems Engineering		
Rule:	All spacecraft shall be designed to prevent loss of command authority and command integrity.						
Rationale:	Mission control needs to be maintained.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Ensure that vehicle commanding scheme design is robust against failures that will result in loss of control. 2. Ensure that in the case of an encrypted primary command link, there is a backup with adequate command integrity.	1. Incorporate features, commensurate with mission class that facilitates restoration of command link in the case of loss.	1. Test scheme against likely command link loss scenarios.	1. Validate primary and backup command link, as applicable.	N/A	N/A
Verification:	N/A	1. Review summary documentation at MDR.	1. Review summary documentation at peer reviews and PDR.	1. Review summary documentation at peer reviews and CDR.	1. Review summary documentation at PSR.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G		**Owner:** Mission Systems Engineering Branch (599)			**Reference:**		

1.41	GSE Use At Launch Site				Systems Engineering		
Rule:	All testing of flight systems at the launch site shall only use GSE and test configurations that have been previously demonstrated with the flight hardware. Proper operation of the spacecraft with umbilical length equal to or with similar impedance and circuit characteristics to that expected at the launch site shall be demonstrated. Note: Does not apply to launch site resident GSE.						
Rationale:	New test configurations introduce unknown variables that could possibly result in unexpected test results or damage flight hardware						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Develop preliminary list of planned launch site testing and GSE configuration.	1. Refine list of planned launch site testing and GSE configurations.	1. Develop final list of planned launch site test activities and GSE configurations to support those activities. 2. Develop and execute test procedures for the planned launch site test activities using the planned launch site GSE configurations.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. G			**Owner:** Flight Systems I&T Branch (568, Primary),Mission Systems Engineering Branch (599)			**Reference:**	

1.42	**Powering Off RF Command Receiver**				**Systems Engineering**		
Rule:	The spacecraft RF Command Receiver shall not be powered off during nominal flight operations.						
Rationale:	Preserves spacecraft command receipt capability.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. As part of Fault Protection design, develop preliminary scenarios where Fault Protection will be allowed to power off the command receiver.	1. Finalize fault protection scenarios that result in command receiver power off. 2. Make Command Receiver power-off ground command a critical command.	1. Verify Fault Protection Command Receiver power-off scenarios. 2. Develop flight rules and contingency for powering off Command Receiver	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER. MOR	N/A	N/A
Revision Status: Rev. G			**Owner:** Mission Systems Engineering Branch (599, Primary), Flight Microwave and Telecommunication Systems Branch (567)			**Reference:**	

1.43	Flight Software Update Demonstration				Systems Engineering		
Rule:	There shall be a pre-flight, end-to-end demonstration of code change, using the MOC and flight observatory, for any software which can be changed in flight.						
Rationale:	Demonstration of this capability for software not hosted in the spacecraft primary computer is often overlooked prior to launch						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Identify preliminary list of reprogrammable flight processors in the system	1..Finalize list of reprogrammable processors in the flight system 2. Develop preliminary plans for demonstrating the ability to update code on each of the processors identified.	1. Demonstrate capability to update code on each of the flight system processors in the I&T environment. 2. Demonstrate the capability to update code on each of the flight system processors from the Mission Operations Center.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. G			**Owner:** Mission Engineering and System Analysis Division (590)			**Reference:**	

1.44	Early Interface Testing				Systems Engineering		
Rule:	Spacecraft-to-payload electrical interfaces, including protocol and software compatibility, shall be tested with breadboard or engineering unit hardware, as soon as the hardware is available, preferably before the instrument (or component) CDRs.						
Rationale:	On multiple missions, it has been demonstrated that the time and effort to execute early interface tests reduces the overall mission cost and schedule by finding and correcting incompatibilities before they impact system-level I&T. While having well-written ICDs and/or the use of industry-standard interfaces, can minimize interface incompatibilities, there are often nuances that can only be uncovered via test.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Develop preliminary spacecraft-to-payload electrical interfaces 2. Ensure that Statements of Work for development of new or significantly-modified components include provisions for interface tests	1. Develop preliminary spacecraft-to-payload ICDs. 2. Identify early interface test opportunities and configuration (i.e. breadboard versus ETU, etc.)	1. Execute interface testing using the configurations identified.	N/A	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. G			**Owner:** Mission Engineering and System Analysis Division (590, Primary) and Electrical Engineering Division (560)			**Reference:**	

1.45	System Alignments				Systems Engineering		
Rule:	System alignment verifications shall be performed before and after exposure to system environmental testing to demonstrate alignment stability.						
Rationale:	Demonstrates stability of alignments through the environments which gives confidence that alignments will not shift due to launch vibro-acoustic environment or post-launch thermal environment						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Develop preliminary system alignment plan	1. Refine system alignment plan	1. Finalize system alignment plan and identify the points in the system-level test flow where alignments will be performed.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. G	Mission Engineering and System Analysis Division (590)	

1.46	Use of Micro-Switches				Systems Engineering		
Rule:	Micro-switches shall be used for information only and shall not be used to initiate on-board autonomous activity or as an on-board interlock.						
Rationale:	Micro-switches have known reliability issues.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Assess applicability. 2. Complete initial compliance assessment, based upon applicability.	1. Reassess compliance. 2. Ensure flow-down traceability to appropriate sub-system in draft technical requirements and Design-To specifications. 3. Define verification approach.	1. Reassess compliance. 2. Ensure flow-down traceability to appropriate sub-system in technical requirements and Design-To specification baselines. 3. Update verification approach.	1. Reassess compliance. 2. Perform verification activity.	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. G		**Owner:** Mission Engineering and System Analysis Division (590)				**Reference:**	

1.47	**Design Deployables For Test**				**Systems Engineering**		
Rule:	Whenever practical, appendages and other deployables shall be capable of deployment under 1G conditions without the use of g-negation ground support equipment. When it is not practical to design for unassisted 1G deployment, the design shall have provisions for interfacing to gravity off-load GSE.						
Rationale:	Numerous occasions where instrument doors, etc. are not designed for 1G deployment and don't have provisions built in for g-negation.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Identify deployable requirements	1. Preliminary design of deployables 2. Preliminary assessment of 1G deployment capability	1. Final design of deployables. 2. Final assessment of 1G capability. 3. Verify that design includes provisions for 1G off-load where applicable	1. Demonstrate deployments.	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. G			**Owner:** Mission Engineering and System Analysis Division (590)			**Reference:**	

1.48	Space Data Systems Standards				Systems Engineering		
Rule	Space data systems standards (e.g. CCSDS, OMG, commercial) shall be utilized by missions and implemented in all space communication systems.						
Rationale:	Standardization of space data system interfaces, formats, and protocols within the Agency reduces the cost of specification and implementation of data systems. It increases reliability through the use of proven interfaces and heritage software and tested vendor products. Space data systems standards enable easier and lower-cost data interoperability between systems within a local system, across a Center or Agency, and with external partners.						
Phase:	<A	A	B	C	D	E	F
Activities:	Examine all data interfaces and investigate applicable space data systems standards for those interfaces. Consult with the Center CCSDS Standards POC in identifying useful standards, and provide feedback on any gaps or issues in the standards.	Perform trade studies to confirm the feasibility and benefits of the space data systems standards selected in pre-phase A. Incorporate the confirmed space data systems standards into system requirements and present at the SRR. Where CCSDS or OMG standards are planned provide feedback on any gaps or issues in standards to the Center CCSDS Standards POC.	Incorporate selected space data systems standards into the preliminary design and present at the PDR.	Finalize selected space data systems standards in the detailed design.	Implement and test for compliance with selected space data systems standards. Where CCSDS or OMG standards are planned report any issues or limitations with the selected space data systems standards to the Center CCSDS Standards POC.	Where CCSDS or OMG standards are planned report any identified operational issues or limitations with the selected space data systems standards to the Center CCSDS Standards POC.	
Verification:	Verify that the proposal identifies space data systems standards where applicable.	Verify at SSR.	Verify at PDR.	Verify at CDR.	Verify at I&T and system readiness testing.		
Revision Status: Rev G	**Owner:** Applied Engineering and Technology Directorate (Code 500)				**Reference:** www.ccsds.org www.ccsds.org/publications www.omg.org/space/		

Notes: 1) The Center CCSDS Standards Point of Contact (POC) is a recommended resource for learning the current breadth of standards to be considered and the status of CCSDS and OMG standards currently under development. 2) The Consultative Committee for Space Data Standards (CCSDS) publications span a wide range of technical areas which may be of benefit to missions, including both optical and RF communications, uplink and downlink messaging, file transfer protocols, delay-tolerant networking, navigation messages, service-oriented approaches to increase interoperability, data compression and security, and more. The Object Management Group (OMG) is an international, not-for-profit technology standards consortium. The OMG Space Domain Task Force (Space DTF) maintains standards specific to space applications,

including common telemetry and command definition formats, scripting standards, and ground equipment interface definitions. Commercial or general use standards, including internet protocol or mobile device standards may also provide significant benefit to some missions and shall not be precluded.

2.01	Flight Electronic Hardware Operating Time				Electrical		
Rule:	One thousand (1000) hours of operating/power-on time shall be accumulated on all flight electronic hardware (including all redundant hardware) prior to launch The last 350 hours of operating/power-on time shall be failure-free, of which at least 200 hours shall be in vacuum. For Class D and below, only the failure-free and vacuum requirements shall apply.						
Rationale:	Accumulated power-on time that demonstrates trouble-free parts performance helps reduce the risk of failures after launch.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Draft test plan.	1. Approve test plan.	1. Update test plan.	1. Conduct 1000 hours of testing of all flight hardware and spares. The last 350 hours shall be trouble-free. At least 200 shall be in vacuum.	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PSR that testing has been conducted. 2. Verify at PER that the test plan is sufficient for completion of required hours.	N/A	N/A
Revision Status: Rev. F		**Owner:** Applied Engineering and Technology Directorate (500) and Electrical Engineering Division (560, Primary)				**Reference:** GEVS 2.3.4	

2.05	System Grounding Architecture				Electrical		
Rule:	For all missions, a system grounding design shall be developed and documented for flight and GSE test configurations. Except for coaxial interfaces, structure or shields shall not be used for the primary circuit current return path. A dedicated conductor shall be included to provide the current return path with the smallest loop area possible.						
Rationale:	Poor system grounding design will lead to grounding incompatibility between different systems during the integration phase, with potential degradation of end-to-end functional performance.. Failure to consider GSE grounding could result in damage to flight hardware.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify a preliminary grounding concept.	1. Complete a preliminary grounding design and communicate it to all hardware developers.	1. State grounding requirements in all Electrical ICDs for the users.	1. Prepare a detailed System Grounding Document. 2. Implement the design.	1. Oversee implementation of the design. 2. Demonstrate safety, compatibility, and system performance.	N/A	N/A
Verification:	1. Verify at MCR.	1. Verify at MDR.	1. Verify through peer review and at PDR.	1. Verify through peer review and at CDR.	1. Verify through peer review prior to TRR and at PER.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G		**Owner:** Avionics and Electrical Systems Branch (565)			**Reference:**		

2.06	System Fusing Architecture				Electrical		
Rule:	A system fusing architecture shall be developed and documented for all missions, including the payloads. All circuit breakers that can't be reset by command (i.e., fuses) should be easily accessible for replacement and/or for integrity verification at any time prior to launch vehicle integration.						
Rationale:	Lack of a system fusing design may lead to fuse incompatibilities between the power source and the payloads, which could lead to the power source fuse being blown prior to the payloads. The system fusing design should maximize the reliability of the system.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Identify a preliminary system fusing architecture for the mission and communicate with all hardware developers.	1. Develop system fusing requirements for the mission and state requirements in all Electrical ICDs for the users, including transient requirements.	1. Prepare a detailed System Fusing Document.	1. Oversee correct implementation of design by all users.	N/A	N/A
Verification:	N/A	1. Verify through peer review and at MDR.	1. Verify all system fusing requirements (including the payloads) through peer review and at PDR.	1. Verify user implementation at electrical systems peer preview and at CDR.	1. Verify that design verification includes fusing design prior to TRR.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G		**Owner:** Parts, Packaging, and Assembly Technologies Office (562, Primary), Avionics and Electrical Systems Branch (565)				**Reference:** EEE-INST-002	

2.13	Electrical Connector Mating				Electrical		
Rule:	All flight connectors where mating cannot be verified via ground tests, shall be clearly labeled and keyed uniquely, and mating of these connectors shall be verified visually to prevent incorrect mating. The design shall not use connectors that require a blind mating in system-level integration, test and launch operations.						
Rationale:	Error in mating of interchangeable connectors can result in mission degradation or failure.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Identify operations that cannot be tested on the ground.	1. Present plans to prevent error in mating of electrical connectors.	1. Verify by inspection & photo documentation that electrical connectors are mated correctly.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. F, Updated Rev. G	Avionics and Electrical Systems Branch (565)	Electrical Systems Design Guidelines

2.14	**Protection of Avionics Enclosures External Connectors Against ESD**				**Electrical**		
Rule:	All avionics enclosures shall be protected from ESD. All external connectors must be fitted with shorting plugs or appropriate caps during transportation between locations. Additionally, all test points and plugs must be capped or protected from discharge for flight.						
Rationale:	Capping open connectors provides protection from electrostatic discharge resulting from space charging.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Develop electrical systems requirements. 2. Identify the need for capping all open connectors and grounding the caps to chassis.	1. Develop electrical ICD stating requirement for capping open connectors. 2. Develop harness drawings.	1. Verify by inspection of build records (WOAs, traveler, etc.) that provisions for capping open connectors have been completed. 2. Verify final blanket closeout procedure includes check to verify connectors are capped.	N/A	N/A
Verification:	N/A	N/A	1. Verify through peer review and at PDR. 2. Ensure parts and materials list include connector caps.	1. Verify harness drawings include connector caps for any open connectors and their grounding provisions.	1. Inspect during pre-fairing, post fairing installation and final blanket closeouts.	N/A	N/A
Revision Status: Rev. F			**Owner:** Avionics and Electrical Systems Branch (565)		**Reference:** Electrical Systems Design Guidelines		

2.22	Corona Region Testing of High Voltage Equipment				Electrical		
Rule:	Assemblies containing a High Voltage supply that is not tested through the Corona region shall undergo venting / outgassing analysis to determine when it is safe to turn on and operate after launch.						
Rationale:	Each High Voltage supply is different in its design and the voltage where coronal discharge may occur will vary by the construction and materials used. It will also be dependent on how clean the supply is and how well the outgassing products are vented to space.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Complete applicability assessment.	1. Reassess and update applicability. 2. Complete initial compliance assessment, based upon applicability.	1. Reassess compliance. 2. Ensure flow-down traceability to appropriate sub-system in draft technical requirements and Design-To specifications. 3. Define verification approach.	1. Reassess compliance. 2. Ensure flow-down traceability to appropriate sub-system in technical requirements and Design-To specification baselines. 3. Update verification approach.	1. Reassess compliance. 2. Perform verification activity.	N/A	N/A
Verification:	1. Verify at MCR.	1. Verify at SRR, MDR, and PNAR.	1. Verify at PDR and NAR.	1. Verify at CDR and SIR.	1. Verify at ORR, SMSR, and FRR.	N/A	N/A
Revision Status: Rev. F		**Owner:** Power Systems Branch (563, Primary), Instrument Systems and Technology Division (550)				**Reference:**	

2.23	RF Component Testing for Multipaction and Corona				Electrical		
Rule:	Components of RF communications subsystems shall not exhibit Corona or Multipaction. If compliance is satisfied by test, the test shall be done at least 6 dB above the nominal power level. If satisfied by analysis, the analysis shall show at least 10 dB of margin above the nominal power level.						
Rationale:	Unless significant design margin is demonstrated, small unit-to-unit variations make it impossible to predict whether an RF component is susceptible to Multipaction or Corona.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. When formulating cost estimates, include cost of testing and analyses needed to verify that components do not exhibit Multipaction or Corona effects.	1. Plan schedule to include milestones for activities necessary to verify absence of Multipaction and Corona effects.	1. Baseline system design using RF system components that are good candidates (low risk) based on whether they have been designed with sufficient margin to minimize possibility of Multipaction or Corona effects. 2. Analyses (to determine extent of design margin) and testing of RF Flight Components.	1. Complete RF component multipaction / corona analyses and testing prior to I&T. Monitor for Corona and Multipaction during observatory testing in TV.	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify at PDR	1. Verify at CDR.	1. Verify at ORR,	N/A	N/A
Revision Status: Rev. F, Updated Rev. G		**Owner:** Microwave and Communication Systems Branch (567)			**Reference:**		

2.24	Solar Arrays				Electrical		
Rule:	a. Solar arrays shall incorporate solar cells that have been qualified per AIAA-S-111A-2014, "Qualification and Quality Requirements for Space Solar Cells." If a later revision of AIAA-S-111 has been released by the time of contract award for the mission, the later revision shall govern. b. Solar panels shall be qualified to the mission environment via qualification panels per AIAA-S-112A-2013, "Qualification and Quality Requirements for Electrical Components on Space Solar Panels." If a later revision of AIAA-S-112 has been released by the time of contract award for the mission, the later revision shall govern. c. Qualification and flight solar panels shall be tested at ambient temperature and at their highest predicted operating temperature including calibrated I-V curves before and after panel-level environmental testing. d. Flight solar arrays shall be tested at wing level or array level at ambient temperature including calibrated I-V curves after all environmental testing (integrated to the spacecraft or not) is complete. Should the flight solar array be stored for a period of more than two years after the post-environmental array testing is complete, the calibrated I-V curve measurements at ambient temperature shall be repeated prior to launch.						
Rationale:	Space solar arrays must survive severe environments including particulate radiation, UV, and up to tens of thousands of very rapid temperature excursions between cold and hot. Incremental changes to parts and processes can have unexpectedly large consequences. Therefore, it is essential that the solar array for each mission be rigorously qualified and tested for that mission.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Design the array in accordance with mission requirements and established procedures.	1. Design the array in accordance with mission requirements and established procedures.	1. Revise the design of the array in accordance with mission requirements and established procedures.	1. Revise the design of the array in accordance with mission requirements and established procedures. Write an ICD.	1. Simulate the environment as accurately as possible. 2. Test q-panel(s) and flight array under illumination (including calibrated IV curves) at highest predicted operating temperature. 3. Qualify the solar panels to latest revision of AIAA S-112-2005 as tailored for the mission. 4. Fabricate the flight solar array in accordance with approved procedures.	1. Monitor array output on an hourly basis for 48 hours subsequent to launch and on a weekly basis thereafter. 2. Check output versus predictions and reconcile.	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Peer review the array design, applicable ICDs and test program.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G		**Owner:** Mechanical Systems Division (540) and Power Systems Branch (563, Primary)				**Reference:**	

2.25	**Electrical Interface Verification**				**Electrical**		
Rule:	Electrical Interface (i.e., copper-path) Verification Test (IVT) shall be performed on all flight connectors following final flight mating. This may be performed via powered testing and/or physical (e.g., resistance) measurements.						
Rationale:	Final verification of flight interfaces is required to ensure proper electrical integrity and function, thereby minimizing the probability of system failure and maximizing probability of mission success.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:		1. Identify electrical interfaces required for safety or mission success, and define means by which interfaces will be verified. 2. Review/update the identified list of interfaces and tests. 3. Define success criteria for verification and incorporate into verification plan. 4. Review/update verification plan and schedule. 5. Identify facilities and other resources (e.g., GSE) required.	1. Review/update list of interfaces and tests identified in Phase A. 2. Review/update verification plan and schedule. 3. Identify test plans, facilities, and resources that need to be in place for IVT.	1. Draft final verification plan and IVT. 2. Sign off on plan and IVT, and put under CM control.	1. Perform IVT. 2. Assess acceptability of interface verification. 3. Close verification plan and tracking log for interface.	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify at SDR or SRR, PDR.	1. Verify at CDR.	1. Verify at PSR and LRR.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G			**Owner:** Electrical Engineering Division (560, Primary) and Mission Engineering and Systems Analysis Division (590)			**Reference:**	

2.26	**Power-On Reset Visibility**				**Electrical**		
Rule:	A power-on reset occurrence shall be unambiguously identifiable via telemetry. Note: This does not imply real-time telemetry as the reset is occurring.						
Rationale:	An unexpected power-on reset could be an indication of a serious issue and should be able to be distinguished from resets that are indicative of less serious conditions.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Establish requirements (and flow-down) for being able to detect power-on reset occurrences.	1. Establish preliminary design of power-on reset monitoring capability including the routing of that telemetry to the spacecraft telemetry system.	1. Finalize power-on reset telemetry monitoring design.	1. Demonstrate the ability to detect and telemeter power-on reset occurrences.	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. G	Electrical Engineering Division (560, Primary) and Flight Software Systems Branch (582)	

2.27	Spacecraft Strip-Charting Capability				Electrical		
Rule:	A minimal set of hard-line spacecraft parameters, sufficient to establish spacecraft health and safety, shall be monitored and captured (stored), independent of the spacecraft telemetry system, by the EGSE whenever the spacecraft is powered. This data should be sampled at a rate sufficiently high to aid in diagnosis of abnormal power events.						
Rationale:	This capability is necessary to capture data for anomalous behavior on the spacecraft during I&T when spacecraft telemetry is not available.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Develop preliminary list of hard-line parameters required for monitoring. 2. Develop preliminary design of EGSE functions required for monitoring the hard-line parameters.	1. Finalize list of hard-line parameters. 2. Finalize design of EGSE hard-line monitoring functions	1. Employ hard-line functionality at start of system-level I&T	N/A	N/A
Verification:	N/A	1. N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. G			**Owner:** Flight Systems Integration and Test Branch (568, Primary) and Mission Systems Engineering Branch (599)			**Reference:**	

3.01	Verification and Validation Program for Mission Software Systems					Software
Rule:	A thorough verification and validation process shall be applied to all mission software systems. This process shall trace customer/mission operations concepts and science requirements to implementation requirements and system design, and shall include requirements based testing of all mission elements, and end-to-end system operations scenario testing.					
Rationale:	Mission software, especially flight software, must be tested thoroughly to ensure a successful mission/project. The activities described below provide guidance on recommended software verification and validation activities at each lifecycle phase to supplement the requirements found in NPR 7150.2.					
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Develop first version of Operations Concept with customer. 2. Document SW functionality at high level. 3. Document SW verification and validation approach. 4. Document cost estimate for overall SW design.	1. Update Operations Concept. 2. Identify test tools to be used for software testing (i.e., fidelity, quality, etc.). 3. Update verification and validation approach and associated cost and schedule based on updated requirements.	1. Draft Software Test Plan. 2. Draft SW bi-directional traceability matrix showing SW requirements traced to parent requirements and to SW components and tests. 3. Plan SW test environment.	1. Complete Software Test Plan. 2. Identify verification and validation program risks. 3. Update SW bi-directional traceability matrix. 4. Set up FSW test environment. 5. Execute FSW tests.	1. Develop detailed test scenarios/cases. 2. Complete bi-directional traceability of requirements to SW design and SW test program. 3. Set up ground SW test environment. 4. Modify FSW test environment as necessary to increase fidelity. 5. Execute ground SW tests.	1. Develop detailed test scenarios/cases. 2. Complete bi-directional traceability of requirements to SW design and SW test program. 3. Set up ground SW test environment. 4. Modify FSW test environment as necessary to increase fidelity. 5. Execute ground SW tests	N/A
Verification:	1. Verify by inspection through peer reviews and at MCR.	1. Review by analysis the verification and validation approach for the mission through peer review and at MDR.	1. Verify SW development and test program by analysis and through peer review. 2. Verify that budget and schedule accommodate regressions and end-to-end mission testing at SDR and software PDR.	1. Verify by analysis at software CDR.	1. Verify by analysis through peer review and at Test Readiness Review.	1. Verify by analysis through peer review and at Test Readiness Review	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. E, Updated Activities in Rev. G	Software Systems Engineering Branch (581)	NPR 7150.2

3.02	Elimination of Unnecessary and Unreachable Software			Software		
Rule:	An analysis of unnecessary and/or unreachable code, as defined per Table 3.02-1, shall be performed on the intended flight load for launch. The analysis shall identify all instances (areas) of unnecessary/unreachable flight code, the general functionality associated with the code, the reason each is intended to be left within the flight load, and the justification (e.g. mitigating action) that explains why the included code does not provide a risk to the mission. The focus is on technical risk to the long-term mission, not cost.					
Rationale:	There are significant benefits to re-using software from past missions but each mission has different requirements and re-using heritage software often carries forward software not required by the current mission. Unnecessary and unreachable software can also occur within a mission's lifecycle as system and software requirements change during the software development process. Unnecessary and unreachable software is typically not verified or validated as part of the current mission test programs, as a mission is only required to verify its mission requirements. This creates the potential for negative side-effects, costs, and risks during the current mission's on-orbit life. Table 3.02-2 provides sample types of unnecessary or unreachable code.					
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Document that a FSW Reuse Plan and risk assessment of unnecessary and/or unreachable code will be developed.	1. Document the FSW Reuse Approach and the plan for managing unnecessary and/or unreachable code in the FSW Management/Devel-opment Plan(s). 2. Identify and document code capabilities/ requirements that are not required for the current mission but are intended to be included in the FSW product(s). 3. Provide initial risk identification, assessment & anticipated mitigation technique for each known type of unnecessary/ unreachable code. 4. Present analysis at FSW reviews.	1. Analyze the potential risk of leaving the code in the flight product rather than removing it. 2. Remove unnecessary and unreachable software that creates risk. 3. Update software verification plans if justified to reduce risk. 4. Present analysis and risk mitigations at FSW reviews. 5. Update the documentation of unnecessary and unreachable code associated with the intended flight products.	1. Update and analyze the documentation of unnecessary and unreachable code from heritage and newly developed flight products. 2. Remove unnecessary and unreachable software that creates risk. 3. Update software verification plans if justified to reduce risk. 4. Present analysis at FSW reviews.	N/A	N/A
Verification:	N/A	Verify at MDR.	1. Verify at FSW SRR and FSW PDR. 2. Verify at SDR and PDR.	1. Verify at FSW CDR. 2. Verify at CDR.	1. Verify at FSW Acceptance Test Review. 2. Verify at PSR and FRR.	N/A	N/A

Revision Status:	Owner:	Reference:
Rev. E, Updated Rev. G	Software Systems Engineering Branch (581) Flight Software Systems Branch (582, Primary)	

Table 3.02-1 Unnecessary and Unreachable Software Definitions

Term	Definition
Unnecessary Software	Source code that is not linkable to any mission software requirements. Classic examples include: 1) functions in a mathematic library not applicable for the mission; and, 2) source code that interfaces with hardware that is not present in the current mission design.
Unreachable Software	Source code that should never be executed within normal software execution. A classic example would be source code that is guarded by a control statement or statements that should never be true; hence, the software is unreachable.
Note	Well known Commercial Off-the-Shelf (COTS) and Open Source products with flight heritage and unnecessary and unreachable features are to be included in the analysis and will likely not require extensive mitigation actions. Source code is the description of a computer program that is translated into machine code by another program such as an assembler, compiler or interpreter. If the translator creates object code modules, then the modules are combined using a linker program. The end result of the process is a program or library of functions that is executable or a processing unit. Source code includes higher level languages, including visual languages, which are first translated into lower level languages (e.g., C or Assembler) before translation to executable code.

Table 3.02-2 Examples Areas To Consider For Analysis

Examples	Definition
Unused Design Capability	Application Program Interfaces (API) are developed to promote software reuse. For example, an Operating System (OS) API will have interface calls for dealing with semaphores (e.g. *create, give, take*, etc.). If a new mission does not require the use of semaphores, then these OS API functions will never be executed.
Unused Reuse Capabilities	A reused software component/library or set of reused software components/libraries will typically contain capabilities and features not required by a mission.
Debug/Test Features	Debug and test features, which are not a required part of the operational system, are often required to test the software system. For example, debug software is often used in conjunction with testing Error Detecting And Correcting (EDAC) memory. It is extremely difficult to inject correctable and uncorrectable errors into EDAC memory, whereas a test command can easily inject these erroneous conditions to verify that the application software handles and reports the EDAC errors correctly.

3.03	High Fidelity Interface Simulation Capabilities					Software
Rule:	A high fidelity software simulation capability for each external interface to FSW shall be provided in the FSW development/maintenance environments. Both nominal and anomalous data inputs to FSW shall be configurable in real-time using the procedure language of the FSW test workstation.					
Rationale:	When adequate simulation capabilities aren't planned, there may be significant impact to FSW development/maintenance productivity and funds.					
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Describe functional and performance capabilities for each flight processor external interface in technical proposal. 2. Include cost estimate.	1. Update description of required simulation capabilities to reflect any changes in requirements since previous phase. 2. Document acquisition strategy for acquiring simulation capabilities, including responsible organizations.	1. Update requirements to reflect any changes since previous phase. 2. Deliver FSW external interface test tools to FSW team.	1. Maintain FSW external interface test tools.	1.Maintain FSW external interface test tools	N/A
Verification:	N/A	1. Verify by observation at MDR.	1. Verify by observation at SW SRR. 2. Verify flight simulation capability defined to accommodate test of all FSW data I/O, FSW modes, nominal and anomalous conditions, and load/stress tests for each flight CPU. 3. Verify simulator development and FSW schedules are consistent.	1. Verify by observation at software CDR.	1. Verify by observation at MOR.	1. Verify after maintenance or repair activities	N/A
Revision Status: Rev. E		**Owner:** Flight Software Systems Branch (582)				**Reference:**	

3.04	Independent Software Testing					Software	
Rule:	Software functional/requirements and comprehensive performance verification/validation testing shall be performed by qualified testers that are independent of the software designers and developers. NOTE: For small projects, members of the same development team can perform independent testing as long as the assigned testers have not been involved in any part of the design and development of the software components being tested.						
Rationale:	Ideally, an independent team should develop the software test plan and verification/validation test procedures, and execute the tests. Frequently the software development team will be used to perform these functions as a means to reduce cost and schedule. Having authored the code, they already know how it should function and can quickly perform the testing activities. The independent test team approach is non-biased, with an end-user perspective, and specialized test teams frequently have greater expertise on various test tools and technologies; thus, providing a more thorough and comprehensive test program. An independent test team ensures adequate time for testing because there is a clear demarcation between development and testing. However, if utilizing an independent test team is not feasible, at a minimum, the use of independent testers who were not involved with the software design and development process allows alternate interpretations of requirements and multiple approaches to testing.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Project provides WBS for Test Team Lead. Test Team Lead is given signature authority on the Mission Flight Software Require-ments document. 2. Test Team Lead reviews requirements for testability, plus compatibility with the Operations Concept. 3. Software Test Plan is written and approved.	1. Software Test Plan is updated as needed. 2. Requirements to Test Procedures Matrix is drafted.	1. Software Test Team staffed. Ensure members are independent from development team. 2. Continue to update Requirements to Test Procedures Matrix and begin drafting test procedures.	1. Test procedures drafted, reviewed, and executed.	1. Independent verification/validation testing completed.	N/A
Verification:	N/A	Verify at SRR.	Verify at PDR.	Verify at CDR.	Verify at TRR.	N/A	N/A
Revision Status: Rev. E		**Owner:** Software Engineering Division (580)				**Reference:**	

3.05	**Flight / Ground System Test Capabilities**				**Software**		
Rule:	Access to flight system interface and functional capabilities, provided either by the spacecraft or by spacecraft simulators, shall be negotiated with all stakeholders, including the ground system and operations teams. Schedules and agreements should address the spacecraft and spacecraft simulators at all levels of fidelity.						
Rationale:	The ground system must be compatible with the S/C it is being designed to support, and this must be proven prior to launch via tests. Similarly, the operations team must be able to develop and validate a variety of operations products, such as procedures, databases, display pages, and launch scripts. The operations team must also have opportunities to learn about operating the S/C and prove this knowledge has been acquired prior to launch.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Develop plans for providing the flight system interfaces for use by the ground system and flight operations teams.	1. Develop preliminary simulation concepts.	1. Generate preliminary simulator requirements and identify long lead procurement items. 2. Establish preliminary agreements on simulator usage between all stakeholders. 3. Identify critical ground system and operations readiness tests along with estimated durations and equipment dependencies, and incorporate into the mission I&T schedule.	1. Complete simulator requirements, design, and delivery plan/schedules. 2. Refine previously established agreements on simulator and spacecraft access times. 3. Ensure all ground system and operations readiness test details, including test durations and equipment dependencies, are incorporated into the detailed I&T plans and schedules.	1. Provide simulator and S/C hardware access for both ground system verification and validation, and for operations teams to prepare for launch.	N/A	N/A
Verification:	1. Verify at MCR.	1. Verify at MDR.	1. Verify at PDR.	1. Verify at CDR.	1. Verify at MOR.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. E	Software Systems Engineering Branch (581)	

3.06	Dedicated Engineering Test Unit for Flight Software Testing					Software	
Rule:	An ETU flight data system testbed(s) shall be dedicated to FSW teams specifically for FSW development and test. The number of flight data system testbed units shall be sufficient to support the FSW development schedule and the overall mission schedule.						
Rationale:	Early investment in dedicated FSW testbed hardware fidelity saves costs and avoids significant schedule risks to FSW and I&T teams. Anything less than a dedicated ETU will add to mission risk and threaten cost/schedule.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Define high-level ETU requirements for FSW with clear and detailed rationale.	1. Update ETU requirements from Phase A. 2. FSW team ensures that ETU development and delivery schedule is consistent with FSW development team need dates. 3. FSW team develops ETU acceptance criteria for ETU deliveries.	1. Review ETU design. 2. Review ETU delivery schedule.	1. FSW team verifies availability of ETUs to meet FSW development and test schedules. 2. FSW team lead accepts ETU deliveries and verifies functionality.	1. FSW team reviews and provides inputs on ETU maintenance plan.	N/A
Verification:	N/A	1. Verify by observation at MDR that ETU-quality FSW testbeds are clearly represented in the technical proposal, and that costs for dedicated FSW testbed ETUs are included in the electronics cost proposal.	1. Verify by observation at SDR and SW SRR that: a) FSW ETU testbed(s) represent maturing flight architecture; b) minimum 1 testbed with full ETU fidelity is costed and delivery schedule is consistent with FSW needs; and, c) I&T plans minimize sharing ETU, or dedicated ETU is provided.	1. Verify by observation at SW PDR that: a) delivery plans for ETU-quality FSW testbed(s) are consistent with FSW development needs; and, b) I&T plans require minimal use of a shared ETU, or I&T has their own dedicated ETU.	1. Verify by observation at SW CDR that: a) ETU-quality FSW testbed(s) have been delivered to FSW team; and, b) ETU FSW testbed is confirmed to be adequate by FSW staff for on-orbit maintenance and operations support.	1. Verify by observation at FOR that: a) FSW ETU testbeds have been moved to their long-term environment for FSW maintenance & operations support; and, b) system administration, facility, and hardware support are in place.	N/A
Revision Status: Rev. E, Updated Rev. G		**Owner:** Flight Software Systems Branch (582)				**Reference:**	

3.07	Flight Software Margins				Software		
Rule:	Flight software resource margins shall be maintained in accordance with Table 3.07-1 and presented at Key Decision Point (KDP) milestone reviews.						
Rationale:	Early and repeated attention by flight software teams to resource utilization will improve resource margins for future phases of the mission.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Establish clear rationale for FSW resource estimates using the proposed hardware.	1. Update software margins based on updated requirements. 2. Coordinate with S/C and instrument procurement and hardware development teams to ensure margins can be maintained.	1. Design FSW within defined design margins. 2. Continue coordination with S/C and instrument hardware development teams. 3. If margins are below guidelines at PDR, provide rationale as to how mission requirements can still be met and necessary mitigation and/or corrective actions needed.	1. Track development to design margins. If margins are below guidelines at CDR, provide rationale as to how meeting mission requirements are not at risk.	N/A	N/A
Verification:	N/A	1. Verify by observation at MDR.	1. Verify by observation at FSW PDR and Mission PDR.	1. Verify by observation at FSW CDR and Mission CDR.	1. Verify by observation at SIR and ORR.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G			**Owner:** Software Systems Engineering Branch (581, Primary), Flight Software Systems Branch (582)			**Reference:** Table on next page	

Resource Margins for Flight Software Development

The numbers provided in the table below are margins for different mission phases and maturity levels. These do not represent hard limits, but levels where the software development team should start to get concerned. Project waivers are not required unless the resource starvation means the system can't meet one of its performance requirements.

Table 3.07-1. Flight Software Margins

	Mission Phase (with Method)			
	FSW SRR	**FSW PDR**	**FSW CDR**	**Ship/Flight**
Resource	Estimate	Analysis	Analysis/ Measured	Measured
Average CPU Usage	50%	50%	40%	30%
Deadlines	50%	50%	40%	30%
PROM	50%	30%	20%	0%
EEPROM	50%	50%	40%	30%
RAM	50%	50%	40%	30%
PCI Bus	75%	70%	60%	50%
1553 Bus	30%	25%	20%	10%
Spacewire (1355)	30%	25%	20%	10%
UART/Serial I/F	50%	50%	40%	30%

Margin is calculated using the formula: (total allocated resource – used resource)/total allocated resource

Total allocated resource = the total magnitude of the resource that allocated for use by flight software.

Used resource is estimated, analyzed and/or measured.

Note: Selecting which column to use at a particular time is not always obvious. Generally, one should pay more attention to the “Method” row rather than the “Mission Phase” row. For example, if there is a lot of re-use and you have actual measured code sizes for most modules, your PROM could be 80% full at PDR without causing concern. Different resource elements can be at different maturity levels at any given point in a project. The right-most column should only be used when the code is fully integrated and tested. Those are the margins we want to save for in-flight maintenance.

Average CPU Usage: This is the percentage of time the CPU is doing non-background processing work. Background processing may include tasks such as memory scrubbing, memory validation (such as memory checksum), or any process that is interruptible or has very loose timing requirements. This average should be estimated/measured over an interval that exceeds the longest real-time event rate under normal worst-case operating conditions.

Deadlines: This row usually represents the interrupt timing requirements of the system. For example: How quickly does the processor need to re-fill that FIFO after the HW interrupt is asserted? If you have a 50 ms deadline for an ISR and you estimate the processor can meet it in 20ms, your usage (margin) is 40% (60%). All deadlines in the system should be considered, and compared individually to the recommended margin.
Also, consider which deadlines can occur simultaneously to calculate the worst-case timing.

PROM is non-volatile memory that cannot be modified in flight.

EEPROM is non-volatile memory that can be modified in flight.

RAM is volatile memory where the executing code and data are stored. This memory is always on the processor’s local bus. Note: Bulk memory used for storage of housekeeping and science data has been removed from this table. The amount of bulk memory is driven more by mission parameters (data rates, number of ground contacts, etc.) than software design. So, systems engineers should track the bulk memory margin. However, some systems have the “bulk” memory on the processor card, indistinguishable from regular RAM. In this case, the software team should track margins on this combined RAM/bulk memory space.

1553 Bus: Usage calculations should include 1 retry for each transaction, unless mission requirements specify otherwise. If the scheduling of bus traffic is segmented into slots or channels, the usage should be calculated based on the number of slots used (rather than actual bus time).

For software resources that do not appear in the table, use an analogous resource that does appear or work with the project systems engineer to define acceptable margins for that unique resource.

3.10	Flight Operations Preparations and Team Development				Software		
Rule:	Experienced operations personnel shall participate as early as possible during mission development, preferably during the mission operations concept phase and the development of specifications for the spacecraft and/or instruments which impact operations. Ideally, the Flight Operations Team (FOT) will supply Test Conductors to support Observatory I&T, which will serve to prepare and train the FOT. As a minimum, the FOT shall participate in flight operations readiness tests that are specified in Table 3.10. Note that these serve as guidelines and are not intended to be prescriptive.						
Rationale:	Involving experienced operations personnel early in the mission helps ensure that the mission design will be considerate of operational requirements and practicalities. It will allow the operations team to become intimately familiar with the mission design, including design rationale, spacecraft limitations, and operating constraints. Involving FOT members during mission operations readiness tests gives them a great deal of hands-on experience with the observatory prior to launch thereby enhancing their training; and, the FOT will be able to assume their responsibility with a reasonable degree of skill and knowledge for conducting on-orbit spacecraft operations.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Assess the flight operations team's role throughout the mission lifecycle. Flight operations experts develop preliminary operations concepts.	1. Flight operations and software experts support the development of more detailed operations concepts, and flight/ground architecture. 2. Update mission design estimates.	1. Identify roles and responsibilities for FOT members. 2. Review and update operations concepts and identify details on approach to operations team support. 3. Conduct peer review of flight/ground architecture. 4. Develop test plans (see Table 3.10).	1. Involve FOT and Test Conductor(s) in test plan development. 2. Support the completion of the operations concepts.	1. Ensure all FOT members and Test Conductor(s) gain knowledge and experience on ground systems during I&T. 2. Conduct tests (see Table 3.10). 3. Complete flight operations plan. 4. Assess the number of available FOT personnel against peak needs for conducting operations and managing anomalies at the same time.	1. Conduct Tests or Re-Tests of critical events using available simulation and flatsat resources.	N/A
Verification:	1. Verify at MCR: a) Ensure flight development experts were consulted during mission formulation. b) Ensure that operations concept covers flight operations team's role during entire mission lifecycle.	1. Verify at MDR: a) Flight operations concepts are sound.	1. Verify at PDR: a) Flight operations roles are defined and personnel identified. b) Flight and ground system interfaces to all mission support elements are well defined and documented.	1. Verify at CDR: a) Flight operations experts have been consulted on the overall ground system design. b) The project has completed full mission lifecycle design to include extended mission and mission termination phases.	1. Verify at MOR and FOR: a) MRT items completed by MRR.	1. Verify at an associated readiness review (such as Critical Event Readiness Review, CERR).	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. E, Updated Rev. G	Flight Systems Integration and Test Branch (568, Primary) Software Systems Engineering Branch (581) Mission Validation & Operations Branch (584)	

Table 3.10 Simulation Types and Minimum Number of Successful Simulations/ Test Hours versus Mission Class

Simulation Type	Class A	Class B	Class C	Class D
End-to-end	5 tests	4 tests	3 tests	3 tests
Day-in-the-life (focused on instrument)	3 tests	2 tests	1 test	1 test
Day-in-the-life (focused on spacecraft)	3 tests	2 tests	1 test	1 test
Launch & early-orbit phase	4 tests	3 tests	2 test	2 test
Critical operations	each planned critical operation included in at least 2 simulations, 1 of which is in LE&O phase	each planned critical operation included in at least 2 simulations, 1 of which is in LE&O phase	each planned critical operation included in at least 1 simulation	each planned critical operation included in at least 1 simulation
Contingency operations	each contingency/critical operation included in at least 2 simulations, one of which is in LE&O phase	each contingency/critical operation included in at least 2 simulations, one of which is in LE&O phase	each contingency/critical operation included in at least 1 simulation	each contingency/critical operation included in at least 1 simulation
Flight system operation with spacecraft	400 hours	300 hours	250 hours	200 hours

Note: Simulations and tests may be performed in parallel or in combination, if appropriate, to satisfy above goals. End-to-end test implies spacecraft-to-Control Center interface and includes all supporting elements, i.e., Science Data Center, communications network, etc. Ground Readiness Tests (GRTs) are not included in this table.

3.11	**Long Duration And Failure Free System Level Test of Flight and Ground System Software**				**Software**		
Rule:	Ground test of the fully integrated FSW and ground system shall include demonstration of error free operations-like scenarios over an extended time period. The minimum duration of uninterrupted FSW system-level test (on the highest fidelity FSW testbed) and ground system operations is 72 hours for Class A and B missions; 48 hours for Class C missions; and, 36 hours for Class D missions, respectively.						
Rationale:	Frequent restart of FSW and the ground system during ground tests may mask problems which will only occur following extended execution of these systems. Also, ground system stress testing is needed to ensure reliable operation. The number of hours specified is based on discussion with senior-level engineers, and reflect best practices accumulated over a period of 15 years.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Complete Draft FSW and Ground System Test Plans.	1. Complete Final FSW and Ground System Test Plans.	1. Complete and execute test plans, to include long duration FSW and ground system testing.	N/A	N/A
Verification:	N/A	N/A	N/A	1. Verify at CDR that FSW and Ground System Test Plans are baselined and that they include long-duration testing.	1. Verify at MOR: a) The longest duration, uninterrupted FSW system-level test (on the highest fidelity FSW testbed), and ground system testing have been completed. b) Verify at FOR that realistic post-launch science operations and safehold operations were represented by the long duration test(s).	N/A	N/A
Revision Status: Rev. E		**Owner:** Software Systems Engineering Branch (581) Flight Software Systems Branch (582, Primary)				**Reference:**	

3.13	Maintaining Adequate Resources for Mission Critical Components					Software
Rule:	The updating of mission critical components during the mission operations phase (including any combination of hardware platforms, hardware devices, and software code) shall not compromise the capability of the system to meet mission requirements. Missions shall provide sufficient quantities of flight and ground resources to allow development, test, and operations activities to be conducted without compromising mission availability requirements.					
Rationale:	Missions should provide sufficient resources to allow updates to mission critical/high availability components, such as flight software and ground system components directly supporting space-ground communications, to be developed and tested without compromising operations. Missions should also ensure against inadvertent updates or deliberate concurrent updates of mission critical/high availability components. For example, under no circumstances should prime and redundant components, such as prime and backup flight software code images, be modified/updated concurrently, before the operational performance of the change is properly verified in a single unit.					
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Ensure preliminary flight and ground system design contains adequate strings or quantities of equipment to satisfy both maintenance and mission availability requirements during Phase E.	1. Ensure flight and ground system level design does not allow modification of software between one CPU and its redundant elements. 2. Ensure final flight and ground system design contains adequate strings or quantities of equipment to satisfy both continuing maintenance and mission availability requirements during Phase E.	1. Ensure flight and ground system maintenance plans define approach and required resources for development and test of changes to mission critical functions before committing to operations. 2. Declare and enforce Ground S/W Freeze and Change Control for all Mission Critical Components"	1. Enforce change control for all Mission Critical Components 2. Verify all changes to Mission Critical Components on non-operational strings	N/A
Verification:	N/A	N/A	Verify at PDR.	1. Verify at CDR.	Verify at MOR.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G		**Owner:** Software Systems Engineering Branch (581, Primary) and Mission Engineering and Systems Analysis Division (590)				**Reference:**	

3.14	Command Procedure Changes					Software	
Rule:	Command procedures and/or scripts, and mission databases (onboard and ground) shall be controlled (treated with the same rigor as changes to flight critical software). This includes formal configuration management, peer review by knowledgeable technical personnel, and full verification with up-to-date simulations wherever possible. (Routine command loads to perform nominal operations may require less test rigor based on experience of senior engineers.)						
Rationale	Changes in command procedures and critical database areas that are not tracked, controlled, and fully tested can cause loss of science and/or the mission.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Ensure draft CM plans address items defined in this rule.	1. Ensure that the final CM and test plans address the items defined in this rule. 2. Ensure that operations and sustaining engineering plans address the items defined in this rule.	1. Implement CM plans. Make changes to procedures and databases as necessary based on changing mission needs/requirements.	1. Enforce CM plans and Change Control. Maintain command procedures, scripts, and mission databases as necessary based on changing mission needs/requirements (i.e., aging S/C, etc.).	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	N/A	N/A	N/A
Revision Status: Rev. E		**Owner:** Software Systems Engineering Branch (581) Flight Software Systems Branch (582) Mission Validation & Operations Branch (584, Primary)				**Reference:**	

4.01	Contamination Control, Planning, and Execution					Mechanical	
Rule:	Specific contamination control requirements and processes (such as analytical modeling, laboratory investigations, and contamination protection and avoidance plans) that support mission objectives shall be identified.						
Rationale:	Contamination sensitive components are often critical elements that directly affect system performance. It is essential that critical component performance be preserved and not allowed to degrade due to contamination exposure & accumulations.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Provide within the conceptual study the preliminary contamination control requirements that will drive mission cost, schedule, and design.	1. Update requirements and develop control methodologies. 2. Write draft Contamination Control Plan (CCP) to document cost, schedule, and design requirements.	1. Update CCP as mission and design details evolve.	1. Finalize CCP. 2. Implement appropriate elements of CCP in fabrication.	1. Implement all elements of the CCP.	1. Monitor system performance for evidence of contamination related degradation and prepare mitigation plans if necessary.	N/A
Verification:	1. Verify above at MCR.	1. Verify through peer review, proposal team, and at MRR.	1. Verify through peer review and at MDR.	1. Verify that CCP is under formal configuration control. 2. Verify through peer review and at PDR and CDR.	1. Verify through peer review.	1. Verify mitigation plan at ORR.	N/A

Revision Status:	**Owner:**	**Reference:**
Rev F	Mechanical Systems Division (540)	GEVS 2.7.1

4.03	**Factors of Safety for Structural Analysis and Design, and Mechanical Test Factors & Durations**				**Mechanical**		
Rule:	Structural analysis and design factors of safety shall apply to all systems in accordance with GEVS Section 2.2.5. The project shall employ the mechanical test factors and durations in accordance with GEVS Section 2.2.4.						
Rationale:	This will provide confidence that the hardware will not experience failure or detrimental permanent deformation under test, ground handling, launch, or operational conditions.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Employ design factors of safety in accordance with GEVS 2.2.5.	1. Employ design factors of safety in accordance with GEVS 2.2.5.	1. Employ design factors of safety in accordance with GEVS 2.2.5. 2. Formulate test plans for all structural elements incorporating the requirements described in the rule.	1. Employ design factors of safety in accordance with GEVS 2.2.5. 2. Write Test plans and execute tests.	N/A	N/A
Verification:	N/A	1. Verify that factors of safety are defined at MDR.	1. Verify that factors of safety are defined at SDR and PDR.	1. Verify these factors of safety, test factors, and test durations at CDR.	1. Verify these factors of safety, test factors, and test durations at EPR, PER, and PSR.	N/A	N/A
Revision Status: Rev. E		**Owner:** Mechanical Systems Analysis and Simulation Branch (542) and Mechanical Engineering Branch (543)				**Reference:** GEVS 2.2.4 & 2.2.5	

4.06	Validation of Thermal Coatings Properties				Mechanical		
Rule:	All thermal coatings properties shall be determined, measured and validated to be accurate for materials and mission flight parameters over the lifecycle of the mission. All thermal analysis shall employ these properties. The GSFC Coatings Committee (chaired by Code 546) shall review and approve the coatings properties.						
Rationale:	Thermal coatings properties directly affect Mission success through S/C or instrument thermal design. Early assessment of thermal coating ensures the mission objectives will be met.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Assess proposed thermal coatings for the mission design parameters.	1. Assess proposed thermal coatings for mission design parameters.	1. Determine appropriate BOL and EOL coatings properties to be used in the thermal analysis. 2. Determine mission specific thermal coating requirements.	1. Update thermal coatings properties as coatings selection matures.	1. Update thermal coatings properties as coatings selection matures. 2. Measure coatings properties when appropriate as determined by the Thermal Engineer/Coatings Engineer 3.Develop notional plan for assessing in flight	1. Assess thermal coatings performance through flight data as appropriate.	N/A
Verification:	1. Specify needed environmental tests on thermal coatings.	1. Specify needed environmental tests on thermal coatings.	1. Verify through peer review/GSFC Coatings Committee, test results, analysis and at PDR.	1. Verify through peer review/GSFC Coatings Committee, test results, analysis and at CDR.	1. Verify at PER as determined by the Thermal Engineer/Coatings Engineer	1. Confirm performance with available flight data as appropriate.	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. E, Updated Rev. G	Contamination & Coatings Engineering Branch (546)	NASA/TP-2005-212792

4.10	Minimum Workmanship					Mechanical	
Rule:	All electrical, electronic, and electro-mechanical components shall be subjected to minimum workmanship test levels as specified in GEVS Section 2.4.2.5.						
Rationale:	The workmanship levels defined in GEVS Section 2.4.2.5 have been found to be the minimum input level necessary to adequately screen the hardware types above for workmanship flaws.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Envelop minimum workmanship levels when deriving component random vibration test levels.	1. Envelop minimum workmanship levels when deriving component random vibration test levels.	1. Envelop minimum workmanship levels when deriving component random vibration test levels.	N/A	N/A
Verification:	N/A	N/A	1. Verify that component test levels envelop minimum workmanship.	1. Verify that component test levels envelop minimum workmanship.	1. Verify that components have been adequately screened for workmanship.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. E	Mechanical Systems Analysis and Simulation Branch (542) and Electrical Engineering Division (560)	GEVS Section 2.4.2.5

4.11	Testing in Flight Configuration				Mechanical		
Rule:	Mechanical environmental testing (sine, random, & acoustic, shock, etc.) of flight hardware shall be performed with the test article in the flight like configuration. Mechanisms shall be configured for flight, and the flight (or flight like) blankets and harness shall be present for test. The flight optical system shall also be present for the test and configured for flight.						
Rationale:	Testing in-flight configuration ensures that hardware which is difficult to analyze (i.e. blankets, harnesses, mechanisms) will be adequately screened by environmental testing for design or workmanship flaws. The presence of the optical system in this testing enables verification that the performance stability of the as-built opto-mechanical configuration is compliant to requirements (e.g., wave-front error, alignment, etc.) before and after testing.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	N/A	1. Develop plans necessary to allow testing of hardware in flight configuration.	1. Perform testing in flight configuration.	N/A	N/A
Verification:	N/A	N/A	N/A	1. Verify that appropriate planning has been performed to conduct test in flight configuration.	1. Verify that testing has been performed with the test article in flight configuration.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G			**Owner:** Mechanical Systems Analysis and Simulation Branch (542, Primary), Electrical Engineering Division (Code 560), and Optics Branch (Code 551)			**Reference:** GEVS Sections 2.4	

4.12	Structural Proof Testing					Mechanical	
Rule:	Primary and secondary structures fabricated from nonmetallic composites, beryllium, or containing bonded joints or bonded inserts shall be proof tested in accordance with GSFC-Std-7000 Section 2.4.1.4.1.						
Rationale:	The mechanical strength of the above items is dependent on workmanship and processing and can only be verified by proof testing.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Identify structure requiring proof testing.	1. Develop test methods and plans for performing proof testing.	1. Perform proof testing to verify mechanical strength.	N/A	N/A
Verification:	N/A	N/A	1. Verify that all structural elements requiring proof testing have been identified.	1. Verify that approach for proof testing appropriate structural elements has been defined.	1. Verify that proof testing has been performed.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. E, Updated Rev. G	Mechanical Systems Analysis and Simulation Branch (542)	GEVS 2.4.1.4.1

4.14	Structural and Mechanical Test Verification				Mechanical		
Rule:	Structural and Mechanical Test Verification program shall comply with GEVS-Table 2.4-1, Structural and Mechanical Verification Test Requirements.						
Rationale:	Demonstration of structural requirements is a key risk reduction activity during mission development.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Develop outline of structural qualification methodology.	1. Update structural qualification methodology and develop preliminary strength qualification plan.	1. Develop draft structural qualification methodology and plan.	1. Finalize structural qualification plan. 2. Implement plan.	1. Demonstrate that flight hardware supports expected mission environments and complies with specified verification requirements.	N/A	N/A
Verification:	1. Verify at MCR.	1. Verify at MDR.	1. Verify that plan is under configuration control. 2. Verify through Engineering Peer Review and at PDR.	1. Verify through CDR, and Engineering Peer Review and at CDR.	1. Verify at PER, Engineering Peer Review, and PSR.	N/A	N/A
Revision Status: Rev. E		**Owner:** Mechanical Engineering Branch (543 (Primary), Mechanical Systems Analysis and Simulation Branch (542)				**Reference:** GEVS Sections 2.4.1	

4.15	**Torque Margin**					**Mechanical**	
Rule:	The Torque Margin (TM) requirement defined in GEVS section 2.4.5.3 shall apply to all mechanical functions, those driven by motors as well as springs, etc. at beginning of life (BOL). End of Life (EOL) mechanism performance shall be determined by life testing, and/or by analysis; however, all torque increases due to life test results and/or analysis shall be included in the final TM calculation and verification. Margins shall include all flight drive electronics effects and limitations.						
Rationale:	The torque or force margin needs to be sufficiently large to guarantee system-performance under worst-case conditions throughout its life by fully accommodating the uncertainty in the resisting forces or torques and in the source of energy.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Identify and create a plan for determination and implementation for Torque Margin verification.	1. The Torque Margin (TM) shall be calculated per the guidelines in GEVS Section 2.4.5.3 using PDR Factors of Safety. Identify basis for input to analysis.	1. The Torque Margin (TM) shall be calculated per the guidelines in GEVS Section 2.4.5.3 using CDR Factors of Safety. Identify basis for input to analysis. 2. Present all available engineering test data used for these analyses.	1. The Torque Margin (TM) shall be Calculated per the guidelines in GEVS Section 2.4.5.3 using Post Acceptance / Qualification Factors of Safety.	1. Monitor system performance for evidence of mechanism degradation. Use this data to improve future design approaches. 2. Prepare mitigation plan to extend the life of the mission if degradation becomes evident.	N/A
Verification:	N/A	1. The Torque Margin Plan shall be presented at MDR as part of the analysis and verification process.	1. Present TM analysis at PDR.	1. Present TM analysis at CDR.	1. Present final test verified TM analysis at PSR. Identify basis for input to analysis. Present all available hardware verification test data used for these analyses.		N/A
Revision Status: Rev. E		**Owner:** Electro-Mechanical Systems Branch (544, Primary), Mechanical Engineering Branch (543)				**Reference:** GEVS 2.4.5.3	

4.18	Deployment and Articulation Verification					Mechanical	
Rule:	All flight deployables, movable appendages, and mechanisms shall demonstrate full range of motion and articulation under worst-case conditions, when being driven by the flight avionics (i.e., not EGSE) prior to flight.						
Rationale:	Environmental factors such as temperature, gravity, acceleration fields, wire bundle stiffness, and others can adversely affect successful deployment. Additionally, initiation of mechanism release with EGSE could result in masking system-level design issues. Verification of these systems under worst-case conditions will improve on-orbit success.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Include articulation in the verification plan and verification matrix.	1. Analyze design and use environment to determine worst case deployment conditions. 2. Demonstrate that all deployable system test plans include provisions to verify deployment under worst case conditions.	1. Update worst case analysis and test plans. 2. Write test procedure(s). 3. Conduct tests.	N/A	N/A
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify worst case condition analysis and test plans/procedures through engineering peer review and at CDR.	1. Verify test procedures and test results through engineering peer reviews, and at PER and PSR.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G			**Owner:** Mechanical Engineering Branch (543, Primary and Electrical Engineering Division (560)			**Reference:**	

4.20	Fastener Locking				Mechanical		
Rule:	All threaded fasteners shall employ a locking feature.						
Rationale:	If not locked in the torqued, preloaded position, threaded fasteners subjected to vibration and thermal cycling loads may back out causing a reduction in preload and potentially jeopardize the mission.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	N/A	1. Review all design drawings and specifications to assure all fasteners employ an appropriate locking feature.	1. Inspect all threaded fastener related assemblies to verify that the specified locking feature has been properly applied.	N/A	NA
Verification:	N/A	N/A	N/A	1. Verify at CDR.	1. Verify at PER and PSR.	N/A	N/A
Revision Status: Rev. F		**Owner:** Mechanical Engineering Branch (543 Primary Owner), Electromechanical Systems Branch (544)				**Reference:**	

4.21	**Brush-type Motor Use Avoidance**				**Mechanical**		
Rule:	Designs shall avoid brush-type motors for critical applications with very low relative humidity or vacuum operations. Intentionally excluded from this rule are contacting sensory and signal power transfer devices such as potentiometers and electrical contact ring assemblies (slip rings, roll rings), etc.						
Rationale:	The operating life of the brush-type motors can be significantly decreased in extremely dry or vacuum conditions. Critical components relying on brush-type motors could be rendered inoperable due to excessively worn brushes or brush particulate contamination.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Identify all motor applications and motor types.	1. Mechanisms and Controls shall be designed to avoid the use of brush-type motors. If Brush-type motor is used, it shall be carefully scrutinized, and an alternative motor design and selection trade study shall be seriously considered.	1. Finalize motor and control design.	1. Trending Motor Performance during Integration and Test activities.	N/A	NA
Verification:	N/A	1. Verify at EPR & MDR.	1. Verify at EPR and PDR.	1. Verify at EPR and CDR. Conducted Life Test consistent with Gold Rule 4-23, Life Test Verification.	1. Verify at EPR, PER and PSR.	N/A	N/A
Revision Status: Rev. E		**Owner:** Electromechanical Systems Branch (544)				**Reference:**	

4.22	Precision Component Assembly				Mechanical		
Rule:	When precise location of a component is required, the design shall use a stable, positive location system (not relying on friction) as the primary means of attachment.						
Rationale:	When in the domain of arc-sec to sub-arc-sec location requirements, the use of pinning or similar non-friction reliant method will help ensure alignment is maintained through all expected stresses.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Begin to identify potential high precision interfaces.	1. Refine identification of high precision interfaces.	1. Identify methodology for precise location attachment.	1. Design and document attachment methods.	1. Inspect assemblies to assure specified attachment techniques are properly applied.	N/A	N/A
Verification:	N/A	N/A	1. Verify through peer review and at PDR.	1. Verify through peer review and at CDR.	1. Verify through peer review and at PER.	N/A	N/A
Revision Status: Rev. E			**Owner:** Electromechanical Systems Branch (544)			**Reference:**	

4.23	Life Test					Mechanical	
Rule:	A life test shall be conducted, within representative operational environments, to at least 2x expected life for all repetitive motion devices with a goal of completing 1x expected life by CDR. The differences between the life-test drive electronics and the flight drive electronics (e.g., voltage, current, duty cycle, etc.) could affect mechanism operating life and should be considered in the life-test.						
Rationale:	Degradation in repetitive motion devices from wear, fatigue, lubrication degradation, etc., can have serious negative impacts on mission success.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Develop a life test outline for all repetitive motion devices.	1. Develop draft life test plan.	1. Finalize plan and implement.	1. Present life test conclusions and compare to mission performance requirements.	N/A	N/A
Verification:	N/A	1. Verify at MDR.	1. Verify that plan has been drafted at PDR.	1. Verify plan and any existing life test data.	1. Verify life test results at PER and PSR.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G		**Owner:** Electromechanical Systems Branch (544 Primary Owner, Mechanical Engineering Branch (543)				**Reference:** GEVS 2.4.5.1	

4.24	Mechanical Clearance Verification					Mechanical	
Rule:	Verification of mechanical clearances and margins (e.g. potential reduced clearances after blanket expansion) shall be performed on the final as-built hardware.						
Rationale:	Proper mechanical clearances are often critical to successful on-orbit performance (e.g. free-movement area, thruster impingement, FOV, etc.). Verification through analysis and drawing checking alone is not sufficient to properly demonstrate adequate clearance.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	N/A	1. Demonstrate that mechanical integration plans include provisions for verifying mechanical clearances at appropriate integration milestones. 2. Conduct inspections and measurements.	1. Demonstrate that mechanical integration plans include provisions for verifying mechanical clearances at appropriate integration milestones. 2. Conduct inspections and measurements.	N/A	N/A
Verification:	N/A	N/A	N/A	1. Verify at CDR.	1. Verify at PER and PSR.	N/A	N/A
Revision Status: Rev. E		**Owner:** Electromechanical Systems Branch (544)				**Reference:**	

4.25	Thermal Design Margins				Mechanical		
Rule:	Thermal design shall provide adequate margin between stacked worst-case flight predictions and component allowable flight temperature limits per GEVS 2.6 Note: This applies to normal operations and planned contingency modes. This does not apply to cryogenic systems.						
Rationale:	Positive temperature margins are required to account for uncertainties in power dissipations, environments, and thermal system parameters.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Thermal design concept produces minimum 5C margins, except for heater controlled elements which have a maximum 70% heater duty cycle, and two-phase flow systems which have a minimum 30% heat transport margin. For Pre-A, larger margins advisable.	1. Thermal design concept produces minimum 5C margins, except for heater controlled elements which have a maximum 70% heater duty cycle, and two-phase flow systems which have a minimum 30% heat transport margin. For Phase A, larger margins advisable.	1. Thermal design concept produces minimum 5C margins, except for heater controlled elements which have a maximum 70% heater duty cycle, and two-phase flow systems which have a minimum 30% heat transport margin.	1. Thermal design concept produces minimum 5C margins, except for heater controlled elements which have a maximum 70% heater duty cycle, and two-phase flow systems which have a minimum 30% heat transport margin.	1. System thermal balance test produces test-correlated model. Test and worst-case flight thermal analysis with test-correlated model demonstrate minimum 5C margins, except for heater controlled elements which demonstrate a maximum 70% heater duty cycle, and two-phase flow systems which demonstrate a minimum 30% heat transport margin.	1. Thermal analysis with flight-correlated model shows minimum 5C margins for mission trade studies, except for heater controlled elements which have a maximum 70% heater duty cycle, and two-phase flow systems which have a minimum 30% heat transport margin.	1. Thermal analysis with flight-correlated model shows minimum 5C margins for mission disposal options, except for heater controlled elements which have a maximum 70% heater duty cycle, and two-phase flow systems which have a minimum 30% heat transport margin.
Verification:	1. Verify at MCR.	1. Verify worst-case thermal analysis of concept through peer review and at SRR and MDR.	1. Verify worst-case thermal analysis of design through peer review and at PDR.	1. Verify worst-case thermal analysis of detailed design through peer review and at CDR.	1. Verify through peer review and at PER and PSR.	1. Verify thermal analysis of flight system using flight-correlated thermal model through peer review.	1. Verify thermal analysis of flight system using flight-correlated thermal model through peer review.
Revision Status: Rev. E, Updated Rev. G		**Owner:** Thermal Engineering Branch (545)				**Reference:** GEVS 2.6	

4.27	Test Temperature Margins				Mechanical		
Rule:	Components and systems shall be tested beyond allowable flight temperature limits, to proto-flight or acceptance test levels as specified in GEVS section 2.6.2.4a Note that at levels of assembly above component, full specified margins may not always be achievable for all components due to test setup limitations. In these cases, the expected test levels shall be approved by the GSFC Project, and shall be presented at the earliest possible formal review, no later than PER.						
Rationale:	The test program shall ensure that the flight hardware functions properly (meets performance requirements) at temperatures more severe than expected during the mission to demonstrate robustness to meet its mission lifetime requirements. (Note: This rule does not apply to cryogenic systems.)						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities: Revalidate	N/A	N/A	1. Component proto-flight thermal vacuum test temperatures shall be specified with the required margin as stated in the Reference (GEVS 2.6.2.4a).	1. Component, subsystem, and system proto-flight thermal vacuum test temperatures shall be specified with the required margin as stated in the Reference (GEVS 2.6.2.4a).	1. Components and systems shall undergo proto-flight thermal vacuum testing with the required margin as stated in the Reference (GEVS 2.6.2.4a). Yellow and Red limits for flight temperature telemetry database shall be consistent with actual proto-flight system thermal vacuum (TV) test temperatures.		
Verification:	N/A	N/A	1. Verify at PDR.	1. Verify at CDR.	1. Verify results of component and subsystem thermal vacuum (TV) tests, and present plans for system TV test at PER. 2. Verify results of system thermal vacuum test at PSR. 3. Verify flight database limits at MRR and/or FRR.		

Revision Status:	**Owner:**	**Reference:**
Rev. E, Updated Rev. G	Thermal Engineering Branch (545, Primary) and Electrical Engineering Division (Code 560)	GEVS 2.6.2.4a

4.28	Thermal Design Verification					Mechanical	
Rule:	All subsystems/systems having a thermal design with identifiable thermal design margins shall be subject to a Thermal Balance Test at the appropriate assembly level per GEVS Section 2.6.3.						
Rationale:	This test shall provide an empirical verification of the subsystem/system's thermal design margin. In addition, steady state temperature data from this test shall be used to validate subsystem/system thermal math models (TMMs).						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify thermal balance test concepts.	1. Include thermal balance test in environmental test plan.	1. Identify preliminary thermal balance test architecture and scope.	1. Identify specific thermal balance test architecture and cases.	1. Implement test.	N/A	N/A
Verification:	1. Verify at MCR.	1. Verify at MDR.	1. Verify at SDR and PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. E	Thermal Engineering Branch (545)	GEVS 2.6.3

4.29	Thermal-Vacuum Cycling				Mechanical		
Rule:	All systems flying in unpressurized areas shall have been subjected to a minimum of eight (8) thermal-vacuum test cycles prior to installation on a spacecraft. For an instrument, a minimum of four (4) of these eight (8) Thermal Vacuum cycles shall be performed at the instrument level of assembly. For units where there is an institutional or organizational delivery to an interim level of assembly, pre-delivery testing should include a minimum of 4 cycles.						
Rationale:	This provides workmanship and performance verifications at lower levels of assembly where required environments can be achieved and reduces the risk to cost during spacecraft Integration and Test (I&T).						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify environmental test concept.	1. Develop preliminary environmental test plan.	1. Update environmental test plan and put under configuration control.	1. Update plan.	1. Implement test cycles.	N/A	N/A
Verification:	1. Verify at MCR.	1. Verify at MDR.	1. Verify at SDR and PDR.	1. Verify at CDR.	1. Verify that all components have seen required testing prior to spacecraft I&T at PER.	N/A	N/A
Revision Status: Rev. F, Updated Rev. G			**Owner:** Mission Systems Engineering Branch (599)			**Reference:** GEVS 2.6.2.4.b	

5.04	**Instrument Testing for Multipaction**				**Instruments**		
Rule:	Active RF components, such as radars, that develop significant RF power shall be designed and tested for immunity to multipaction. If multipaction immunity is demonstrated by test alone, the test shall be performed at least 6dB above the nominal power level, If satisfied by analysis and test, the analysis shall show at least 10dB of margin above the nominal power level and the test shall be performed at least 3dB above the nominal power level. Due to the inherent uncertainty in the analysis at these power levels, satisfaction by analysis alone is not allowed.						
Rationale:	Multipaction on RF components that carry large amounts of RF power can degrade overall performance and cause damage. Unless significant design margin is demonstrated, small unit-to-unit variations make it impossible to predict whether an RF component is susceptible to multipaction.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Determine the likely maximum power levels that components are going to see and determine if multipaction could be an issue.	1. Further refine power requirements and for components that are likely to have multipaction issues. 2. Begin vendor research to determine the extent of the issues.	1. Down select vendor and finalize component performance and power requirements. 2. Develop multipaction immunity verification plan.	1. Build engineering models of all components that could experience multipaction and perform testing on these components before and after environmental testing.	1. Build flight models and perform multipaction testing on all flight components before and after environmental testing.	1. Monitor instrument performance to determine if component damage or degradation is occurring due to multipaction.	N/A
Verification:		1. Gather data from multiple vendors to have several points of comparison.	1. Verify design and verification plan at PDR.	1. Verify results of EM testing at CDR.	1. Verify results of testing at PSR.	1. Track long-term performance of instrument for trends in overall performance and compare to expectations.	N/A
Revision Status: Rev. E, Updated Rev. G			**Owner:** Microwave Instrument Technology Branch (555)			**Reference:**	

5.05	Fluid Systems GSE					Instruments	
Rule:	Fluid systems GSE used to pressurize flight systems shall be compliant with the fault tolerance requirements of Rule 1.26.						
Rationale:	Fluid systems GSE is usually at a pressure significantly above the flight systems final pressure and therefore poses a risk of over-pressurizing the flight system.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Recognize the need for this specialized GSE.	1. Determine if candidate GSE exists and availability (versus a new build).	1. Secure agreement for existing GSE. 2. Design new GSE and procure components.	1. Recertify existing GSE before use. 2. Assemble and certify GSE.	1. Use GSE to test flight system (and components if necessary).	N/A	N/A
Verification:	1. Verify inclusion in proposal write-up and cost estimate.	1. Present GSE assessment at MDR.	1. Verify through peer review and at PDR.	1. Present certification at CDR.	1. Verify that procedures for GSE are approved by PER.	N/A	N/A
Revision Status: Rev. E			**Owner:** Cryogenics and Fluids Branch (552)			**Reference:** NPR 8715.3	

5.06	Flight Instrument Detector Characterization Standard			Instruments			
Rule:	Instrument detector systems and associated components, shall demonstrate performance via test over the expected operating temperature range before the Pre-Environmental Review (PER) to establish a performance baseline and provide a provisional verification of performance prior to exposure to non-operational environments, such as vibration, acoustics, non-operational temperatures, or other conditions required to demonstrate survival. At the conclusion of environmental testing, performance shall again be characterized via test and the results compared to the baseline results.						
Rationale:	Detector performance falls off rapidly as a function of temperature for both increasing and decreasing temperature. Additionally, structural-thermal and optical performance models need to be correlated against tests.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Test mission-enabling parts and components at room temperature (extrapolate performance at other than room temperature).	1. Test critical parts and components over the flight operation temperature range, plus margin (no extrapolations) beyond intended operating range.	1. Test flight-like subsystem and components over the flight operation temperature range, plus margin beyond intended operating range.	1. Test flight-like systems and components operating temperature range, plus margin beyond intended operating range.	1. Test flight system over operating temperature range, plus margin beyond intended operating range. Show results of pre-environmental baseline tests in the operating environment.	N/A	N/A
Verification:	1. Test result reviewed by principal investigator.	1. Test result reviewed by principal investigator and science working group.	1. Review summary of results at PDR.	1. Review summary of results at CDR.	1. Verify through peer review and at PER.	N/A	N/A
Revision Status: Rev. E, Updated Rev. G			**Owner:** Instrument Systems and Technology Division (550)			**Reference:**	

5.08	Laser Development Contamination Control					Instruments	
Rule:	All flight laser development shall include an approved laser-specific Contamination Control Plan (CCP).						
Rationale:	Component and/or system contamination has been identified as the contributing cause in most laser failures to-date. There are unique requirements of a laser CCP that differ significantly from those of a general CCP (as required by 4.01).						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	N/A	1. Review 'Laser Contamination Control Plan Outline' and prepare a program specific CCP.	1. Implement CCP at the component level.	1. Continue implementation of the CCP through launch.	1. Continue any post-launch aspects of the CCP.	N/A
Verification:	N/A	N/A	1. Review documentation at PDR.	1. Verify at CDR.	1. Verify at PER and PSR.	1. Verify post-launch summary of activities.	N/A
Revision Status: Rev. F			**Owner:** Laser and Electro-Optics Branch (554)			**Reference:**	

5.09	Cryogenic Pressure Relief				Instruments		
Rule:	Stored cryogen systems (and related GSE) shall be compliant with the fault tolerance requirements of Rule 1.26.						
Rationale:	Unintended conditions can lead to potential system over-pressurization.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Identify personnel or organization to conduct the appropriate analyses during subsequent phases.	1. Identify underlying assumptions and conduct preliminary emergency venting analysis.	1. Refine analysis and identify candidate relief devices.	1. Finalize analysis and include relief devices in design. Procure devices and test them at the component level.	1. Include the devices in the hardware build-up and test function during build-up as appropriate. 2. Review flight hardware and GSE configurations prior to testing to ensure that relief paths are not circumvented.	N/A	N/A
Verification:	1. Grass-root cost estimate to include cryogenic engineering.	1. Ensure venting analysis included in larger cryogenic system analysis report/summary that is reviewed by the system engineer and/or review team.	1. Review at PDR.	1. Review at CDR.	1. Review at PER.	N/A	N/A
Revision Status: Rev. F		**Owner:** Cryogenics and Fluids Branch (552)				**Reference:** NPR 8715.3	

5.10	**Early Demonstration Of Instrument Opto-Mechanical System Alignment and Test**				**Instruments**		
Rule:	For instrument opto-mechanical systems without significant flight heritage, an early demonstration of the capability to fabricate, assemble, align, and test the opto-mechanical system shall be performed. Optics, mechanisms, structures, and other components relevant to the instrument system, including all opto-mechanical features and interfaces, using components of the approximate fit, form, and function of the flight hardware should be part of the early demonstration. The hardware configuration for the demonstration shall be agreed to by all stakeholders and phased with the flight unit to ensure that demonstration occurs early enough to be valuable.						
Rationale:	Early demonstration of the capability to fabricate, assemble, align and test opto-mechanical systems saves cost and mitigates schedule risks.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Develop preliminary opto-mechanical demonstration configuration.	1. Finalize demonstration configuration and procure parts.	1. Build and test the demonstration hardware.	N/A	N/A	N/A	N/A
Verification:	1. Present plan at MCR	1. Review design at SRR	1. Review test results at PDR.	N/A	N/A	N/A	N/A
Revision Status: Rev. G			**Owner:** Optics Branch (551)			**Reference:**	

5.11	Instrument System Performance Margins					Instrument Systems	
Rule:	Instrument performance budgets shall be developed for instrument systems and their sub-systems. The performance budgets shall account for uncertainties including, but not limited to, fabrication, assembly, stability and test/verification. The project must have justification for the adequacy of their margins; test demonstration of predicted on-orbit performance with margins against the performance budgets is the preferred justification.						
Rationale:	Failure to properly allocate uncertainties in the fabrication, assembly, stability and test/verifications of instrument systems can result in an instrument that does not meet its performance requirements on orbit.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Develop preliminary allocations based on top-level instrument performance requirements.	1. Perform analysis to develop error budgets. Identify any driving requirements that impact technical risk, schedule and cost.	1. Develop detailed budgets for fabrication, assembly, stability, and test/verification uncertainties.	1. Demonstrate that hardware meets its requirements with allocated margins.	1. Demonstrate that hardware meets its requirements with allocated margins by test.	N/A	N/A
Verification:	1. Verify at MCR	1. Verify at SRR	1. Verify at PDR.	1. Verify at CDR.	1. Verify at PER.	N/A	N/A
Revision Status: Rev. G			**Owner:** Mission Engineering and Analysis Division (590, Primary) and Instrument Systems and Technology Division (550)			**Reference:**	

5.12	Instrument Alignment, Integration and Test				Optics		
Rule:	Instruments containing optical systems shall develop an alignment plan in Phase A which will be refined and tracked throughout the project life cycle. The alignment plan should address such considerations as: alignment philosophy including the number of datasets required for appropriate statistics to verify requirements; cross-checks for critical data; leveling the instrument to gravity during metrology as appropriate; fiducials and other references; and authority to proceed before breaking an alignment configuration. In addition, consideration must be given to likely failure modes during testing to ensure that the hardware and test design is adequate to determine test failure causes and corrective action.						
Rationale:	Projects that do not incorporate assembly/integration, alignment and test planning early into the concept and design phases increase risk to cost and schedule, alignment efficiency, alignment requirement feasibility, and overall instrument performance.						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	1. Develop preliminary alignment and test concept flow chart.	1. Develop preliminary alignment and test plan.	1. Finalize alignment and test plan.	1. Develop draft alignment and test procedures.	1. Develop final alignment and test procedures.	N/A	N/A
Verification:	1. Verify at MCR	1. Verify at SRR	1. Verify at PDR.	Verify at CDR.	Verify at PER.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. G	Optics Branch (551)	

5.13	**Laser Life Testing**				**Instruments**		
Rule:	There shall be a project-approved and peer-reviewed plan, consistent with the mission risk profile, for life-testing a laser prototype to a minimum of 1x of the mission lifetime requirement. The life-test unit should be a high fidelity representation of the flight laser and any differences between the life test unit and the flight laser should be delineated in the plan. The plan should include system and component-level testing and/or analysis. Any components that have a wear-out or failure mechanism need to be addressed in the plan either by testing or with justification for why testing is unnecessary. Accelerated tests are permitted (and even encouraged) if the acceleration factors are understood and justified. The plan should include technical, budget, schedule and resource assumptions upon which the plan is based.						
Rationale:	There are unique requirements for laser life testing that differ significantly from those of electro-mechanical life-testing (GR 4.23)						
Phase:	**<A**	**A**	**B**	**C**	**D**	**E**	**F**
Activities:	N/A	1. Identify any components that have a wear-out or failure mechanism. 2. Develop draft plan and identify if risk is addressed either by testing or with justification for why testing is unnecessary. 3. If appropriate start testing of high-risk components.	1. Finalize plan and hold peer review. 2. Accelerated tests are permitted (and even encouraged) if the acceleration factors are understood and justified. 3. Perform testing of components and/or subsystems.	1. Perform testing of subsystems or ETU as appropriate.	1. Present life test conclusions and compare to mission performance requirements.	N/A	N/A
Verification:		1. Verify at MDR	1. Verify that plan has been drafted at PDR. 2. Review results of any available data	1. Review plan updates and any existing life test data at CDR.	1. Verify life-test results at PER and PSR.	N/A	N/A

Revision Status:	**Owner:**	**Reference:**
Rev. G	Laser and Electro-Optics Branch (554)	

GLOSSARY AND ACRONYM GUIDE

AIAA	American Institute of Aeronautics and Astronautics
Anomaly	An unexpected event that is outside of certified design/performance specification limits. NOTE: Certified design limits are those identified in approved design-level documents
Assembly	A functional subdivision of a component consisting of parts or subassemblies that perform functions necessary for the operation of a component as a whole (Ref: GEVS 1-6)
ACS	Attitude Control System
API	Application Program Interfaces
BOL	Beginning of Life
Breadboard	A model used to test hardware at TRL 4 or 5 (See TRL levels.)
Catastrophic Hazard	A hazard, condition or event that could result in a mishap causing fatal injury to personnel and/or loss of spacecraft, launch vehicle or ground facility
CCP	Contamination Control Plan
CCSDS	Consultative Committee for Space Data Systems
CDR	Critical Design Review
CM	Configuration Management; A management discipline applied over the product's life cycle to provide visibility and to control performance and functional and physical characteristics (Ref: NPR 7120.5)

Component	A functional subdivision of a subsystem and generally a self-contained combination of items performing a function necessary for the subsystem's operation (Ref: GEVS 1-6)
COTS	Commercial Off-The-Shelf
CPU	Central Processing Unit
Critical Hazard	A condition that may cause severe injury or occupational illness, or major property damage to facilities, systems, or flight hardware
Debug Features	With the best of intentions of helping to debug software and/or hardware problems, there exists a feature that is not needed by the operation software, but was accidentally or intentionally left in the code for debug purposes. (May be advertised or unadvertised; May be documented or undocumented; May be tested or untested)
DR	Decommissioning Review
EDAC	Error Detecting and Correcting
EEE	Electrical, Electronic, and Electromechanical
EEPROM	Electrically Erasable Programmable Read-Only Memory
EGSE	Electrical Ground Support Equipment
Element	A portion of a hardware or software unit that is logically discrete
End-to-end test	A test performed on the integrated ground and flight system, including all elements of the payload, its control, stimulation, communications, and data processing (Ref: GEVS 1-4)
ESD	Electro-Static Discharge
ETU	Engineering Test Unit

EOL	End of Life
FDAC	Failure Detection and Correction
FIFO	First-In / First-Out
FOR	Flight Operations Review
FOS	Factors of Safety
FOV	Field of View
FRR	Flight Readiness Review
FSW	Flight Software
GEVS	General Environmental Verification Standard
GN&C	Guidance, Navigation, and Control
GOLD	Goddard Open Learning Design
GPR	Goddard Policy Requirement
GRT	Ground Readiness Test
GSE	Ground Support Equipment
Heritage hardware	Hardware from a previous project, program, or mission
High fidelity	Addresses form, fit, and function. Equipment that can simulate and validate all system specifications within a laboratory setting (Ref: Defense Acquisition University)

HW	Hardware
I&T	Integration and Test
ICD	Interface Control Document
I/F	Interface
I/O	Input / Output
ISR	Interrupt Service Routine
ITU	Integrated Test Unit
IVT	Interface Verification Test
KDP	Key Decision Point. The event at which the Decision Authority determines the readiness of a Program/project to progress to the next phase of the life cycle (or to the next KDP)
L&EO	Launch and Early Orbit
LRR	Launch Readiness Review
OS	Operating System
Margin	The amount by which hardware capability exceeds requirements (Ref: GEVS 1-7)
MAE	Materials Assurance Engineer
MDR	Mission Definition Review
MCR	Mission Concept Review

MEL	Mission Exceptions List
Mission-critical	Item or function that must retain its operational capability to assure no mission failure (See Mission success) (Ref: MSFC SMA Directorate)
Mission Success	Those activities performed in line and under the control of the program or project that are necessary to provide assurance that the program or project will achieve its objectives. The mission success activities will typically include risk assessments, system safety engineering, reliability analysis, quality assurance, electronic and mechanical parts control, software validation, failure reporting/resolution, and other activities that are normally part of a program or project work structure (Ref: NPR 7120.5)
MOR	Mission Operations Review
MRR	Mission Readiness Review
MRT	Mission Readiness Test
ms	milliseconds
M&P	Materials and Processes
MSPSP	Missile System Prelaunch Safety Package
NDE	Non-Destructive Examination
NPR	NASA Procedural Requirements
ORR	Operational Readiness Review
OS	Operating System

Payload	An integrated assemblage of modules, subsystems, etc., designed to perform a specified mission in space (Ref: GEVS 1-6)
PCI	Peripheral Component Interconnect
PDR	Preliminary Design Review
PER	Pre-Environmental Review
Performance Verification	Determination by test, analysis, or a combination of the two that the payload element can operate as intended in a particular mission (Ref: GEVS 1-7)
PLD	Programmable Logic Device
POC	Point Of Contact
PROM	Programmable Read-Only Memory
Prototype hardware	Hardware of a new design. It is subject to a design qualification test program; it is not intended for flight (Ref: GEVS 1-5)
PSR	Pre-Ship Review
RAM	Random Access Memory
RF	Radio Frequency
RHA	Radiation Hardness Assurance
Safe Hold Mode	A control mode designed to provide a spacecraft with a mode to preserve its health and safety while recovery efforts are undertaken

Safety	Freedom from those conditions that can cause death, injury, occupational illness, damage to or loss of equipment or property, or damage to the environment (Ref: NPR 7120.5)
SAR	System Acceptance Review
S/C	Spacecraft
SDR	System Design Review
SEMP	Systems Engineering Management Plan
Simulation	A synthetic representation of the characteristics of real world system or situation, typically by interfacing controls and displays (operational or simulated) and positions of the system with a computer (Ref: MIL-HDBK-220)
SORR	Science Operations Readiness Review
Spare (part)	A replacement part (reparable or expendable supplies) purchased for use in the maintenance of systems such as aircraft, launch vehicles, spacecraft, satellites, ground communication systems, ground support equipment, and associated test equipment. It can include line-replaceable units, orbit-replaceable units, shop-replaceable units, or piece parts used to repair subassemblies (Ref: NPR 5900.1)
SRR	System Readiness Review
Subsystem	A functional subdivision of a payload consisting of two or more components (Ref: GEVS 1-6)
System	The combination of elements that function together to produce the capability required to meet a need. The elements include all hardware, software, equipment, facilities, personnel, processes, and procedures needed for this purpose (Ref: NPR 7120.5, NASA Program and Project Management Processes and Requirements)
SW	Software

TBD	To Be Determined
Test Features	With the best of intentions of helping to test and validate the software, there exists a feature that is not needed by the operational software, but is desirable to have for testing purposes. (May be advertised or unadvertised; May be documented or undocumented; May be tested or untested)
TAYF	Test As You Fly
TM	Torque Margin
TRL	Technology Readiness Level - A systematic metric/measurement system that supports assessments of the maturity of a particular technology and the consistent comparison of maturity between different types of technology. NASA recognizes nine technological readiness levels: TRL 9 Actual system “flight proven” through successful mission operations TRL 8 Actual system completed and “flight qualified” through test and demonstration (ground or flight) TRL 7 System prototype demonstration in a space environment TRL 6 System/subsystem model or prototype demonstration in a relevant environment (ground or space) TRL 5 Component and/or breadboard validation in relevant environment TRL 4 Component and/or breadboard validation in laboratory environment TRL 3 Analytical and experimental critical function and/or characteristic proof-of-concept

	TRL 2 Technology concept and/or application formulated
	TRL 1 Basic principles observed and reported
	(Ref: Space Science Enterprise Management Handbook, Appendix E 11)
Traceability Matrix	A matrix demonstrating the flow-down of requirements to successively lower levels
UART	Universal Asynchronous Receiver / Transmitter
Validation	Proof that Operations Concept, Requirements, and Architecture and Design will meet Mission Objectives, that they are consistent, and that the “right system” has been designed. May be determined by a combination of test or analysis. Generally accomplished through trade studies and performance analysis by Phase B and through tests in Phase D (Ref: GPG 7120.5)
Verification	Proof of compliance with requirements and that the system has been “designed and built right.” May be determined by a combination of test, analysis, and inspection (Ref: GPG 7120.5)

DOCUMENT HISTORY LOG

Revision	Effective Date	Description
-	10-Dec-04	Baseline
A	30-May-05	[P. 10] User's Guide: removed text examples, replaced with bullets explaining what general information goes into each rule section.
		Addition of Change History page (against 12/10 baseline rulebook).
		[P. 7] Revised Front Matter Graphics (architectural diagram - Figure 2).
		[Rule 1.17, Glossary] 1. Added "credible" to Principle, Phase B, and Phase C; 2. Added "credible" definition to Glossary.
		[Rule 1.22] Phase C revision - Replaced existing language with: "Demonstrate that the method for drying the wetted system has been validated by test on an equivalent or similar system."
		[Rule 1.14] Revision to the Principle and Rationale. Revised Principle: Telemetry coverage shall be acquired during all mission-critical events. *Continuous telemetry and command capability shall be maintained during launch and until the spacecraft has been established on-orbit in a stable, power-positive mode."*
		[Rule 1.06] Added table 1.06-1 to website rule set.
		[Rule 3.07] Added table 3.07-1 to website rule set.
		[Rules: 2.01, 2.07, 2.11, 4.01, 4.03, 4.09, 4.10, 4.11, 4.12, 4.13, 4.14, 4.15, 4.23, 4.25, 4.27, 4.28, 4.29] 1. Corrected GSFC-STD-7000 (GEVS) references in GSFC-STD-1000. 2. Created reference PDFs. 3. Added reference links.
		[Rule 3.09] Added web links to source material (NPR 7150.2, GPG 8700.5).

Revision	Effective Date	Description
B	**30-June-06**	[P. 6] Updated Introduction.
		[P. 9] Revised Figure 3 Lifecycle Chart - Removed "from SMO"
		[P. 10] Updated User's Guide.
		New Systems Engineering Rule: 1.04 – System Modes.
		New Systems Engineering Rule: 1.08 – End to End Testing.
		[Rule 1.14] Revised Principle, Rationale, Activities (Phase E), and Verification (Phases pre-A, A, C → E). Revised Principle: *Continuous telemetry and command coverage shall be maintained during all mission-critical events. Mission-critical events shall be defined to include separation from the launch vehicle; power-up of major components or subsystems; deployment of mechanisms and/or mission-critical appendages; and all planned propulsive maneuvers required to establish mission orbit and/or achieve safe attitude.* Revised Rationale: *With continuous telemetry and command capability, operators can prevent anomalous events from propagating to mission loss. Also, flight data will be available for anomaly investigations.*
B.1	**29-Sept-06**	Formatting changes to Rules 1.17, 2.02, 2.17, 3.03, 3.06, 3.07, 3.09, 3.10, 3.14, 3.15, 4.07, 4.15, 4.20, 4.28, Page 2, Table 307-1 and Glossary "Space Part"
		Typographical errors corrected on Rule 1.28, 3.10, 4.08, 4.18, 4.23, 4.26
		Replaced Page 2 and 3 of Table 3.07-1
C	**30-Oct-06**	Rule 1.14 – Revised Language in "Principle" Statement
		Rule 1.26 – Major Revision
		New Systems Engineering Rule: 1.29 Leakage of Hazardous Propellant
		Glossary – Added definitions for critical and catastrophic hazards
		Table of Contents – Updated to Reflect Changes for Rules 1.26, 1.29
C.1	**12-Dec-06**	New Systems Engineering Rule: 1.09 Test Like You Fly
		New Software Rule: 3.02 Elimination of Dead Software Code
		Table of Contents – Updated to Reflect Changes/Insertion for Rules 1.09, 3.02
		Glossary – Added Definitions for Dead Software/Code & Acronym for "Test Like You Fly"
		Table of Contents – Typographical error in Rule 1.08 title corrected
		[Rule 1.14] Revised Verification for Phases pre-A → E.
C.2	**12-Dec-06**	Introduction – Corrected language for GPR 8070.4
		Table 1.06-1 – Deleted "RF Link" Margin

Revision	Effective Date	Description
D	01-March-08	Table of Contents – Revised to Reflect Rev D Changes
		Rule 1.03 – Revised “Principle” Statement
		Rule 1.11 – Revised “Principle” Statement
		Rule 1.16 – Revised “Principle” Statement
		Rule 3.07 – Revised “Title” and “Principle” Statement
		Rule 5.05 – Revised “Principle” Statement
		Rule 5.09 – Revised “Principle” Statement
		New Systems Engineering Rule: 1.18 Physically Co-Located Redundant Elements
		New Systems Engineering Rule: 1.23 Spacecraft “OFF” Command
		New Systems Engineering Rule: 1.25 Redundant Systems
		New Electrical Engineering Rule: 2.08 Secondary Circuit Failures
		New Electrical Engineering Rule: 2.18 Redundant Functions
		New Electrical Engineering Rule: 2.19 Multiple Circuit Power Bus Loss
		New Electrical Engineering Rule: 2.20 Single Control Line Dependency
		New Electrical Engineering Rule: 2.21 Gross Failure of Integrated Circuits
		New Electrical Engineering Rule: 2.22 Corona Region Testing of High Voltage Equipment
		Table 3.07-1 – Revised first paragraph
E	07-July-09	Major Revision / Rewrite
E	03-Aug-09	Administrative Changes Only - Rule 1.06 (pages 12 thru 16) and associated tables, modified throughout for clarity, regarding system margin.
E	21-Feb-12	Administrative Changes Only – Rule 1.06 (pages 12 - 13); reverts to previous version, in its entirety, for immediate near-term efficiency of mission application.
		Glossary and Acronym Guide – changed definition of Catastrophic Hazard (ref. Rule 1.26), for consistency with NASA-STD 8719.24.
F	10-Dec-12	New Rules 1.39, 2.23, 2.24, 2.25; Added Rule 4.01 Introduction and elsewhere as needed: Removed Rev. E delineation between Rules and Principles to identify all rules; rule = requirement Updated all GEVS references to align with latest version (TBD) of GEVS Updated owner organization throughout. Glossary – corrected definitions of anomaly and EEE CCR-D-0047
F	22-Jan-13	Administrative Change Only – Table 1.06-1: Phase B in Power line changed from 15% to 20%
F1	8-Feb-2013	Administrative Change Only – Table 1.09: Note corrected to “not a global approval to waive TAYF for all elements”. Acronym TYF corrected to TAYF.

G	**30-June-2016**	Rev G is an extensive revision **Deleted The Following Rules:** 1.34 Close-out Photo Documentation Of Key Assemblies 2.02 EEE Parts Program For Flight Missions 2.03 Radiation Hardness Program 2.12 Printed Circuit Board Analysis 2.15 Flight and Ground Electrical Hardware 4.07 Solder Joint Intermetallics Mitigation 4.08 Space Environments Effects on Material Selection **Merged the Following "duplicate" Rules:** 2.07 End-to-End Test of Release Mechanism For Flight Deployable) merged with 4.18 (Deployment and Articulation Verification) and 2.07 removed 2.18 (Implementation of Redundancy) merged with 1.25 (Redundant Systems) and 2.18 removed **Revised The Following Rules (not a complete list):** 1.05 Single Point Failures – Clarified Wording 1.06 System Margins – Revised calculation to be consistent with industry practices; clarified margin and contingency to remove double bookkeeping 1.08 End-To-End Testing – Clarified Wording 1.23 Spacecraft "Off" Command – Simplified and clarified wording 1.40 Maintaining Command Authority of a Passive Spacecraft – significant rewrite 2.05 System Grounding Architecture – Added requirement to include GSE 2.24 – Solar Arrays – Significant Rewrite to give more detail on cell qualification and panel testing 3.07 Flight Software Margins – Rewrite of Table 3.07-1 to define verification methods 4.06 Validation of Thermal Coatings Properties – added detail on how to validate 4.23 Life Test – Added consideration for differences between drive electronics used in the life test versus the flight drive electronics 5.04 Instrument Testing for Multipaction – Significant rewrite 5.06 Flight Instrument Detector Characterization Standard – Added detector to title since that was the intent of the rule; added detail **Added The Following New Rules:** New Systems Engineering Rule 1.41 GSE Use At Launch Site New Systems Engineering Rule 1.42 Powering Off RF Command Receiver New Systems Engineering Rule 1.43 Flight Software Update Demonstration

		New Systems Engineering Rule 1.44 Early Interface Testing New Systems Engineering Rule 1.45 System Alignments New Systems Engineering Rule 1.46 Use of Micro-Switches New Systems Engineering Rule 1.47 Design Deployables for Test New Systems Engineering Rule 1.48 Space Data Systems Standards New Electrical Rule 2.26 Power-On Reset Visibility New Electrical Rule 2.27 Spacecraft Strip-Charting Capability New Instrument Rule 5.10 Early Demonstration of Instrument Opto-Mechanical Alignment and Test New Instrument Rule 5.11 Instrument System Performance Margins New Instrument Rule 5.12 Instrument Alignment, Integration and Test New Instrument Rule 5.13 Laser Life Testing