3 August 1979

## **MILITARY HANDBOOK**

# INTERFACE CONTROL DOCUMENT FOR INFRARED DETECTING SET AN/AAS-36



FSC 5855

## DEPARTMENT OF DEFENSE WASHINGTON, D C 20360

MIL-HDBK-258(AS)

Interface Control Document for Infrared Detecting Set AN/AAS-36

- 1. This interface control handbook was developed by the Department of Defense with the assistance of the Naval Air Systems Command in accordance with established procedure.
- 2. This document was approved on for printing and inclusion in the military interface control handbook series.
- 3. This document provides basic and fundamental information on the physical and functional interface requirements for aircraft installation of the AN/AAS-36 Infrared Detecting Set. The defined interfaces establish the compatibility between cofunctioning elements and control the interface design. This handbook is intended to be referenced in purchase specifications for applicable equipment.
- 4. Every effort has been made to reflect the latest information on installation interface requirements for the AN/AAS-36 Infrared Detecting Set. It is the intent to review this handbook periodically to insure its completeness and currency. Beneficial comments (recommendations, additions, deletions) and any pertinent data which q ay be of use in improving this document, should be addressed to: Commanding Officer, Naval Air Engineering Center, Engineering Specifications and Standards Department (ESSD) Code 93, Lakehurst, NJ 08733, by using the self-addressed Standardization Document Improvement Proposal (DD Form 1426) appearing at the end of this document or by letter.

## CONTENTS

			<u>Page</u>
Paragraph	1. 1.1 1.2 1.3 1.3.1	SCOPE Scope Purpose General conditions and responsibilities Associated equipment	1 1 1 1
	2. 2.1 2.2	REFERENCED DOCUMENTS Issues of documents Non-Government documents	2 2 3
	3. 3.1	DEFINITIONS	5 5
	4. 4.1 4.1.1 4.1.2 4.1.3 4.1.4 4.1.5 4.1.6 4.2 4.3 4.3.1 4.3.1.1 4.3.1.2 4.3.1.3 4.3.1.4 4.3.2 4.3.2.2 4.3.2.3 4.3.2.2 4.3.2.3 4.3.2.4 4.3.3 4.3.3.4	GENERAL STATEMENT OF REQUIREMENTS Functional description	6 6 6 7 7 7 7 7 8 8 8 8 8 8 8 9 9 9 9 9 9 10 10 10 10 10 10 10 10 10 10 10 10 10
	4.3.4 4.3.4.1 4.3.4.2 4.3.4.3 4.3.4.4	Control, detecting set, infrared Location of unit Limits to normal operation attitude Precautions	11 11 11 11 11

## CONTENTS - Continued

			<u>Page</u>
Paragraph		Environmental limits	
	4.3.5	Control, sight, target tracking	11
	4.3.5.1	Location of unit	
	4.3.5.2	Limits to normal operation attitude	
	4.3.5.3	Precautions	L 2
	4.3.5.4	Mounting instructions	12
	4.3.5.5	Environmental limits	
	4.3.6	Indicator, video	12
	4.3.6.1	Location of unit	
	4.3.6.2	Limits to normal operation attitude	
	4.3.6.3	Precautions	
	4.3.6.4	Mounting instructions	
	4.3.6.5	Environmental limits	13
	5.	DETAILED STATEMENT OF REQUIREMENTS	
	501	AN/AAS-36 (IRDS)/aircraft interfaces	
	5.1.1	Mechanical1	
	5.1.1.1	WRA (outline dimension drawings)	14
	5.1.2	Aircraft installation retractable turret (typical)1	4
	5.1.3	Aircraft installation fixed turret (typical)	
	5.1.4	Thermal characteristic requirements	
	5.1.5	Receiver converter aircraft alignment accuracy requirement	
	5.1.6	Receiver-converter assembly - mechanical	14
	5.1.0	alignment check - retractable turret	15
	5.1.7	Receiver-converter assembly - mechanical	13
	3.1.7	alignment check - fixed turret	15
	5.2	Electrical	1.5
	5.2.1	Aircraft power	
	5.2.1.1	Aircraft power characteristics	
	5.2.2	Equipment power requirements	16
	5.2.2,1	AN/AAS-36 input power	16
	5.2.2.2	AN/AAS-36 input power requirements	
	5.2.2.3	IRDS/aircraft electrical system interface -	
	5.2.2.3.1	IRDS aircraft electrical system interface -	
	5.2.2.3.2	IRDS/lamp test power source interface	
	5.2.3	Interconnection diagrams	
	5.2.4	Cabling details	17
	5.2.5	Ground/bonding	
	5.2.5.1	Aircraft interconnecting cables	18
	5.2.6	Video characteristics	

## CONTENTS - Continued

			<u>Paqe</u>
Paragraph	5.3 5.3.1	AN/AAS-36 data system interfaces AN/AAS-36/data processing system interface ( P - 3 C )	18 18
	5.3.1.1 5.3.1.2 5.3.2 5.3.2.1 5.3.3	Data update timing requirements Data bit identification	19 20 20 20 21
	5.3.3.1 5.3.3.2 5.4 5.4.1	Synchro excitation reference Electrical zero	21 21 22 22

## FIGURES

			Page
1	Receiver converter, outline drawing	_	62
2			
	drawing	-	67
3	Control servomechanism, outline drawing	_	69
4	Control, detecting set, infrared, outline		
	drawing	-	71
5	Control, sight, target tracking, outline		
	drawing	-	72
6		-	73
7			
		-	77
8			
			78
			80
		-	81
11			0.0
			82
		-	83
13			0.4
1.4			84 85
			87
			-
		-	00
18			89
1.0	· · · · · · · · · · · · · · · · · · ·		
			91
			92
==			93
			93
23		_	94
24			
		_	95
25		_	96
26	IRDS interconnecting diagram		97
	2 3 4 5 6 7 8 9 10 11 12 13 14 15 16 17 18 19 20 21 22 23 24 25	Power supply/video converter, outline drawing	Receiver converter, outline drawing Power supply/video converter, outline draw in g

### TABLES

		Page
Table	I	IRDS input power requirements (maximum steady state)17
	II III IV	IRDS interwiring listing 23 Angle rate codes60 Metric equivalents inches to millimeters 79

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#### 1. SCOPE

- 1.1 <u>Scope.</u> This handbook establishes the physical and functional interface for aircraft installation of the AN/AAS-36 infrared detecting set (IRDS). The physical and electrical interfaces are defined for the IRDS supplier, the airframe contractor and the operational program.
- 1.2 <u>Purpose.</u> The defined interfaces establish the compatibility between cofunctioning elements and control the interface design. Any changes in these areas may affect the installation compatibility or operation. Contemplated changes affecting any of the defined area must be coordinated with all custodial and review activities.
- 1.3 <u>General conditions</u> responsibilities. The AN/AAS-36 IRDS was designed and is fabricated by Texas Instruments. Intended airborne installation of the IRDS is for either retractable or fixed turret applications for such aircraft as P-3B, P-3C, S-3A, etc. Target tracking by the IRDS is either manual or computer controlled, via on-board data processing systems, when applicable. Lockheed Aircraft Company designed and fabricates a turret retraction mechanism for P-3C IRDS installations. NADC developed the necessary software programs to control IRDS tracking for this configuration.
- 1.3.1 <u>Associated equipment.</u> The AN/AAS-36 interfaces with data processing systems such as the AN/AYA-8 [MIL-D-81347C(AS)] and AN/ASQ-114(V) [MIL-C-81332B(AS)], a synchro to digital converter such as the CV-2461 A/A [MIL-C-81344(AS)], aircraft power and lighting supplies and aircraft maintenance control devices.

#### 2. REFERENCED DOCUMENTS

2.1 <u>Issues of documents.</u> The following documents of the exact issue indicated, form a part of this handbook to the extent specified herein.

#### SPECIFICATIONS

MILITARY MIL-C-172C - Cases, Bases, Mounting; Mounts, Vibration. - Military Specification MIL-C-81332B(AS) 1 May 1967 for Computer, Digital AN/ASQ-114(V). - Military Specification MIL-C-81344(AS) for Signal Data Con-1 May 1968 verter CV-2461A/A. - Military Specification MIL-D-81347C(AS) for Data Analysis Pro-13 March 1974 gramming Group AN/AYA-8.

## NAVAL AIR SYSTEMS COMMAND

MIL-I-85295(AS) 15 April 1979

## - Military Specification

- Detecting Set, Infrared AN/AAS-36.

#### BUREAU OF NAVAL WEAPONS

WR-101, Part I dated (15 Feb 1968) - Electromagnetic Control Requirements for Advanced ASW Avionics System.

#### STANDARDS

#### MILITARY

MIL-STD-704A 9 August 1966 - Military Standard - Electric Power, Air-craft, Characteristics and Utilization.

MIL-STD-1472B 31 December 1974 Human Engineering Design Criteria for
 Military Systems Engineering and Facilities.

#### DRAWINGS

MILITARY

MS25213

- Control Panel, Aircraft Equipment, Typical Installations.

(Copies of specifications, standards, drawings and publications required by contractors in connection with specific procurement functions should be obtained from the procuring activity or as directed by the contracting officer.)

 $2.2 \ \underline{\text{Non-Government}} \ \underline{\text{publications.}}$  The following documents of the exact issue date indicated, form a part of this handbook to the extent specified herein.

#### ELECTRONIC INDUSTRIES ASSOCIATES

EIA-RS-343-A September 1969

- Electrical Performance Standard for High Resolution Monochrome Closed Circuit Television Camera.

### GENERAL ELECTRIC COMPANY

G.E. 7528383

- Device Specification - Line Receiver.

G.E. 7528376

- Device Specification - Line Driver.

### TEXAS INSTRUMENTS

T.I. 536993

Device Specification -Line Receiver (Equivalent to National -DM7820).

T.I. 536996-1

Device Specification - Line Driver (Equivalent to National DM7830).

Application for copies of non-government documents should be addressed to the Naval Air Systems Command, Washington, D C 20360, Attn: AIR-549332.

## 3. DEFINITIONS

3.1 <u>Symbols, abbreviations and acronyms.</u> Symbols, abbreviations and acronyms applicable to this handbook are defined as follows:

FT Feet FRP Fuselage Reference Plane GA Gauge GE General Electric Company GFE Government Furnished Equipment GND/GRD Ground Hz Hertz ICD Interface Control Document IRDS Infrared Detecting Set LCC Lockheed-California Company LED Light Emitting Diode LOS Line of Sight LSB Least Significant Bit LU-1 Logic Unit No. 1 MA Milliamperes MAX Maximum MHz Megahertz MIN Minimum MSB Most Significant Bit MSEC Milliseconds NOM Nominal OA Output Acknowledge Sec Second S/D Synchro to Digital SDC Signal Data Converter SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly O Phase	AC A/C AZ DC DIM DOM DPS	Alternating Current Aircraft Azimuth Direct Current Digital Input Multiplexer Digital Output Multiplexer Data Processing system Elevation
FRP Fuselage Reference Plane GA Gauge GE General Electric Company GFE Government Furnished Equipment GND/GRD Ground Hz Hertz ICD Interface Control Document IRDS Infrared Detecting Set LCC Lockheed-California Company LED Light Emitting Diode LOS Line of Sight LSB Least Significant Bit LU-1 Logic Unit No. 1 MA Milliamperes MAX Maximum MHz Megahertz MIN Minimum MSB Most Significant Bit MSEC Milliseconds NOM Nominal OA Output Acknowledge Sec Second S/D Synchro to Digital SDC Signal Data Converter SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly	EL ET	
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GND/GRD Ground Hz Hertz ICD Interface Control Document IRDS Infrared Detecting Set LCC Lockheed-California Company LED Light Emitting Diode LOS Line of Sight LSB Least Significant Bit LU-1 Logic Unit No. 1 MA Milliamperes MAX Maximum MHz Megahertz MIN Minimum MSB Most Significant Bit MSEC Milliseconds NOM Nominal OA Output Acknowledge Sec Second S/D Synchro to Digital SDC Signal Data Converter SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly	-	
ICD Interface Control Document IRDS Infrared Detecting Set LCC Lockheed-California Company LED Light Emitting Diode LOS Line of Sight LSB Least Significant Bit LU-1 Logic Unit No. 1 MA Milliamperes MAX Maximum MHz Megahertz MIN Minimum MSB Most Significant Bit MSEC Milliseconds NOM Nominal OA Output Acknowledge Sec Second S/D Synchro to Digital SDC Signal Data Converter SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly	GND/GRD	
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MSEC Milliseconds  NOM Nominal  OA Output Acknowledge  Sec Second  S/D Synchro to Digital  SDC Signal Data Converter  SS-3 Sensor Station 3  TBD To Be Determined  TBS To Be Supplied  TTSC Target Tracking Sight Control  TV Television  UF Microfarads  USEC Microseconds  VA Volt Amperes  VRMS Volts, Root Mean Square  WRA Weapon Replaceable Assembly		
NOM Nominal OA Output Acknowledge Sec Second S/D Synchro to Digital SDC Signal Data Converter SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly		
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Sec Second S/D Synchro to Digital SDC Signal Data Converter SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly	-	
S/D Synchro to Digital SDC Signal Data Converter SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly	-	
SDC Signal Data Converter SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly		2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2 2
SS-3 Sensor Station 3 TBD To Be Determined TBS To Be Supplied TTSC Target Tracking Sight Control TV Television UF Microfarads USEC Microseconds VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly	•	
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VA Volt Amperes VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly	UF	Microfarads
VRMS Volts, Root Mean Square WRA Weapon Replaceable Assembly	USEC	Microseconds
WRA Weapon Replaceable Assembly	VA	<u>-</u>
	VRMS	
0 Phase	WRA	
	0	Phase

#### 4. GENERAL STATEMENT OF REQUIREMENTS

4.1 <u>Functional description</u>. Infrared Detecting Set AN/AAS-36 is a modularized IR sensor system composed of the following six WRA's:

Receiver Converter, Infrared	R-2005/AAS-36
Power Supply/Video Converter	PP-7267/AAS-36
Control Servomechanism	C-9982/AAS-36
Control, Detecting Set, IR	C-9983/AAS-36
Control, Sight, Target Tracking	C-9984/AAS-36
Indicator Video	IP-1240/AAS-36

The receiver converter is installed in a fixed or retractable turret, preferably on the underside of the aircraft fuselage. Sensor operation is controlled by on-board operators by means of the control, sight, target tracking (hand control) in manual mode and by data processing system interfaces in computer track mode. In the computer track mode, the data processing system accepts IRDS gimbal position data, computes the angular difference between the LOS to the target and the platform boresight reference axis and provides azimuth and elevation rate commands to reposition the gimbals.

4.1.1 Receiver converter. The receiver converter contains the IR sensing unit mounted on a two-axis gimbal system. The outer turret housing rotates  $\pm 200^{\circ}$  from the FRP(YZ) of the aircraft with the azimuth gimbal. The elevation gimbals are not subjected to airloads, operating completely inside the turret housing within +16 and -820 limits referenced to the FRP(YZ).

The sensor has a two-position lens system providing two fields of view, 250 (diagonal) and approximately 80 (diagonal), selectable by the operator. Cooling for the detector elements is provided by a self-contained closed-cycle, cryogenic cooler. The individual IR image channels are amplified and operate a companion LED channel. These elements are converted to standard EIA imagery by mirror-sweeping these channels over a vidicon tube. Standard TV signal processing provides the image on the TV display.

The receiver converter is designed to operate satisfactorily over an ambient temperature range of  $-54\,^{\circ}\text{C}$  to  $+55\,^{\circ}\text{C}$ . At ambient temperatures below  $+20\,^{\circ}\text{C}$ , the unit maintains an internal temperature of approximately  $+25\,^{\circ}\text{C}$  by automatically-controlled heater elements. At ambient temperatures above  $+25\,^{\circ}\text{C}$  and up to a maximum steady state temperature of  $+55\,^{\circ}\text{C}$ , the receiver converter utilizes external ambient air and an air to air heat exchanger to maintain proper internal receiver-converter operating temperatures.

Because the receiver converter weight exceeds the lift capability of one or even two men as defined in MIL-STD-1472B, this WRA is provided with lift points for removal/replacement in the aircraft.

- 4.1.2 <u>Power supply/video converter.</u> This unit provides the interface between the aircraft 28 VDC and 115/200 V 400 Hz aircraft power sources and the IRDS system. The power supply provides  $\pm 14$  and  $\pm 15$  VDC for the sensor focus;  $\pm 5$ ,  $\pm 8$ ,  $\pm 10$ ,  $\pm 15$  VDC for sensor preamp, post amps and scanner circuits;  $\pm 5$ ,  $\pm 8.5$ ,  $\pm 40$  VDC for TV circuits; and  $\pm 15$  VDC for the gimbal angle indicator circuitry. Video signals from the receiver converter are combined with gimbal angle signals for presentation on the video indicator. The grey scale generator for setting video indicator controls is also located in this unit.
- 4.1.3 <u>Control servomechanism</u>. The unit accepts data processing system generated rate signals or target tracking position inputs to generate proper azimuth and elevation rate drive signals to position the receiver converter. Receiver-converter azimuth and elevation position feedback to the data processing system is provided for position compensation. Four power supplies provide ±30, ±15, and +5 VDC for servo and turret drive functions.
- 4.1.4 <u>Control</u>, <u>detecting set</u>, <u>infrared</u>. This unit provides all IRDS control functions except for video indicator controls and the sight control. All power to the AN/AAS-36 is controlled by the mode selector. A grey scale control switch is provided. Manual elevation and azimuth position controls permit selective positioning of the receiver-converter LOS with the mode selector in POS. Six status indicators and a bit control on demand only provide system status. A RTCL BRT (reticle brightness), LEVEL, and GAIN pots provide operator control of these functions. A focus control provides four, manual selectable focus options to the operator. FOV (field of view) and POL (polarity) switches permit operator selection of narrow or wide field of view and white or black hot images.

When the mode select is in CPTR TRK position, the IRDS will accept data processing system generated rate commands. Depressing the trigger switch on the sight control permits operator override of computer track but the target position to the computer is continuously available. In the MAN mode, receiver-converter LOS is directed by operation of the sight control.

4.1.5 <u>Control, sight, target tracking.</u> This unit provides for manual control of the receiver converter when the mode is set to MAN, and permits override of CPTR TRK. Overriding CPTR TRK, by depressing the trigger switch, disconnects data processing system control. The new turret position(s) directed by the operator are transferred to the data processing system when the switch is released.

Receiver-converter manual positioning is controlled by a thumb ball on top of the control - fore/aft motion causes correlated motion of LOS in elevation, left/right pressure causes the receiver LOS to move counterclockwise/clockwise proportionally to the applied pressure.

4.1.6 Indcator, video. This unit, a  $9^{\text{N}}$  display, provides the video image to the operator. Gimbal angle indicators located on the left side and top of the unit provide direct readout of the receiver-converter LOS relative to the aircraft. The unit provides a 32:1 contrast ratio with a capability of displaying ten grey shades.

This unit requires 115 V 400 Hz aircraft power, and is a self-contained unit. Power to the unit is controlled by the IRDS control. Brightness and contrast controls are operator adjustable. A power on/off switch is also provided. Impedance switching between hi and 75 ohms is provided on the rear as are two triax video connectors.

- 4.2 Overall characteristics. The operational requirements of the IRDS as well as the sensitive infrared receiver performance characteristics such as spectral bandpass, square wave response, minimum resolvable temperature and noise equivalent temperature differential are classified (Confidential) and may be obtained from corresponding paragraph references in AS-3900A.
- 4.3 Aircraft installation. The following provides installation limitations and precautions for the six IRDS weapons replaceable assemblies.

#### 4.3.1 Receiver converter.

4.3.1.1 Location of the unit. This unit contains the gimbaled receiver. Its aperture must be mounted so that energy can be received from at least the lower hemisphere under the aircraft. The outline dimension drawing (see figure 1) defines the aperture location with respect to the mounting structure and shows gimbal angle coverage. The lower forward portion of the aircraft fuselage is a preferred location.

Buffeting that could be caused by propellers or skin discontinuities should be avoided.

Damage to the optical window that could be caused by debris from the landing gear or by leaks from a hydraulic system should be avoided.

4.3.1.2 Limits to normal operation attitude. The forward direction is shown on the outline dimension drawing. The unit should be mounted parallel to aircraft FRP to provide correct gimbal angle readouts and prevent tilting of the displayed infrared image. Receiver-converter alignment requirements are defined in paragraph 5.1.5.

#### 4.3.1.3 Precautions.

- a. Avoid sharp bends in all cables
- b. Maximum length of cables to the receiver converter is 40 feet
- c. Provide access at top for connectors
- d. Avoid excessive loading by the mounting structure that could cause gimbal binding
- e. Maintain air space and circulation around upper shroud to maintain cooling
- f. Provide overhead access for hoisting into place (see figure 1 for hoisting eye location)
- g. Provide access for boresight pins
  - 10 Azimuth pin shown on outline dimension drawing
  - Elevation pin access is attained by removal of the 20-inch diameter turret
- h. Provide proper grounding of unit for personnel safety
- i. Provide access to elapsed time meter when in stowed position
- i. Provide access for turret window cleaning
- 4.3.1.4 Mounting instructions. A rigid mounting structure is required that securely restrains the unit at the four perimeter locations.
  - 4.3.2 Powe supply video converter.
- 4.3.2.1 Location of unit. The Power Supply Video Converter, PP-7267/AAS-36 will be located in a conventional equipment mounting area as near as possible to the other interconnected WRA'S to minimize cable lengths.
- 4.3.2.2 Limits to normal operation attitude. The Power Supply Video Converter, PP-7267/AAS-36 may be operated in any attitude. For easiest maintenance, it should be approximately level.

## 4.3.2.3 Precautions.

- a. Avoid sharp bends in all cables
- b. Provide access in front of unit for electrical connectors and elapsed time meter
- c. Provide proper grounding for personnel safety
- d. Provide air space and circulation around filters in front and the fan outlet in the rear of unit
- e. Avoid excessive loading in mounting that could damage case
- f. Provide clearance for drainhole in bottom of unit
- g. Provide access for filter cleaning maintenance
- 4.3.2.4 <u>Mounting instructions</u>. The power supply-video converter is designed for use on a mounting base such as prescribed in MIL-C-172C except for non-standard size and fastener spacing.

#### 4.3.3 <u>Control-servomechanisms.</u>

- 4.3.3.1 <u>Location of unit.</u> The Control-Servomechanism, C-9982/AAS-36 will be located in a conventional equipment mounting area as near as possible to the other interconnected WRA's to minimize cable lengths.
- 4.3.3.2 <u>Limits to normal operation attitude.</u> The Control-Servomechanism C-9982/AAS-36 may be operated in any attitude. For easiest maintenance, it should be approximately level.

## 4.3.3.3 Precautions.

- a. Avoid sharp bends in all cables
- b. Provide access in front of unit for electrical connectors and elapsed time meter
- c. Provide proper grounding for personnel safety
- d. Provide air space and circulation around filters in front and the fan outlet in the rear of unit
- e. Avoid excessive loading in mounting that could damage case

- f. Provide clearance for drainhole in bottom of unit
- q. Provide access for filter cleaning maintenance
- 4.3.3.4 Mounting instructions. The Control-Servomechanism C-9982/AAS-36 is designed for use on a mounting base such as described in MIL-C-172C except for non-standard size and fastener spacing.
- 4.3.4.1 Location of unit. Control, Detecting Set, Infrared, C-9983/AAS-36 shall be mounted in the IRDS AN/AAs-36 operator's station as near as possible to interconnecting units to minimize cable lengths (40 foot maximum cable length). The unit should be located for easy access to controls in flight. Unit is to be operated in conjunction with the Control, Sight, Target Tracking, C-9984/AAS-36 and the Indicator, Video, IP-1240/AAS-36.
- 4.3.4.2 Limits to operation attitude. Control, Detecting Set, Infrared, C-9983/AAS-36 may be mounted in any attitude that meets paragraph 4.3.4.1 requirements.

#### 4.3.4.3 Precautions.

- a. Avoid sharp bends in all cables
- b. Provide service length in cables for unit installation and removal
- co Provide proper grounding for operator safety
- 4.3.4.4 Mounting Instructions. Control, Detecting Set, Infrared, C-9983/AAS-36 shall be mounted as described in MS25213.
- 4.3.4.5 Environmental limits. The Control, Detecting Set, Infrared, C-9983/AAS-36 is limited to 15,000 feet altitude operation (may be operated at higher altitudes in a pressurized area).
  - 4.3.5 Control, sight. target tracking.
- 4.3.5.1 Location of unit. Control, Sight, Target Tracking C-9984/AAS-36 will be located in the IRDS operator's station as near as possible to interconnecting units in order to minimize cable lengths (40 foot maximum cable length). The unit should be located for ease of operation. The unit is operated in conjunction with the Control, Detecting Set, Infrared, C-9983/AAS-36 and the Indicator, Video IP-1240/AAS-36.

4.3.5.2 <u>Limits to normal operation attitude.</u> Control, Sight, Target Tracking C-9984/AAS-36 may be mounted in any attitude for operator convenience.

#### 4.3.5.3 Precautions.

- a. Avoid sharp bends in cable
- b. Provide service length in cable for unit installation and removal
- c. Provide proper grounding for operator's safety
- 4.3.5.4 <u>Mounting instructions.</u> The Control, Sight, Target Tracking C-9984/AAS-36 shall be mounted similar to the method described in MS25213 except spacing of fasteners is not standard.
- 4.3.5.5 <u>Environmental limits</u>. The Control, Sight, Target Tracking C-9984/AAS-36 is limited to 15,000 feet ambient altitude operation (may be operated at higher altitudes in a pressurized area).

#### 4.3.6 <u>Indicator</u>, video.

- 4.3.6.1 Location of unit. The Indicator, Video IP-1240/AAS-36 will be located in the IRDS operator's station, as near as possible to interconnecting units, "to minimize cable lengths (maximum cable length is 40 feet). The indicator should be located for easy access to operator controls and should be positioned for comfortable viewing (18 to 24 inches from operator's eyes). The indicator is operated in conjunction with the Control Detecting Set, Infrared, C-9983/AAS-36 and the Control, Sight, Target Tracking, C-9984/AAS-36.
- 4.3.6.2 Limits to normal operation attitudes. The Indicators, Video IP-1240/AAS-36 may be mounted in any attitude for operator convenience.

## 4.3.6.3 Precautions.

- a. Avoid sharp bends in all cables
- b. Provide proper grounding for operator's safety
- c. Provide air space and circulation around bottom intake filters and fan outlet in rear of unit
- d. Provide access to air filter in bottom of unit for maintenance

- e. Mount in an area of low illumination and protect screen from glare and reflected light
- 4.3.6.4 <u>Mounting instructions.</u> The Indicator, Video IP-1240/AAS-36 shall be mounted by the 4 holes in the bottom. The 0.19 inch clearance provided by the mounting pads shall not be obstructed to insure adequate cooling air inlet. Leave space for removal of air filters.
- 4.3.6.5 <u>Environmental limits</u>. The Indicator, Video IP-1240/AAS-36 is limited to 15,000 feet altitude operation (may be operated at higher altitudes in a pressurized area).

#### 5. DETAILED STATEMENT OF REQUIREMENTS

5.1 <u>AN/AAS-36</u> (IRDS)/aircraft interfaces. The infrared detecting set consists of six weapon replaceable assemblies requiring electrical interconnection with each other and with other aircraft systems. Mechanical interface details including WRA outline dimension drawings, aircraft location and installation requirements, thermal characteristics etc. are presented in paragraph 5.1. Electrical interface details including input power requirements, cable division and aircraft subsystem interface interconnection, connector types, detail pin and wire assignments, grounding, shielding, interface timing, etc. are presented in paragraphs 5.2 and 5.3.

Every consideration shall be given in location of equipment and in design of installation details to promote operator efficiency and maintenance facility.

### 5.1.1 Mechanical.

- 5.1.1.1 WRA(outline dimention drawings). Outline dimension drawings for the IRDS WRA's are provided in figures 1 through 6. The outline drawings include weight, center of gravity, maximum heat dissipation and special installing instructions/notes, in addition to the dimensional information for each WRA.
- 5.1.2 <u>Aircraft installation [retractable turret (typical).</u> The location and mechanical interface for the IRDS receiver converter is shown in figure 7 for a typical (P-3C) retractable turret installation.
- 5.1.3 Aircraft installation fixed turret(typical) The location and mechanical interface for the IRDS receiver converter is shown in figure 8 for typical fixed turret installations.
- 5.1.4 Thermal character/requirements. The heat dissipation, air inlet and air outlet sizes and locations for each IRDS unit are given in outline figures 1 through 6. Minimum distance from an obstruction to an air outlet opening is also indicated in the outline figures.
- 5.1.5 Receiver converter aircraft alignment accuracy requirements. In the computer track mode, the data processing system, utilizing sensed target location (relative to the aircraft), will provide IRDS LOS pointing (rate) commands. The computer will utilize target azimuth, target range and aircraft altitude to continuously predict IRDS elevation and azimuth angles to intercept the designated target. These angles will utilize the fuselage reference planes (FRP) as the origin. Proper rate (az and el) commands will be generated and provided to the IRDS to position the LOS on the target. A designated

target will fall within the narrow FOV under computer control when all external system errors are limited to 2.4 degrees elevation and 3.2 degrees azimuth (3 sigma values) and the stabilized turret platform is aligned to the FRP within 0.50 degree.

Note: Any relaxation of this installation requirement will result in a decrease in the allowable system error to provide the same acquisition probability.

5.1.6 Receiver-converter assembly - mechanical alignment check -

should be accomplished when a receiver converter is fitted to a retraction package.

- a. Down stop engagement on both sides shall be adjusted for minimum contact unbalance with the receiver converter in its fully extended position (no extension load), to prevent excessive warpage within the receiver-converter main casting.
- b. With the receiver converter fully extended, the angular dimension of 72° ±0° 15' shown in figure 7 should be verified.
- 5.1.7 Receiver-converter assembly mechanical alignment check fixed turret (refer to figure 8).
- 5.2 Electrical.
- 5.2.1 Aircraft powerl
- 5.2.1.1 Aircraft power characteristics. The characteristics of the electrical power supplied to the AN/AAS-36 shall be as follows:
  - a. AC Power The AC power system shall be a 3 phase, 4-wire WYE System, having a nominal voltage of 115/200 VRMS and a nominal frequency of 400 Hertz. The neutral point of the source of power is connected to ground and the ground is considered the fourth conductor. The AC power characteristics shall be within the limits of MIL-STD-704A for category B equipment.
  - b. DC Power The DC power system shall be a 2-wire, grounded system having a nominal voltage of 28 VDC. The negative of the power source is connected to ground and ground is considered the second wire. The DC power characteristics shall be within the limits of MIL-STD-704A for category B equipment.

#### 5.2.2 Equipment power requirements.

- 5.2.2.1 <u>AN/AAS-36 input power.</u> The AN/AAS-36 equipment shall operate within specified limits when supplied with category B, MIL-STD-704A power except as modified herein. The equipment shall operate within the bounds of MIL-STD-704A, figure 3, limits 2 and 3, except the lower limit of curve 3 shall not fall below 80 volts. Equipment malfunction may occur when the input voltage exceeds the above limits but remains within limits 1 and 4 (MIL-STD-704A, figure 3). However, no damage to the equipment shall result when subjected to the following conditions:
  - a. Loss of power Accidental or deliberate stoppage of electrical power, regardless of the time in equipment operating cycle and regardless of duration of stoppage.
  - b. Under and overvoltage Voltages below the minimum or up to 125 percent of the maximum emergency steady state specified in MIL-STD-704A.
  - c. Transients Transient voltage surges that, when converted to their equivalent step functions, are within the limits of figure 3 of MIL-STD-704A.
  - d. Phase Reversal or Phase Loss The reversal of any AC phase or the loss of any combination of AC phases.

Normal operation of equipment shall be automatically resumed upon return of the input voltage to levels within limits 2 and 3 (MIL-STD-704A, figure 3) as modified herein, and/or restoration of proper rotation.

5.2.2.2 <u>AN/AAS-36 input power requirements.</u> Maximum power requirements for the infrared detecting set are as follows:

3	phase	115/200	VRMS	3000	VA
28	VDC			140	VA
18	VDC			2.8	VΑ

The IRDS power requirements as a function of operating mode are presented in table I.

TABLE I.	<u>IRDS</u>	<u>input</u>	<u>power</u>	<u>requirements</u>	<u>(maximum</u>	<u>steady</u>	<u>state).</u>
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Power Input	Standby Excluding Heat Exchanger	Operational Modes Excluding Heat Exchanger And Receiver Slewing	Operational Modes Receiver Slewing Power Only	Operational Modes Heat Exchanger Only		
115 VAC, 30 28 VDC 18 VDC	613 VA 7.26 VA	955 VA 14.56 VA 18 VA	297 VA - -	1341 VA 3.64 VA -		

IRDS panel lighting requires 5 to 28 VDC power (0.5 amps at 28 VDC)

- 5.2.2.3 <u>IRDS/aircraft electrical system interface.</u> Overall interface of the IRDS and aircraft 3 phase 115/200 VRMS and 28 VDC primary power sources and 18 VDC indicator lamp power source is presented in figure 9.
- 5.2.2.3.1 <u>IRDS/aircraft electrical system interface.</u> A 5 to 28 VDC panel edge light power signal is provided to the IRDS control, detecting set. The edge panel light load shall be 0.5 amp maximum.
- 5.2.2.3.2 IRDS/lamp test power source interface. An 18 VDC indicator lamp test signal is provided to the IRDS control, detecting set. The indicator lamp test load shall be 1.0 amp maximum.
- 5.2.3 <u>Interconnection diagrams.</u> Electrical interconnections are required between the six IRDS weapon replaceable assemblies (WRA) and between the applicable IRDS WRA's and other aircraft systems. Cable division and a cable connection identification chart are presented in figure 10, IRDS interconnection block diagram.
- 5.2.4 <u>Cabling details.</u> Detailed cabling information, including connector pin assignments, and conductor signal function for the IRDS and associated aircraft subsystem interconnections (illustrated in figure 10) is presented in an interwiring listing (table II) on pages 23 through 59. This listing provides the point-to-point wiring requirements between IRDS WRA's and between IRDS and associated aircraft subsystems. The wiring data is applicable for any IRDS installation and does not identify wire segments peculiar to a particular installation.
- $5.2.5~\underline{\text{Ground/bonding.}}$  The ground/bonding practices employed in the installation of IRDS electronic circuits in the aircraft shall be in

accordance with requirements of WR-101 Part I and as qualified herein. IRDS grounding, bonding of cable chassis connectors to IRDS WRA's and preparation of IRDS WRA metallic mating surfaces, for bonding, where applicable, shall be in accordance with WR-101 Part I.

- 5.2.5.1 <u>Aircraft interconnecting cables</u>. All interconnecting cables between the receiver-converter WRA and other IRDS WRA's and between the receiver-converter WRA and other aircraft circuits shall include an overall tight braid shield which will be adequately terminated on the appropriate back-shell of each connector. The overall shield shall not be interconnected through connector pins. Conductive "Y" or "T" transitions or comparable components shall be used at cable splits to insure that no discontinuities in the overall shield will occur in branched cables.
- 5.2.6 <u>Video characteristics</u>. Independent and essentially identical video output signals are provided at each of three output connectors on the power supply/video converter WRA (2J7, 2J8, 2J9). Each output is single ended and capable of driving a properly matched 75 ohm video line. TV and timing and amplitude format of the video signals is in accordance with EIA RS-343-A, 4:3 aspect ratio, 875 horizontal line rate at 30 frames/see, with 2:1 interlace. The output connectors are triaxial type (DAGE 2677-1). One video output, (2J7), is connected to the video indicator WRA (6J2) via 75 ohm triaxial transmission line (Raychem 7524D511 or equivalent). Two video outputs (2J8, 2J9) are spares and provided as Inputs to a GFE conventional video recording/playback unit, a GFE auxiliary display unit or a GFE data link unit. Connections between the video output connectors of the power supply and the auxiliary GFE shall be as described for the video indicator interface.
- 5.3 <u>AN/AAS-36 data system interfaces.</u> The IRDS provides data interfaces with aircraft data processing systems such as (for P-3C installations) the AN/ASQ-114 Digital Computer/AN/AYA-8 Data Analysis Programming group and the CV-2461 A/A Signal Data Converter. Figure 11 is a functional illustration of a typical (P-3C) IRDS/aircraft data processing system interface configuration.
- 5.3.1 AN/AAS-36 data processing system interface (P-3C). In the CPTR TRK mode of operation, the IRDS will receive rate commands from the P-3 computer via the digital output multiplexer (DOM) channel 14 of logic unit 1 (LU-1) of data analysis programming group AN/AYA-8. Azimuth and elevation gimbal rate signals will be provided to the IRDS via a one way digital data transfer in accordance with the following:
  - a. Computer program initiates a normal Output buffer for the channel assigned to the DOM.

- b. The DOM sets the output data request (ODR) line indicating it is in a condition to accept data.
- c. The CP-901 1/0 subunit detects the ODR and at its convenience places 12 data bits and 4 address bits (identifies) peripheral to accept data) on 16 computer data lines.
- d. The DOM transmits the 12 data bits to each peripheral being serviced by the assigned computer channel.
- e. The computer sets the output acknowledge (OA) line indicating data is stable and ready for sampling.
- f. The DOM decodes the address bits and sends the OA to the applicable peripheral.
- q. The peripheral sample data.
- h. Computer drops to OA to DOM.
- i. DOM drops the OA to peripheral.

The data lines to peripheral will be stable during the period when the OA is active (logic '1") in accordance with the timing diagram presented in figure 12. Overall interface of LU-1 DOM channel 14 with IRDS control, servomechanism unit is illustrated in figure 13. Detailed electrical and mechanical Information for individual data line 1/ and the output acknowledge control line between LU-1 and IRDS control servomechanism unit is provided in figures 14 through 16. Logic voltage levels, transition times and interface timing requirements specified shall exist at the line driver output circuit terminals with the specified maximum cable length and circuit loads connected.

- 5.3.1.1 <u>Data update timing requirements.</u> System design assumes 'hat the computer will supply data updates (azimuth and elevation angle rate commands) at approximately a 10 Hz rate. To discriminate between data updates and between the first (AZ) and second (EL) words of data updates, the IRDS control servomechanism imposes the following timing requirements upon data from the computer (see figure 17).
- 1/ Electrical and mechanical interface details for data bits 00 and 11, LSB and MSB respectively, is provided. Details for data bits 01 through 10 are identical with the exception of connector pin assignment, which can be obtained from figure 13.

- a. In general a data word from the computer is interpreted as the first word of a data update unless timing requirement b., below is satisfied.
- b. A word is recognized as the second word of an update only if it is received within 5 milliseconds of a previous word that was recognized as the first word of a data update.
- 5.3.1.2 <u>Data bit identification</u>. The angle rate commands shall be in sign-magnitude format as shown in table III. The sign (bit 11) convention is as follows:
  - a. Azimuth when viewed from above, the aircraft centerline looking forward shall be 0°, positive angles CW and negative angles CCW.
  - b. Elevation when viewed from the cockpit, looking forward (parallel to aircraft centerline) shall be 0°, positive angles up and negative angles down.
- 5.3.2 AN/AAS-36 data processing system status logic interface. The IRDS control servomechanism unit will provide two status signals to the data processing system. A typical (P-3C) status logic interface of the control servomechanism unit with the data processing system is presented in figure 18. Detailed electrical and mechanical information for the individual status signals is presented in figures 19 and 20. Voltage levels specified shall exist across the line driver output circuit terminals with the specified maximum cable lengths and circuit loads connected.
- 5.3.2.1 <u>IRDS status logic signals.</u> The two status signals supplied by the IRDS to the aircraft computer are:
  - a. Computer track informs computer that IRDS mode select switch is in computer track position and IRDS equipment is not performing built-in test (BIT).

- b. Manual track override informs computer that the trigger of the target tracking sight control is depressed, i.e., subsystem is in manual track mode.
- 5.3.3 <u>AN/AAS-36</u> synchro data interface. The IRS control servomechanism unit will provide azimuth and elevation gimbal position readout signals to the aircraft data processing systems, in synchro form. The gimbal position signals will utilize 11.8 V, 400 Hz, 3 wire synchro format compatible with synchro to digital converters such as the CV-2461 A/A. Typical (P-3C) electrical and mechanical synchro interface details are presented in figures 21 and 22.
- 5.3.3.1 Synchro excitation reference. The aircraft data processing system must provide a 26 V, 400 Hz excitation signal for the azimuth and elevation position synchro transmitters in the IRDS receiver-converter, via the control servomechanism unit. Detailed electrical and mechanical interface information for the synchro reference signal is presented in figure 23. Typical (P-3C) overall wiring details for the IRDS synchro signals and the 26 VAC reference is provided in figure 24.
- 5.3.3.2 <u>Electrical zero.</u> The following method can be implemented to provide a coarse electrical zero verification. This is not an accurate test, but will determine which of two possible null positions correspond to electrical zero.

All signals necessary for this determination are present on 3J3, the control-servomechanism WRA to aircraft interface connector. They are R1 (26 VAC 400 Hz LO), R2 (26 VAC 400 Hz HI), AS1, AS2, AS3 (azimuth synchro S1, S2 and S3) and ES1, ES2, ES3 (elevation synchro S1, S2 and S3). Detail pin connections are provided in figure 24. The AN/AAS-36 must be energized through 3J3. A means of break-out of these signals will be required. An oscilloscope with two vertical input channels will be used with horizontal time base synchronized to channel 2. Convert R2 to channel 2 vertical input.

#### Procedures:

- a. Initially point the system LOS to approximately boresight. All cables must be connected for test, but system power (mode switch) may be off.
- b. For azimuth axis, connect AS1 and AS3 together, and to channel 1 of the scope. Connect AS2 to R1 together and connect to scope return if the proper electrical zero has been chosen, the two waveforms displayed will be approximately in time phase. If incorrect electrical zero has been chosen, the two waveforms will be approximately 180° out of time phase.

- c. For elevation axis, repeat b. except use ES1, ES2 and ES3 instead of AS1, AS2 and AS3.
- 5.4 <u>AN/AAS-36</u> <u>electrical interlocks</u>.
- 5.4.1 <u>AN/AAS 36 maintenance switch.</u> The IRDS receiver-converter will interface with a remote receiver-converter maintenance switch. The maintenance switch will be a 3 position device which establishes the following operating conditions:
  - Upper position (normal) normal receiver converter operation
  - b. Center position (gimbal disable) normal receiverconverter operation except power (+30 VDC) is removed from the gimbal drive mechanism.
  - c. Lower position (brake release) same as center Position except, gimbal brake release connections are made through the maintenance switch to the receiver-converter. Brake release high (Hi), +28 VDC (when enabled) and brake release low (Lo), a ground.

Figure 25 details the overall interfaces of the receiver converter and the q aintenance switch.

- 6. COGNIZANCE
- 6.1 This handbook is under the engineering cognizance of AIR-549332.

Preparing Activity-NAVY AS Project No. 5855-0028

TABLE II. IRDS interwiring list.

REMARKS	NO CONTACT	NO CONTACT	NO CONTACT	75 OHM VIDEO	RG-108 TWIN AX SHIELD TERMINATED AT	1J1-F AND 2J4-F	NOT USED	NOT USED	SHIELDED TWISTED PAIR	(SHIELD TO NO. 19)	TWISTED TRIPLET, W/	No. 33	SHIELDED TWISTED PAIR	SHIELD TO NO. 19)	
WIRE				22	22				22	22	22	22	22	22	
CURR									1.6	1.6	r.	٠.	1.6	1.6	
FUNCTION				VIDEO HI	VIDEO LO	VIDEO SHIELD			POST AMP +10 VDC HI	POST AMP +10 VDC RETURN	FOCUS +15 VDC	FOCUS -15 VDC	POST AMP -9 VDC HI	POST AMP -9 VDC RETURN	
TO CONNECTOR PIN				234-D	2J4-E	2J4-F			234-3	234-K	2J4-L	2J4-M	2J4-N	2J4-P	
FROM CONNECTOR PIN	1J1-A	1J1-B	1J1-C	1J1-D	1J1-E	1J1-F	1J1-G	1J1-H	1.11-3	1J1-K	1J1-L	1J1-M	1J1-N	1J1-P	
WIRE NO.	-	8	m	#	ß	9	7	80	6	10	=	12	13	<del>1</del>	

TABLE II. IRDS interwiring list. - Continued

REMARKS	MISTER BATE	UTUJ GTCTNI	SHIELDED TWISTED PAIR	$\int$ (SHIELD TO NO. 19)	SHIELD TERMINATED AT 1J1-V AND 2J4-V	SHIELDED TWISTED PAIR	(SHIELD TO NO. 19)	SHIELDED TWISTED PAIR	$\int$ (SHIELD TO NO. 28)	TWISTED PAIR	AT 28 VDC	•	5 VDC SWITCHED	SHIELD TERMINATED AT 1J1-ZE AND 2J4-ZE	5 VDC SWITCHED
WIRE SIZE	22	22	22	22		22	22	25	22	22	55	55	22		22
CURR	1.2	1.2	1.8	1.8	0	۶.	۲.	.02	.02	.13	.13		.002		9.
FUNCTION	+5 VDC BITE RETURN	+5 VDC BITE HI	PREAMP +10 VDC HI	PREAMP +10 VDC RETURN	SHIELD FOR WIRES NO. 9-10,13-14,17-18,20-21	PREAMP SENSE HI	PREAMP SENSE RETURN	+10 VDC SENSE HI	+10 VDC SENSE RETURN	SYSTEM INTERLOCK	SYSTEM INTERLOCK	SPARE	OVERHEAT HI	SHIELD FOR WIRES NO. 22-23, 40-41	CAMERA PREHEAT
TO CONNECTOR PIN	2J4-R	2J4-S	2J4-T	2.74-0	2J4-V	M-4-C2	2J4-X	2J4-Y	274-2	2J4-ZA	2J4-ZB	2J4-ZC	2J4-ZD	2J4-ZE	2J4-ZF
FROM CONNECTOR PIN	1J1-R	1J1-S	1J1-T	1J1-U	1J1-V	1J1-W	1J1-X	1J1-Y	131-2	1J1-ZA	1J1-ZB	1J1-ZC	1J1-ZD	1J1-ZE	1J1-ZF
WIRE NO.	15	16	17	18	19	20	21	22	23	172	25	92	27	28	53

TABLE II. IRDS interwiring list. - Continued

REMARKS				TWISTED TRIPLET W/ NO. 11,12	TWISTED TRIPLET WITH	NO. 49	NO LOAD IN UNIT 2		5 VDC SWITCHED	NO LOAD IN UNIT 2		NO. 28)	SHIELDED TWISTED TRIPLET WITH NO. 44,45	SHIELDED TWISTED TRIPLET WITH NO. 46,47
WIRE SIZE	22	22	22	22	50	50	22	22	22	22	50	50	22	22
CURR				č.	3.0	0.4			.002		4.5	4.5	.01	0.
FUNCTION	SPARE	SPARE	SPARE	±15 VDC RETURN	+14 VDC	±14 VDC RETURN	RECEIVER TOO COLD	SPARE	RECEIVER BITE	RECEIVER BITE INHIBIT	LED +10 VDC HI	LED +10 VDC RETURN	BEAM DRIVE IN	VERT SYNC
TO CONNECTOR PIN	2J4-ZG	2J4-ZH	234-21	234-23	2J4-ZK	2J4-ZM	2J4-ZN	2J4-ZP	234-20	2J4-ZR	2J4-ZS	2J4-ZT	2J4-ZU	2J4-ZV
FROM CONNECTOR PIN	1J1-ZG	1J1-ZH	1J1-ZI	1J.1-ZJ	1J1-ZK	1J1-ZM	1J1-ZN	1J1-ZP	131-20	1J1-ZR	1J1-ZS	1J1-ZT	1J1-ZU	1J1-ZV
WIRE NO.	30	31	32	33	34	35	36	37	38	39	0 †	41	42	#3

FABLE II. IRDS interwiring list. - Continued

REMARKS	SHIELDED TWISTED TRIPLET WITH NO. 42								SHIELDED TWISTED	TRIPLET WITH NO. 43	SHIELD TERMINATED AT 1J1-AA AND 2J4-AA	TWISTED TRIPLET W/ NO. 34, 35			NO CONTACT	NO CONTACT	TWI JO AIR		5 VDC SWITCHED	
WIRE SIZE	22	22	22	22		50	22	22			22	22	. 25	·						
CURR	.03	.03	.03	.03		3.0					.01	.01	.02							
FUNCTION	HORIZ DRIVE	CATHODE DRIVE	DARK CURRENT SAMPLE	CAMERA PEAK DET ENABLE	SHIELDS FOR WIRES NO. 42,44,45 AND 43,46,47	-14 VDC	SPARE	SPARE			SCAN SYNC	SCAN SYNC RETURN	CAMERA BITE							
TO CONNECTOR PIN	2J4-ZW	2J4-ZX	2J4-ZY	274-22	2J4-AA	2J4-BB	2J4-CC	2J4-DD			2J4-GG	2J4-HH	234-33							
FROM CONNECTOR PIN	1J1-ZW	1J1-ZX	1J1-ZY	1J1-ZZ	1J1-AA	1J1-BB	1J1-CC	1J1-DD	1J1-EE	1J1-FF	1J1-GG	1J1-HH	1J1-JJ							
WIRE NO.	11 11	45	917	247	81	617	50	51	52	53	54	55	26							

TABLE II. IRDS interwiring list. - Continued

REMARKS			SHIELDED TWISTED QUAD SHIELD TERMINATED AT	1J1-PP AND 2J4-PP		TWISTED PAIR	NO CONTACTS IN 1J2	NO CONTACT IN 1J2	NO CONTACT IN 1J2	NO CONTACT		TWISTED TRIPLET NO CONTACTS IN 1J2		NO CONTACT	NO CONTACT
WIRE	22	22	22	22		55	22	22	22		22	22	55		
CURR	ε.	∞.	ĸ.	2.0											
FUNCTION	CAMERA +40 VDC	CAMERA +8.5 VDC	CAMERA -8.5 VDC	CAMERA RETURN	SHIELD FOR WIRES NO. 57-60	SPARE	SPARE	SPARE	SPARE		SPARE	SPARE	SPARE		
TO CONNECTOR PIN	2J4-KK	2J4-LL	2.J.4-MM	2.J.4-NN	2J4-PP	2J2-V	2J2-W	2J2-C	2J2-F		2J3-A	2J3-B	2J3-C		
FROM CONNECTOR PIN	1J1-KK	1J1-LL	1J1-MM	1J1-NN	1J1-PP	1J2-A	1J2-B	1J2-C	1J2-D	1J2-E	1J2-F	132-6	1J2-H	1J2-J	1J2-K
WIRE NO.	57	58	59	09	61	62	63	<b>19</b>	65	99	19	68	69	70	7.1

TABLE II. IRDS interwiring list. - Continued

REMARKS		NO CONTACT	NO CONTACT		TWISTED PATE	0.15 V MAX LINEDROP	TWISTED PATE	O.15 V MAX LINEDROP	TWISTED PAIR	O.25 V MAX LINEDROP	TWISTED PAIR	0.25 V MAX LINEDROP	NO CONTACT IN 1J2			
WIRE	SIZE		50		8	8	50	2	20	8	20	20	22			
CURR	AMP		0		1.0	1.0	1.0	1.0	1.1	1.1	1.1	1.1				
FUNCTION		·	SAFETY GROUND	-	SCAN -5 VDC HI	SCAN -5 VDC RETURN	SCAN +5 VDC HI	SCAN +5 VDC RETURN	SCAN +15 VDC HI	SCAN +15 VDC RETURN	SCAN -15 VDC HI	SCAN -15 VDC RETURN	SPARE		•	
00 N	ZIG		233-33	•	233-20	2J3-ZR	2J3-ZN	2J3-ZP	2J3-EE	2J3-FF	2J3-GG	2J3-НН	2J3-ZT			
FROM	Z Z	1J2-L	1J2-M	1J2-N	1J2-P	1J2-R	132-8	1J2-T	1J2-U	1J2-V	1J2-W	1J2-X	1J2-Y			
WIRE	2	72	73	<b>1</b> 2 €	75	92 .	77	78	79	8	81	82	83			_

TABLE II. IRDS interwiring list. - Continued

REMARKS	NO CONTACT IN 1J2		INTERNALLY CONNECTED. DO NOT USE.	TWISHED DATE	NO CONTACTS IN 1J2	NO CONTACT	NO CONTACT	TWISTED PAIR	RELAY SWITCHED	NO CONTACT	NO CONTACT				
WIRE	22	22		22	22	22	22	22	25			50	50		
CURR		.13										2.0	2.0		
FUNCTION	SPARE	SYSTEM INTERLOCK		SPARE	SPARE	SPARE	SPARE	SPARE	SPARE			+28 VDC HI	28 VDC RETURN		
TO CONNECTOR PIN	2J3-ZA	1J2-ZB		2J2-A	2J2-B	2J2-G	2J2-Н	2J3-D	2J3-E			2J3-KK	2J3-LL		
FROM CONNECTOR PIN	132-Z	1J2-ZA	4.31-3	1J2-ZC	1J2-ZD	1J2-ZE	1J2-ZF	132-2G	1J2-ZH	132-21	132-23	1J2-ZK	1J2-ZM	1J2-ZN	1J2-ZP
WIRE NO.	₩8	85	98	87	88	89	6	9	92	93	<b>†6</b>	95	96	46	. 98

TABLE II. IRDS interwiring list. - Continued

REMARKS	NO CONTACT	NO CONTACT	AN PATACT	87 <b>8</b> 78 3	NO CONTACT	N CONTACT	NC CONTACT	NO CONTACT	NO CONTACT	SHORT TOGETHER FOR NORMAL OPEN FOR	FOR REMOTE GIMBAL	SUPPLY EXTERNAL +28 V (HI) AND RETURN (LO)	
WRE 3:ZE		ton r wasanda								22	50	20	
CURR AMP										.13	1.0	1.0	
FUNCTION										GIMBAL DISABLE +30 VDC OUT	REMOTE BRAKE HI	REMOTE BRAKE LO	
TO TO CONNECTOR										TO IRDS	SWITCH SEE FIGURE 25.		
FROM CONNECTO PIN	1J2-ZP	1J2-ZR	132-28	1J2-ZT	1J2-ZU	1J2-ZV	1J2-ZW	1J2-ZX	1J2-ZY	132-22 132-AA	1J2-BB	1J2-CC	
WIRE NO.	66	100	101	102	103	104	105	106	107	108	110	1	

TABLE II. IRDS interwiring list. - Continued

REMARKS	SHORT TOGETHER FOR	IKDS OFERALION	SHIELD TERMINATED AT 132-FF AND 232-ZE		SHIELDED TWISTED GUAD	(SHIELD TO NO. 114)				(Selent To No. 114)	··········
WIRE SIZE	22			50	20	20	50	20	20	50	O N
CURR	.13			11.7	დ ე;	3.9	<u>ه.</u>	7.5	.41	. 41	1
FUNCTION	SYSTEM INTERLOCK		SHIELD FOR WIRES NO. 115-118, 119-122	HEAT EXCHANGER 115 VAC 400 HZ NEUT	SEAT EXCHANGER 115 VAC 400 HZ PH C	HEAT EXCHANGER 115 VAC 400 HZ PH B	HEAT EXCHANGER 115 VAC 400 HZ PH A	STANDEY 115 VAC 400 HZ NEUT	STANDBY 115 VAC 406 HZ PH A	STANDBY 115 VAC 400 HZ PH B	STANDBY 115 VAC 400 HZ PH C
TO CONNECTOR PIN	1J2-EE		2J2-ZE	232-2D	272-20	2J2-ZB	2J2-ZA	2J2-ZJ	2J2-ZF	20-25 20-25	2J2~?E
FPOM CONNECTOR PIN	1J2-DD		1J2-FE	1J2-GG	1.72-HH	132-33	1J2-KK	1J2-LL	1J2-MM	2-NN-2-NN	α. Δ. (γ.
WIRE NO.	112	113	11.4	115	116		<u>&amp;</u>	119	120	121	122

TABLE II. IRDS interwiring list. - Continued

REMARKS	TWISTED PAIR WITH NO. 147					5 VDC SWITCHED	-10 TO +10 VDC	SHIELDED TWISTED PAIR	No. 134	SHIELDED TWISTED PAIR	No. 134	SHIELD TERMINATED AT 3J2-M AND 2J3-DD		5 VDC SWITCHED
WIRE SIZE	25	25	22	22	22	22	22	22	22	22	22		22	22
CURR	!					.002	.02	.001	.001	.001	.001		.002	.002
FUNCTION	SPARE	SPARE	SPARE	SPARE	SPARE	GYRO READY HI	STOW FEEDBACK	GAI AZ DC HI	GAI AZ DC LO	GAI EL DC HI	GAI EL DC LO	SHIELD FOR WIRES NO. 130-131, 132-133	SERVO BITE RETURN	SERVO BITE INITIATE
TO CONNECTOR PIN	4J1-G	2J3-Z	2J3-Y	2J3-X	2J3-W	2J3-ZH	2J3-ZI	273-22	2J3-AA	2J3-BB	273-CC	2J3-DD	2J3-ZV	2J3-ZW
FROM CONNECTOR PIN	3J2-A	3J2-B	3J2-C	3J2-D	3J2-E	3J2-F	3J2-G	3J2-Н	3J2-J	3J2-K	3J2-L	3J2-M	3J2-N	3J2-P
WIRE NO.	123	124	125	126	127	128	129	130	131	132	133	134	135	136

TABLE II. IRDS interwiring list. - Continued

r															
	REMARKS	5 VDC SWITCHED	VDC		TWISTED PAIR RELAY CONTROLLED	<b>-</b>		SHIELDED TUISTED OHAD	SHIELD TERMINATED AT 3J2-ZA AND 2J2-R			TWISTER DATE WANT	NOT HEED TAIN W/NO. 123	OF CONTRACT OF CON	NOT USED
	WIRE SIZE	22	22	50	20	22	50	20	20	20		2	<del></del>		
	CURR	.002	.002	1.0	1.0	0	.55	.55	.55	1.65				<del></del>	
	FUNCTION	SERVO BITE COMP	SERVO BITE	+28 VDC HI	+28 VDC RETURN	SAFETY GND	SERVO 115 VAC 400 HZ PH A	SERVO 115 VAC 400 HZ PH B	SERVO 115 VAC 400 HZ PH C	SERVO 115 VAC 400 HZ NEUT	SHIELD	SPARE			
10	CONNECTOR PIN	2J3-ZX	2J3-ZY	2J3-NN	2J3-PP	2J3-MM	2J2-P	2J2-N	2J2-M	2J2-L	2J2-R	4J1-H			
	CONNECTOR	3J2-R	3J2-S	3J2-T	3J2-U	3J2-V	3J2-W	3J2-X	3J2-Y	3J2-Z	3J2-ZA	3J2-ZB	3J2-ZC	3J2-ZD	
WIRE	ō.	137	138	139	140	141	142	143	441	145	146	147	148	149	

TABLE II. IRDS interwiring list. - Continued

REMARKS	NOT USED	NOT USED	NOT USED	NOT USED					5 VDC SWITCHED	5 VDC SWITCHED	5 VDC SWITCHED	5 VDC SWITCHED	+5 VDC SWITCHED	+5 VDC SWITCHED	+5 VDC SWITCHED	
WIRE					22	22	22	22	22	22	22	22	22	22	22	
CURR									.002	.002	.002	.002	.002	.002	.002	
FUNCTION		•			SPARE	SPARE	SPARE	SPARE	FORWARD COMMAND	POSITION COMMAND	CPTR TRK COMMAND	MAN TRK COMMAND	STANDBY COMMAND	OFF COMMAND	SERVO MODE SELECT	
R CONNECTOR PIN		-			5J1-N	5J1-P	5J1-R	5J1-ZA	4J1-M	4J1-N	4J1-P	4J1-R	4J1-S	4J1-T	4J1-U	
FROM CONNECTO PIN	3J2-ZE	3J2-ZF	3J2-ZG	3J2-ZH	3J2-ZI	332-23	3J2-ZK	3J2-ZM	3J2-ZN	3J2-ZP	3J2-ZQ	3J2-ZR	3J2-ZS	3J2-ZT	3J2-ZU	
WIRE NO.	150	151	152	153	154	155	156	157	158	159	160	161	162	163	164	

TABLE II. IRDS interwiring list. - Continued

REMARKS	SHIELD TERMINATED AT 3J2-ZV AND 4J1-V	SHIELDED TWISTED	TRIPLET (SHIFILD TO NO 16E)	ANALOG	SHIELDED TWISTED		±15 VDC ANALOG	SHIELDED TWISTED PAIR	TO NO. 176	SHIELDED TWISTED PAIR	TO NO. 176	SHIELD TERMINATED AT 3J2-GG AND 5J1-Z		Y TWISTED PAIR
WIRE SIZE		22	22	22	22	22	22	22	22	22	22		22	22
CURR		.01	.002	.01	.01	.002	.01	.01	.01	.01	.01		.01	.01
FUNCTION	SHIELD FOR WIRES NO. 166-168, 169, 171	EL POS CW	EL POS WIPER	EL POS CCW	AZ POS CW	AZ POS WIPER	AZ POS CCW	AZ MAN RATE HI	AZ MAN RATE LO	EL MAN RATE HI	EL MAN RATE LO	SHIELD FOR WIRES NO. 172, 173 AND 174, 175	MAN OVRD	SERVO +5 VDC RETURN
TO CONNECTOR PIN	4J1-V	4J1-W	4J1-X	4J1-Y	4.31-2	4J1-ZA	4J1-ZB	5J1-V	5J1-W	5J1-X	5J1-Y	5J1-Z	5J1-F	5J1-G
FROM CONNECTOR PIN	3J2-ZV	3J2-ZW	3J2-ZX	3J2-ZY	3J2-ZZ	3J2-AA	3J2-BB	372-CC	3J2-DD	3J2-EE	3J2-FF	3J2~GG	3J2-НН	3J2-JJ
WIRE NO.	165	166	167	168	169	170	171	172	173	174	175	176	177	178

TABLE II. IRDS interwiring list. - Continued

REMARKS		SHIELDED TWISTED TRIPLET		SHIELD TERMINATED AT 3J2-NN AND 5J1-L		INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED.  DO NOT USE.		TWISTED TRIPLET		
WIRE SIZE	22	22	22		22				22	22	22	 
CURR	.05	.10	.05									
FUNCTION	+15 VDC HI	±15 VDC RETURN.	-15 VDC HI	SHIELD	SAFETY GROUND				SPARE	SPARE	SPARE	
TO CONNECTOR PIN	5J1-H	5J1-J	5J1-K	5J1-L	5J1-M				2J3-Н	2J3-ZB	2J3-ZC	
FROM CONNECTOR PIN	3J2-KK	3J2-LL .	3J2-MM	3J2-NN	3J2-PP	4J1-A	4J1-B	4J1-C	4J1-D	4J1-E	4J1-F	
WIRE NO.	179	180	181	182	183	184	185	186	187	188	189	

TABLE II. IRDS interwiring list. - Continued

REMARKS	SUPPLY EXTERNAL +28	TEST CONTROL PANEL INDICATOR LAMPS	28 VDC SWITCHED			+18 VDC SWITCHED	+18 VDC SWITCHED	+18 VDC SWITCHED	+18 VDC SWITCHED	+18 VDC SWITCHED	+18 VDC SWITCHED	+18 VDC SWITCHED	5 VDC SWITCHED	
WIRE	22	22	22	50	22	22	22	22	22	22	22	22	22	
CURR	1.0	1.0	.02	.10	0	.13	.13	.13	.13	.13	.13	.13	500.	
FUNCTION	LAMP TEST HI	LAMP TEST RETURN	GRAY SCALE HI	+28 VDC RETURN	SAFETY GROUND	SYSTEM GO	RCVR FAIL	POWER SUPPLY FAIL	SERVO FAIL	NOT READY	BIT SWITCH	OVERTEMP	GO RESET	
TO CONNECTOR PIN	AIRCRAFT LAMP TEST CONTROL	AIRCRAFT LAMP TEST CONTROL	2J3-V	2J3-U	2J3-ZU	2J3-R	2J3-P	2J3-N	2J3-M	2J3-L	2J3-K	2J3-J	2J3-S	
FROM CONNECTOR PIN	4J1-K	4J1-L	4J1-2C	4J1-ZD	4J1-ZE	4J1-ZF	4J1-ZG	4J1-ZH	4J1-ZI	4J1-ZJ	4J1-ZK	4J1-ZM	4J1-ZN	ineman,
WIRE NO.	190	191	192	193	194	195	196	197	198	199	200	201	202	_

TABLE II. IRDS interwiring list. - Continued

REMARKS	+18 VDC SWITCHED		TWISTED TRIPLET +28 VDC SWITCHES		INTERNALLY CONNECTED. DO NOT USE.		INTERNALLY CONNECTED. DO NOT USE.	TWISTED PAIR W/NO. 212	INTERNALLY CONNECTED. DO NOT USE.	TWISTED PAIR W/NO. 210		***************************************
WIRE	22	25	22	22		20		22		22		22
CURR	.13	ı.	.13	.26		1.0		ੇ ੜ		₹.		0.13
FUNCTION	BIT INDICATOR	+28 VDC SUPPLY	STANDBY COMMAND	OPERATE COMAND		+18 VDC SUPPLY		PANEL LIGHT SUPPLY		PANEL LIGHT RETURN		SYSTEM INTERLOCK
TO CONNECTOR PIN	2J3-T	2J3-G	2J3-F	2J3-ZG		2J3-ZS		AIRCRAFT PANEL LIGHT SUPPLY		AIRCRAFT PANEL LIGHT CONTROL		4J1-ZZ
FROM CONNECTOR PIN	dZ-1Γħ	4J1-ZQ	4J1-ZR	4J1-ZS	4J1-ZT	4J1-ZU	4J1-ZV	4J1-ZW	4J1-ZX	4J1-ZY		4J1-AA
WIRE NO.	203	204	205	206	207	208	209	210	211	212	213	214

TABLE II. IRDS interwiring list. - Continued

REMARKS	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.		TWISTED TRIPLET			SHIELDED TWISTED PAIR DISPLAY POWER	➤ SHIELD TERMINATED AT 6J1-C AND 2J2-Y		NO CONTACT
WIRE SIZE					22	22	22	22	20	20		
CURR AMP					.01	.01	.01	.13	.82	.82		
FUNCTION					FOCUS +15 VDC	FOCUS -15 VDC	FOCUS ±15 VDC RETURN	INTERLOCK	DISPLAY 115 VAC 400 HZ PH B	DISPLAY 115 VAC 400 HZ NEUT	SHIELD	
TO CONNECTOR PIN					2J3-ZJ	2J3-ZK	2J3-ZM	2J2-E	272-2	2J2-J	2J2-Y	
FROM CONNECTOR PIN	4J1-BB	4J1-CC	4J1-DD	4J1-EE	4J1-FF	4J1-GG	4Л1-НН	2J2-D	6J1-A	6J1-B	6J1-C	2J2-K
WIRE NO.	215	216	217	218	219	220	221	222	223	224	225	226

TABLE II. IRDS interwiring list. - Continued

REMARKS	NO CONTACT	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	NOT USED	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.
WIRE SIZE											
CURR											
FUNCTION											
TO TO CONNECTOR PIN											
WIRE CONNECTOR NO. PIN	2J2-X	2J2-S	2J2-T	2J2-U	2J2-ZK	2J3-ZD	2J3-ZE	2J3-ZF	5J1-A	5J1-B	5J1-C
WIRE NO.	227	228	229	230	231	232	233	234	235	236	237

TABLE II. IRDS interwiring list. - Continued

REMARKS	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	NOT USED	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	atted nametrum ned lette	SHIELDED INTSIED FAIR SHIELD TERMINATED AT		TWISTED PATE	28 VDC TO RELAY
WIRE SIZE								22	22		20	20
CURR											.13	.13
FUNCTION					SPARE			SPARE	SPARE	SHIELD	+30 VDC SUPPLY	GIMBAL DISABLE
TO CONNECTOR PIN					A. A			3J1-A	3J1-B	3J1-C	3J1-D	3J1-E
FROM CONNECTOR PIN	5J1-D	5J1-E	5J1-S	5J1-T	5J1-U	5J1-ZB	5J1-ZC	1.34-A	1J4-B	1J4-C	1.34-D	1.J.4_E
WIRE NO.	238	239	240	241	242	243	<b>11</b> 17 2	245	546	242	248	546

TABLE II. IRDS interwiring list. - Continued

REMARKS	TWISTED PAIR	28 VDC SWITCHED			SHIELDED TWISTED TRIPLET	SERVO	TWISTED PAIR	SYNCHRO EXCITATION	<b>3</b>	SHIELD TERMINATED AT	1J4-R AND 3J1-R SHIELDED TWISTED PAIR	±15 VDC ANALOG	SHIELDED TWISTED	TRIPLET  ±15 VDC ANALOG	SHIELD TO NO. 265	
WIRE	20	20		22	22	22	22	22	22		25	22	22	22	22	
CURR	1.0	1.0		.5	.5	5.	<b>⊉</b> L.	41.			.01	.01	.01	.001	.01	
FUNCTION	BRAKE HI	BRAKE LO	SHIELD	SERVO +15 VDC HI	SERVO ±15 VDC RETURN	SERVO -15 VDC HI	26 VAC LOO EXCITATION	26 VAC LOO RETURN	SPARE	SHIELD	AZ RATE HI	AZ RATE LO	EL POS POT CW	EL POS POT WIPER	EL POS POT CCW	
TO CONNECTOR PIN	3J1-F	3J1-G	3J1-Н	3J1-J	3J1-K	3J1-L	3J1-M	3J1-N	3J1-P	3J1-R	3J1-S	3J1-T	3J1-U	3J1-V	3J1-W	
FROM CONNECTOR PIN	¶ - ነገ ነ	1.74-G	H-11 F	1.461	λ-μι.	1-4C1	1.J4-M	1.4-N	1.J4-P	1J4-R	1.74-5	1.J.4-T	1J4-U	134-V	134-W	
WIRE NO.	250	251	252	253	254	255	256	257	258	259	260	261	262	263	264	

TABLE II. IRDS interwiring list. - Continued

REMARKS	SHIELD TERMINATED AT 154-X AND 3J1-X	SHIELDED TWISTED	PAIRS (SHIELDS TO NO. 275)		11.8 VAC, 400 HZ	ANALOG			<u> </u>	SHIELD TERMINATED AT 154-ZW AND 3J1-ZW		SHIELD TERMINATED AT		PAIR
WIRE		22	22	22	22	22	22	22	22	<b></b>	22		50	02
CURR		.01	.01	.0.	.01	.01	.0.	٥.	.01		.01		0.	1.0
FUNCTION	SHIELD TO WIRES NO. 262-264	AZ RESOLVER S1	AZ RESOLVER S3	AZ RESOLVER S2	AZ RESOLVER S4	EL RESOLVER S1	EL RESOLVER S3	EL RESOLVER S2	EL RESOLVER S4	SHIELD	GYRO TEMP RETURN	SHIELD	SERVO +5 VDC HI	SERVO +5 VDC RETURN
TO CONNECTOR PIN	3J1-X	3J1-Y	3J1-2	3J1-ZA	3J1-ZB	3J1-ZK	3J1-ZM	3J1-ZN	3J1-ZP	3J1-ZW	3J1-ZC	3J1-ZD	3J1-ZE	3J1-ZF
FROM CONNECTOR PIN	1J4-X	1.J4-Y	1.34-2	1J4-ZA	1J4-ZB	1J4-ZK	1J4-ZM	1.J4-ZN	1.J4-ZP	1.34-ZW	134-ZC	1J4-ZD	1J4-ZE	1J4-ZF
WIRE NO.	265	200	267	268	269	270	27.1	272	273	12 h	275	276	27.7	278

TABLE II. IRDS interwiring list. - Continued

WIRE NO.	WIRE CONNECTOR	TO CONNECTOR PIN	FUNCTION	CURR	WIRE SIZE	REMARKS
279	1.54-ZG	371-26	AZ TACH HI	.01	22	SHIELDED TWISTED PAIR
280	1.J4-ZH	3J1-ZH	AZ TACH LO	.01	22	14 VRMS 400 HZ ANALOG SHIELD TERMINATED AT
281	134-ZI	3J1-ZI	SHIELD			134-ZI AND 331-ZI
282	134-23	3J1-ZJ	SPARE		22	
283	134-20	331-20	EL RATE HI	.01	22	SHIELDED TWISTED PAIR
58π	1J4-ZR	3J1-ZR	EL RATE LO	.0	22	±15 VDC ANALOG SHIELD TERMINATED AT
285	1,34-28	331-28	SHIELD			
286	134-ZT	3J1-ZT	GYRO TEMP	.005	22	5 VDC SWITCHED
287	134-ZU	3J1-ZU	GIMBAL FAIL HI	.002	22	THE CONTRACT OF THE CONTRACT O
288	134-ZV	3J1-ZV	GIMBAL FAIL LO	.002	22	VINISIED FAIN
289	134-2X					NO CONTACT
230	134-ZY	3J1-ZY	+15 VDC SUPPLY	1.0	20	TAG CORPORTED
291	134-22	3J1-ZZ	+15 VDC RETURN	1.0	20	A INTOIGH CAIN
292	1J4-AA					NOT USED
293	1J4-BB	3J1-BB	-15 VDC SUPPLY	1.0	20	atva camerum
1294	134-CC	311-cc	-15 VDC RETURN	1.0	50	INTOIEM FAIR

TABLE II. IRDS interwiring list. - Continued

REMARKS	SHIELDED TWISTED PAIR	±30 VDC SERVO POWER	SHIELDED TWISTED PAIR	±30 VDC SERVO POWER	SHIELD TERMINATED AT 1J4-HH AND 3J1-HH		SHIELD TERMINATED AT 134-13 AND 331-JJ	SHIELD-TWISTED TRIPLET ±15 VDC		!		NO CONNECTION			
WIRE SIZE	20	50	50	20	50		22	22	22	22	22		50	22	
CURR	9° h-0	0-4.5	0-4.5	0-4.5			.002	.002	.002						
FUNCTION	EL TORQ HI	EL TORQ LO	AZ MOTOR DRIVE HI	AZ MOTOR DRIVE LO	SHIELD FOR WIRES NO. 295, 296 AND 297, 298	SHIELD	AZ POS POT CW	AZ POS POT WIPER	AZ POS POT CCW	SPARE	SAFETY GROUND		SPARE	SPARE	
TO CONNECTOR PIN	3J1-DD	3J1-EE	3J1-FF	3J1-GG	3J1-НН	3J1-JJ	3J1-KK	3J1-LL	3J1-MM	3J1-NN	3J1-PP		1J3-Y	1J3-Z	
FROM CONNECTOR PIN	1J4-DD	1J4-EE	1.34 FF	1J4⊢GG	1.J4-HH	1.54-33	1.34-KK	1J4-LL	1.34-MM	1.J.4-NN	1J4-PP	4J1-G	4J2-A	4J2-B	
WIRE NO.	295	296	297	298	299	300	301	302	303	304	305	306	307	308	

TABLE II. IRDS interwiring list. - Continued

CONNECTOR	3		Cuan	WIRE		•
PIN	CONNECTOR	FUNCTION	***************************************	54.ZE	REMARKS	
U2-C	1J3-G	POCIIS HI	-002	22	SHIELDEN-TWISTER SAIR	·
7	133-8	FOCUS 1.0	7007	22	,	
<b>42-8</b>	133-F	SHEED	<b>****</b> ******			
W2.F	MI CAL	COOL 1900	90.	22	±18 VDC SWITCHED	
#12-G	1.73-58	+28 VDC STANDBY	ιὐ	22		
4J2-H	1J3-AA	RETICLE INT	-	22	+28 VDC ANALOG	
175-3	133-23	TIME OF THE NEAR	.13	22		
Y-ZC-K	13-21	FIELD OF VIEW RETURN	.13	22		
3	1.13.W	POLARITY SELECT	.0.	22	TWISTED PAIR -5 VDC	
W2-4	1J3-W	POLARITY RETURN	.01	22	SWITCHED	
4.J2-N	1J3-X	SHIELD FOR WIRES NO. 320-322, 323-325			SHIELD TERMINATED AT 4J2-N AND 1J3-X	
4J2-P	1J3-S	VIDEO LEVEL POT CW	.002	22		
4J2-R	1J3-T	VIDEO LEVEL POT WIPER	.001	22	SHIELDED-TWISTED TRIPLET 5 VDC ANALOG	
4J2-S	1J3-U	VIDEO LEVEL POT CCW	.002	22	SHIELD TO NO. 319	
a in a tid that the time of tid tid time the			1.33-88 +28 VDC STANDBY 1.33-8A RETICLE INT 1.33-AA RETICLE INT 1.33-Y POLARITY SELECT 1.33-V POLARITY SELECT 1.33-V SHIELD FOR WIRES 320-322, 323-325 1.33-Y VIDEO LEVEL POT 1.33-U VIDEO LEVEL POT 1.33-U VIDEO LEVEL POT	1.3-89  1.3-4A  RETICLE INT  1.3-AA  RETICLE INT  FIELD OF VIEW RETURN  1.3-V  POLARITY SELECT  POLARITY SELECT  POLARITY RETURN  1.3-X  SHIELD FOR WIRES NO.  320-322, 323-325  1.33-X  VIDEO LEVEL POT CW  1.13-T  VIDEO LEVEL POT CW  1.13-U  VIDEO LEVEL POT CCW	1.3-48	1.33-4A RETICLE INT  1.1 22 +28 VDC SMITCHED  1.33-AA RETICLE INT  1.1 22 +28 VDC ANALOG  TIELD OF VIEW RETURN  1.3 22 TWISTED PAIR  1.43-V POLARITY SELECT  1.01 22 SWITCHED  1.13-V POLARITY RETURN  1.01 22 SWITCHED  1.03-X SHIELD FOR WIRES NO.  1.03-X VIDEO LEVEL POT CW  1.03-X VIDEO LEVEL POT CW  1.03-Y SHIELD TO NO. 319

TABLE II. IRDS interwiring list. - Continued

REMARKS	SHIELDED TWISTED	TRIPLET 5 VDC ANALOG	SHIELD TO NO. 319	NO CONTACT	28 VDC SWITCHED	NO CONTACT	NO CONTACT									
WIRE SIZE	22	22	25										54	<del></del>		
CURR AMP	.002	.001	.002										.13			_
FUNCTION	VIDEO GAIN POT CW	VIDEO GAIN POT WIPER	VIDEO GAIN POT CCW										SYSTEM INTERLOCK			
TO CONNECTOR PIN	1J3-N	1J3-P	1J3-R	100									1J3-ZB			_
FROM CONNECTOR PIN	T-50#	4J2-U	4J2-V	1J3-A	1J3-B	1J3-C	1J3-D	1J3-E	133-3	1J3-K	1J3-L	1J3-M	1J3-ZA	1J3-ZC	1J3-ZD	
WIRE NO.	323	324	325	326	327	328	329	330	331	332	333	334	335	336	337	

TABLE II. IRDS interwiring list. - Continued

WIRE NO.	FROM CONNECTOR PIN	TO CONNECTOR PIN	FUNCTION	CURR	WIRE SIZE	REMARKS
338	1J3-ZE					NO CONTACT
339	1J3-ZF		SPARE			NOT USED
340	1J3-2G					NO CONTACT
341	1J3-ZH					NO CONTACT
342	13-21					NO CONTACT
343	133-23		SPARE			NOT USED
344	1J3-ZK		SPARE			NOT USED
345	1J3-2P		SPARE			NOT USED
346	133-20		SPARE			NOT USED
347	1J3-2R		SPARE			NOT USED
348	133-28		SPARE			NOT USED
349	1J3-ZT		SPARE			NOT USED
350						
35.1	1J3-ZU					INTERNALLY CONNECTED. DO NOT USE.
	1J3-ZV					INTERNALLY CONNECTED. DO NOT USE.

TABLE II. IRDS interwiring list. - Continued

REMARKS	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	NOT USED	NO CONTACT									
WIRE SIZE														
CURR														
FUNCTION				SPARE	SPARE	SPARE	SPARE	SPARE						
TO CONNECTOR PIN														
FROM CONNECTOR PIN	1J3-ZW	1J3-ZX	1J3-ZY	1J3-ZZ	1J3-CC	1J3-DD	1J3-EE	1J3-FF	1J3-GG	1J3-HH	133-13	1J3-KK	1J3-LL	133-MM
WIRE NO.	353	354	355	356	357	358	359	360	361	362	363	364	365	366

TABLE II. IRDS interwiring list. - Continued

REMARKS	NOT USED															
WIRE SIZE														-		
CURR																
FUNCTION	SPARE															
TO CONNECTOR PIN																
FROM CONNECTOR PIN	1J3-PP	3J3-1	373-2	3J3-3	3√3-4	3-3-5	373-6	3J3-7	3-3-8	373-9	3J3-10	3J3-11	3J3-11	3J3-13	3J3-14	
WIRE NO.	367	368	369	370	371	372	373	374	375	376	377	378	379	380	381	

TABLE II. IRDS interwiring list. - Continued

REMARKS	NOT USED	INTERNALLY CONNECTED. DO NOT USE.											
WIRE SIZE													
CURR													
FUNCTION													
TO CONNECTOR PIN													
FROM CONNECTOR PIN	3J3-15	333-16	3J3-17	3J3-18	3J3-19	313-20	3J3-21	3J3-22	3J3-23	333-24	313-25	333-26	3J3-27
WIRE NO.	382	383	384	385	386	387	388	389	390	391	392	393	394

TABLE II. IRDS interwiring list. - Continued

REMARKS	NOT USED	+5 VDC SWITCHED		NOT USED	SHIELDED-TWISTED	PAIR SHIELD TERMINATED AT 3J2-34 AND 26 VAC BEEFPENCE SOURCE	NEFENENCE SOUNCE	SHIELDED TWISTED	PAIRS 5 VDC SWITCHED INTO 130 \( \Omega\) AC,	SHIELDS TO NO. 430		NO: USED		
WIRE		22		22	22			25	22	22	22		 	
CURR					41.	<b>₹</b> 1.		ħ0.	ħ0·	٠٥٠	ħ0.			
FUNCTION		PILOT FWD			26 VAC 400 HZ HI	26 VAC 400 HZ LO	SHIELD	DATA BIT 00	RETURN	DATA BIT 01	RETURN			
TO CONNECTOR PIN		313-30			AIRCRAFT	REFERENCE SOURCE. SEE PARA-	GRAPH 5.3.3.		DATA PRO-	SYSTEM SPE DADA	GRAPH	5.3.1.		
FROM CONNECTOR PIN	3J3-28	313-29		333-31	3J3-32	313-33	333-34	313-35	333-36	333-37	313-38	333-39		:
WIRE NO.	395	396	397	398	399	0017	401	402	403	ħ0ħ	405	9017	<del></del>	

TABLE II. IRDS interwiring list. - Continued

	REMARKS		SHIELDED-TWISTED PAIRS +5 VDC SWITCHED INTC 130 A C, 2K Q DC LOADS SHIELDS TO WIRE NO. 430														
-	ш,,,	1	<u>^</u>		<u>^</u>		<u> </u>		<u>^</u>		<u>^</u>		<u>~</u>		<u>~</u>	_	$\leq$
	WIRE SIZE	22	22	22	22	22	22	22	22	22	22	22	22	22	22	22	22
	CURR	70.	ħ0.	ħ0.	ħ0.	ħ0°	ħ0°	ħ0.	40.	40.	40.	40.	ħ0°	ħ0.	ħ0·	ħ0.	ħ0.
	FUNCTION	DATA BIT 02	RETURN	DATA BIT 03	RETURN	DATA BIT 04	RETURN	DATA BIT 05	RETURN	DATA BIT 06	RETURN	DATA BIT 07	RETURN	DATA BIT 08	RETURN	DATA BIT 09	RETURN
T0	CONNECTOR		AIRCRAFT DATA PRO- CESSING SYSTEM. SEE PARA- GRAPH 5.3.1.														
	CONNECTOR PIN	373-40	3J3-41	3J3-42	3J3-43	3J3-44	3J3-45	373-46	3J3-47	3J3-48	3J3-49	333-50	3J3-51	373-52	343-53	373-54	373-55
WIRE	S O	407	408	409	410	411	412	413	414	415	416	417	4 18	419	420	421	422

TABLE II. IRDS interwiring list. - Continued

REMARKS		SWITCHED-IWISTED PAIRS +5 VDC	SWITCHED INTO	ZK DC LOADS		SHIELD TERMINATED AT 3J3-63 AND DATA PROCESSING SYSTEM CONNECTOR	SHIELDED TWISTED PAIR	+5 VDC SWITCHED SHIELD TERMINATED AT 3.13-66 AND DATA PRO-	CESSING SYSTEM CONNECTOR			
	سے	<u></u>		رے	$\subseteq$		<u>_</u>	<u> </u>				<u> </u>
WIRE SIZE	22	22		22	22	22	22		22	22		
CURR	₩0.	πο.		# O.	70.	₩0.	ħ0°		.002	.002		
FUNCTION	DATA BIT 10	RETURN		DATA BIT 11	RETURN	OUTPUT ACKNOWLEDGE	RETURN	SHIELD	CPTR TRK	RETURN	SHIELD	
TO CONNECTOR PIN			AIRCRAFT DATA PRO-	CESSING	SEE PARA- GRAPH	5.3.1.			AIRCRAFT	CESSING SYSTEM.	GRAPH 5.3.2.	
FROM	373-56	333-57	313-58	333-59	333-60	333-61	333-62	313-63	333-64	333-65	373-66	
WIRE NO.	423	<b>#2#</b>	425	426	. 427	428	429	1430	431	432	433	

TABLE II. IRDS interwiring list. - Continued

REMARKS	SHIELDED TWISTED TRIPLETS 11.8 VRMS SHIELD TO NO. 440 400 HZ ANALOG INTO 500 \( \oldsymbol{Q} \)						SHIELD TERMINATED AT 3J3-73 AND DATA PRO-CESSING SYSTEM CONNECTOR	SHIELDED TWISTED	PAIR +5 VDC SWITCHED	SHIELD TERMINATED AT 3J3-76 AND DATA PRO-CESSING SYSTEM CONNECTOR	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.
WIRE	22	22	22	22	22	22		22	22		<b></b>	
CURR		-			····			.002	200.			-
FUNCTION	AZ CX S1	AZ CX S2	AZ CX S3	EL CX S1	EL CX S2	EL CX S3	SHIELD FOR WIRES NO. 434-436 AND 437-439	MAN TRACK HI	MAN TRACK LO	SHIELD		
TO CONNECTOR PIN			THE A CLOCK	DATA PRO-	SYSTEM.	GRAPH	3.5.5.5	AIRCRAFT	CESSING	SISIEM. SEE PARA- GRAPH 5.3.2.		
FROM CONNECTOR PIN	333-67	373-68	333-69	333-70	3J3-71	333-72	3J3-73	333-74	333-75	3J3-76	333-77	3J3-78
WIRE NO.	ħ£ħ	435	436	η37	436	4 39	0 11 11	441	442	E 11 11	7 7 7 7	544

TABLE II. IRDS interwiring list. - Continued

REMARKS	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.	INTERNALLY CONNECTED. DO NOT USE.		
WIRE									
CURR AMP									
FUNCTION									
TO CONNECTOR PIN									
FROM CONNECTOR PIN	3J3-79	3J3-80	3J3-81	3J3-82	3J3-83	3J3-84	313-85		
WIRE NO.	944	<b>244</b>	8111	61/11	450	451	452		

TABLE II. IRDS interwiring list. - Continued

REMARKS		TWISTED TRIPLET 108-118 VRMS (LINE TO NEUTRAL			24-28.5 VDC			NO CONTACT	
WIRE	20	50	20	707	50	50,	50		
CURR	5.0 max	5.0 max	5.0 max	1.0	5.0 max	5.0 max			
FUNCTION	SYS PWR 115 VAC 400 HZ PH A	SYS PWR 115 VAC 400 HZ PH B	SYS PWR 115 VAC 400 HZ PH C	AC RETURN	+28 VDC SUPPLY	+28 VDC RETURN	SAFETY GROUND		
TO CONNECTOR PIN	AIRCRAFT POWER SYSTEM	AIRCRAFT POWER SYSTEM	AIRCRAFT POWER SYSTEM	AIRFRAME GROUND	AIRCRAFT POWER SYSTEM	AIRFRAME GROUND	AIRFRAME GROUND		
WIRE CONNECTOR	2J1-A	2J1-B	2J1-C	2J1-D	2J1-E	2J1-F	2J1-G	2J1-H	
WIRE NO.	453	n2n	455	456	457	458	459	7460	

MIL-HDBK-258(AS)

TABLE II. IRDS interwiring list. - Continued

REMARKS		TWISTED TRIPLET 108-118 VRMS (LINE TO NEUTRAL)			18 ±1 VDC		NO CONTACT	NO CONTACT	75 OHM VIDEO TRIAX		
WIRE SIZE	20	50	50	50	50	50					
CURR	5.0 max	5.0 max	5.0 max	0	1.3 max	1.3 max					
FUNCTION	HEATER 115 VAC 400 HZ PH A	HEATER 115 VAC 400 HZ PH B	HEATER 115 VAC 400 HZ PH C	AC RETURN	+18 VDC HI	+18 VDC RETURN			VIDEO OUT		
TO CONNECTOR PIN	AIRCRAFT POWER SYSTEM	AIRCRAFT POWER SYSTEM	AIRCRAFT POWER SYSTEM	AIRFRAME GROUND	AIRCRAFT 18 VDC	AIRFRAME GROUND			6J2		
FROM CONNECTOR PIN	2J1-J	2J1-K	2J1-L	2J1-M	2J1-N	2J1-P	2J1-R	2J1-S	237		
WIRE NO.	1911	462	£9ħ	11911	465	9917	194	1468	f 69	470	471

TABLE II. IRDS interwiring list. - Continued

REMARKS	NO CONTACT	NO CONTACT	NO CONTACT	NOT USED	NOT USED	NOT USED	·				
WIRE SIZE					والمستدان المستور						
CURR											
FUNCTION								GROUND LUG CHASSIS			
TO TO CONNECTOR											
WIRE CONNECTOR	2J4-A	2J4-B	234-C	2J4-G	2J4-H	2J4-EE	2J4-FF	3J1-ZX	3J1-AA	6J1-D	
WIRE NO.	472	473	727	475	921	477	478	479	480	481	

TABLE III. Angle rate codes.

Angle Rate	Sign	MSB					Bit					LSB
(degrees/second)	11	10	9	8	7	6	5	4	3	2	1	0
+60.0	1	1	1	1	1	1	1	1	1	1	1	1
+30.00000	1	1	0	0	0	0	0	0	0	. 0	0	0
+15.0	1	0	1	0	0	0	0	0	0	0	0	0
+7.5	1	0	0	1	0	0	0	0	0.	0	0	0
+3.75	1	0	0	0	1	0	0	0	0	0	0	0
+1.875	1	0	0	0	0	1	0	0	0	0	0	0
+0.938	1	0	0	0	0	0	1	0	0	0	0	0
+0.469	1	0	0	0	0	0	0	1	0	0	0	0
+0.234	1	0	0	0	0	0	0	0	1	0	0	0
+0.117	1	0	0	0	0	0	0	0	0	1	0	0
+0.058	1	0	0	0	0	0	0	0	0	0	1	0
+0.029	1	0	0	0	0	0	0	0	0	0	0	1
+0.00000000	1	0	0	0	0	0	0	0	0	0	0	0
-0.00000000	0	0	0	0	0	0	0	0	0	0	0	0
-0.029	0	0	0	0	0	0	0	0	0	0	0	1
-0.058	0	0	0	0	0	0	0	0	0	0	1	0
-0.117	0	0	0	0	0	0	0	0	0	1	0	0
-0.234	0	0	0	0	0	0	0	0	1	0	0	0
-0.469	0	0	0	0	0	0	0	1	0	0	0	0
-0.938	0	0	0	0	0	0	1	0	0	0	0	0
-1.875	0	0	0	0	0	1	0	0	0	0	0	0

TABLE III Angle rate codes. - Continued

Angle Rate	Sign	MSB					Bit					LSB
(degrees/second)	11	10	9	8	7	6	5	4	3	2	1	0
-3.75	0	0	0	0	1	0	0	0	0	0	0	0
-7.5	0	0	0	1	0	0	0	0	0	0	0	0
-15.0	0	0	1	0	0	0	0	0	0	0	0	0
-30.0	0	1	0	0	0	0	0	0	0	0	0	0
-60.0	0	1	1	1	1	1	1	1	1	1	1	1

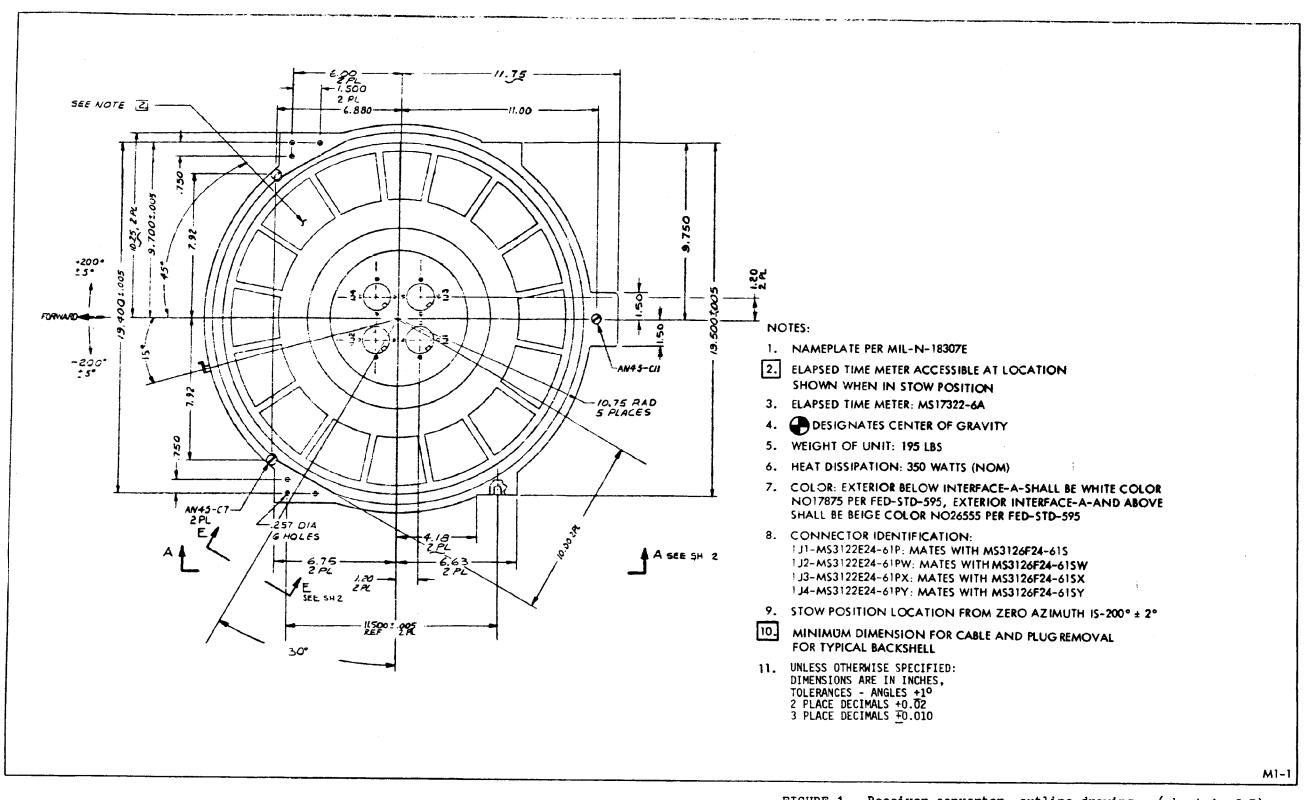


FIGURE 1. Receiver converter, outline drawing. (sheet 1 of 5)

## MIL-HDEE-CHI(AS)

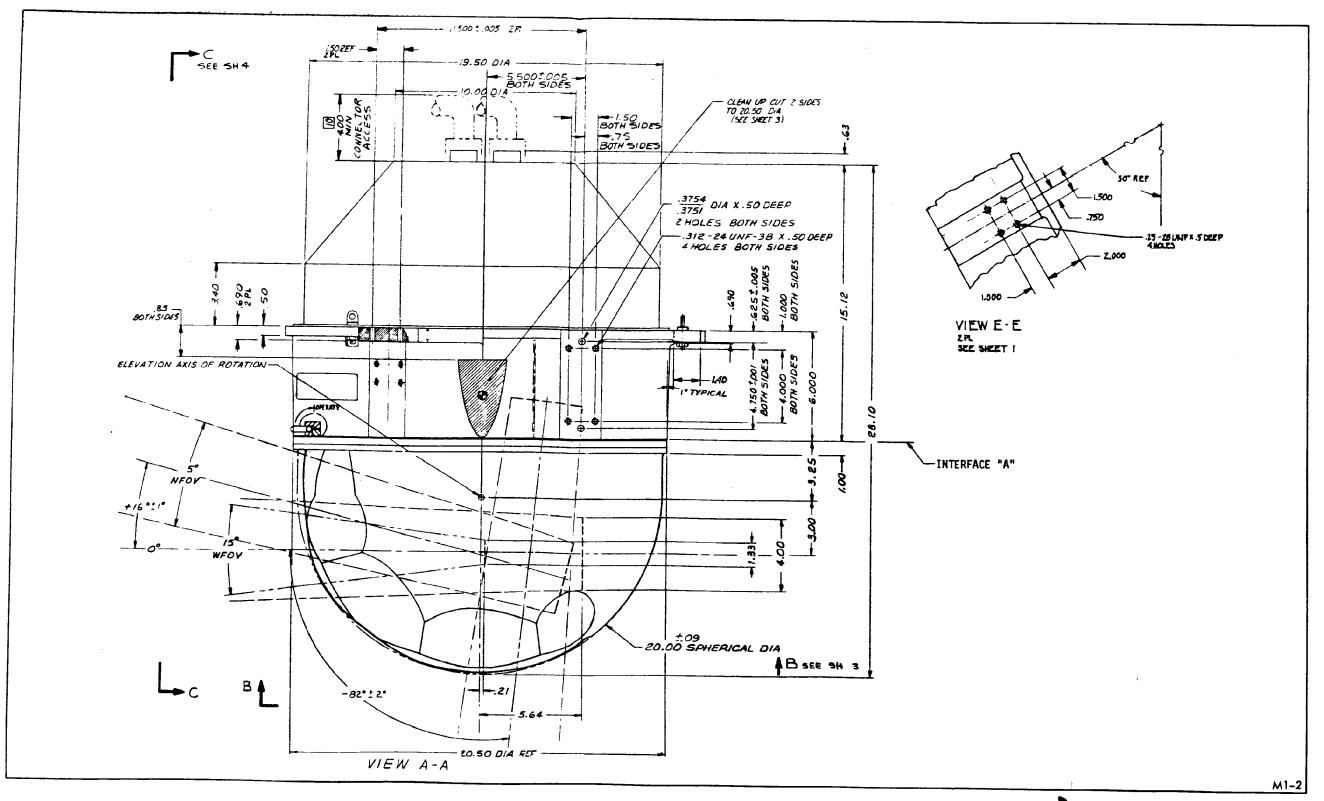


FIGURE 1. Receiver converter, outline drawing. (sheet 2 of 5)

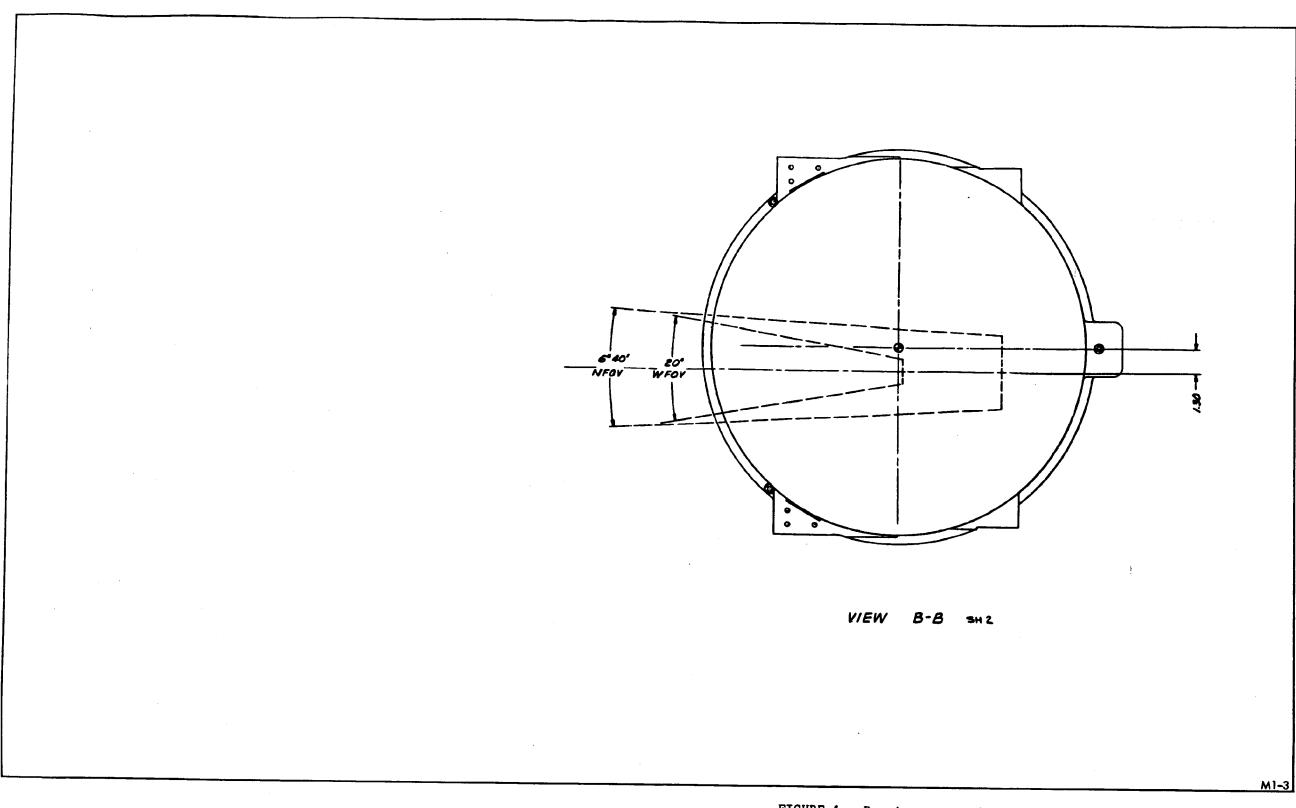


FIGURE 1. Receiver converter, outline drawing. (sheet 3 of 5)

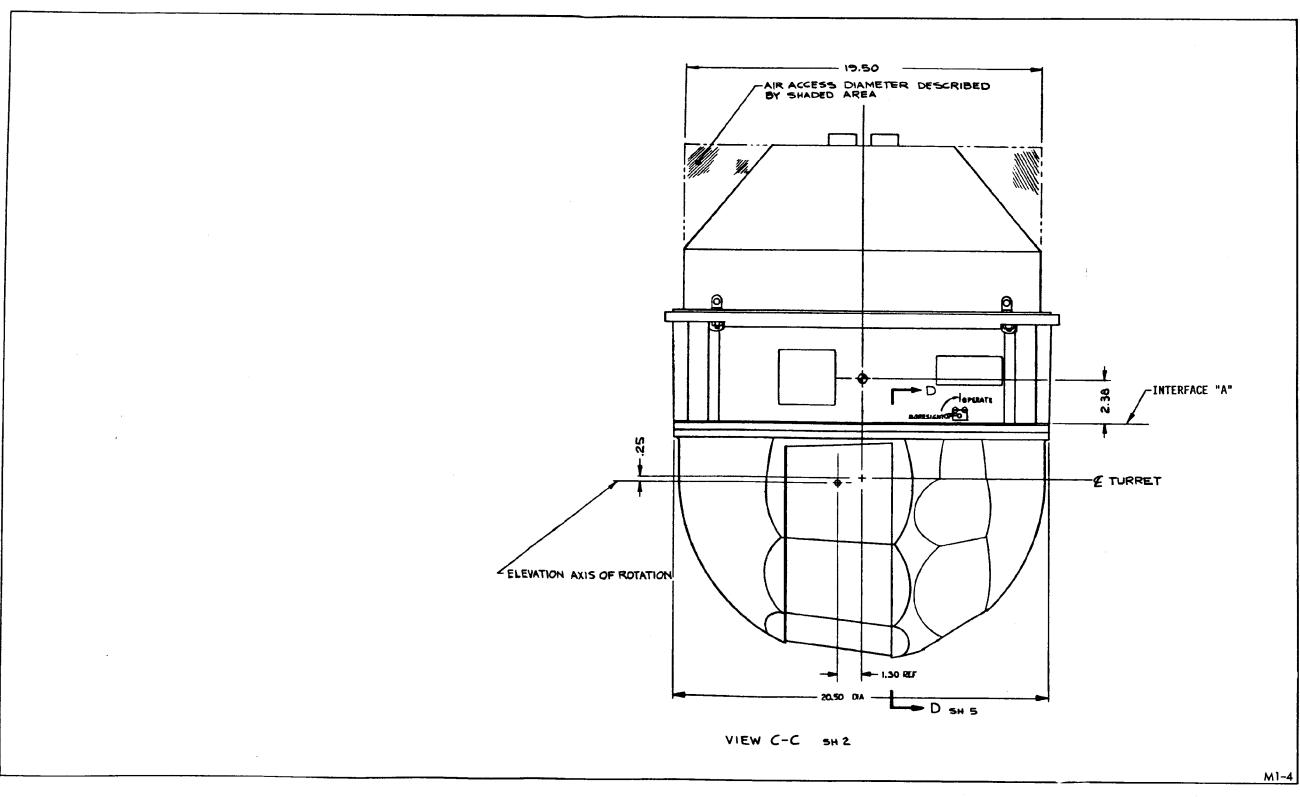


FIGURE 1. Receiver converter, outline drawing. (sheet 4 of 5)

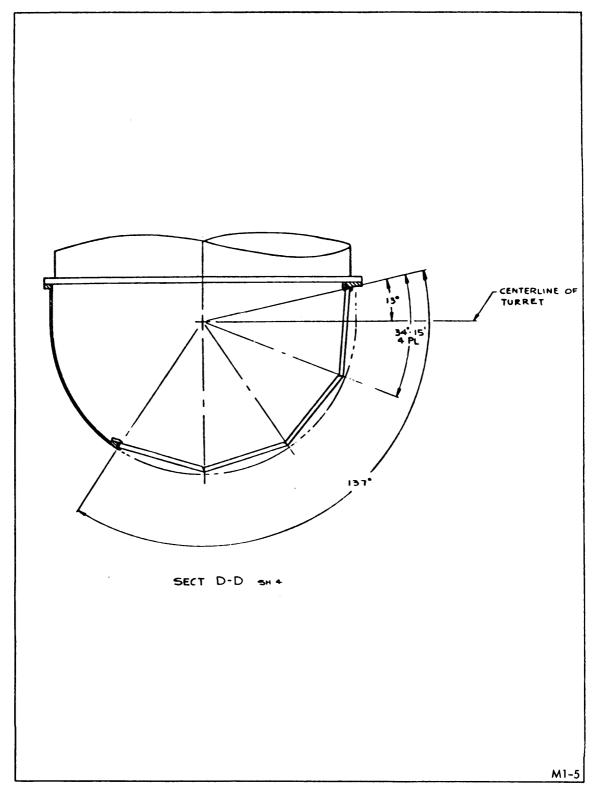
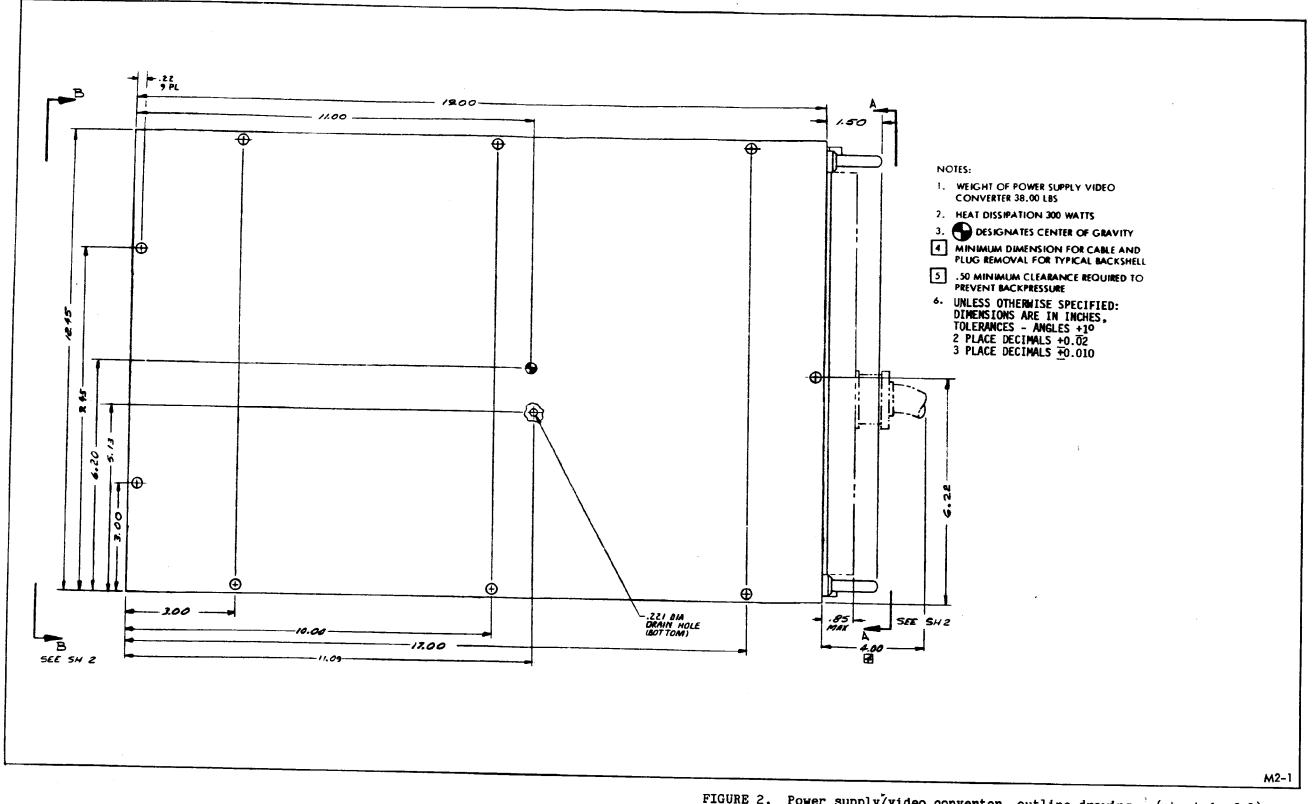


FIGURE 1. Receiver converter, outline drawing. (sheet 5 of 5)





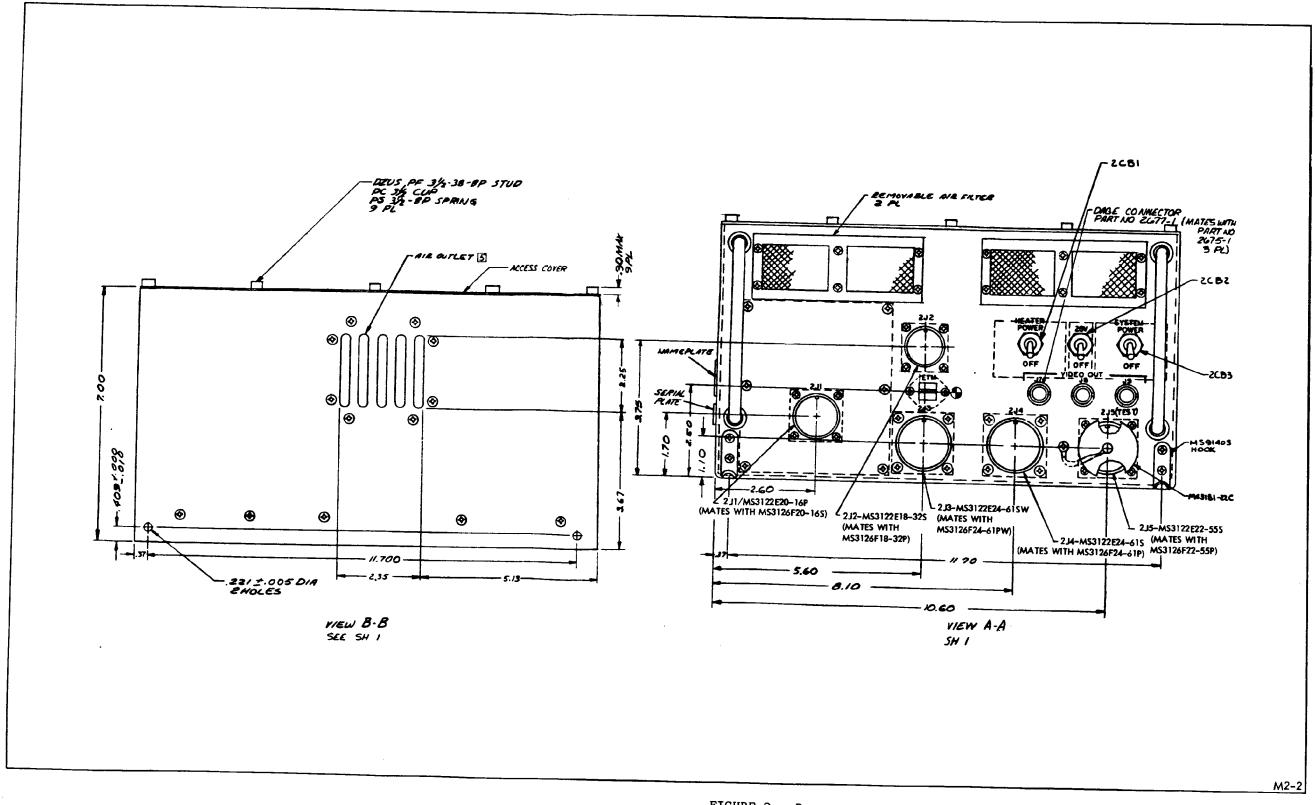


FIGURE 2. Power supply/video converter, outline drawing. (sheet 2 of 2)

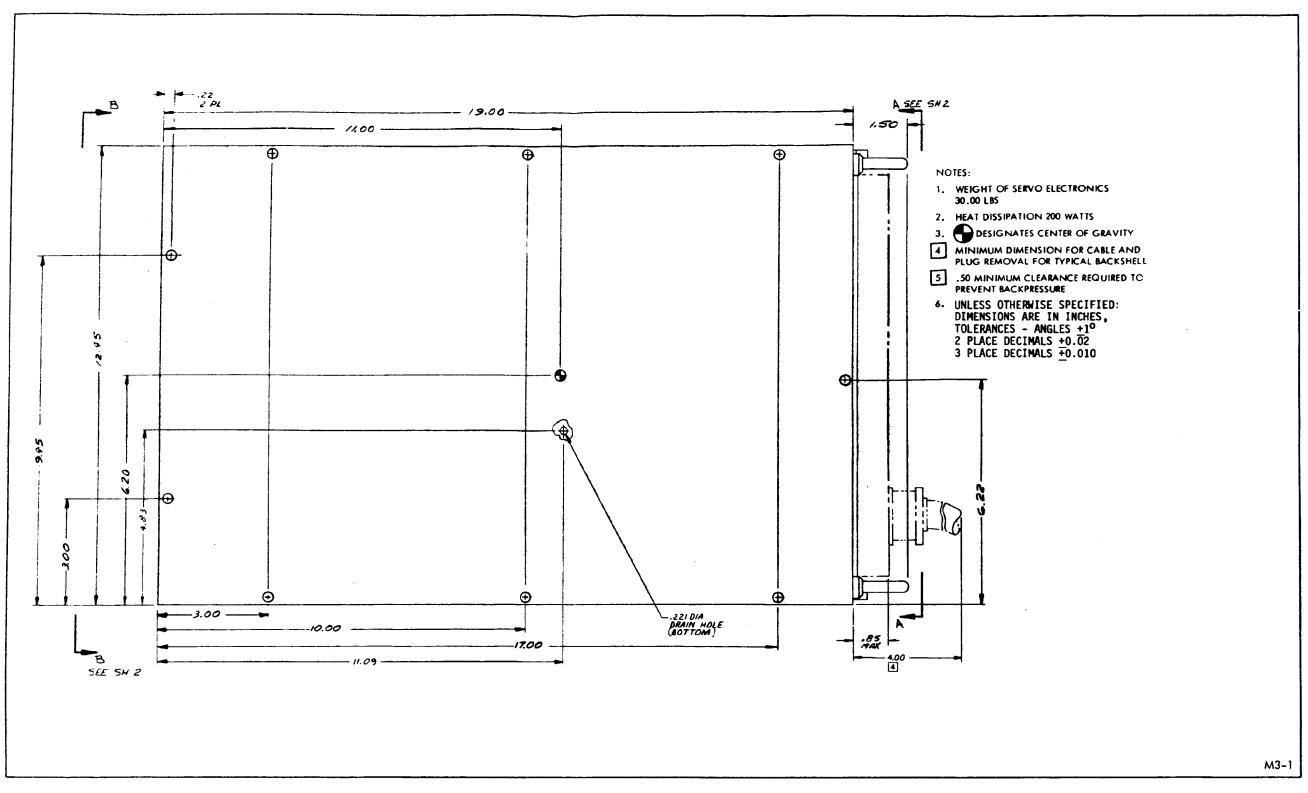


FIGURE 3. Control servomechanism, outline drawing. (sheet 1 of 2)

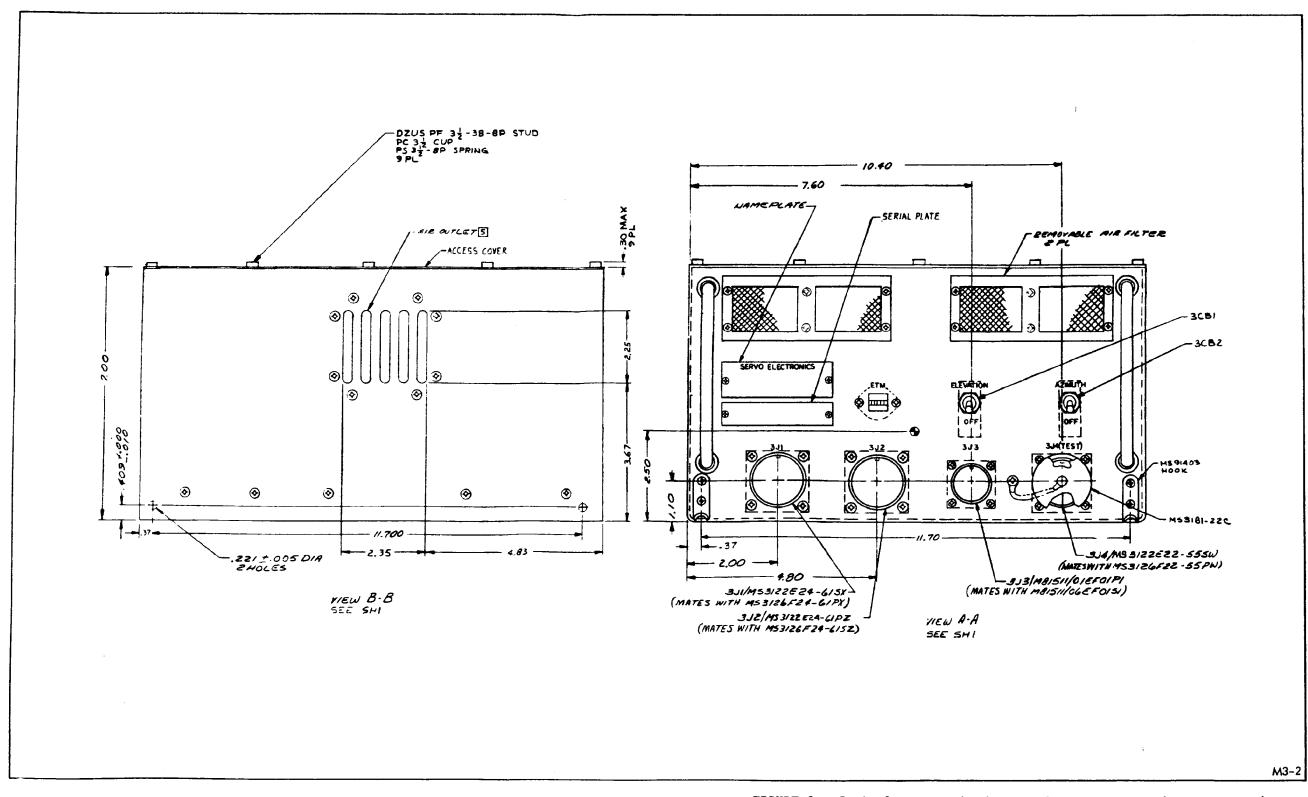


FIGURE 3. Control servomechanism, outline drawing. (sheet 2 of 2)

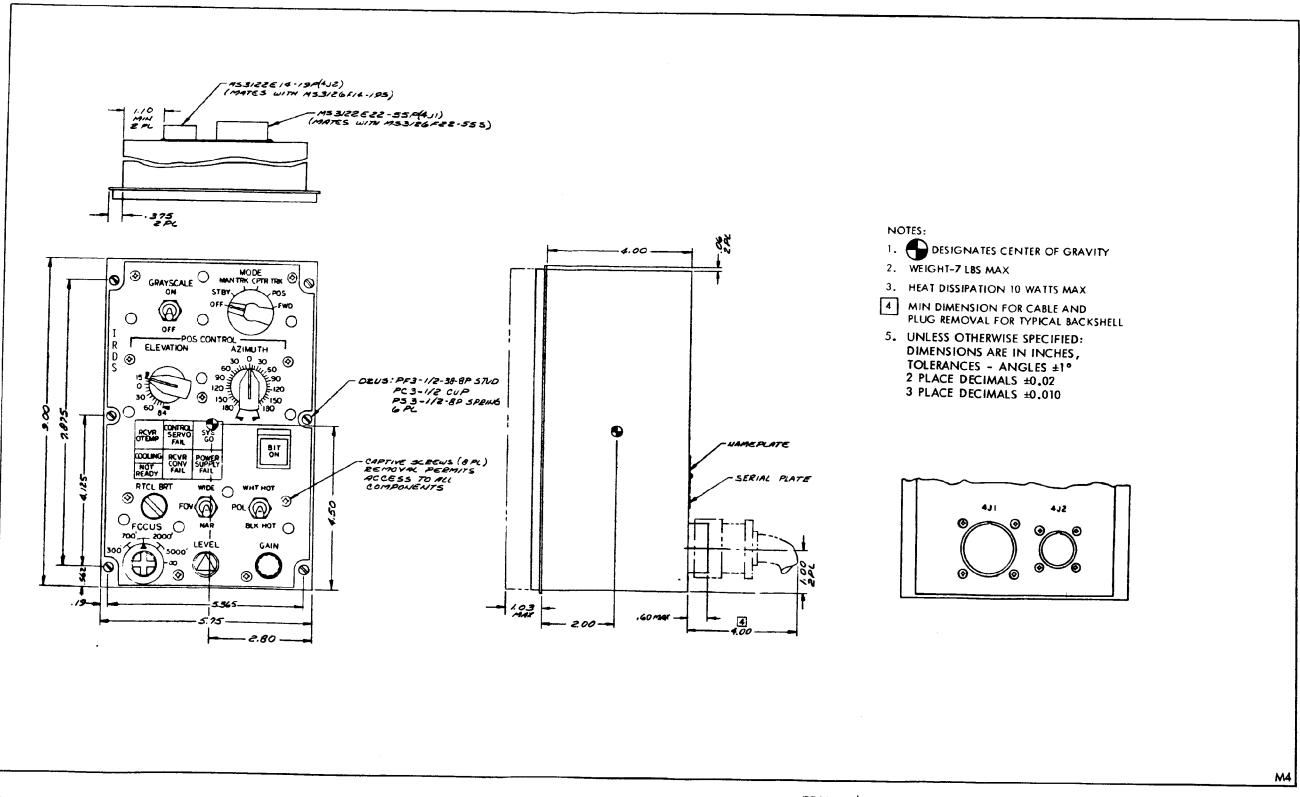


FIGURE 4. Control, detecting set, infrared, outline drawing.

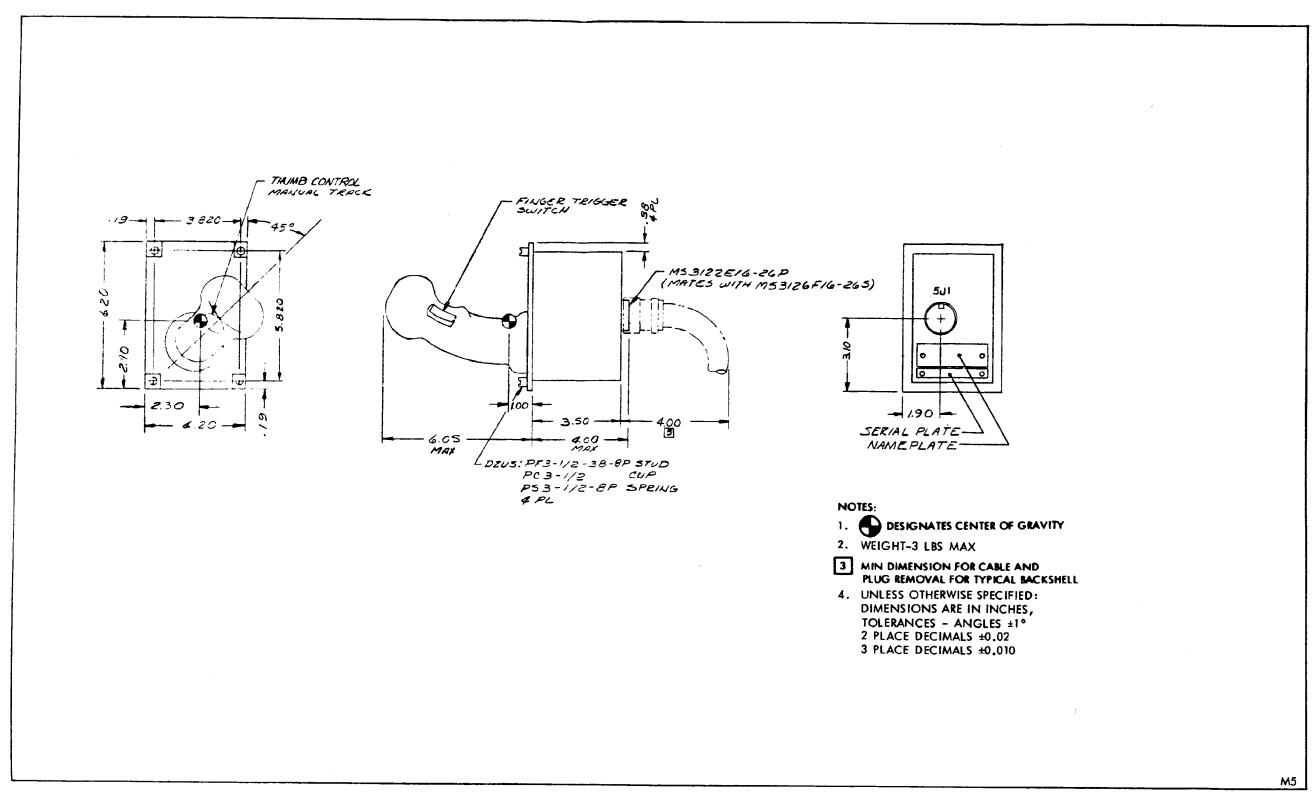


FIGURE 5. Control, sight, target, tracking, outline drawing.

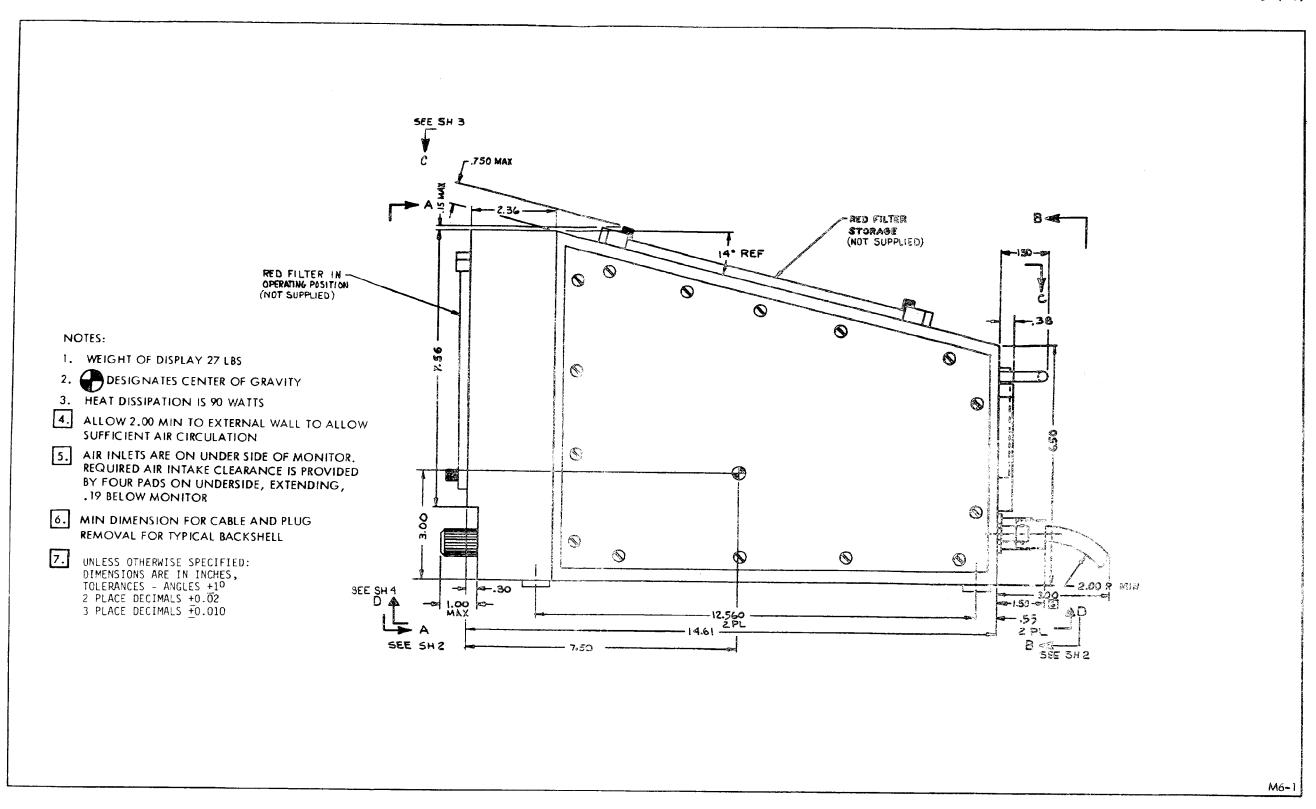


FIGURE 6. Indicator, video, outline drawing, (sheet 1 of 4)

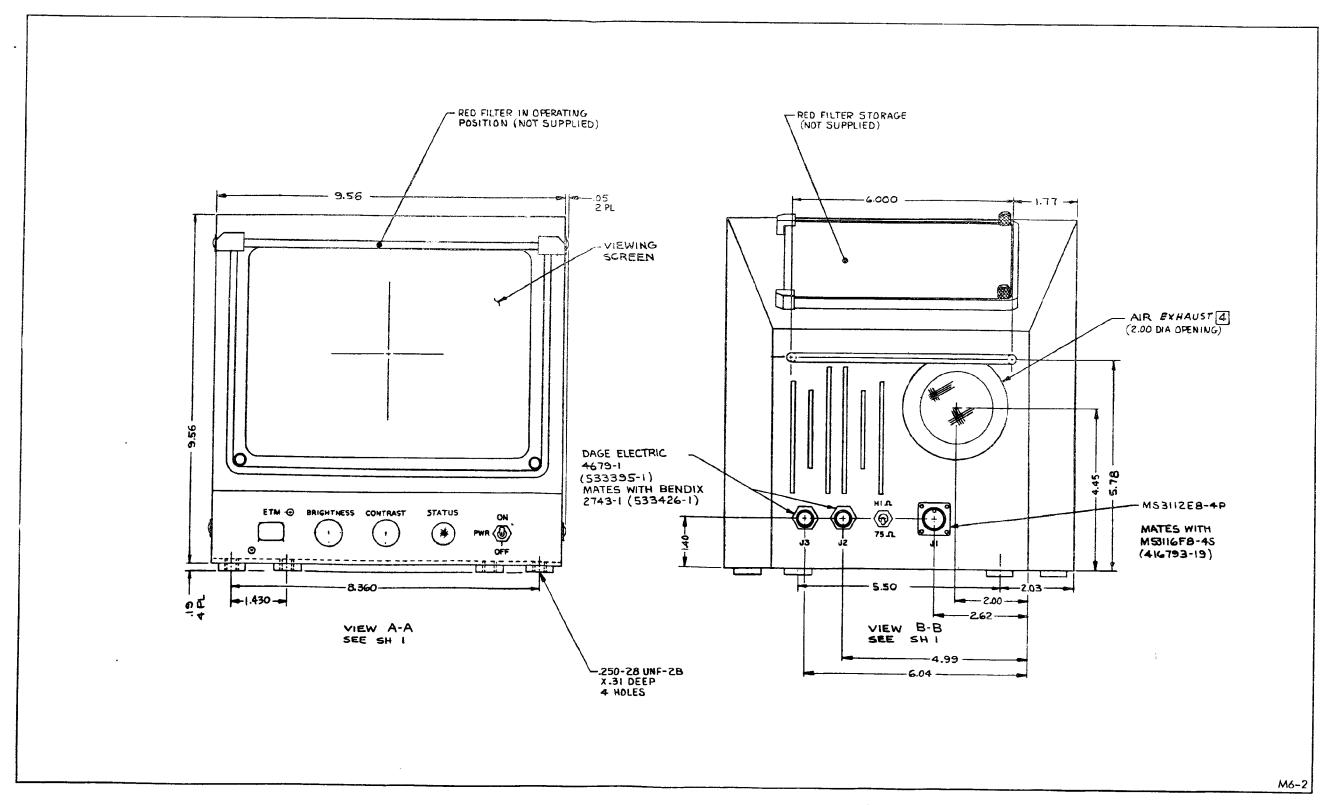


FIGURE 6. Indicator, video, outline drawing. (sheet 2 of 4)

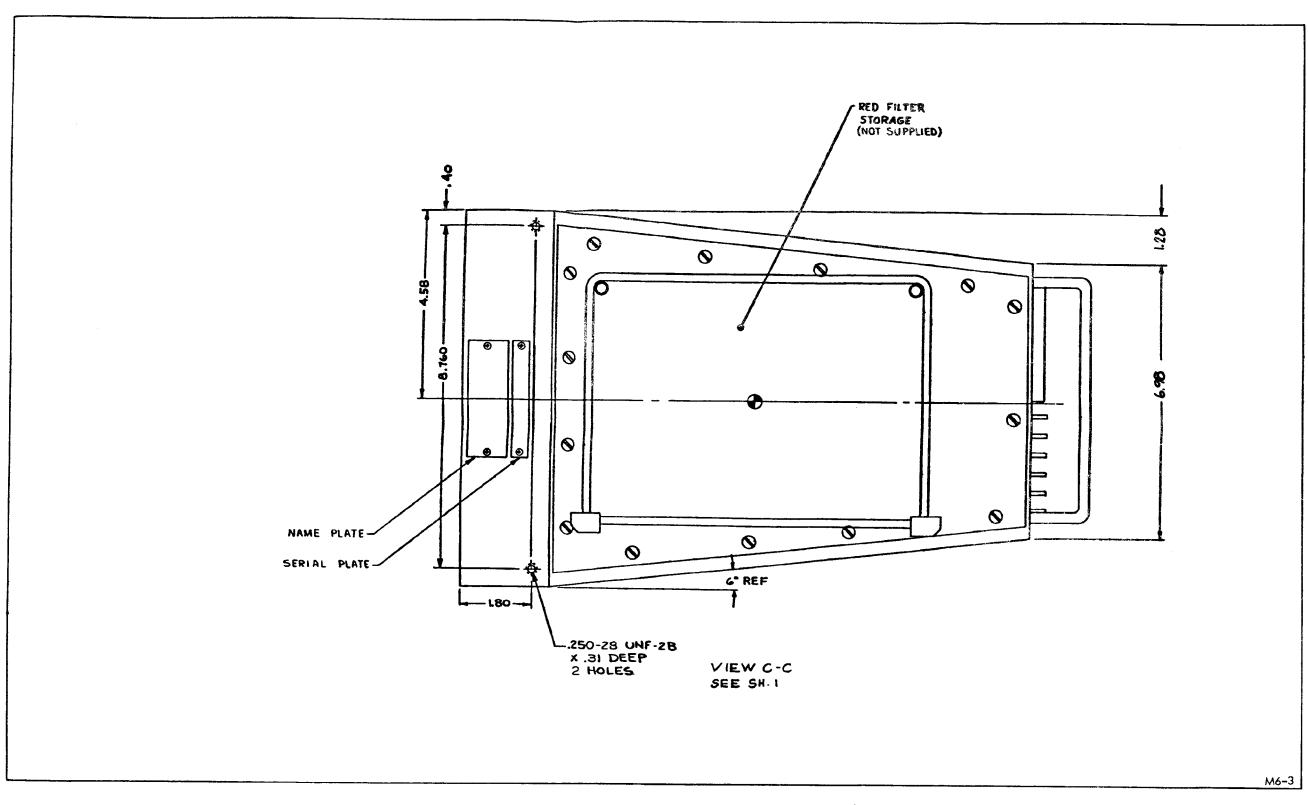


FIGURE 6. Indicator, video, outline drawing. (sheet 3 of 4)

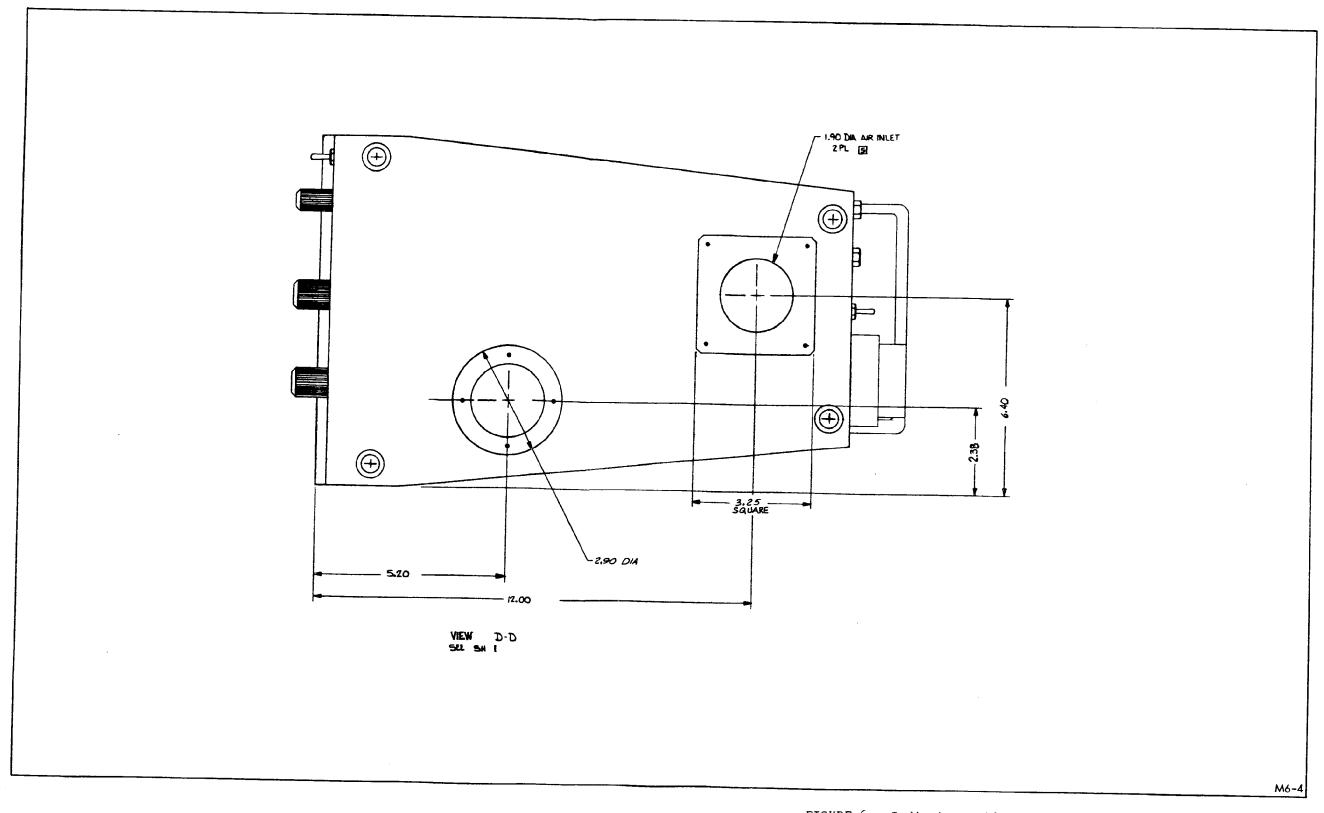


FIGURE 6. Indicator, video, outline drawing. (sheet 4 of 4)

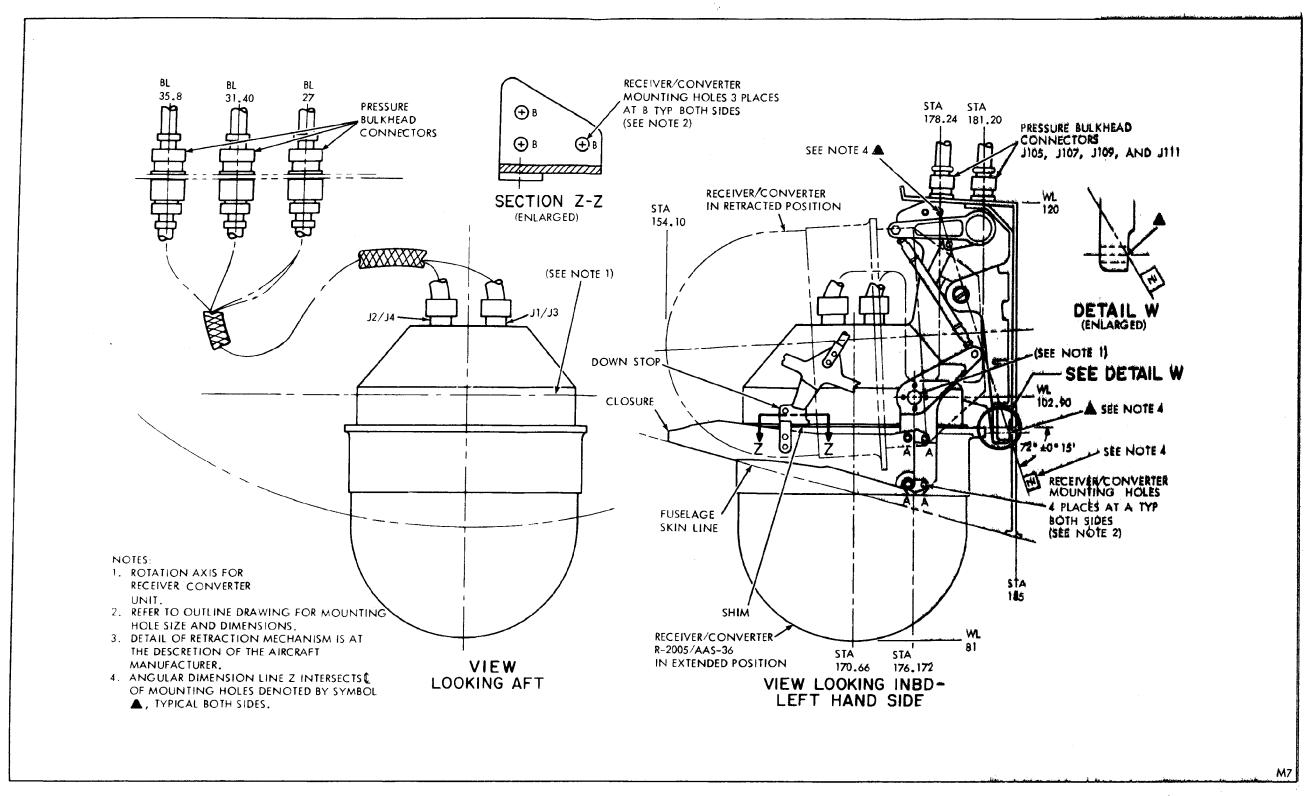


FIGURE 7. Receiver converter retractable turnet installation (typical).

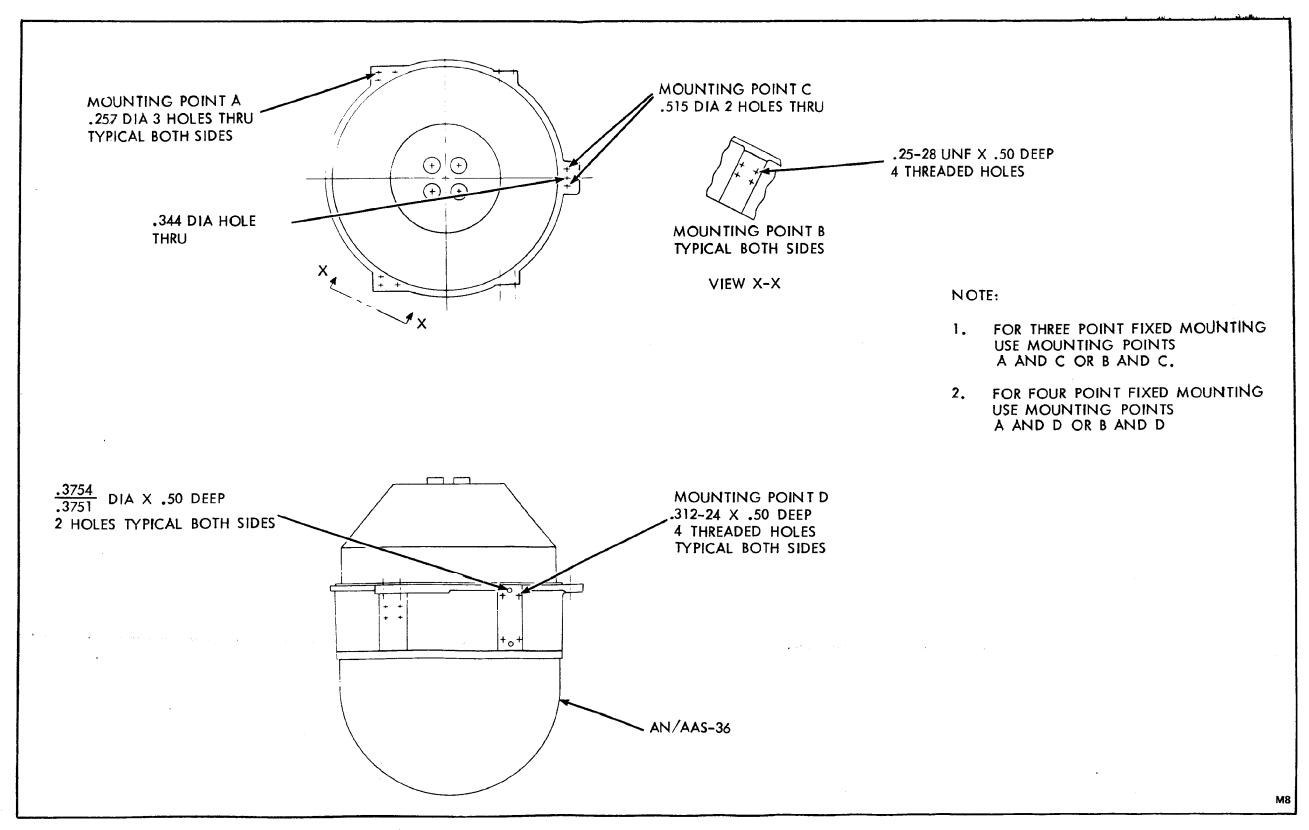
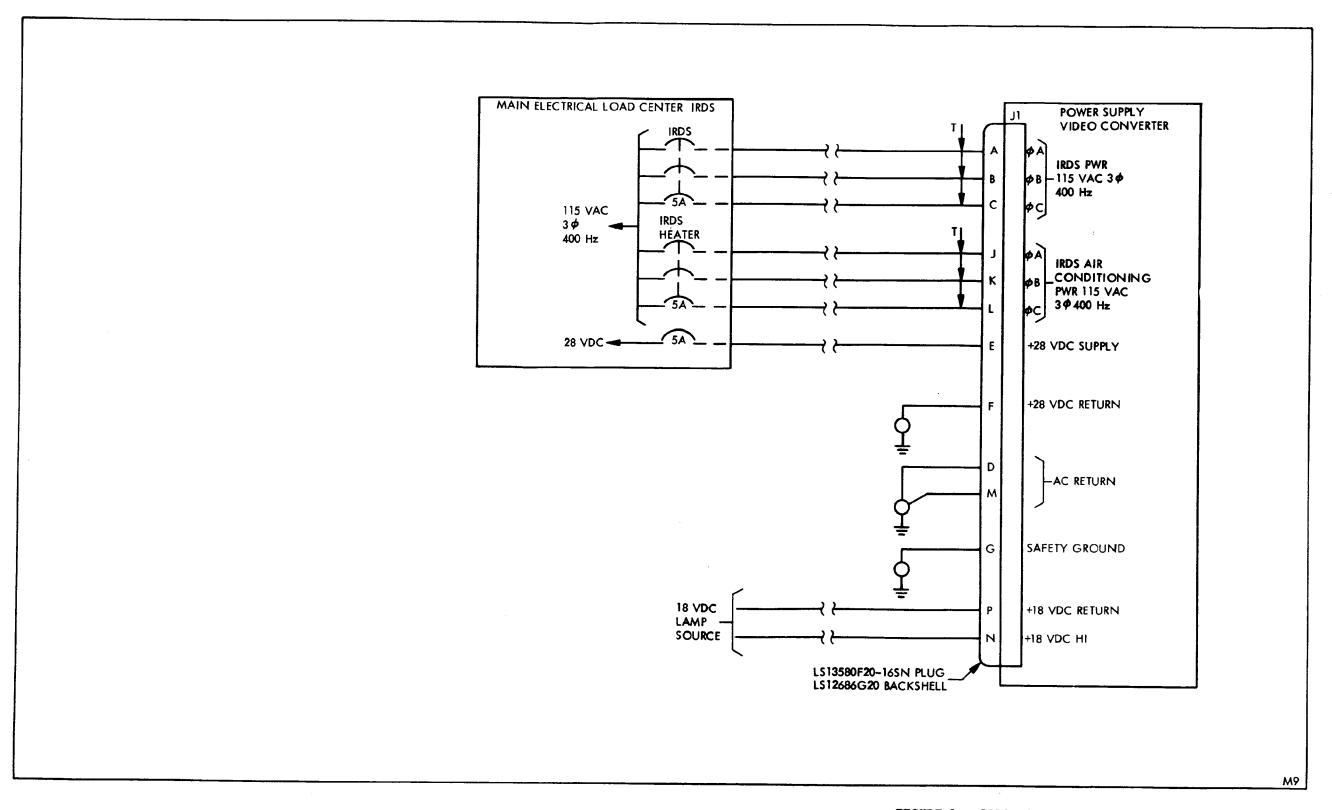


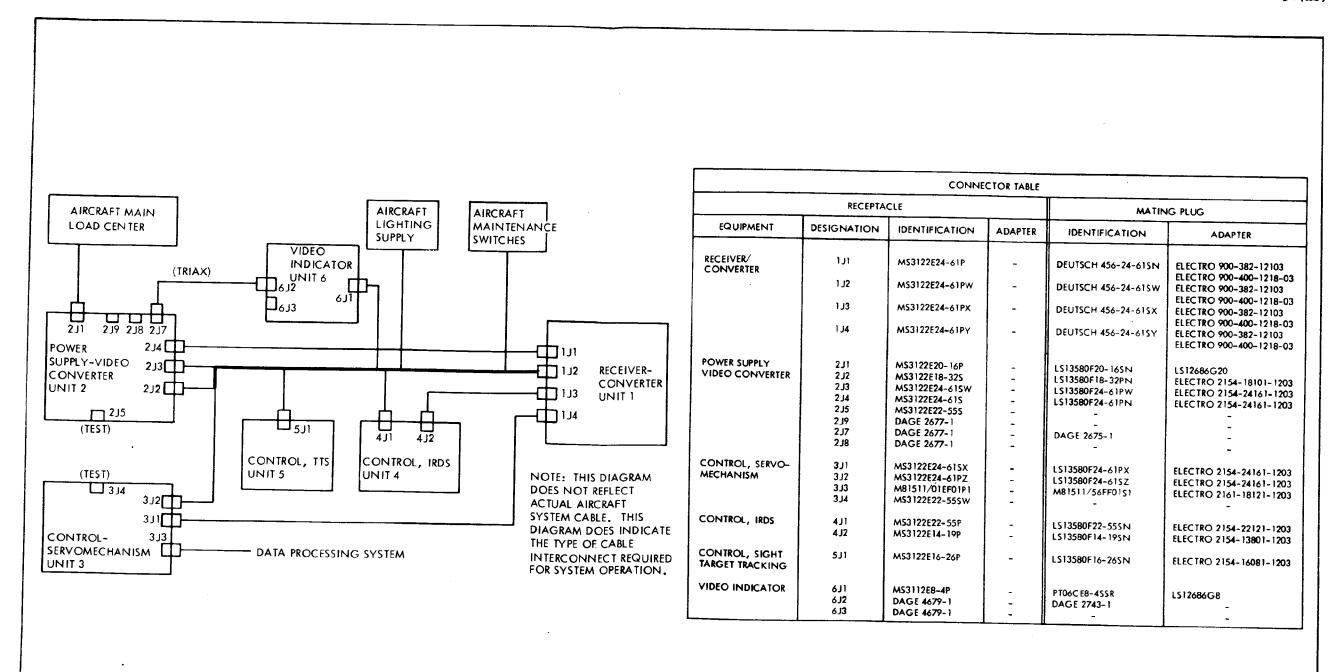
TABLE IV. Metric equivalents inches to millimeters.

Inch	MM	Inch	MM	Inch	ММ
*****	*****	*****	******	******	******
0.0010	0.025	1.9000	48.260	6.2000	157.480
0.0050	0.127	2.0000	50.800	6.2200	157.988
0.0100	0.254	2.0300	51.562	6.4000	162.560
0.0200	0.508	2.2500	57.150	6.5000	165.100
0.0500	1.270	2.3000	58.420	6.6300	168.402
0.0600	1.524	2.3500	59.690	6.7500	171.450
0.0900	2.286	2.3600	59 <b>.</b> 944	6.8800	171.752
0.1500	3.810	2.3800	60.452	6.9800	177.292
0.1900	4.810	2.5000	63.500	7.0000	177.800
0.2100	5.334	2.6000	66.040	7.5000	190.500
0.2200	5.588	2.6200	66.548	7.5600	192.024
0.2210	5.613	2.8000	71.120	7.6000	193.040
0.2500	6.350	2.9000	73.660	7.8750	200.025
0.2570	6.528	3.0000	76.200	7.9200	201,168
0.3000	7.620	3.1000	78.740	8.1000	205.740
0.3100	7.874	3.2500	82.550	8.3600	212.344
0.3120	7.925	3.4000	86.360	8.7600	222.504
0.3700	9.398	3.5000	88.900	9.0000	228.600
0.3750	9.525	3.6700	93.218	9.4500	240.030
0.3751	9.528	3.7500	95.250	9.5600	242.824
0.3754	9.535	3.8200	97.028	9.7000	246.380
0.3800	9.652	4.0000	101.600	9.7500	247.650
0.4000	16.160	4.1250	104.775	10.0000	254.000
0.4090	10.389	4.1800	106.172	10.2500	260.350
0.5000	12.700	4.2000	106.680	10.4000	264.160
0.5500	13.970	4.4500	113.030	10,6000	269.240
0.5620	14.275	4.5000	114.300	10.7500	273.050
0.6000	15.240	4.5800	116.332	11.0000	279.400
0.6250	15.875	4.7500	120.650	11.0900	281.686
0.6900	17.526	4.8000	121.920	11.5000	292.100
0.7500	19.050	4.8300	122.682	11.7000	297.180
0.8500	21.590	4.9900	126.746	11.7500	298.450
1.0000	25.400	5.1300	130.302	12.0000	304.800
1.0300	26.162	5.2000	132.080	12.4500	316.230
1.1000	27.940	5.3650	136.271	12.5600	319.024
1.2000	30.480	5.5000	139.700	14.6100	371.094
1.2800	32.512	5.6000	142.240	15.1200	384.048
1.3000	33.020	5.6400	143.256	17.0000	431.800
1.3300	33.782	5.7500	146.050	19.0000	482.600
1.4000	35.560	5.7800	146.812	19.4000	492.760
1.4300	36.322	5.8200	147.828	19.5000	495.300
1.5000	38.100	6.0000	152.400	20.0000	508.000
1.7000	43.180	6.0400	153.416	20.5000	520.700
1.7700	44.958	6.0500	153.670	28.1000	713.740
1.8000	45.720				



1

FIGURE 9. IRDS aircraft primary power interface.



M10

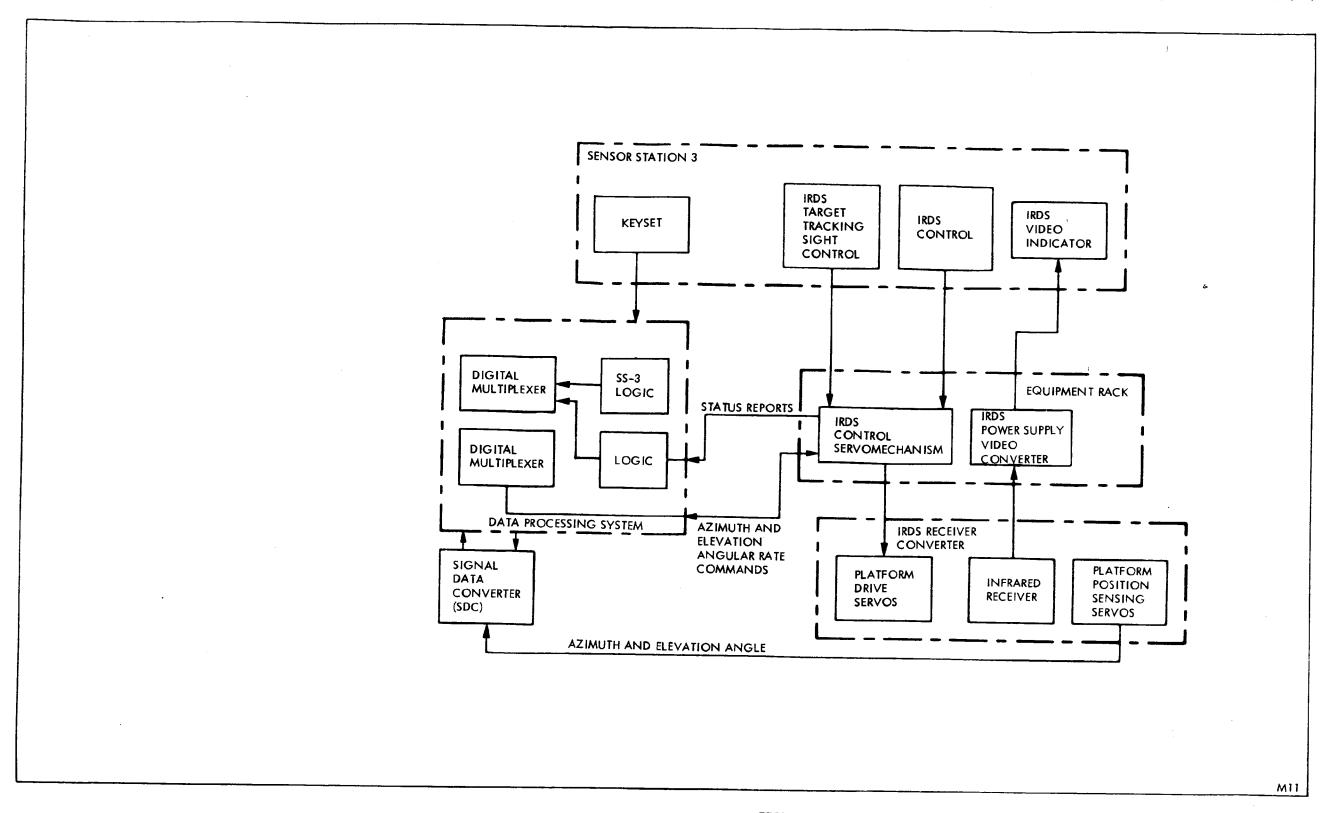


FIGURE 11. Typical IRDS/data processing system interfaces (P-3C).

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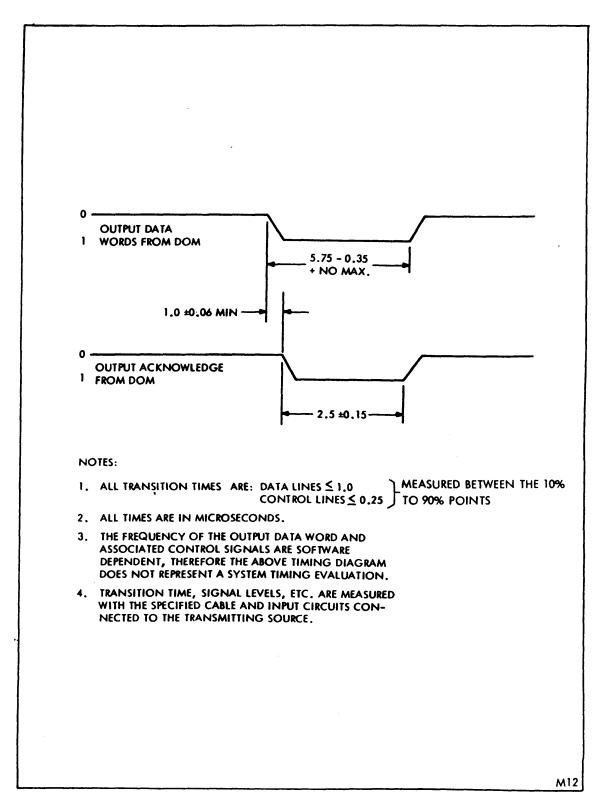


FIGURE 12. DOM/IRDS interface timing diagram (P-3C).

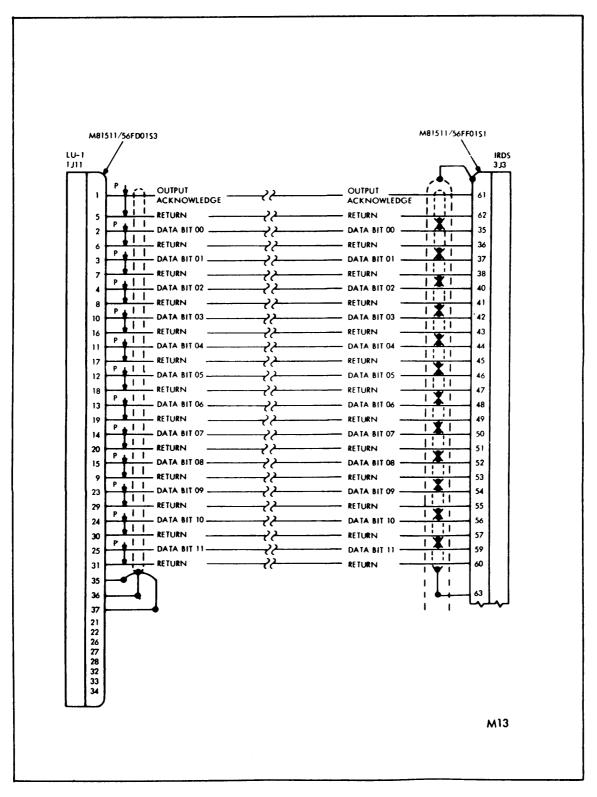


FIGURE 13. LU-1 DOM/IRDS CONTROL SERVOMECHANISM INTERFACE (P-3C).

		RIGIN	1	TERMINATION
EQUIPMENT	DPS AN/AYA-8		IRDS	
UNIT	Logic Unit 1- DOA	1	Control S	ervomechanism
CONNECTION	1,111-25,31		3,13-59,6	0
CHARACTERIST	CS:			
WIRE		Logic "1" Voltage		0 + 0.5 - 0.0 VD Sinking 40 MA
SIZE	See Schematic 22, 24 GA	Logic "0" Voltage		4 + 1 VDC Sourcing 10 MA
LENGTH	100 Ft. Max (overall)	Rise Time (10-90%)		1.0 usec Max
TYPE	See Schematic Twisted Pr/Shielded	Fall Time (10-90%)		1.0 usec Max
ine Receiver AC	130 Ohms Nom			
ine Receiver DÖ				

#### **REMARKS:**

Aircraft installation requirements are as specified in WR-101, Part I. Interface timing is per FIGURE 12.

This will be the most significant bit (MSB). Specified logic levels measured with cable meeting characteristics of 130 Ohms impedance, bandwidth of 10 MHz and attenuation factor of one percent or less.

#### SCHEMATIC

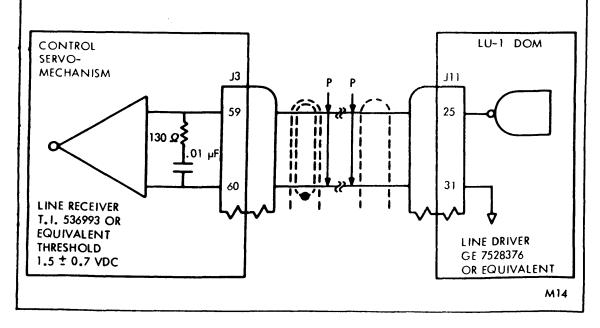


FIGURE 14. Data bit 11 signal characteristics.

		RIGIN	TERMINATION
EQUIPMENT	DPS (AN/AYA-8)		IRDS
UNIT	Logic Unit 1- DO	М	Control Servomechanism
CONNECTION	2,6–11ل		3J3-35,36
CHARACTERISTI	CS:		
WIRE		Logic "1" Voltage	0 + 0.5 - 0.0 VDC Sinking 40 MA
SIZE	See Schematic 22,24 GA	Logic "0" Voltage	4 ± 1 VDC Sourcing 10 MA
LENGTH	100 Ft. Max (Overall)	Rise Time (10-90%)	1.0 usec Max
TYPE	See Schematic Twisted Pr/Shielded	Fall Time (10-90%)	1.0 usec Max
ine Receiver AC Input Impedance			
Line Receiver D Input Impedance			

#### **REMARKS:**

Aircraft installation requirements are as specified in WR-101, Part I. Interface timing is per FIGURE 12. This will be the least significant bit (LSB). Specified logic levels measured with cable meeting characteristics of 130 Ohms impedance, bandwidth of 10 MHz and attenuation factor of one percent or less.

### **SCHEMATIC**

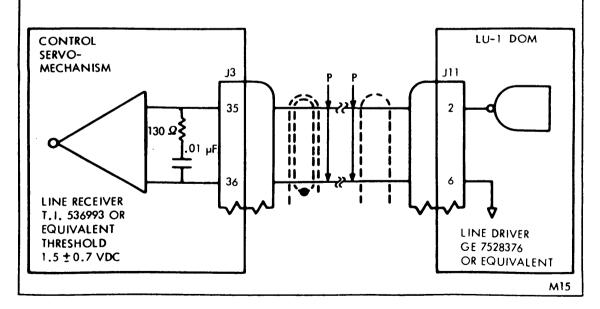


FIGURE 15. Data bit 00 signal characteristics.

	O	RIGIN	1	TERMINATION
EQUIPMENT	DPS (AN 'AYA-8)	DPS (AN 'AYA-8)		
JNIT	Logic Unit 1 DOM	Logic Unit 1 DOM Control Servomechanism		Servomechanism
CONNECTION	1,11-1,5		3J3-61,	62
CHARAC TERISTIC	<b>S</b> :			
VIRE		Logic "1" Voltage		0 + 0.5 - 0.0 VDC Sinking 40 MA
SIZE	22, 24 GA See Schematic	Logic "0" Voltage		4 + 1 VDC Sourcing 10 MA
	100 Ft. Max (overall)	Rise Time (10-90%)		0.25 usec Max
TYPE	See Schematic Twisted Pr 'Shielded	Fall Time (10-90%)		0.25 usec Max
ine Receiver AC				
ine Receiver DC	2000 Ohms Nom			
		requirements are as spe r FIGURE 12. Specifie		
SCHEMATIC	Interface timing is per	r FIGURE 12。Specific naracteristics of 130 Ob	ed logic level ims impedance	ls measured

FIGURE 16. Output acknowledge signal characteristics.

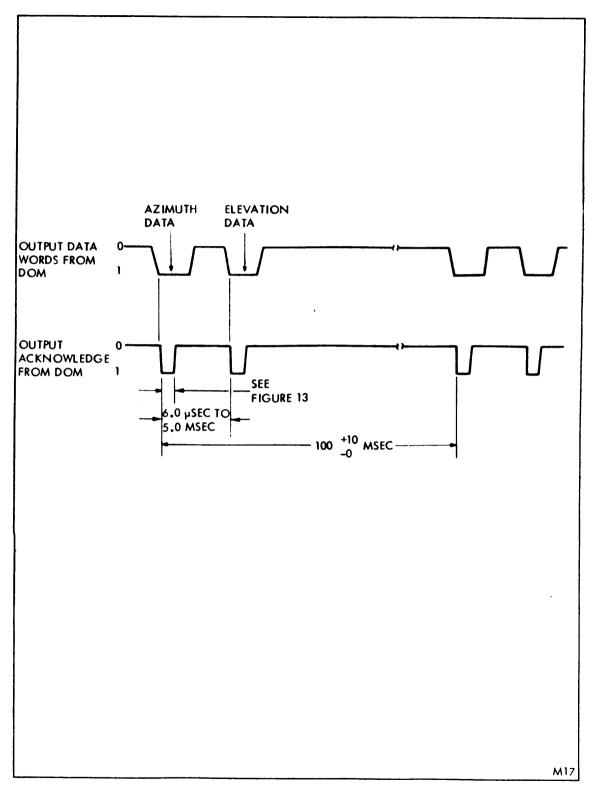


FIGURE 17. DOM/IRDS data update timing requirements.

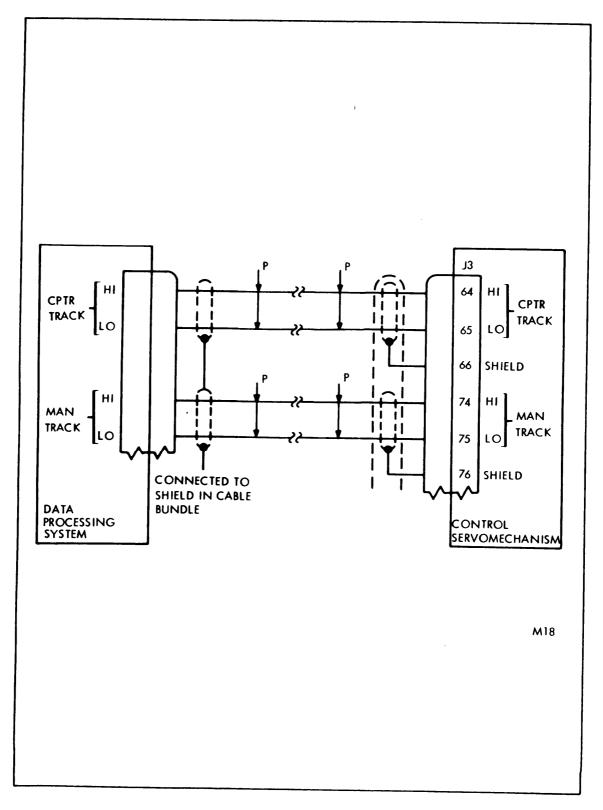


FIGURE 18. IRDS/data processing system status logic interface (P-3C).

	Of	IIGIN	TERMINATION
EQUIPMENT	IRDS		Data Processing System
UNIT	Control Servomech	onism	
CONNECTION	3J3-64, 65, 66		
CHARACTERISTI	CS:		
WIRE		Logic "1"	0 + 0.5 - 0.0 VDC Sinking 40 MA
SIZE	22 GA	Logic "0"	4.0 ± 1.0 VDC Sourcing 10 MA
LENGTH	100 Ft. Max overall		
TYPE	Twisted Pair Shielded		
Line Receiver Input	AC 130 Ohms		
Impedance	DC 2000 Ohms Nom		

#### **REMARKS:**

Aircraft installation requirements are as specified in WR-101, Part I. Status signal shall be a logic 1 when both of the following conditions are met:

- 1. Mode Selector Switch on IRDS Control Panel is in CPTR TRK position
- 2. IRDS is not executing built-in test functions.

Specified logic levels measured with cable meeting characteristics of 130 Ohms impedance, bandwidth of 10 MHz and attenuation factor of one percent or less.

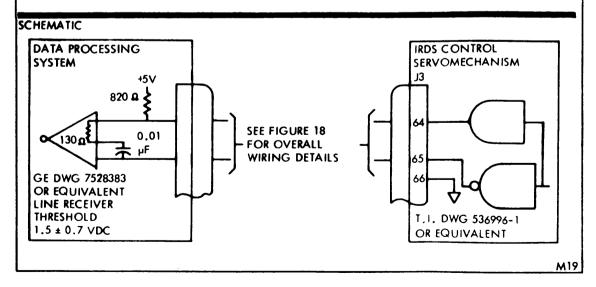


FIGURE 19. Computer track signal characteristics.

		RIGIN	TERM	INATION	
EQUIPMENT	IRDS		Data Processing S	Processing System	
UNIT	Control Servomed	hanism			
CONNECTION	3 13-74, 75, 76				
CHARAC TERISTI	CS:				
WIRE		Logic "1"	0 + 0.5, Sinking	- 0.0 VDC 40 MA	
SIZE	22 GA	Logic "0"	4.0 ± 1. Sourcing	0 ADC	
LENGTH	100 Ft. Max overall		Societing		
TYPE	Twisted Pair Shielded				
ine Receiver	AC 130 Ohms Nom				
nput mpedance	DC 2000 Ohms Nom			<del></del>	
EMARKS:		and the second			
A					
GE DWG 75283 OR EQUIVALEN LINE RECEIVER THRESHOLD 1.5 ±0.7 VDC	15V 320 Ω 0.01 六 μF	SEE FIGURE 18 FOR OVERALL WIRING DETAILS	J3 74 75 76 76	5 536996-1	
GE DWG 75283 OR EQUIVALENT THRESHOLD	15V 320 Ω 0.01 六 μF	FOR OVERALL	SERVOMI J3 74 75 76 T.I. DWC	5 536996-1	

FIGURE 20. Manual track override signal characteristics.

		ORIGIN		TERMINATION
EQUIPMENT	IRDS		Signal D	ata Converter
UNIT	Control Servome	echanism		
CONNECTION	3J3 - 67, 68, 6	69		
CHARACTERISTI	CS:			
WIRE		Voltage (Line to Line)		0 to 11.8 VRMS (400 Hz)
SIZE	22 GA	Impedance (SDS)		5000 ohms Min (Line to Line)
LENGTH	40 Ft. Max Overall	Load Unbalance		(TBD) Ohms Min ±2% (Line to Line)
TYPE	M27500A22-ML3T08	For Load of 5000 ohm	s synchro	zero will represent
	or equivalent	a zero azimuth angle	when air	rcraft wiring in
		accordance with FIGU	RE 24 is p	rovided.
	Aircraft installation	requirements are as speci	fied in Wi	R-101, Part I.
				м

FIGURE 21. IRDS az position signal characteristics.

EQUIPMENT IRDS Signal Date Converter  UNIT Control Servemechanism Unit  CONNECTION 3J3 - 70, 71, 72, 73  CHARACTERISTICS:  WIRE Voltage (Line to Line) 0 to 11,8 VRMS (400 Hz)  SIZE 22 GA Impedance (SDC) 5000 ohms min (Line to Line)  IENGTH 40 Fr. Max overall  FYPE M27500A22-ML3788 or equivalent a zero elevation angle when aircraft wiring in accordance with Figure 24 is provided.  REMARKS:  Aircraft installation requirements are as specified in WR-101, Part I.			O	RIGIN		TERMINATION
CONNECTION 3J3 - 70, 71, 72, 73  CHARACTERISTICS:  WIRE Voltage (Line to Line) 0 to 11.8 VRMS (400 Hz)  SIZE 22 GA Impedance (SDC) 5000 ohms min (Line to Line)  LENGTH 40 Ft. Max overall Load Unbalance (Line to Line) (Line to Ground)  TYPE M27500A22-ML3T08 or equivalent a zero elevation angle when aircraft wiring in accordance with Figure 24 is provided.  REMARKS:	EQUIPMENT		IRDS		Signal Data Converter	
CHARACTERISTICS:  WIRE Voltage (Line to Line) 0 to 11.8 VRMS (400 Hz)  SIZE 22 GA Impedance (SDC) (Line to Line)  LENGTH 40 Ft. Max overall (Load Unbalance (Ine to Line))  TYPE M27500A22-ML3T08 or equivalent For Load of 5000 ohms synchro zero will represent a zero elevation angle when aircraft wiring in accordance with Figure 24 is provided.  REMARKS:	UNIT		Control Servomech	Control Servomechanism Unit		
SIZE 22 GA Impedance (SDC) S000 ohms min (Line to Line)  LENGTH 40 Ft. Max overall (Line to Line) (Line to Line)  TYPE M27500A22-ML3T08 or equivalent (To Line) (Line to Line)  a zero elevation angle when aircraft wiring in accordance with Figure 24 is provided.	CONNECTION		3J3 - 70, 71, 72,	73		
SIZE  LENGTH 40 Ft. Max overall  TYPE  M27500A22-ML3T08 or equivalent  A zero elevation angle when aircraft wiring in accordance with Figure 24 is provided.  REMARKS:	CHARACTERISTIC	CS:				
LENGTH 40 Ft. Max overall (Line to Line)  Warsonaze-ML3T08 or equivalent  Lend Unbalance (Line) (TBD) ohms Min ±2% (Line to Ground)  For Load of 5000 ohms synchro zero will represent a zero elevation angle when aircraft wiring in accordance with Figure 24 is provided.  REMARKS:	WIRE			Voltage (Line to Line)		<u></u>
LENGTH 40 Ft. Max overall  TYPE M27500A22-ML3T08 or equivalent  Accordance with Figure 24 is provided.  Load Unbalance (Line to Line)  For Load of 5000 ohms synchro zero will represent a zero elevation angle when aircraft wiring in accordance with Figure 24 is provided.	SIZE	22	GA	Impedance (SDC)		5000 ohms min (Line to Line)
or equivolent  a zero elevation angle when aircraft wiring in  accordance with Figure 24 is provided.  REMARKS:	LENGTH	40	Ft. Max overall	Load Unbalance (Line to Line)		(TBD) ohms Min ±2%
a zero elevation angle when aircraft wiring in accordance with Figure 24 is provided.  REMARKS:	TYPE				s synchro	
REMARKS:		or	equivalent	a zero elevation ang	le when a	ircraft wiring in
				accordance with Figu	re 24 is p	rovided.
		A	ircraft installation re	equirements are as specif	ied in WR	-101, Part 1.

Figure 22. IRDS el position signal characteristics.

		OF	IIGIN		TERMINATION
EQUIPMENT		Signal Data Conv	erter	IRDS	
UNIT				Control	Servomechanism Unit
CONNECTION				3J3 - 32	2, 33, 34
CHARACTERIST	CS:				
WIRE			Voltage		26 ± 3 VRMS, 400 Hz
SIZE	22	? GA	Input Impedance (IRDS	5)	200 Ohras Min (400 Hz)
LENGTH	L	) Ft. Max Overall	Line to Ground Imped	ance	2000 Ohms Min
TYPE	Tv Sł	visted Pair nielded			
REMARKS:					
		•			
					101
			quirements are as specifi	ed in WK-	IUI, Part I.
Ti di	Se	ee FIGURE 24 for wiri	ng details		
ii					
					M23

FIGURE 23. 26 VAC reference voltage signal characteristics.

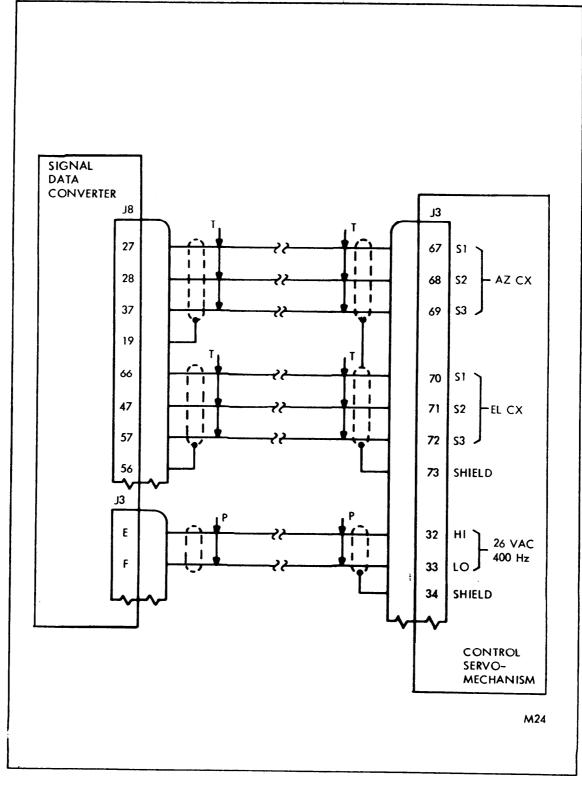
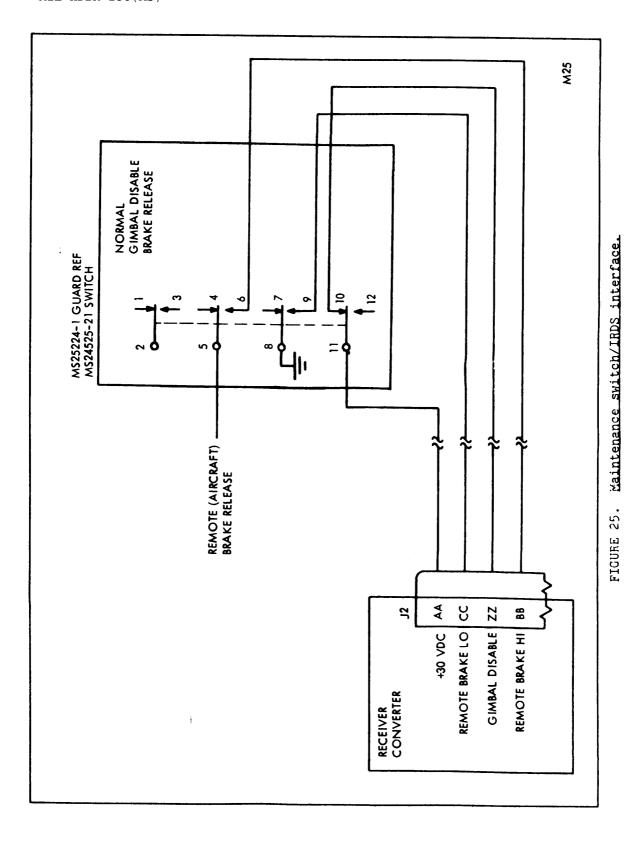


FIGURE 24. IRDS/signal data converter interwiring details.



96

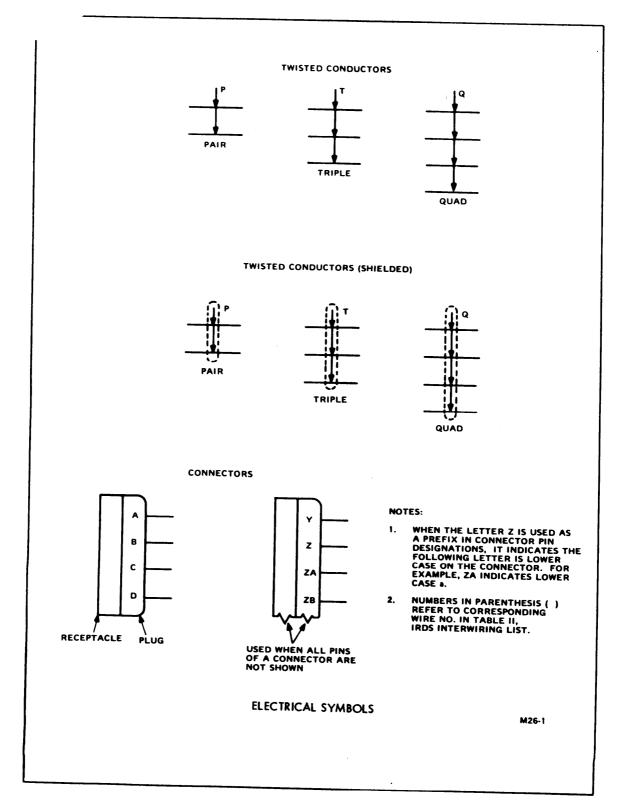


FIGURE 26. IRDS interconnecting diagram. (sheet 1 of 27)

111			<del></del>
1J1 Cut P	POST AMP +10 VDC HI (9)		0.71
J			2J4-J
K HV	POST AMP +10 VDC RETURN (10)		2J4-K
N HIT	POST AMP -9 VDC HI (13)	*******	2J4-N
P   I IX	POST AMP -9 VDC RETURN (14)		2J4-P
T	PRE AMP +10 VDC HI (17)		2J4-T
U	PRE AMP +10 VDC RETURN (18)		2J4-U
W	PRE AMP SENSE HI (20)		2J4-W
x   <del>                               </del>	PRE AMP SENSE RETURN (21)	<del></del>	2J4-X
v	SHIELD (19)		
L HIT	FOCUS +15 VDC (11)		2J4-L
M H	FOCUS -15 VDC (12)		2J4-M
ZJ I	<u>+</u> ±15 VDC RETURN (33)		2J4-ZJ
$R \downarrow \downarrow P$	+5 VDC BITE RETURN (15)	<del></del>	2J4-R
s	+5 VDC BITE (16)		2J4-S
Y P	+10 VDC SENSE HI (22)		2J4-Y
$  z  ^{\frac{1}{1+\frac{1+1}{1+\frac{1+1}{1+\frac{1+1}{1+\frac{1}{1+\frac{1}{1+\frac{1}{1+\frac{1}{1+\frac{1}{1+\frac{1}{1+\frac{1+1}{1+\frac{1+\frac{1}{1+\frac{1+\frac{1+1}{1+\frac{1+\frac{1+1}{1+\frac{1+\frac{1+1}{1+\frac{1+1}{1+\frac{1+\frac{1+1}{1+\frac{1+1}{1+\frac{1+\frac{1+1}{1+1+\frac{1+1}{1+\frac{1+1}{1+\frac{1+1}{1+1}$	+10 VDC SENSE RETURN (23)		2J4-Z
ZE	SHIELD (28)		
ZS IIIP	LED +10 VDC HI (40)		2J4-ZS
ZT	LED +10 VDC RETURN (41)		2J4-ZT
zc     · · ·	SPARE (26)	<del></del>	2J4-ZC
ZD II	OVERHEAT HI (27)		2J4-ZD
ZA I P	SYSTEM INTERLOCK (24)	-	2J4-ZA
ZB	- SYSTEM INTERLOCK (25)		2J4-ZB
ZK	+14 VDC (34)		2J4-ZK
ZM	±14 VDC RETURN (35)		2J4-ZM
BB	14 VDC (49)		2J4-BB
zQ	RCVR BITE (38)		2J4-ZQ
ZN	RECEIVER TOO COLD (36)		2J4-ZN
ZR	RECEIVER BITE INHIBIT (39)		2J4-ZR
ZP	SPARE (37)		2J4-ZP
CC	— SPARE (50)		2J4-CC
	22 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \		M26·2

FIGURE 26. IRDS interconnecting diagram. (sheet 2 of 27)

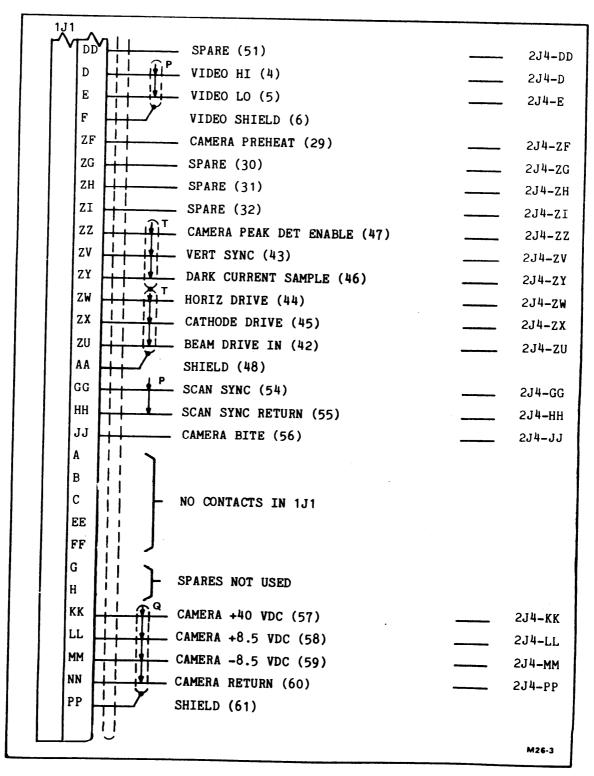


FIGURE 26. IRDS interconnecting diagram. (sheet 2 of 27).

1J2 I P			
A	- SPARE (62)		2J2-V
B B	SPARE (63)		2J2-W
c	SPARE (64)		2J2-C
D	SPARE (65)	-	2J2 <b>-</b> F
F T	SPARE (67)		2J3-A
G	SPARE (68)		2J3 <b>-</b> B
H + +	SPARE (69)		2J3-C
M	SAFETY GROUND (73)		2 <b>J3-</b> JJ
P P	SCAN -5 VDC HI (75)		2J3-ZQ
R	SCAN -5 VDC RETURN (76)		2J3-ZR
S P	SCAN +5 VDC HI (77)		2J3-ZN
T -	SCAN +5 VDC RETURN (78)		2J3-ZP
U	SCAN +15 VDC HI (79)		2J3-EE
V	SCAN +15 VDC RETURN (80)		2J3-FF
W P	SCAN -15 VDC HI (81)		2J3-GG
X X	SCAN -15 VDC RETURN (82)		2J3 <b>-</b> HH
Υ	SPARE (83)		2J3 <b>-</b> ZT
z	SPARE (84)	<del></del>	2J3-ZA
ZA	SYSTEM INTERLOCK (85)		
ZB	SISIEM INTERLOCK (03)		
ZC P	SPARE (87)		2J2-A
ZD	SPARE (88)	-	2J2 <b>-</b> B
ZE -	SPARE (89)		2J2 <b>-</b> G
ZF	SPARE (90)		2J2 <b>-</b> H
ZG	SPARE (91)		2J2-D
ZH	SPARE (92)	<del></del>	2J2 <b>-</b> E
ZK	+28 VDC HI (95)		2J3-KK
ZM	+28 VDC RETURN (96)		2J3-LL
DD -	SYSTEM INTERLOCK (112)		
EE	J SISIEM INTERBOOK (112)		
ι <b>∕</b> νι <b>∕</b> νι			M26-4

FIGURE 26. IRDS interconnecting diagram. (sheet 4 of 27)

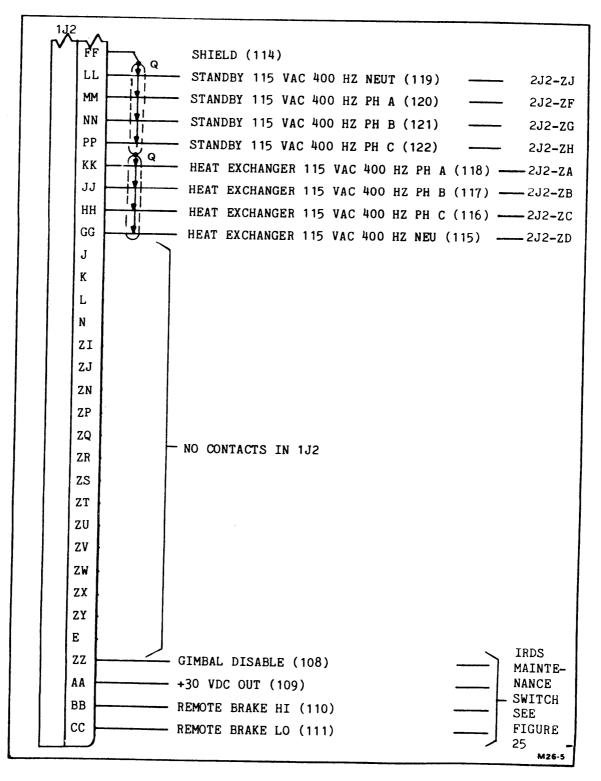


FIGURE 26. IRDS interconnecting diagram. (sheet 5 of 27)

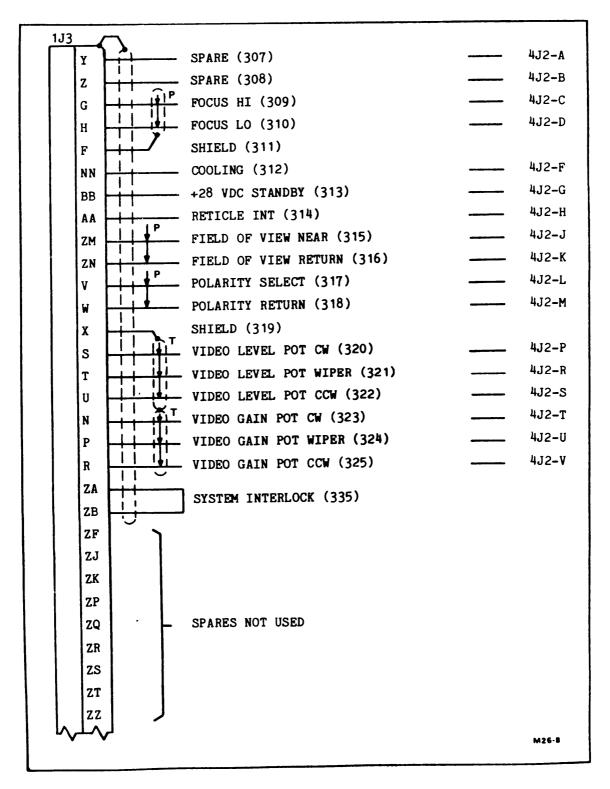


FIGURE 26. <u>IRDS interconnecting diagram.</u> (sheet 6 of 27)

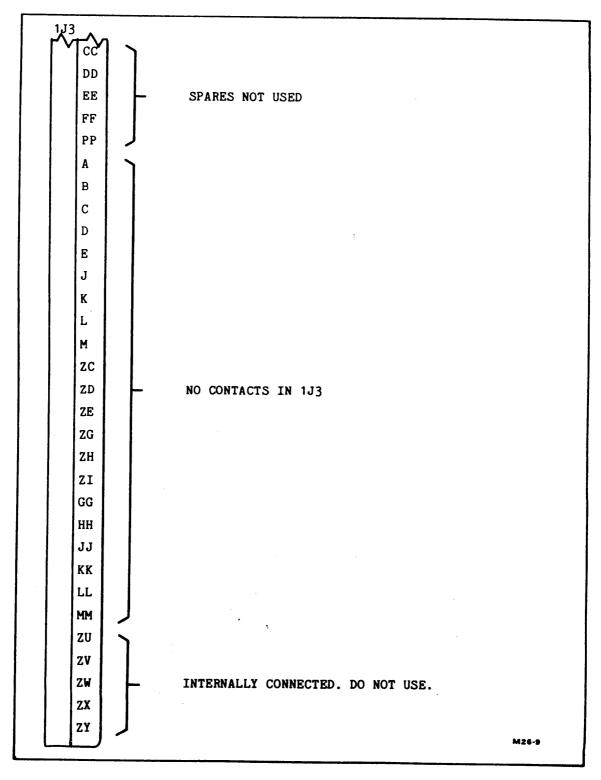


FIGURE 26. IRDS interconnecting diagram. (sheet 7 of 27)

1J4		<del></del>
A P SPARE (245)	**********	3J1-A
B SPARE (246)		3J1 <b>-</b> B
C SHIELD (247)		50 . 2
D +30 VDC SUPPLY (248)	<del></del>	3J1-D
E GIMBAL DISABLE (249)	-	3J1-E
F BRAKE HI (250)	**********	3J1-F
G BRAKE LO (251)		3J1-G
H SHIELD (252)		
J SERVO +15 VDC HI (253)		3J1-J
K SERVO ±15 VDC RETURN (254)		3J1-K
L SERVO -15 VDC HI (255)		3J1-L
M P 26 VAC ∠O° EXCITATION (256)		3J1-M
N 26 VAC ∠O° RETURN (257)		3J1-N
P SPARE (258)		3J1-P
R SHIELD (259)		
S AZ RATE HI (260)		3J1-S
T AZ RATE LO (261)		3J1-T
U EL GIM POS POT CW (262)		3J1-ช
V EL GIM POS POT WIPER (263)		3J1-V
W EL GIM POS POT CCW (264)		3J1-W
SHIELD (265)		
Y AZ RESOLVER S1 (266)	-	3J1-Y
Z AZ RESOLVER S3 (267)		3J1-Z
ZA AZ RESOLVER S2 (268)		3J1-ZA
ZB AZ RESOLVER S4 (269)	·	3J1-ZB
ZK EL RESOLVER S1 (270)		. 3J1-ZK
ZM EL RESOLVER S3 (271)	<del></del>	3J1-ZM
ZN P EL RESOLVER S2 (272)		3J1-ZN
ZP EL RESOLVER S4 (273)		3J1-ZP
ZW SHIELD (274)		
ZC SPARE (275)	-	3J1-ZC
· <b>v v</b>		M26-7

FIGURE 26. <u>IRDS interconnecting diagram.</u> (sheet 8 of 27)

I			
1,14	7	QUITE D. (27.6)	
ŽD	P	SHIELD (276)	
ZE		SERVO +5 VDC HI (277)	3J1-ZE
ZF		SERVO +5 VDC RETURN (278)	3J1-ZF
ZG	1	AZ TACH HI (279)	 3 <b>J 1-</b> ZG
ZH	<del>                                     </del>	AZ TACH LO (280)	 3J1-ZH
ZI	<del>                                     </del>	SHIELD (281)	
ZJ	<del></del>	SPARE (282)	 3J1 <b>-</b> ZJ
ZQ	AP P	EL RATE HI (283)	 3J1-ZQ
ZR	<del></del>	EL RATE LO (284)	 3J1-ZR
ZS	<del> </del>	SHIELD (285)	
ZT		GYRO TEMP (286)	 3J1-ZT
zu	P	GIMBAL FAIL HI (287)	 3J1-ZU
ZV	<u> </u>	GIMBAL FAIL LO (288)	 3J1-ZV
ZY	<u> </u>	+15 VDC SUPPLY (290)	 3J1-ZY
ZZ	 	+15 VDC RETURN (291)	 3J 1-ZZ
ВВ		-15 VDC SUPPLY (293)	 3J1-BB
cc		-15 VDC RETURN (294)	 3J1-CC
DD	₽ P	EL TORQ HI (295)	 3J1-DD
EE	<u></u>	EL TORQ LO (296)	 3J1-EE
FF	A P	AZ MOTOR DRIVE HI (297)	 3J1 <b>-</b> FF
GG	- <del>  •</del>	AZ MOTOR DRIVE LO (298)	 3J1-GG
нн		SHIELD (299)	
JJ	_	SHIELD (300)	
кк	T	AZ POS POT CW (301)	 3J1-KK
LL		AZ POS POT WIPER (302)	 3J1-LL
MM		AZ POS POT CCW (303)	 3J1-MM
l nn		SPARE (304)	 3J1-NN
PP		SAFETY GROUND (305)	3J 1-PP
			J
ZX	<b> </b>	NO CONTACTS IN 1J4	
AA			
			M26-6
	<del></del>		 

FIGURE 26. IRDS interconnecting diagram. (sheet 9 of 27)

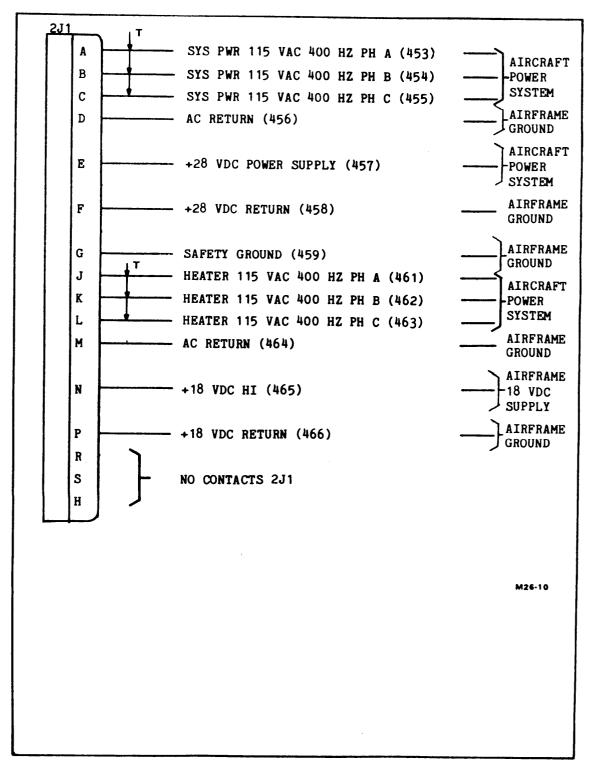


FIGURE 26. IRDS interconnecting diagram. (sheet 10 of 27)

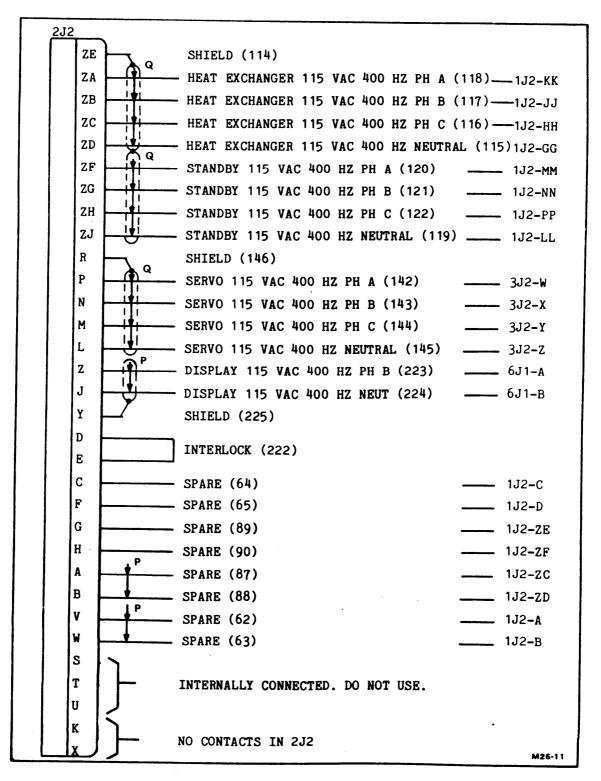


FIGURE 26. IRDS interconnecting diagram. (sheet 11 of 27)

2J3			
R	SYSTEM GO (195)	-	4J1-ZF
P	RCVR FAIL (196)		4J1-ZG
N	POWER SUPPLY FAIL (197)	<del></del>	4J1-ZH
M	SERVO FAIL (198)		4J1-ZI
L -	NOT READY (199)		4J1-ZJ
к	BIT SWITCH (200)		4J1-ZK
J	OVERTEMP (201)		4J1-ZM
\ \v \	GRAY SCALE HI (192)		4J1-ZC
U	+28 VDC RETURN (193)		4J1-ZD
s	GO RESET (202)		4J1-ZN
T T	BIT INDICATOR (203)	****	4J1-ZP
$G \longrightarrow T$	+28 VDC SUPPLY (204)		4J1-ZQ
F	STANDBY COMMAND (205)		4J1-ZR
ZG	OPERATE COMMAND (206)		4J1-ZS
H T	SPARE (187)		4J1-D
ZB	SPARE (188)		4J1-E
zc	SPARE (189)		4J1~F
zu	SAFETY GROUND (194)		4J1-ZE
zs	+18 VDC POWER SUPPLY (207)		4J1-ZU
ZJ	FOCUS +15 VDC (219)		4J1-FF
ZK	FOCUS -15 VDC (220)		4J1-GG
ZM 10	FOCUS ±15 VDC RETURN (221)		4J1-HH
ZN P	SCAN +5 VDC HI (77)		1J2-S
ZP	SCAN +5 VDC RETURN (78)	·	1J2-T
ZQ P	SCAN -5 VDC HI (75)		1J2-P
ZR	SCAN -5 VDC RETURN (76)		1J2-R
EE P	SCAN +15 VDC HI (79)	*****************	1J2-U
FF	SCAN +15 VDC RETURN (80)	*	1J2-V
GG P	SCAN -15 VDC HI (81)		1J2-W
нн	SCAN -15 VDC RETURN (82)	-	1J2-X
JJ ——	SAFETY GROUND (73)	-	1J2-M
			M26-12

FIGURE 26. IRDS interconnecting diagram. (sheet 13 of 27)

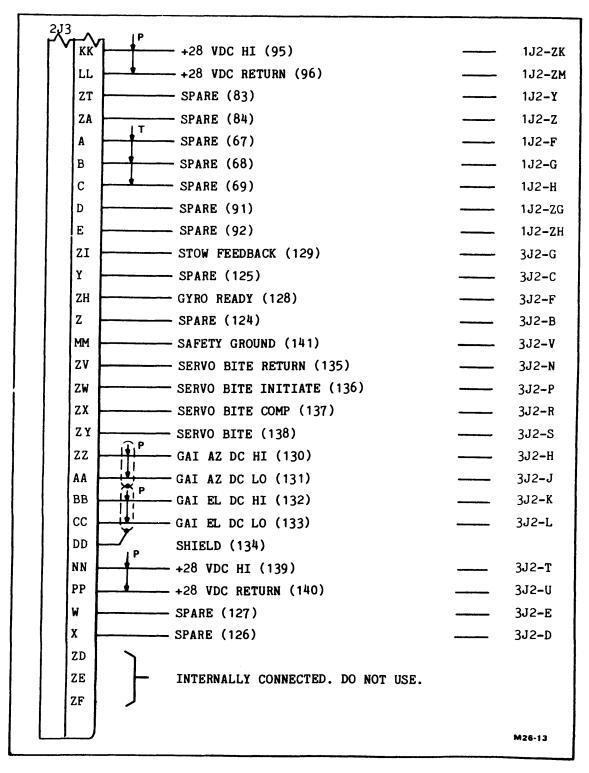


FIGURE 26. IRDS interconnecting diagram. (sheet 13 of 27)

2J4 P		_
J POST AMP +10 VDC HI (9)		1J1-J
POST AMP +10 VDC RETURN (10)		1J1-K
N P POST AMP -9 VDC HI (13)		1J1-N
P POST AMP -9 VDC RETURN (14)		1J1-P
T PRE AMP +10 VDC HI (17)		1J1-T
U PRE AMP +10 VDC RETURN (18)	er-110-	1J1-U
W PRE AMP SENSE HI (20)		1J1-W
X PRE AMP SENSE RETURN (21)		1J1-X
V SHIELD (19)		
15 VDC (11)		1J1-L
NDC (12)		1J1-M
22)		1J1-ZJ
P P P P P P P P P P P P P P P P P P P		1J1-R
1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1		1J1-S
(22)		1J1-Y
1 191 AND DETURN (23)		1J1-Z
ZE SHIELD (28)		1J1-ZS
ZS LED +10 VDC HI (40)		1J1-ZT
ZT LED +10 VDC RETURN (41)		1J1-Z0
ZC SPARE (26)		1J1-ZE
ZD OVERHEAT HI (27)		1J1-ZA
ZA SYSTEM INTERLOOK (21)		1J1-ZE
ZB SYSTEM INTERLOCK (25)		1J1-ZF
ZK +14 VDC (34)		1J1-Z1
ZM ±14 VDC RETURN (35)		1J1-B
BB -14 VDC (49)		1J1-Z
ZQ RCVR BITE (38)		1J1-Z
ZN RECEIVER TOO COLD (36)		1J1-Z
ZR RECEIVER BITE INHIBIT (39)	<del></del>	1J1-Z
ZP SPARE (37)		1J1-C
CC SPARE (50)		M26
\ <del></del>		

FIGURE 26. IRDS interconnecting diagram. (sheet 14 of 27)

2.71			
2J4 1 <b>\(\sqrt{1}\)</b>			
DD T.P	SPARE (51)		1J1-DD
D + + + + + + + + + + + + + + + + + + +	VIDEO HI (4)		1J1-D
E   +	VIDEO LO (5)		1J1-E
F   + + - /	VIDEO SHIELD (6)		
ZF   1	CAMERA PREHEAT (29)	-	1J1-ZF
ZG 1	SPARE (30)		1J1-ZG
ZH ++	SPARE (31)	****	1J1-ZH
ZI	SPARE (32)		1J1-ZI
ZZ + + + + + + + + + + + + + + + + + +	CAMERA PEAK DET ENABLE (47)		1J1-ZZ
	VERT SYNC (43)		1J1-ZV
ZY	DARK CURRENT SAMPLE (46)		1J1-ZY
$ZW = \frac{1}{1} \frac{A}{1} \frac{T}{1}$	HORIZ DRIVE (44)		1J1-ZW
ZX	CATHODE DRIVE (45)	•	1J1-ZX
ZU ZU	BEAM DRIVE IN (42)		1J1-ZU
AA = 1	SHIELD (48)	***********	
GG P	SCAN SYNC (54)		1J1-GG
НН !	SCAN SYNC RETURN (55)		1J 1-HH
JJ H	CAMERA BITE (56)		1J1-JJ
BII			
c   !			
EE	NO CONTACTS IN 2J4		
FF			
KK I Q	CAMERA +40 VDC (57)		1J1-KK
LL I I I	CAMERA +8.5 VDC (58)		1J1-LL
MM	CAMERA -8.5 VDC (59)		
NN III	CAMERA RETURN (60)		1J1-MM
PP	SHIELD (61)		1J1-PP
	CHILDD (OI)		
			M26-15

FIGURE 26. IRDS interconnecting diagram. (sheet 15 of 27)

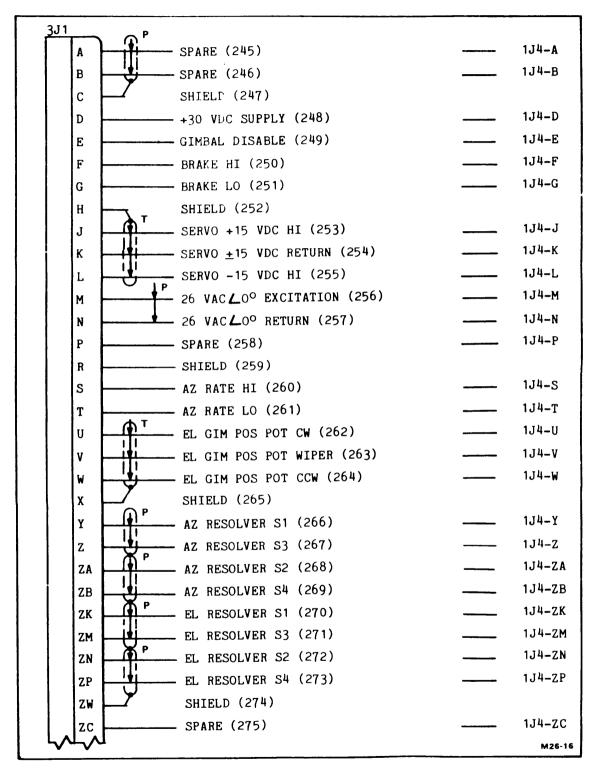


FIGURE 26. IRDS interconnecting diagram. (sheet 16 of 27)

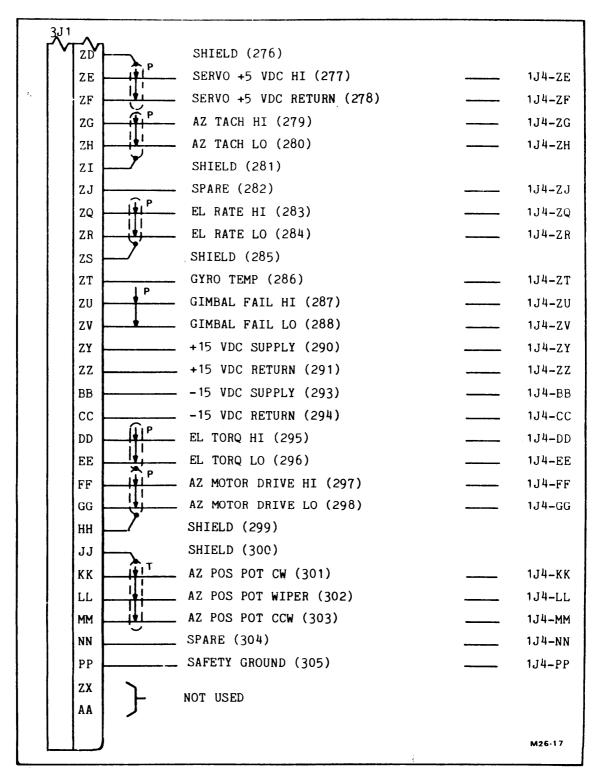


FIGURE 26. IRDS interconnecting diagram. (sheet 17 of 27)

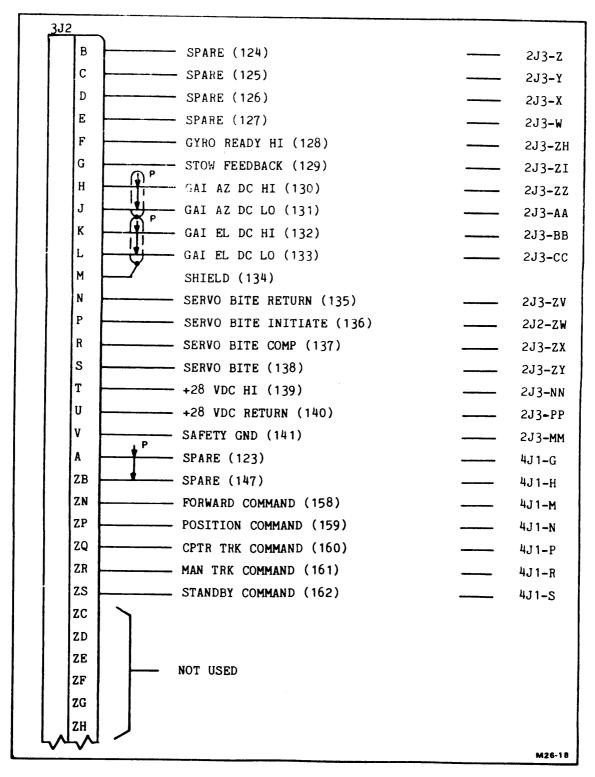


FIGURE 26. IRDS interconnecting diagram. (sheet 18 of 27)

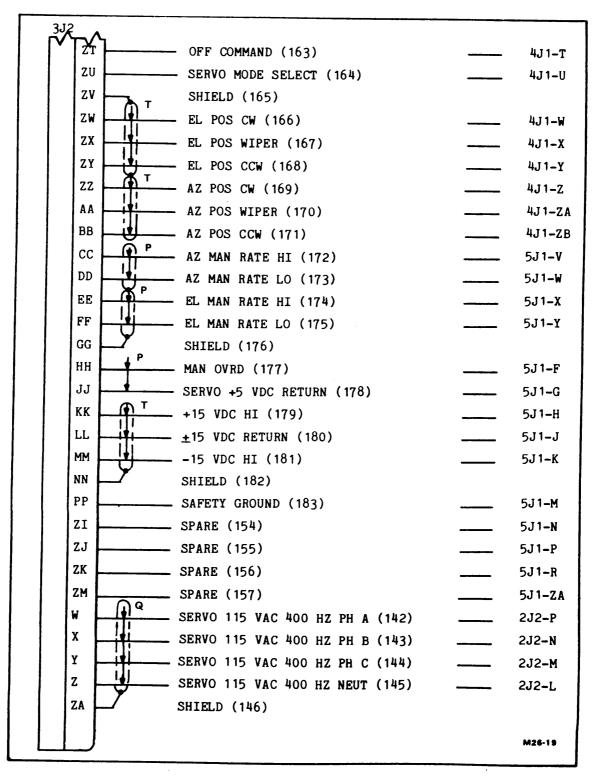


FIGURE 26. IRDS interconnecting diagram. (sheet 19 of 27)

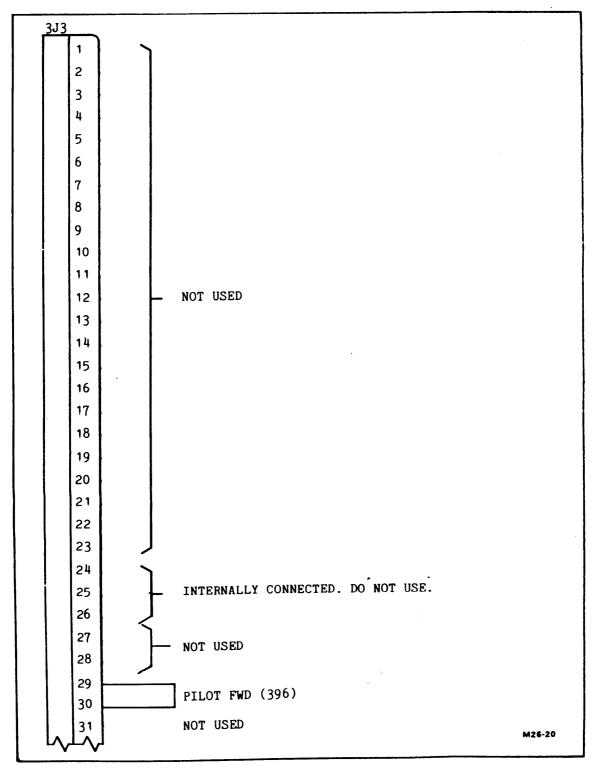


FIGURE 26. IRDS interconnecting diagram. (sheet 20 of 27)

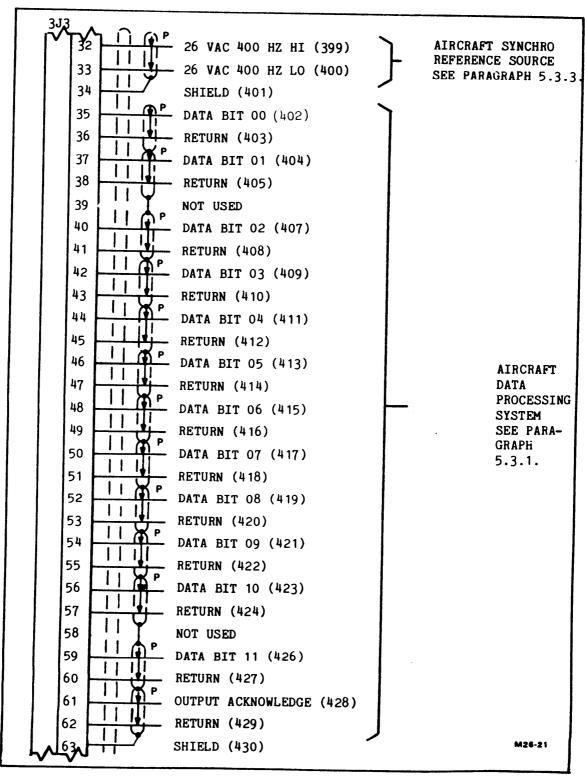


FIGURE 26. IRDS interconnecting diagram. (sheet 21 of 27)

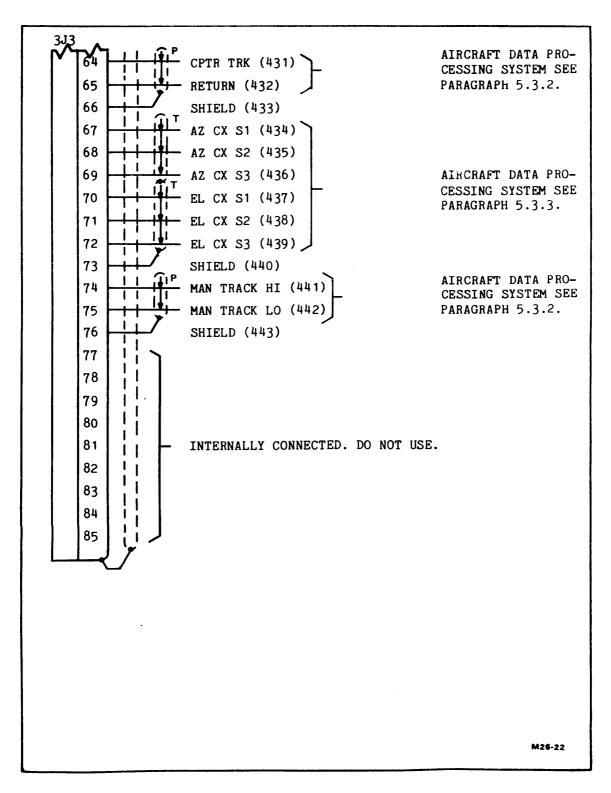


FIGURE 26. IRDS interconnecting diagram. (sheet 22 of 27)

4J1 T			
	- SPARE (187)	<del></del>	2J3-H
E   T	- SPARE (188)		2J3-ZB
F F	- SPARE (189)		2J3-ZC
ZC ZC	- GRAY SCALE HI (192)		2J3-V
ZD	- +28 VDC RETURN (193)		2J3 <b>-</b> U
ZE	- SAFETY GROUND (194)		2J3 <b>-</b> ZU
ZF	- SYSTEM GO (195)		2J3-R
ZG	RCVR FAIL (196)		2J3-P
ZH ———	- POWER SUPPLY FAIL (197)		2J3-N
ZI	- SERVO FAIL (198)	<del></del>	2J3-M
ZJ	- NOT READY (199)		2J3-L
ZK	BIT SWITCH (200)	-	2J3 <b>-</b> K
ZM	OVERTEMP (201)		2J3-J
ZN	- GO RESET (202)		2J3-S
ZP	- BIT INDICATOR (203)		2J3-T
ZQ	- +28 VDC SUPPLY (204)		2J3 <b>-</b> G
ZR	- STANDBY COMMAND (205)		2J3-F
ZS	OPERATE COMMAND (206)	<del></del>	2J3-ZG
ZU	- +18 VDC SUPPLY (207)		2J3-ZS
FF -	- FOCUS +15 VDC (219)		2J3-ZJ
GG	- FOCUS -15 VDC (220)		2J3-ZK
НН —	- FOCUS ±15 VDC RETURN (221)		2J3-ZM
AA	SYSTEM INTERLOCK (214)		
ZZ	SISTEM INTERLOCK (214)		
ZW	PANEL LIGHT SUPPLY (210)	AIRCRAFT	
ZY	PANEL LIGHT RETURN (212)	LIGHTING	CONTROL
К ———	· LAMP TEST HI (190)	AIRCRAFT	
L	- LAMP TEST RETURN (191)	TEST CONT	ROL
لملما	-		1
			M26-23

FIGURE 26. IRDS interconnecting diagram. (sheet 23 of 27)

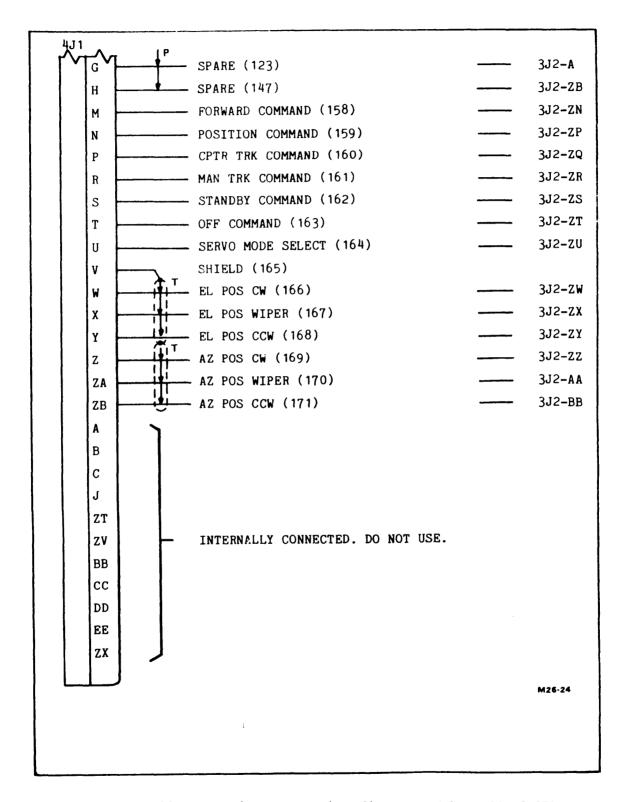


FIGURE 26. IRDS interconnecting diagram. (sheet 24 of 27)

4J2			
I TA	SPARE (307)		1J3-Y
B H			1J3-1 1J3-Z
	FOCUS HI (309)		1J3-G
D   + + + + + + + + + + + + + + + +	FOCUS LO (310)	·	133-U 133-H
$     _{E}  _{II}$	SHIELD (311)		103-11
F   <del>                             </del>	COOLING (312)	Content of the second	1J3-NN
G   <del>     </del>	+28 VDC STANDBY (313) .		1J3-BB
H + +	RETICLE INT (314)		1J3-AA
	FIELD OF VIEW NEAR (315)		1J3-ZM
K   + + + + + + + + + + + + + + +	FIELD OF VIEW RETURN (316)		1J3-ZN
	POLARITY SELECT (317)		1J3-V
M   + + + + + + + + + + + + + + + +	- POLARITY RETURN (318)		1J3-W
N   ++	SHIELD (319)		
P	- VIDEO LEVEL POT CW (320)		1J3-S
R   +   +   +	- VIDEO LEVEL POT WIPER (321)		1J3-T
S THE			1J3-U
] T   T   T   T   T   T   T   T   T   T	- VIDEO GAIN POT CW (323)		1J3-N
U   <del>         </del>	- VIDEO GAIN POT WIPER (324)		1J3-P
v <del>                                  </del>	- VIDEO GAIN POT CCW (325)		1J3-R
			M26-25

FIGURE 26. IRDS interconnecting diagram. (sheet 25 of 27)

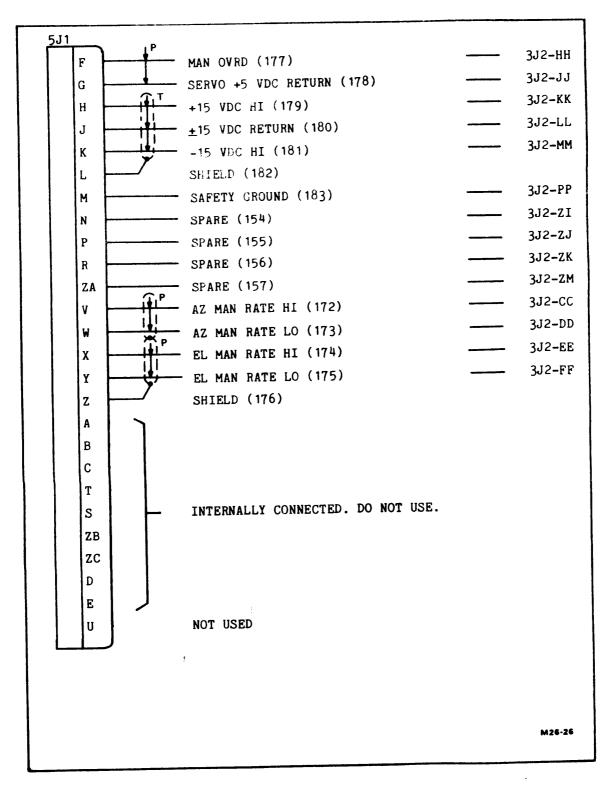


FIGURE 26. IRDS interconnecting diagram. (sheet 27 of 27)

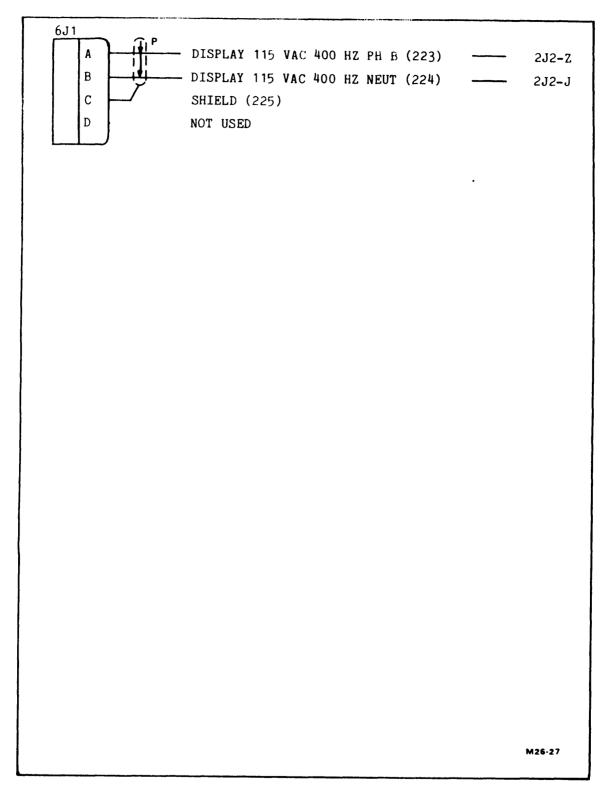


FIGURE 26. IRDS interconnecting diagram. (sheet 27 of 27)

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